HIGH ACCURACY ISENTROPIC COMPRESSION STUDIES WITH HIGH EXPLOSIVE PULSED POWER *

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Abstract

An study of the one-dimensional isentropic compression experiment (ICE), performed with High Explosive Pulsed Power (HEPP), has demonstrated that accurate, high stress, isentropic Equations of State (EOS) data may be obtained with this technique.

The physics and accuracy of electromagnetic loading in the ICE technique is presented. It is shown that the HEPP-ICE load configuration is capable of producing magnetic stresses that are uniform to 1 part in 1000 over the central 87% of the sample faces, and that HEPP-ICE provides exact matching of the stresses between opposing samples. This magnetic uniformity, the exact matching, and the large sample samples possible with HEPP-ICE, are necessary for the highest accuracy isentropic EOS data.

Isentropic EOS data have been obtained with a prototype HEPP-ICE system, and the results for tungsten and copper demonstrate the inaccuracy of the technique, which may be as low as 0.2% in stress. It is shown that a large-scale HEPP-ICE system is capable of producing shock-free loading up to 2.2 TPa in 10-mm thick tungsten samples.

I. INTRODUCTION

The basic techniques of HEPP-ICE have been described previously [1,2,3]. The original ICE technique is due to Asay [4], and a significant body of ICE work has been conducted on the Z-machine at the Sandia National Laboratory. In the ICE experiment, smoothly rising (shock-free) mechanical compression waves are propagated into matched samples of different thicknesses by electromagnetic loading in a planar geometry. A complete EOS isentrope is acquired in one experiment, i.e., continuously from zero up to the peak stress. Good quality isentropic EOS data have been obtained for many materials [5,6,7].

A. ICE method

Two identical samples, with a difference in thickness of \( h \), are compressed by identical B-forces and their particle velocity profiles, \( u(t) \), are obtained from VISAR measurements at the rear free surfaces, Figure 1. The magnetic stress is given by the vector cross-product \( P_B = J \times B \), where \( J \) is the current per unit width (\( dI/dW \)). In the simplest case, when the plate width, \( W >> d \), the plate separation, the magnetic field on the inside surface of one conductor due the current in the opposing surface is \( \frac{1}{2} \mu_0 J \) (SI units are used throughout this paper). Then the stress normal to the inside surfaces \( P_B = J \times B = \frac{1}{2} \mu_0 J^2 \). (As \( d \) increases with time and/or when the current is non-steady, then \( B < \frac{1}{2} \mu_0 J^2 \) and becomes non-uniform, see below.)

Using Lagrangian wave analysis [8] the Lagrangian wave speed is \( C_L(u) = h / \Delta t(u) \). The differential form of the Lagrangian momentum conservation equation is

\[
d \sigma = \rho_0 C_L(u) du
\]

which is used to calculate the change in stress, \( d\sigma \), for each change (step) in particle velocity, \( du \), going up the curve \( u(t) \), where \( \rho_0 \) is the initial density (\( h \) and \( \rho_0 \) are constant in Lagrangian space). Continuous EOS

Figure 1. Top: Velocities \( U_1 \) and \( U_2 \) are measured at the outer surfaces of samples S1, S2. Bottom: velocity \( C_L(u) \) is obtained from \( U_1 \) and \( U_2 \), point by point.
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relationships between stress, wave speed, particle velocity, etc., from zero to the peak stress are thus obtained.

B. HEPP-ICE apparatus

A 6 mF, 20 kV capacitor bank provides a seed current of ~2 MA to a 4-in×5-in plate flux compressor [2]. The FCG transfers up to 12 MA into a storage inductor of ~25 nH and an explosively-formed fuse (EFF) opening switch. Three parallel explosively-driven polyimide closing switches [9] then transfer current to the load at the appropriate time. This prototype circuit is capable of delivering 7 MA (dI/dt ~3 ×10\(^{13}\) A/s) into loads of typically 1 to 2 cm width and will produce isentropic compression at stresses in the range of 0 to 250 GPa. However, advanced HEPP-ICE systems are capable of producing isentropic data beyond 2 TPa [10].

C. Stress uniformity and exact B-field matching in an HEPP-ICE load

It is crucial that the samples are subjected to identical and uniform magnetic stresses. Previously we showed that for static current flow the B-field becomes increasing non-uniform across the width as the ratio of separation to width, \(d/W\), is increased [11]. However, during the EOS-data gathering portions of ICE experiments the current is always rising in the load, i.e., \(dI/dt > 0\). The rise is approximately sinusoidal, rising from 0 to \(\pi/2\) over ~½µs. For parallel plates, the current flows preferentially along the outside edges of the load, where the specific electrical impedance is a minimum. The dynamic current and stress distributions have been modeled with a finite element partial differential equation code [12]; the stress plot is shown in Figure 2.

Figure 2. Magnetic stress \(P_B\) on the inside surface of a parallel conductor. The width of the conductor is along the X-axis, the thickness along the Y-axis (drawn to a 4x larger scale than the X axis for clarity).

The calculation shows that for the parallel plate configuration used in HEPP-ICE, under typical dynamic conditions, the stress is uniform to 1 part in 10\(^3\) across the central 87% of the conductors. (The plot is for a \(d/W\) ratio of 0.3, which would occur towards the end of experiment, when uniformity is at its worst.)

For exactly matched magnetic stress loading, the sample positions are important. In Figure 3 two opposing sample pairs, S1 and S2, S3 and S4 are shown and they share the magnetic fields \(B_{12}\) and \(B_{34}\). Currents flow in and out from the source at the bottom, and as they do so, the currents redistribute themselves as the samples separate under magnetic loading. The samples will have different thicknesses and may have different acoustic impedances and will consequent separate with different accelerations. We have found that the stresses corresponding to \(B_{12}\) and \(B_{34}\) may differ by as much as 5%. The advantages of the parallel plate configuration used in HEPP-ICE are that the B-fields and stresses are exactly matched for opposing samples because they always share the same B-field and the central B-field is very uniform.

D. Higher stresses, larger sample sizes and higher accuracy in HEPP-ICE experiments

One important advantage of the HEPP-ICE over other ICE techniques is that the experiment can be scaled to any magnitude of current, and hence stress, by simply by choosing the appropriate HEPP components. When designing an ICE experiment it is important to prevent the ramp wave developing into a shock wave by the so-called shock-up process. Shock-up is caused by the fact that the compression wave velocity is stress dependent, and in most materials the wave velocity increases with stress. Should shock-up occur in any of the samples in an HEPP-ICE experiment, the compression of the material would no longer be isentropic after the shock has developed. The maximum stress and sample size ultimately depend
on how well the shock-up in a material can be delayed. The method of characteristics [13] can be used to design the optimum current profiles to prevent shock-up, they are shown for 2.2-TPa HEPP-ICE experiments and 20-mm wide tungsten samples in Figure 4. Here, the maximum thickness without shock-up is 10 mm, the maximum current is 65 MA, and the risetime is 2 µs. The current, peak \( \frac{dI}{dt} \) (40 TA/s) and risetime are well within the capabilities of existing HEPP components presently used at LANL.

\[ \Delta t = \frac{h}{C_L(u)} \]

where the three terms on the right hand side are the fractional errors in thickness, particle velocity and transit time. Note that the transit time is \( \Delta t = h \div C_L(u) \), so the timing error increases with wave velocity \( C_L(u) \).

The inaccuracy of the VISAR surface velocity measurement can be as small as 0.1% with careful preparation, and may be ~2% otherwise [15]. The measurement of wave velocity is \( C_L(u) = h \div \Delta t \), and both \( h \) (thickness) and \( \Delta t \) (time difference) are sources of error. Presently, \( h \) may be measured to an accuracy of 1 µm, which represents an error of 0.01% for a 10-mm thick sample.

The errors in time are caused by the lack of synchronization between VISAR signals and by the time resolution, \( \Delta t \), of the VISARs. After synchronization of the data there remains a possible systematic error of up to \( \pm \frac{1}{2} \Delta t \) between channels. This error can have a significant effect on the accuracy of \( C_L \). For example, for \( h = 1 \) mm, \( C_L = 7 \) km/s, and \( \Delta t = 143.86 \) ns, an error of \( \pm 1/2 \) ns would render an error in \( C_L \) of up to \( \pm 0.35\% \).

Despite these systematic timing errors, for the results to be consistent they must all lie on the same isentrope. Consequently, the data may be adjusted by a minimization algorithm that adds a fixed time correction to each curve in turn until the standard deviation between the \( C_L \) vs. stress curves is minimized and the data are self-consistent; within 1%, which is also the estimated error in these tungsten experiments caused by the difficulties of measuring the sample thicknesses to the required accuracy in this particular experiment.

### III. ACCURACY OF ICE TECHNIQUE

The accuracy of the ICE technique is limited by the accuracy of the wave and particle velocity measurements, and the uniformity of the stress loading. Substituting \( \Delta t \)'s for the \( \Delta t \)'s in Equation (1) to represent the finite steps in the data, the fractional error of steps in stress is

\[ \frac{d\Delta \sigma}{\Delta \sigma} \approx \frac{dh}{h} \div \frac{d\Delta u}{\Delta u} + c_L(u) \frac{d\Delta t}{h} \]

where the three terms on the right hand side are the fractional errors in thickness, particle velocity and transit time. Within the inset, \( X \) = HEPP-ICE data, \( C \) = calculated isentrope.

**Figure 5.** Tungsten: pressure vs. particle velocity data. Within the inset, \( X \) = HEPP-ICE data, \( C \) = calculated isentrope.
these adjustments must lie within $\pm \frac{1}{2} dt$. This algorithm works well but presently lacks mathematical rigor. However, using this algorithm the standard deviation between records was reduced to ~0.2% for the copper data. These data demonstrate the capabilities of the technique, but until we can devise a rigorous algorithm we cannot assert that 0.2% is the true error. The use of a velocimeter (VISAR or PDV [16]) with better time resolution is preferred. All errors are summarized in Table 1.

### IV. SUMMARY

It has been shown that the HEPP-ICE load configuration can produce magnetic stress uniformity to better than 1 part in 1000 over the central 87% of the sample faces, and it provides exact matching of the stresses between opposing samples. A large-scale HEPP-ICE system is capable of producing shock-free loading up to 2.2 TPa in 10 mm thick tungsten samples.

The accuracy of the HEPP-ICE system is enhanced by the uniformity and matching of magnetic stress loading, and by the larger sample sizes that can be used in HEPP-ICE. Data for tungsten (and copper) have been presented which demonstrate the inaccuracies of the technique, which may be as low as 0.2% in stress.

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### VI. REFERENCES

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