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**National  
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**RDECOM**

**TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.**

## **RAMP NDIA Brief**

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# Remote Armed Maneuver Platform

Armament Research, Development and Engineering Center's (ARDEC)  
On The Move- Armament & Technology Integration Demonstration (OTM-ATID) Effort



## Mission/Purpose:

- Achieve an **integrated capability** in the area of Remote Weapon System command and control (wireless), platform integration, deployment and C4ISR (Command, Control, Communications, Computers, Intelligence, Surveillance and Reconnaissance), through the **development of an integration platform** to begin **discussions with the user community** in the area of Robotic Lethality, CONOPS & Techniques, Tactics and Procedures (TTPs).

## Product:

- **Enhanced RWS command and control capability** with Man-in-loop remote lethal engagement of threats
- **Enhanced capability to track, engage and deliver effects** on target from a standoff location, **through the integration of Remote Weapon System (RWS) and RSTA (Reconnaissance, Surveillance, and Target Acquisition ) technologies on a robotic platform**
- **Situational Awareness enhancements** through RSTA and the use of Decision Aide



## OTM Integration Platform

- At the direction of the Research, Development and Engineering Command (**RDECOM**) Commanding General, the RAMP program was begun to provide Wireless Robotic capability to existing and emerging RWS, integrated onto Mobile platforms.
- Through the development of enabling ARDEC technology, the Wireless Extension Kit (**WEK**) and RWSs, RAMP will help transition these key technologies to the warfighter to support the development of CONOPS and TTPs to support RWS wireless engagement.
- Additionally, mature technology to support other family of systems, creating a family of wireless RWS solutions on Mobile and Stationary platforms.

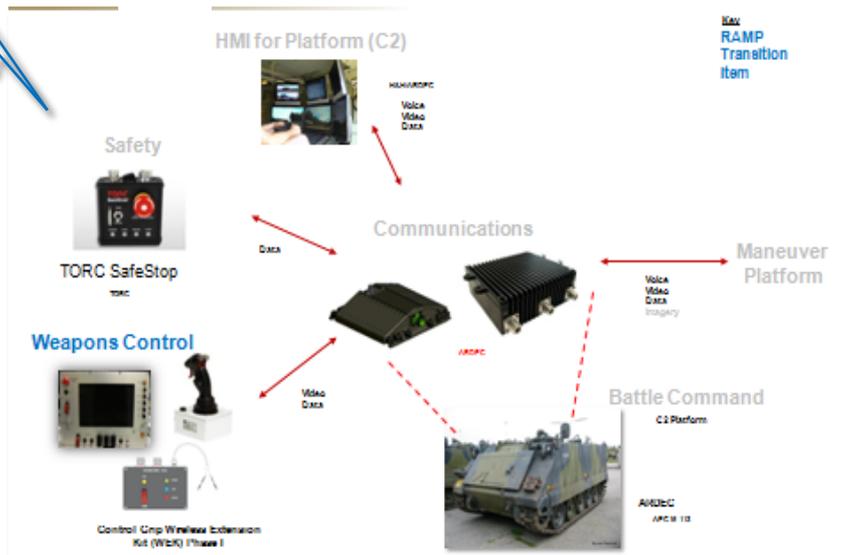
# RAMP Key Systems

- **Platform**- Surrogate Platform for evaluating OTM RWS requirements.
- **Remote Weapon System (RWS)**- Current and emerging systems.
- **Wireless Extension Kit (WEK)**- ARDEC's command and control technology for wireless RWS engagement.
- **Communications**- COTS Radio Frequency (RF) Radio.
- **RSTA**- External sensors to support RWS operation.
- **Safety**- COTS safety equipment.
- **C2**- Battle Command functionality for the system.

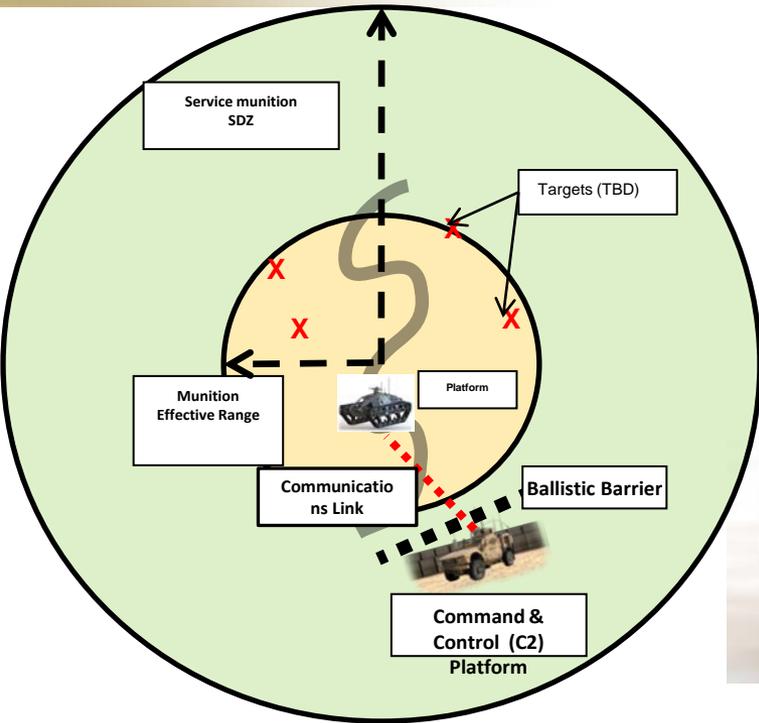


**H&H MS3 Weapon Optimized Platform**  
**CROWS II 50 Cal RWS**  
**Wireless Extension Kit (WEK) 1 Technology**  
**HARV Integration**  
**Communications Backbone**

**APC M113 Command and Control (C2) Platform**  
**RWS, Platform and HARV OCU**



**TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.**



## Maneuver

- MS3 surrogate vehicle
- MS3 modifications & Vehicle Integration Kit (VIK) development
- Weapons Integration onto MS3 Platform

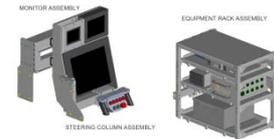


## RIPSAW Mil Spec-3



## OTM Integration Platform

## Battle Command



## C2 Platform or TOC

- Develop, Integrate RWS C2 Package onto platform or C2 TOC

## Muniton



## 7.62mm & .50 Cal SRTA\* & Ball Live Fire

## Lethality



## CROWS

- CROWS (.50cal/ & 7.62 mm capable)
- Phase 1 WEK Tele-Operation

## Weapons Control



## Control Grip Wireless Extension Kit (WEK) Phase I

# OTM-ATIP Weapon and Technology Road Map Objective



## Mil Specification 3 Ripsaw

Side view



3/4 view



+

Advanced  
Remote/Robotic  
Armament  
System  
(ARAS) 50 Cal  
RWS



**TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.**

- Provide Wireless RWS command and control & engagement.
  - Enhanced Slew to cue capability
  - Support Lethal and Non-lethal engagement
  - OTM capability
  - Support Hunter-Killer CONOPs
  - Enhanced RSTA capability
- Mature WEK technology to provide enhanced capability for integration to create larger family of wireless RWS systems.

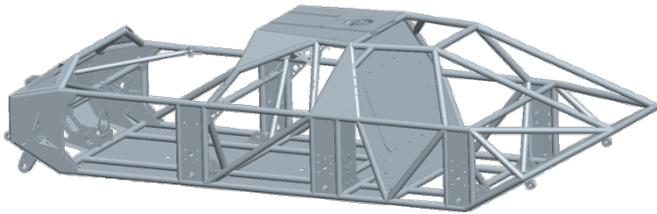
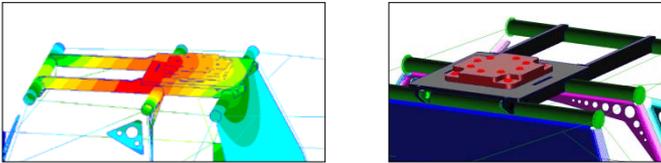
- RAMP supports the development and maturation of a Wireless Extension Kit (WEK) which provides a leap ahead capability in the employment and operation of RWS for robotic or fixed-site applications.
- This is done by providing wireless functionality to current and emerging RWS.
- RAMP's leap ahead capability provides engineers with a better understanding of how RWS are deployed, and impacted from supporting On-the-Move (OTM) TTPs.

- Working with TRADOC and User Community to define Operational ConOps for employment of RAMP and Robotic like assets.
- Working with Army to better define RWS and robotic emerging requirements.
- Working with Army to translate operational user requirements into system requirements to establish technology performance baseline
- Working with government and industry to leverage GOT/COTs technology for RWS applications.

Due to the lethality and nature of RWS, these system place stringent and aggressive requirements on the technology at the subsystem level.

- RWS network and communications requirements challenges can be characterized as needing:
  - Low Latency
  - High Bandwidth
  - High QoS
  - High Reliability
- Other technical challenges
  - RF challenges created from being on the move
  - Low Latency/Low Bandwidth codec development for video transmission to support RSTA functionality.
- Future employment of Security/Encryption on communications links

## Dynamic Structural Analysis for MS3 w/ CROWS 50 Cal (Completed)



- Determined viability of firing CROWS on MS3
- Analyzed frame deflection, stress, and mode shapes

*“Good News Story”*

## ARAS 7.62 and MS3 SWAP Study (On-Going)



- ARAS RWS CAD Integration
- Preliminary SWAP Analysis

## Radio (C4ISR) Characterization Study (On-Going)



**Motorola**

**COBHAM**

Current Best Technical Approach (BTA)

## Wireless Extension Kit (WEK) Development/Integration (On-Going)



Design Optimization for Video



# OTM-ATIP Weapon and Technology Road Map



		Increment 1	Increment 2	Increment 3
Maneuver	<u>Platform</u>	<ul style="list-style-type: none"> <li>• MS3 VIK development</li> <li>• Integration onto RIPS AW MS3</li> </ul>	Continue Integration onto RIPS AW MS3	Integration onto current or updated MS Platform Version
Lethality/ Protection	<u>RWS</u>	<ul style="list-style-type: none"> <li>• CROWS II Split Screen (7.62 mm or 50 Cal capable)</li> <li>• Integration of Phase 1 WEK (Tele-Operation)</li> <li>• Begin development of Phase 2 WEK Enhancements</li> </ul>	<ul style="list-style-type: none"> <li>• CROWS 50 Cal</li> <li>• Integration of Phase 2 WEK (Tele-Operation Enhancements)</li> </ul>	<ul style="list-style-type: none"> <li>• ARAS 50 Cal RWS*</li> <li>• Bore sited Optics Package</li> <li>• Integration of Phase 2+ WEK Enhancements*</li> <li>• TRL 5/6</li> <li>• Full Tele-Operation</li> </ul>
	<u>Slew-to -Cue</u>	None- Only receive S-T-C message, can not be accepted by system only displayed. Manual Slew to position by Gunner	<ul style="list-style-type: none"> <li>• Increased Slew-to-cue capability</li> <li>• Initial integration with external RSTA sensors</li> </ul>	<ul style="list-style-type: none"> <li>• Increased Slew-to-cue and Hunter-Killer capability</li> <li>• Integration with external RSTA sensors and BC decision aid SW</li> </ul>
	<u>Non-Lethal Technologies</u>		<ul style="list-style-type: none"> <li>• Begin looking at potential technologies and integration strategy for Non-lethal technologies</li> </ul>	<ul style="list-style-type: none"> <li>• Tech insertion of Non-Lethal Technologies</li> </ul>
C4ISR	<u>Communications</u>	<ul style="list-style-type: none"> <li>• Begin work with CERDEC and others to ID emerging requirements and architecture</li> <li>• Feasibility of current REDSHIRT Architecture and H&amp;H Radios/Cameras</li> <li>• Acquire radios: CERDEC/H&amp;H/Other</li> </ul>	<ul style="list-style-type: none"> <li>• Continue Radio Characterization Studies to ID radio to meet WEK 2 radio requirements.</li> </ul>	<ul style="list-style-type: none"> <li>• Update, increased robustness communication network to support integrated (Data, Video, Imagery and Voice) requirements</li> <li>• Address Crew Compliance Req</li> </ul>
	<u>RSTA</u>	<ul style="list-style-type: none"> <li>• Limited external support</li> <li>• Work to integrate HARV onto platform</li> <li>• Begin to look at integration strategy for RSTA assets and RWS.</li> </ul>	<ul style="list-style-type: none"> <li>• Full RSTA candidates integration</li> </ul>	RSTA fully integrated with Firestorm.
	<u>Command and Control (C2)</u>	<ul style="list-style-type: none"> <li>• Acquire, &amp; Integrate C2 Package onto: M113 APC, or C2 TOC</li> </ul>	<ul style="list-style-type: none"> <li>• TBD</li> </ul>	TBD
	<u>Battle Command (BC)</u>	NA	<ul style="list-style-type: none"> <li>• Begin initial integration strategy of RSTA assets and RWS with Decision-Aid SW</li> </ul>	<ul style="list-style-type: none"> <li>• Firestorm Decision Aide Capability and integration into RWS</li> </ul>



## ***Project Deliverables***

- *CROWS and initial ARAS 7.62/50 cal. vehicle/platform integration*
- *Wireless Weapon command/control via Wireless Extension Kit (WEK)*
- *Preliminary Hunter-Killer Capability (HARV/CROWS/Firestorm)*
- *System Level, and Subsystem Requirements and Specifications*
- *Limited Scope Capstone Demonstration and Live Fire*

- **ARDEC PATH FORWARD**

- *Continue to mature WEK Technology.*
  - *WEK Safety Documentation, Fabrication and Assembly*
  - *RWS Suite Engineering Level Testing (ELT) and Integration*
- *Communications TIM with CERDEC to identify emerging RWS and Tele-Operation Requirements (Planning Phase)*
  - *ARDEC will provide RWS Overview, & present system requirements (Picatinny)*
  - *CERDEC will provide overview of communication technologies that may meet system needs (APG)*
- *User engagement to define Operational Requirements for RWS deployment.*
  - *Working with ARDEC Liaison's to interface with User community to develop CONOPS and Requirements.*



Questions?

