



# System of Systems Operational Availability Modeling

NDIA SE Conference

San Diego, CA

October 22 – 25, 2012

Dennis J. Anderson\*

Tamara J. Brown

Charles M. Carter

Sandia National Laboratories

Albuquerque, NM

\*[djander@sandia.gov](mailto:djander@sandia.gov), 505-845-9837



# Overview

- Background and definition of System of Systems (SoS) Operational Availability ( $A_o$ )
- $A_o$  calculations
  - System and SoS  $A_o$  calculation and interpretation challenges
  - Requires defined mission durations/operations
    - Fixed vs. variable mission durations
      - Variable mission durations arise from required operating hours to complete missions
- Example SoS  $A_o$  simulation results
  - $A_o$  for individual systems as part of a SoS
  - Lower and higher reliability cases
  - Variable mission durations for fixed operating hours



# Background

---

- $A_o$  is a Department of Defense (DoD) required Key Performance Parameter (KPP) for acquisition programs
  - Represents the operational capability being provided/purchased
- $A_o$  can have different definitions and is evaluated for defined mission durations, utilizations, degraded states, and sustainment CONOPs
  - Makes assessments and comparisons difficult
  - Leads to misunderstandings and misinterpretations
- $A_o$  for a SoS has additional complexities

# A<sub>o</sub> Definitions

- Well-understood, high-level A<sub>o</sub> definition

$$\begin{aligned}A_o &= \frac{Uptime}{Uptime + Downtime} \\ &= \frac{Total\ Time - Downtime}{Total\ Time} \\ &= \frac{Operating\ Time + Operable\ Time}{Operating\ Time + Operable\ Time + Downtime}\end{aligned}$$

- Operable time (or standby time) usually defined as part of A<sub>o</sub>

- Common equation estimator of A<sub>o</sub>

$$A_o = \frac{MTBF}{MTBF + MDT}$$

where MTBF is Mean Time  
Between Failures and MDT is  
Mean Downtime

- Static, steady-state estimation of A<sub>o</sub>
- Can be misapplied
- MTBF can be scaled by utilization for intermittent use systems
- MDT has to be calculated for the specific mission duration



# System $A_o$

- $A_o$  is calculated, estimated, and modeled for
  - A specifically defined collection of *hardware*
  - Performing specifically defined *operations*
  - Over a specifically defined *timeframe*
  - With specifically defined *reliability* and *maintainability* operational performance characteristics, and
  - Specifically defined *sustainment* assumptions
- Any reported  $A_o$  reflects and depends upon all the above assumptions
  - Changes to any one of these definitions changes  $A_o$
- Comparison of  $A_o$  to requirements, other system  $A_o$ s, or across tradeoffs requires “synching up” above definitions to make comparisons valid
- Definitions and assumptions must be addressed for each intended use of  $A_o$  models
  - Assessing current performance
  - Comparison to KPP requirements
  - Prediction of test results
  - Determining sparing strategies



# System of Systems

- SoS definition
  - A SoS is comprised of a set of systems, each performing a defined task or mission, in which at least one system can be dependent on one or more other systems
    - SoS level performance is emerging and cannot be assessed by assessing individual system performances separately, except for the case where the systems operate (and are maintained) independently of each other
    - System dependencies can be of varying complexity
      - Required sequential or parallel system tasks
      - System functional redundancies
      - R of N systems operating
      - Combinations of these
- SoS becoming more common
  - More autonomous systems functioning with other systems
  - Increased network-centric functionality
  - Effectiveness and requirements established for increased system synergies accomplishing increasingly complex missions



# SoS $A_o$

- System  $A_o$  concepts are relevant to SoS  $A_o$ , but SoS adds complexity
- SoS  $A_o$ 
  - Defined as percentage of mission time the SoS is “up” (operating or operable), over a specified time interval involving defined dependent system operations
  - Dependency of systems implies that individual system(s) can be operable while another system is down
    - Produces increased  $A_o$  for individual systems within the SoS (not the same system  $A_o$  as the systems operating independently)
  - Functional interdependencies and complex interrelated sustainment operations must be accounted for in system and SoS downtimes
    - Adds additional complexity
  - Further complicated by intermittently used systems whose utilizations are considerably less than 100% over the mission duration
  - Requires more specification of the SoS systems, boundaries, and missions
- Simulation modeling is usually required to capture complex operating, operable, and downtime hours and to accurately roll up individual system availabilities to higher SoS levels

# SoS $A_o$ for Independent Systems in a SoS

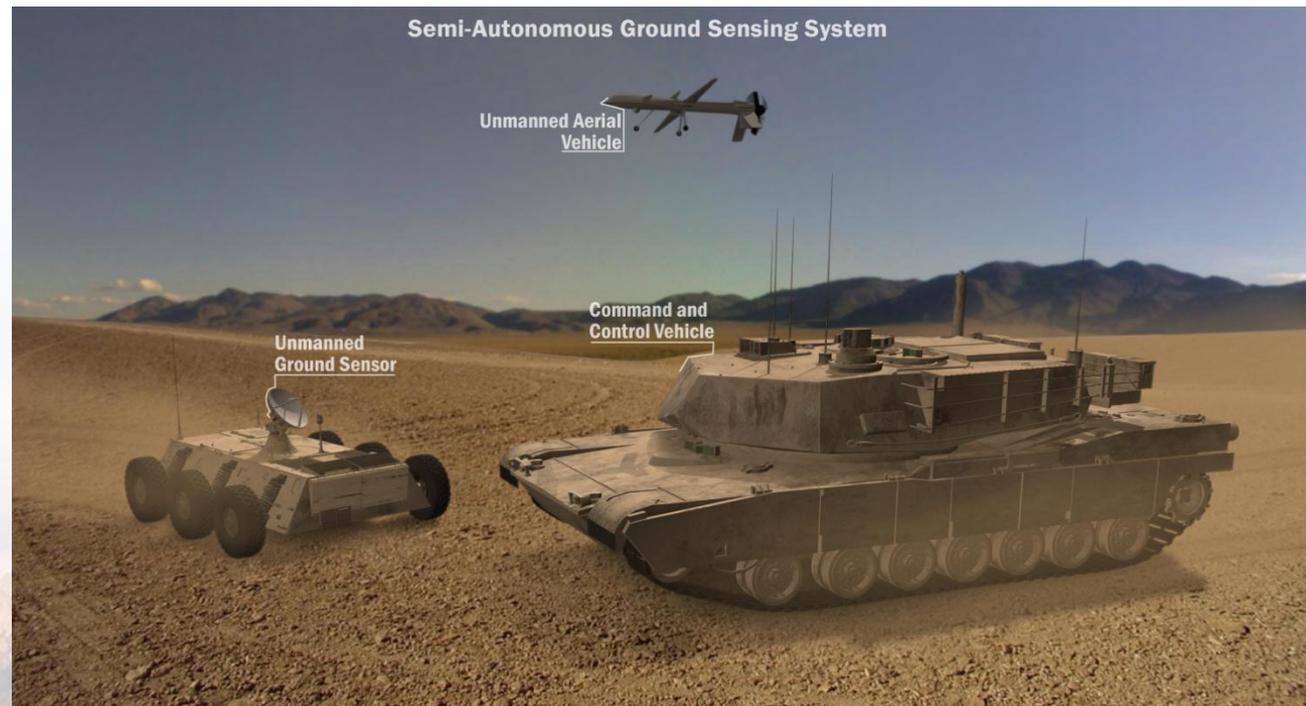
- If all systems in the SoS are operated and maintained independently, the SoS  $A_o$  is equal to the product of the individual system  $A_o$ s

$$\text{SoS } A_o = \prod_{i=1}^n A_{oi} \quad \text{where } A_{oi} \text{ is the } i^{\text{th}} \text{ independent system } A_o$$

- All systems are required for the mission
- Means that failure of one system does not impact the status of the other system(s)
- This SoS  $A_o$  represents the percent of mission time that all systems are available (operating or operable)
- Equation sometimes misunderstood as pertaining to all SoS  $A_o$  calculations, even with dependent systems

# Example SoS

- Semi-Autonomous Ground Sensing System (SAGSS) is a notional SoS to perform an IED detection mission
- SAGSS is comprised of multiple systems executing a particular mission
- Systems within the SAGSS SoS
  - Unmanned Ground Sensor (UGS) System
  - Unmanned Aerial Vehicle (UAV)
  - Command & Control Vehicle (C2V)
  - Transport Vehicle (TV)





# SAGSS Problem

- Need to understand SoS-level availability drivers
  - Support and sparing strategies/CONOPs
- Complex SoS
  - Once transported, UGS and UAV are required to operate concurrently to perform detection
    - If UAV fails during the mission, UGS becomes operable, and vice versa, but SAGSS SoS is in a failed state (down or inoperable)
  - TV only required for parts of the mission
  - C2V required during all required operational hours
  - Based on coverage rates, must perform a fixed number of hours of detection
    - Total mission duration is variable
    - Variable downtime is added to fixed operating time
- SoS  $A_0$  accounts for dependent system utilizations



# SoS $A_o$ Simulation

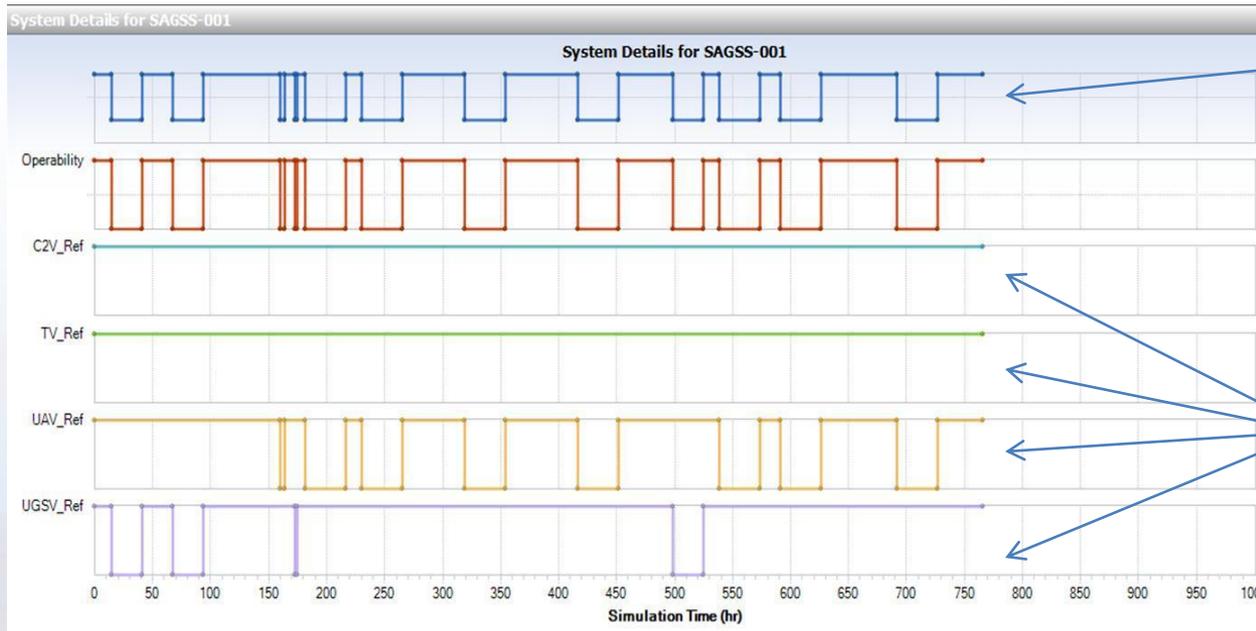
- SoS  $A_o$  for dependent systems and the individual system  $A_o$ s within the SoS cannot usually be calculated without simulation
- Use Systems of Systems Analysis Toolset (SoSAT) to analyze SoS  $A_o$ 
  - Stochastic simulation of system mission and sustainment operations
  - Variability in input parameters
  - Developed by Sandia for several Army programs
  - Developed specifically to address and scale to complex SoS problems
  - Can model thousands of systems, each represented by thousands of subsystems/components
  - Currently being applied for U.S. Army, Navy, Air Force, and Marines programs

# SoS $A_0$ Simulation Calculations

- Simulation keeps track of defined SoS uptime and downtime to calculate SoS  $A_0$  as

$$A_0 = \frac{Uptime}{Uptime + Downtime}$$

- Simulation allows for complex mission and system definitions and dependencies
- Single trial exhibit of SoS and system states (“up” or “down”) over a mission segment



State of the SoS

Individual systems operating as part of an SoS

# Notional SAGSS SoS $A_0$ Simulation Cases

- Individual system reliabilities will impact not only SoS  $A_0$  but also the individual system  $A_0$ s within the SoS
- Impacts higher for lower reliability
  - Impacts of lower individual system reliability on SoS  $A_0$  and individual system  $A_0$ s greater than for higher reliability
  - $A_0$  asymptotes as reliability increases
- Notional SAGSS SoS example analyzed for
  - Lower reliability case
  - Higher reliability case

# Summary of Notional SAGSS SoS $A_o$ Results

## Lower Reliability Case

System	MTBF (Hours)	Average Number of Failures per Mission *	Mean Downtime per Failure (Hours)	Mean Downtime per Mission * (Hours)	Percent Total SAGSS Downtime	Average $A_o$
<b>SAGSS SoS</b>	-	<b>18.8</b>	<b>22.0</b>	<b>413.0</b>	<b>100%</b>	<b>0.618</b>
UAV	50	10.3	28.0	287.6	69.6%	0.734
UGSV	100	4.7	25.5	120.6	29.2%	0.888
C2V	150	3.8	1.3	4.8	1.2%	0.995
TV	10,000	0.0	35.0 (none observed)	0.0	0.0%	1.000

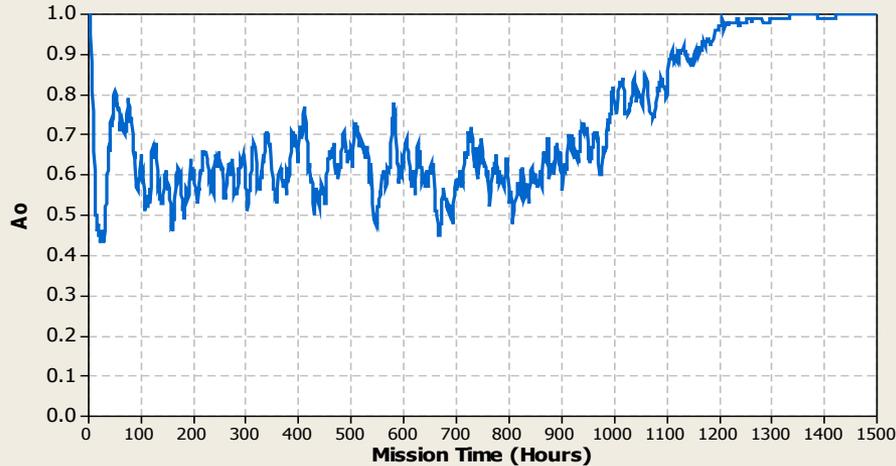
\* Mission = Completed 500 hours of remote sensor time

Low reliability of individual systems can have large impact at SoS level, but a low-reliability system will increase (inflate) the other individual system  $A_o$ s as part of the SoS

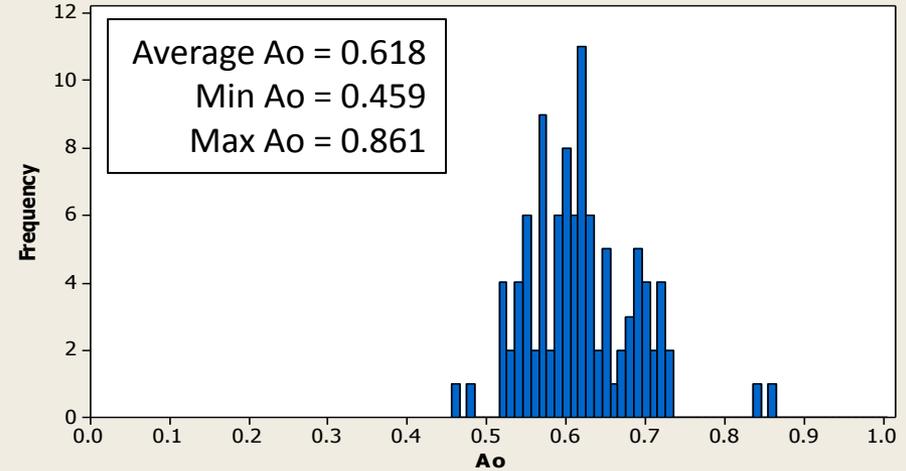
# Notional SAGSS $A_0$ vs. Time, $A_0$ Distribution, and Mission Length Distribution

## Lower Reliability Case

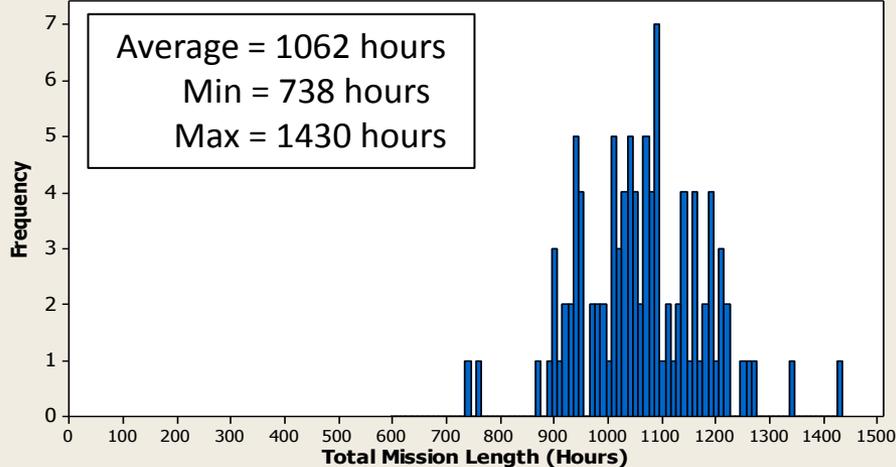
**Ao vs Mission Time (Hours)**



**Histogram of Ao**



**Histogram of Total Mission Length (Hours)**

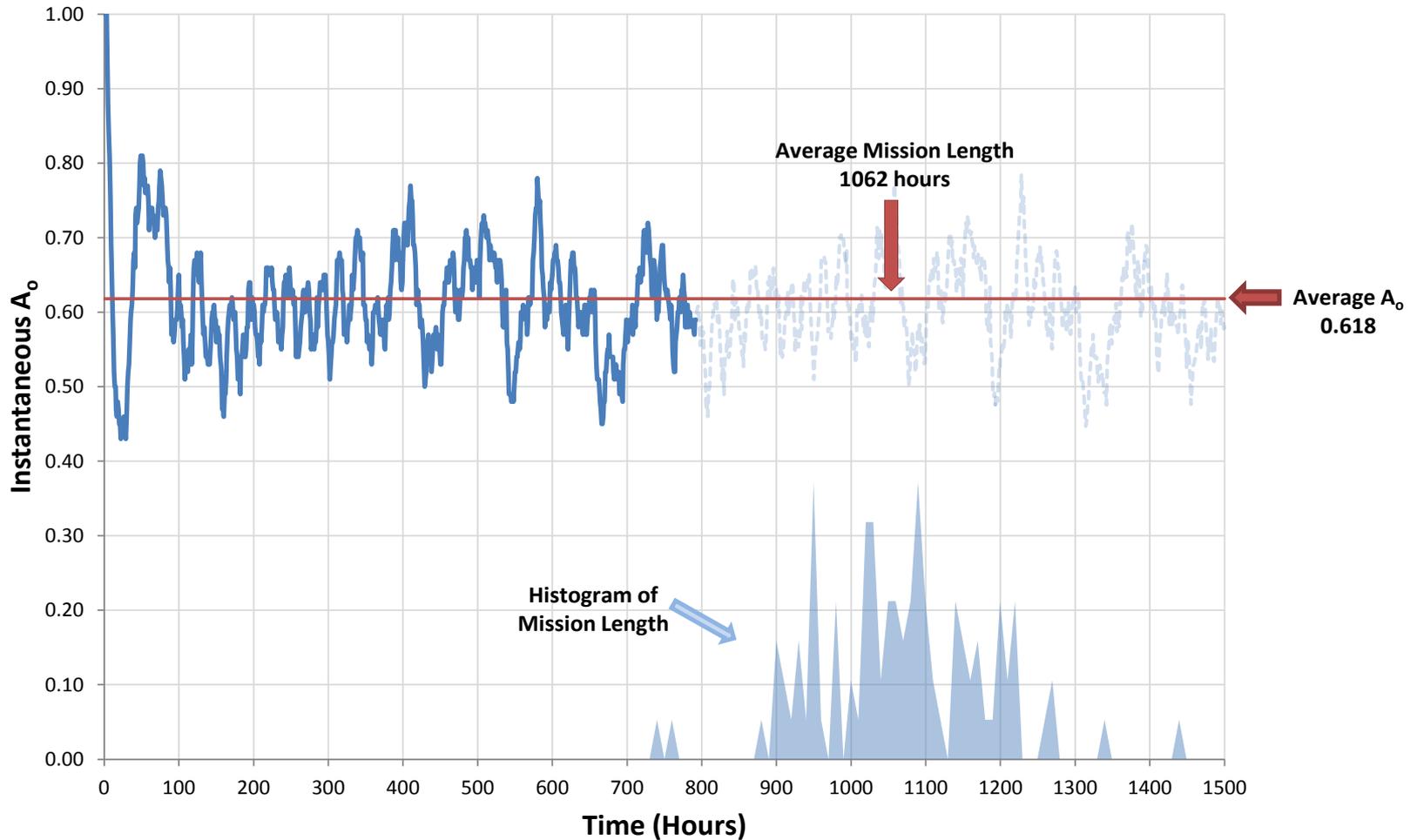


- For  $A_0$  vs. time, plot is average across simulation trials
  - All systems must be operating at end of mission
  - As mission time increases, number of trials decreases and  $A_0$  increases
- Considerable variability in  $A_0$  and mission length distributions

# Notional SAGSS SoS $A_0$ vs. Time with Mission Length Distribution

## Lower Reliability Case

### SAGGS SoS Instantaneous $A_0$ versus Mission Time



# Summary of Notional SAGSS SoS $A_o$ Results

## Higher Reliability Case

System	MTBF (Hours)	Average Number of Failures per Mission *	Mean Downtime per Failure (Hours)	Mean Downtime per Mission * (Hours)	Percent Total SAGSS Downtime	Average $A_o$
<b>SAGSS SoS</b>	-	<b>3.6</b>	<b>21.1</b>	<b>76.0</b>	<b>100%</b>	<b>0.898</b>
UAV	300	1.5	26.3	39.5	51.9%	0.948
UGS	500	1.4	25.3	35.7	47.0%	0.952
C2V	800	0.7	1.3	0.9	1.1%	0.999
CP	10,000	0.0	35.0 (none observed)	0.0	0.0%	1.000

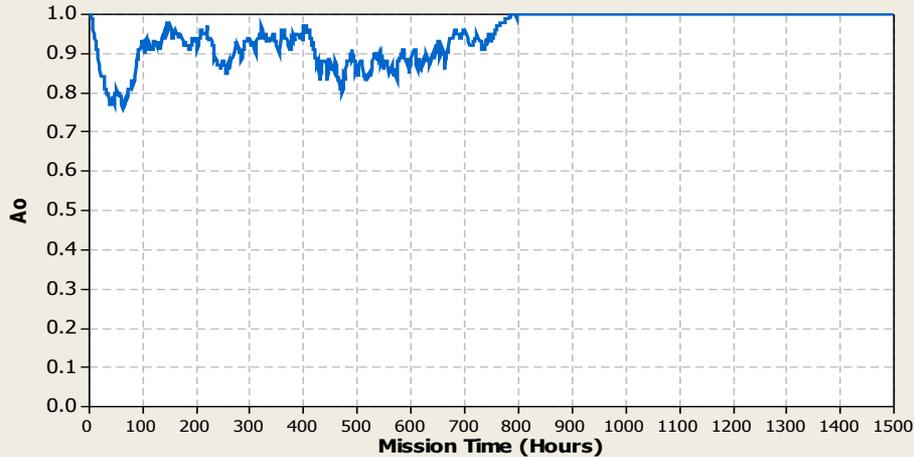
\* Mission = Completed 500 hours of remote sensor time

High reliability of individual systems have smaller impacts at SoS level, in comparison to lower reliability

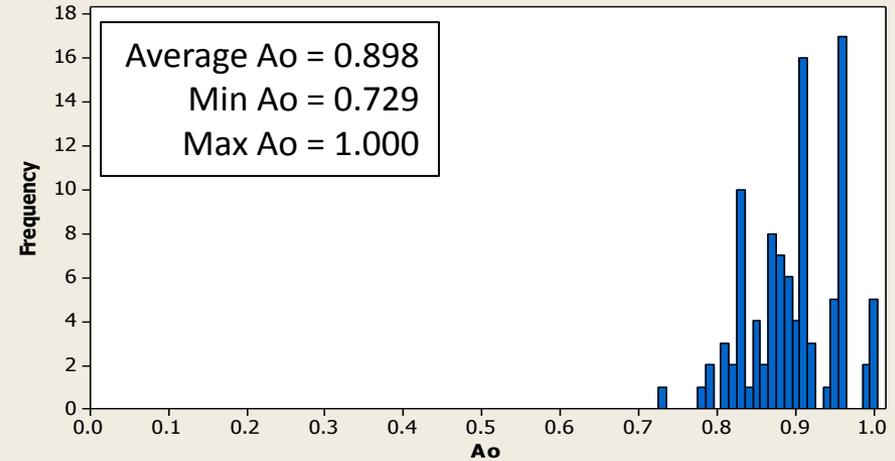
# Notional SAGSS $A_0$ vs. Time, $A_0$ Distribution, and Mission Length Distribution

## Higher Reliability Case

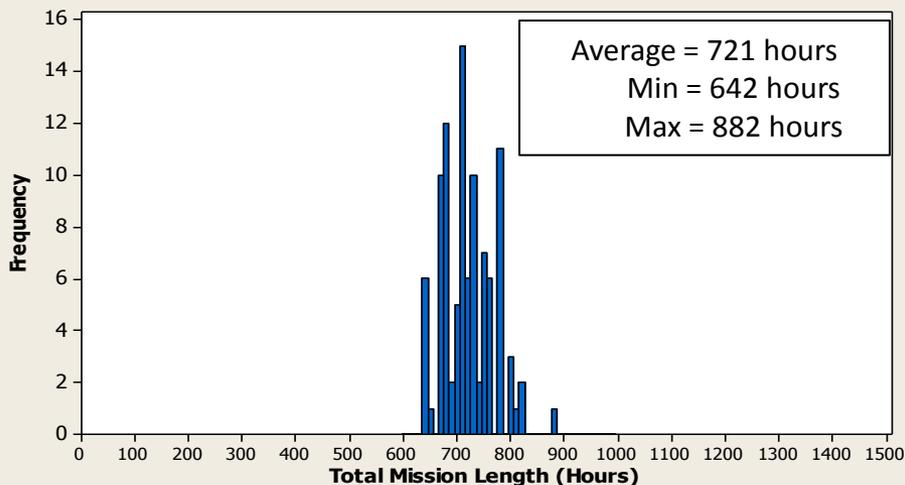
**$A_0$  vs Mission Time (Hours)**



**Histogram of  $A_0$**



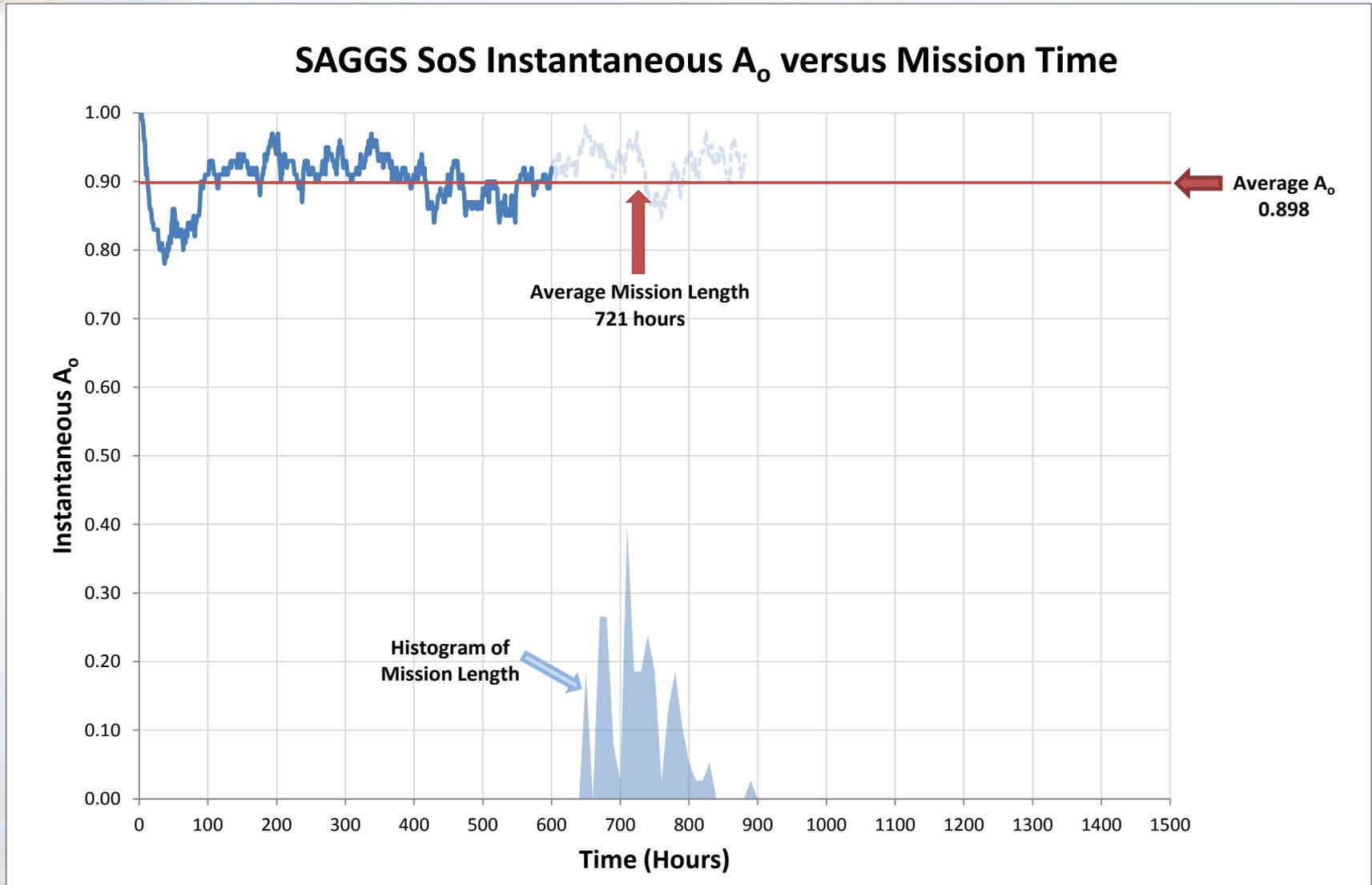
**Histogram of Total Mission Length (Hours)**



- For  $A_0$  vs. time, plot is average across simulation trials
  - All systems must be operating at end of mission
  - As mission time increases, number of trials decreases and  $A_0$  increases
- Less variability in  $A_0$  and mission length distributions in comparison to lower reliability case

# Notional SAGSS SoS $A_0$ vs. Time with Mission Length Distribution

## Higher Reliability Case



# Summary

- System  $A_o$  concepts are relevant to SoS  $A_o$ , but SoS adds complexity
  - Functional interdependencies and complex interrelated sustainment operations must be accounted for in system and SoS downtimes
  - Further complicated by intermittently used systems whose utilizations are considerably less than 100% over the mission duration
  - Requires specification of the SoS systems, boundaries, and missions
  - Dependencies of systems imply that individual system(s) can be operable while another system is down
    - Produces increased  $A_o$ s for individual systems within the SoS (not the same system  $A_o$ s as the systems operating independently)
- SoS functionality becoming more prevalent with robotic systems and networked operations
- For most SoS problems, simulation will need to be used to calculate SoS  $A_o$ 
  - No equation estimators for SoS  $A_o$