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INTEGRABLE EQUATIONS IN MULTI-DIMENSIONS (2+1) ARE BI-HAMILTONIAN SYSTEMS

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1. INTRODUCTION

Ablowitz, Kaup, Newell and Segur [1], following ideas of Lax [2] were the first to solve in the concrete case of the Dirac problem the following question: Given a linear eigenvalue problem find all nonlinear equations that are related to it. They found that associated with a given eigenvalue problem there exists a hierarchy of infinitely many equations. This hierarchy is generated by a certain linear operator. This operator is the squared eigenfunction operator of the underlying linear eigenvalue problem. The operator generating the KdV hierarchy (i.e. the squared eigenfunction operator of the Schrödinger eigenvalue problem) was found by Lenard. For other eigenvalue problems see [3]-[10].

Olver [11] established the group theoretical origin of the above hierarchy: Finding the hierarchy associated with a given equation is equivalent to finding the non-Lie point symmetries of the given equation. He thus interpreted the squared eigenfunction operator as an operator

+Lectures given by one of us (A.S.F.) at the Winter School, Tiruchirapalli, India, January 1987.
mapping symmetries onto symmetries; this lead to a simple mathematical characterization of the recursion operator $\phi$. Olver, was thus the first to establish that certain integrable nonlinear equations possess infinitely many symmetries. This motivates the following question: Is there an algorithmic way for generating equations possessing infinitely many symmetries? Fuchssteiner [12] discovered such a way: If an operator $\phi$ has a certain mathematical property called hereditary then the equations $u_t = \phi^n u_x$, $n$ integer, possess infinitely many symmetries. From the above discussion it follows that both linear eigenvalue problems and hereditary operators yield hierarchies of equations possessing infinitely many symmetries. Actually Anderson and the author [13], following ideas of Fuchssteiner, have shown that eigenvalue problems algorithmically imply hereditary operators.

Equations solvable by the Inverse Scattering Transform are Hamiltonian systems. Magri, in a pioneering paper [14], realized that integrable Hamiltonian systems have additional structure: They are bi-Hamiltonian systems. Actually the underlying hereditary operator can be factorized in terms of the two associated Hamiltonian operators. The theory of factorizable hereditary operators has been further developed by Fuchssteiner and the author [15] and by Gel’fand and Dorfman [16].

The understanding of the central role played by factorizable hereditary operators for equations in $1+1$, motivated a search for hereditary operators for equations in $2+1$. However, in this direction several negative results have appeared in the literature. For example, Zakharov and Konopelchenko [17], in an interesting paper proved that recursion operators (of a certain type naturally motivated from the results in $1+1$) did not exist in multidimensions. A similar result has
been proven for the Benjamin-Ono (BO) equation [18]. It should be noted that the BO equation has more similarities [19] with the Kadomtsev-Petviashvili (KP) equation than with the KdV equation. Fuchssteiner and the author [18] after failing to find a recursion operator for the BO introduced the concept of the master-symmetries $\tau$. Subsequently Oevel and Fuchssteiner [20] found a master-symmetry for the KP equation. The $\tau$ theory for equations in 2+1 has been developed by Dorfman [21] and Fuchssteiner [22]. However, the $\tau$ is not related to the underlying isospectral problem and also cannot be used to construct a second Hamiltonian operator. This is a serious drawback: several prominent investigators, for example Gel'fand [23] have considered the existence of a bi-Hamiltonian formulation as fundamental to integrability. Without finding a recursion operator $\phi$, one cannot find the second Hamiltonian operator. Several investigators have noticed that master-symmetries also exist for equations in 1+1. The theory for the master-symmetries $T$ in 1+1 was developed by Oevel [24] (see also [25]) and is more satisfactory than the theory in 2+1: If one assumes that an equation is invariant under scaling then there exist a one to one constructive relationship between $T$ and the recursion operator $\phi$.

Recently P.M. Santini and the author [26]-[28] have found the recursion operator and the bi-Hamiltonian formulation of a large class of equations in 2+1. They have also established the general theory associated with factorizable recursion operators in multidimensions. Furthermore, both gradient and non-gradient (the 2+1 analogue of $T$) master-symmetries are simply derived and their general theory is developed.
2. MASTER SYMMETRIES

In this section we review certain aspects of non-gradient master-symmetries in 1+1 and gradient master-symmetries in 2+1.

Definition 2.1.

A function \( \tau \) is a master-symmetry of the equation \( q_t = \mathcal{K} \) iff the map

\[
[[\cdot , \cdot ]_L \quad \text{where} \quad [a,b]_L = a'[b] - b'[a] \quad (2.1)
\]

maps symmetries onto symmetries (prime denotes Fréchet derivative).

The first example of a master-symmetry was given for the Benjamin-Ono equation

\[
q_t = Hq_{xx} + 2qq_x, \quad (Hf)(x) = f_x^2 - f_{xx} \quad (4.2)
\]

It was shown in [18] that if \(\tau \neq x(Hq_{xx} + 2qq_x) + q_x^2 + \frac{3}{2} Hq_x\) and \(\sigma_n\) is a symmetry then \(\sigma_{n+1} = [\sigma_n, \cdot]\) is also a symmetry. It was further shown in [18] that \(D^{-1}\) is a gradient function (\(D \cdot D^{-1} \cdot = 0\)).

Master-symmetries are intimately related to time-dependent non-Lie-point symmetries [25]. Indeed, the first non-Lie-point time-dependent symmetry is a natural candidate for a master-symmetry: Consider the evolution equation \(q_t = \mathcal{K}^{(1)}\) and let \(\mathcal{K}^{(2)}, \mathcal{K}^{(3)}, \ldots\) denote its time-independent non-Lie-point symmetries. Let

\[
\tau^{(2)} = t\mathcal{K}^{(2)} \quad (2.3)
\]

be a time-dependent non-Lie-point symmetry. Then

\[
\mathcal{K}^{(2)} + \tau^{(2)} + \ldots, \quad [\mathcal{K}^{(1)}, \cdot]_L = \mathcal{O}, \quad \text{or} \quad \tau^{(2)} = [\mathcal{K}^{(1)}, \cdot]_L
\]

and \(\tau\) is a candidate for a master-symmetry.
2.1. Master-symmetries for equations in 1+1.

Lemma 2.1.

Let

$$S_i \triangleq \phi^i[K_i] + [\phi, K_i], \quad i = 1, 2. \quad (2.4)$$

If \( \phi \) is hereditary, i.e. if

$$\phi^i[vw] - \phi^i[vw] \quad \text{is symmetric w.r.t.} \quad v, w, \text{ then}$$

$$\phi^{n+m}[K_1, K_2]_L = [\phi^nK_1, \phi^mK_2]_L + \phi^n(\sum_{r=1}^{m} \phi^{m-r}S_1\phi^{r-1})K_r - \phi^m(\sum_{r=1}^{n} \phi^{n-r}S_2\phi^{r-1})K_1, \quad (2.5)$$

\( n, m \) are non-negative integers.

Proof.

See Theorem 2.1 of [28].

Corollary 2.1.

Assume that \( \tau_0 \) is a scaling of both \( K \) and of the hereditary operator \( + \), i.e.

$$[K, \tau_0] = \lambda K, \quad [\cdot, \tau_0] + [\cdot, \tau_0] = a. \quad (2.6)$$

Then

(i) \( (a + n\lambda)\phi^{n+1}K = [\phi^nK, \phi\tau_{\cdot, \cdot}]_L \),

\( i.e. \phi_{\cdot, \cdot} \) is a master-symmetry for \( q_t = K \).

(ii) \( (x + n\lambda)\phi^{n+1}K = [\phi^nK, \phi\tau_{\cdot, \cdot}]_L \),

\( i.e. \phi_{\cdot, \cdot} \) is a master-symmetry of order \( m \) for \( q_t = K \).

(iii) \( \phi \) \( (a + n\lambda)\phi^{n+1}K + \tau_{\cdot, \cdot} \) is a symmetry of \( q_t = \phi^nK \).

Proof.

(i) Apply Theorem 2.1 with
\[ K_1 = K, \quad K_2 = \varepsilon_0, \quad [K_1, K_2] = aK, \quad L_1 = 0, \quad L_2 = 8\phi. \]

(ii) Similar to (i).

(iii) Use the definition of a symmetry.

In the above we derive \( T \) from \( \phi \). Now we obtain \( \phi \) from \( T \).

Lemma 2.2.

Let \( \phi \) be a hereditary operator such that \( \phi \phi = \varepsilon \phi^+ \), where \( \varepsilon \) is a constant, invertible, skew-symmetric operator. Then

\[
(\varepsilon T) + \varepsilon(\varepsilon T)^+ \phi^{-1} = \varepsilon(T + \varepsilon(T')^+ \phi^{-1} + \varepsilon S \phi^{-1}),
\]

where

\[ S^+ = \varepsilon^+ T + [T', \phi]. \]

Proof.

See [28].

Theorem 2.1.

(i) If the hereditary operator \( \phi \) admits the scaling \( \varepsilon_0 \) then \( \varepsilon_0 \) is a master-symmetry for the hierarchy generated by \( \phi \).

(ii) Assume that the hereditary operator \( \phi \) admits the scaling \( \varepsilon_0 \) and that it also satisfies \( \phi \phi = \varepsilon \phi^+ \), where \( \varepsilon \) is a constant, invertible, skew-symmetric operator which also admits the scaling \( \varepsilon_0 \).

Then

\[
: = (\varepsilon_0)^+ + \varepsilon(\varepsilon_0)^+ \phi^{-1}. \tag{2.10}
\]

Proof.

(i) If \( \phi \) admits a scaling and \( K \) is generated from \( \phi \) then \( K \) also admits a scaling. Hence Corollary 2.1 implies (i) above.
(ii) Since \( \phi \) admits a scaling, \( \phi^+ \) also admits a scaling, hence \( S^+ \) is proportional to \( \phi^+ \), thus \( \Theta S^+ \Theta^{-1} \) is proportional to \( \phi \). Furthermore, since \( \Theta \) admits the scaling \( \tau_0, \tau_0^+ + \Theta \tau_0^+ = \alpha \Theta \), thus \( \tau_0^+ + \Theta(\tau_0^+ \Theta^{-1} \) equals a constant. Hence (2.9) implies (2.10).

**EXAMPLE**

1. \( \phi = D + q + q_x D^{-1} \) is the hereditary operator associated with Burgers equation. It admits the scaling \( q + \alpha q, x + \alpha^{-1} x \), i.e. \( \tau_0 = q + x q_x \). Thus \( x(q_{xx} + 2qq_x) + q^2 \) is a master-symmetry of Burgers equation.

2. \( \phi = D^2 + 4q + 2q_x D^{-1} \) admits the scaling \( q + \alpha q, x + \alpha^{-2} x \), i.e. \( \tau_0 = q + 2x q_x \). Thus \( T = \tau_0 \) is a master-symmetry of the KdV.

3. If \( \tau_0 = q + 2x q_x \), then \( \tau_0^+ + D(\tau_0^+) D^{-1} = -3 \). Hence if \( T \) is the master-symmetry of KdV,

\[
\tau := \tau' + D(\tau')^+ D^{-1}
\]

is the recursion operator of the KdV.

**2.2. Gradient master-symmetries for equations in 2+1.**

A straightforward generalization of Theorem 2.1 to equations 2+1 fails: i) \( \tau \) could not be found, ii) the known master-symmetries \( \tau \) were gradient functions, hence \( \tau^+ + : (\tau')^+ D^{-1} = 0 \). It will be shown
in §3 that for equations in 2+1: i) Suitable generalizations of φ, denoted by $\phi_{12}$ can be found, ii) there exist non-gradient master-symmetries $T_{12}$ (for example for the KP $T_{12} = \phi_{12}^2 \delta(y_1 - y_2)$, where $\delta$ denotes the Dirac delta function). Hence a generalization of theorem 2.1 to equations in 2+1 is given in §3.

One can still develop a theory for master-symmetries without using the connection with the recursion operator $\phi$: see [21], [22].

3. SYMMETRIES FOR EQUATIONS IN 2+1.

In this section we review the theory recently developed by Paolo Santini and the author. We use the KP as an illustrative example and quote the basic theorems when needed. We hope that this form of presentation will aid the non-expert reader to become familiar with the notions and methods developed in [26]-[28]. We advise the non-expert reader to read [15] before reading this paper since many of the results presented here are two dimensional generalizations of results given in [15].

3.1. Derivation of Recursion Operators.

Given an isospectral eigenvalue problem there exists a simple algorithmic way of obtaining a recursion operator. This approach involves three steps: compatibility, an integral representation of a certain differential operator, and an expansion in terms of delta functions.

Let us consider the eigenvalue equation

$$w_{xx} + q(x,y)w + \alpha w_y = 0, \quad \alpha \text{ is a constant} \tag{3.1}$$

and for convenience of notation we suppress the t-dependence. Using vector notation, (3.1) yields

$$\begin{pmatrix} w \\ w_x \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 0 & \dot{q} \end{pmatrix} \begin{pmatrix} w \\ w_x \end{pmatrix}, \quad \dot{q} = q + \alpha D_y, \quad D_y = \frac{\partial}{\partial y}. \tag{3.2}$$
1. Compatibility

Associated with \( W_x = UW \) we look for compatible flows \( W_t = VW \)
where

\[
V = \begin{pmatrix} A & 2C \\ B & E \end{pmatrix}, \quad A, B, C, E \text{ polynomials in } D_y.
\]

Compatibility implies the operator equation

\[
U_t = V_x - [U, V],
\]

or

\[
\begin{pmatrix} 0 & 0 \\ -\dot{q}_t & 0 \end{pmatrix} = \begin{pmatrix} A_x & 2C_x \\ B_x & E_x \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ -\dot{q} & 0 \end{pmatrix} \begin{pmatrix} A & 2C \\ B & E \end{pmatrix}.
\]

Solving in the above equation for \( A, B, E \) in terms of \( C \) we obtain the following operator equation:

\[
q_t = C_{xxx} + [\dot{q}, C]^+ + [\dot{q}_x, C]^+ + [\dot{q}, D^{-1}[\dot{q}, C]] + A_0 \dot{q} - \dot{q} A_0,
\]

where

\[
[\ , \ ] \text{ is a commutator, } [\ , \ ]^+ \text{ is an anticommutator, } A_0
\]

is an operator such that \( A_0x = 0 \) and \( (D^{-1}f)(x, y) = \int_\infty^x f(\xi, y) d\xi \).

In what follows we take \( A_0 = 0 \) (the general case is considered in [27]).

2. An Integral Representation.

The crucial step is to use an integral representation for the differential operator \( C \):

\[
(Cf)(x, y_1) = \int_R dy_2 T(x, y_1, y_2) f(x, y_2).
\]
Let
\[ q_i \equiv q(x,y_i), \quad D_i \equiv D_{y_i}, \quad i = 1,2, \quad T_{12} \equiv T(x,y_1,y_2). \] (3.5)

Equation (3.4) implies similar integral representations for all quantities appearing in the RHS of (3.3). For example

\[ (\tilde{q}_1 C) f = \int_{\mathbb{R}} dy_2 (q_1 T_{12} + a(D_1 + D_2) T_{12}) f_2. \]

For

\[ (q_1 C) f = \int_{\mathbb{R}} dy_2 (q_1 T_{12}) f, \quad D_1(Cf) = (D_1 C) f + C f y_1 = \int_{\mathbb{R}} dy_2 T_{12} f_2, \]

\[ C f y_1 = \int_{\mathbb{R}} dy_2 T_{12} f_2 y_2 = -\int_{\mathbb{R}} dy_2 T_{12} f_2. \]

Thus \((D_1 C) f = \int_{\mathbb{R}} dy_2 (T_{12} y_1 + T_{12} y_2) f_2.\)

Similarly

\[ (\tilde{q}_1 C : C \tilde{q}_1) f = \int_{\mathbb{R}} dy_2 (q_1^* T_{12}) f_2, \]

where the operators \(q_{12}^*\) are defined by

\[ q_{12}^* \equiv q_1 \ast a(D_1 \ast D_2). \] (3.6)

Using the above integral representations in (3.3) we obtain

\[ \delta_{12} q_1 = T_{12} x_{xx} + (q_{12}^* T_{12}) x + q_{12}^* T_{12} x + q_{12} D^{-1} q_{12}^* T_{12}, \quad \delta_{12} \hat{=} \delta(y_1-y_2) \]

or

\[ \delta_{12} q_1 = \delta^* T_{12} D^2 + q_{12} \ast D^2 + D^{-1} q_{12}^* D + D^{-1} q_{12}^* D^{-1} q_{12}^* D. \] (3.7)
Let us introduce the operator $\phi_{12}$ via
\[ D\phi_{12} = \phi_{12}D, \quad \phi_{12} = D^2 + q_{12} + Dq_{12}^{-1} + q_{12}^{-1}D^{-1}q_{12}^{-1}. \] (3.8)

Thus
\[ \delta_{12}q_{12} = D\phi_{12}\delta_{12} = \phi_{12}D\delta_{12}. \] (3.9)

3. Expansions in terms of delta functions.

We expand $T_{12}$ in the form
\[ T_{12} = \sum_{j=0}^{n} \delta_{12}^{j} \tau^{(j)}; \quad \delta_{12}^{j} \triangleq \frac{d^{j}}{dy_{1}^{j}} \delta(y_{1}-y_{2}). \] (3.10)

It turns out that $\psi_{12}$ admits a simple commutator relationship with respect to $h_{12} = h(y_{1}-y_{2})$. Actually the following operator equation is valid
\[ [\psi, h_{12}] = 4\alpha h_{12}^{2}; \quad h_{12}^{'} = \frac{d}{dy_{1}} h_{12}. \] (3.11)

Hence equation (3.7) yields
\[ \delta_{12}^{n} q_{12} \tau_{12} = \sum_{j=0}^{n} D\psi_{12} \delta^{j} \tau^{(j)} = \sum_{j=0}^{n} D\psi_{12}^{'} \delta^{j} \tau^{(j)} + 4\alpha \sum_{j=1}^{n+1} \delta^{j} \psi_{12}^{'} \delta^{j} \tau^{(j)}. \] (3.12)

Thus
\[ \tau^{(n)}_{12} = 0, \quad \tau^{(j-1)}_{12} = \frac{1}{4\alpha} \psi_{12}^{'} \tau^{(j)}, \quad \delta_{12}^{n} q_{12} \tau_{12} = \delta_{12}^{n} D\psi_{12}^{'} \tau^{(0)}. \] (3.12)

Letting $T^{(n)}_{12} = 1$ we have the following proposition:

Proposition 3.1.

The isospectral equation

\[ \text{...} \]
\[ w_{xx} + \hat{q}w = 0, \quad \hat{q} \triangleq q + \alpha Dy; \quad \alpha \text{ constant} \quad (3.13) \]

is associated with the equations

\[ q_{1t} = Bn \int dy_2 \delta_{12} D^{n+1} \cdot 1 = Bn \int dy_2 \delta_{12}^n (\phi_{12D}) \cdot 1, \quad \delta_n \text{ constant} \quad (3.14) \]

where

\[ \gamma_{12} \triangleq D^2 q_{12} + q_{12}^{-1} q_{12} q_{12}, \quad \phi_{12} \triangleq D^2 q_{12} + D q_{12}^{-1} q_{12}^{-1}, \quad \phi_{12} \triangleq D^2 q_{12} + D q_{12}^{-1} q_{12}^{-1} q_{12}^{-1} = 1, \quad (3.15) \]

and \( \gamma_{12}, \phi_{12} \) and related via \( D \gamma_{12} = \phi_{12D} \). The operators \( q_{12}^* \) are defined by

\[ q_{12}^* \triangleq q_{12}^* \triangleq q_{12}^* \triangleq q_1 + \alpha Dy_1, \quad \hat{q}_1^* \triangleq q_2 - \alpha Dy_2. \quad (3.16) \]

(The notation \( q_{12}^* \) is justified, since \( q_{12}^* \) is indeed the adjoint of \( q_{12} \), see §3.2).

**EXAMPLE.**

1. Equation (3.14) with \( n = 0 \) and \( \beta_0 = 1/2 \) implies \( q_{1t} = q_{1x} \).

2. Equation (3.14) with \( n = 1 \) and \( \beta_1 = 1/2 \) implies the KP equation

\[ q_{1t} = q_{1xxx} + 6q_1q_{1x} + 3a^2q_1^{-1} q_1^{-1} y_{1y_1}. \quad (3.17) \]

**Remark 3.1.**

(i) The operators \( \gamma_{12} \) and \( \phi_{12} \) with \( y_2 = y_1 \) and \( \alpha = 0 \) reduce to \( \phi \) and \( \phi^* \) respectively, where \( \phi \) is the recursion operator of the KdV.
(ii) The starting symmetry \((P_{12}D) \cdot 1\) is given by
\[ q_1^x + q_2^x + (q_1 - q_2)D^{-1}(q_1 - q_2) + aD^{-1}(q_1 y_1 - q_2 y_2). \]
Thus it reduces to \(q_1^x\), the starting symmetry of the KdV, when \(y_2 = y_1\).

3.2. A New Directional Derivative and a New Bilinear Form.

Recall that \(\phi\) generates symmetries and \(\phi^*\) generates conserved covariants. Similarly, it will turn out, that \(P_{12}\) and \(P_{12}^*\) generate extended symmetries and extended conserved covariants respectively. To define these extended notions we need to introduce a new bilinear form and a new directional derivative:

(i) A new bilinear form.

\[
\langle g_{12}, f_{12} \rangle \triangleq \int_{R^3} dx \, dy_1 dy_2 \, \text{trace} \, g_{21} f_{12},
\]

(3.18)

where \(f_{12}\) and \(g_{12}\) are matrix valued functions of \(x, y_1, y_2\), and obviously the trace is dropped if \(f_{12}, g_{12}\) are scalars. In association with the above form we define \(L_{12}^*\) to be the adjoint of \(L_{12}\) iff

\[
\langle L_{12}^* g_{12}, f_{12} \rangle = \langle g_{12}, L_{12} f_{12} \rangle.
\]

(3.19)

We recall that the usual bilinear form and the usual adjoint are defined by

\[
(g, f) \triangleq \int_{R^2} dx \, dy \, \text{trace} \, gf, \quad (L^* g, f) = (g, L f),
\]

(3.20)

where \(f, g\) are matrix valued functions of \(x, y\).

**Example.**

1. The adjoint of \(Q_{1}\) is given by \(Q_{1}^* = Q_{2} - Q_{2}^*\)
2. \((q^{+}_{12})^* = q^{+}_{12}, \quad (q^{-}_{12})^* = -q^{-}_{12}\) \quad (3.21)

3. \(\phi^*_{12} = \psi_{12}\).

Note that the fastest way to compute the adjoint of an operator \(L_{12}\) is to evaluate the adjoint as usually and then interchange \(1 \leftrightarrow 2\).

Let \(I\) be a functional given by

\[
I = \int_{R^2} dx \; dy \; 11 \quad \implies \quad I_{11} = \int_{R^3} dx \; dy_1 \delta_{12} \delta_{12} \; trace \; \rho_{12}. \quad (3.22)
\]

The extended gradient of this functional is defined by

\[
<\text{grad}_{12} I, \cdot> : I_{1d} = \int_{R^3} dx \; dy_1 \; dy_2 \delta_{12} \delta_{12} d_{1d} \left[ \cdot \right], \quad (3.23)
\]

where subscript \(d\) denotes a suitable directional derivative.

It is easily seen that a function \(\gamma_{12}\) is an extended gradient function, i.e. it has a potential \(I\), iff

\[
\gamma_{12} = \gamma_{12}^I. \quad (3.24)
\]

Also

\[
(\text{grad} \; I, \cdot) \cdot I_f = \int_{R^2} dx \; dy \; \phi_f[ \cdot ], \quad (3.25)
\]

and \(\gamma\) is a gradient function iff \(\gamma_f = \gamma_f^+.\)

(ii) A new directional derivative.

Recall the crucial integral representation

\[
(\hat{q}_{1f}) (x, y_1) = \int_{R} dy_3 q(x, y_1, y_3)f(x, y_3).
\]

Allowing \(f\) also to depend on \(y_2\) we obtain

\[
\hat{q}_{1f} = \int_{R} dy_3 q_{1f}^{y_3} y_3 y_3.
\]
The above mapping between an operator and its kernel induces a mapping between derivatives: Let subscript \(d\) denote the new directional derivative. Then

\[
\hat{q}_d^{1}[\sigma_{12}]f_{12} = \int_R dy_3 \sigma_{13} f_{32}.
\]

The integral representation for \(\hat{q}_1\) also induces, via (3.18) an integral representation for the adjoint of \(\hat{q}_1\):

\[
\langle g_{21}, \hat{q}_1 f_{12} \rangle = \int_{R^3} dy_1 dy_2 dx g_{21} \int_R dy_3 \sigma_{13} f_{32} = \int_R dy_3 dy_2 dy_1 dx g_{23} \sigma_{31} f_{12}
\]

\[
= \int_{R^3} dy_1 dy_2 dx G_{21} f_{12}, \quad \text{where we have used } 3' \leftrightarrow 1, \text{ and}
\]

\[
G_{21} = \int_R dy_3 g_{23} \sigma_{31}, \quad \text{thus } G_{12} = \int_R dy_3 g_{13} \sigma_{32}. \quad \text{Thus } \hat{q}_1^* f_{12} = \int_R dy_3 \sigma_{32} f_{13}.
\]

Furthermore, the \(\hat{q}_1^*\) mapping induces a mapping between derivatives. Thus

\[
\hat{q}_1 f_{12} \equiv (q_1 + \alpha D_1) f_{12} = \int_R dy_3 \sigma_{13} f_{32}, \quad \hat{q}_1^* f_{12} \equiv (q_1 - \alpha D_2^*) f_{12} = \int_R dy_3 \sigma_{32} f_{13}
\]

(3.26)

\[
\hat{q}_d^{1}[\sigma_{12}]f_{12} = \int_R dy_3 \sigma_{13} f_{32}, \quad \hat{q}_d^{*}[\sigma_{12}]f_{12} = \int_R dy_3 \sigma_{32} f_{13}. \quad (3.27)
\]

The above derivatives with respect to \(q_1^*\) and \(q_1^*\) imply the following derivatives with respect to \(q_{12}^*, q_{12}^-\):

\[
q_{12d}^* [\sigma_{12}] f_{12} = \int_R dy_3 (\sigma_{13} f_{32} - \sigma_{32} f_{13}).
\]

(3.28)

Furthermore, using the chain rule and (3.28), if an operator \(K_{12}\) depends only on \(q_{12}^*, q_{12}^-\), its directional derivative \(L_{12d}^* [\sigma_{12}] \) is well defined.
This derivative is linear, and satisfies the Leibnitz rule. Also, using (3.28) it follows that the directional derivative in the direction of \( \delta_{12} \) reduces to the usual total Fréchet derivative:

\[
K_{12_d} [\delta_{12} F_{12}] = K_{12_f} [F] \cdot K_{12_q} [F_{11}] + K_{12_q} [F_{22}],
\]

where the subscript f stands for a Fréchet derivative and

\[
K_{12_q_i} [F_{i_j}] = \frac{\delta}{\delta\epsilon} K_{12}(q_i + F_{i}, q_j)|_{\epsilon=0}, \quad i, j = 1, 2, \quad i \neq j.
\]

Operators which depend only on \( q_{12}^{\perp} \) are called admissible. Similarly, a function \( K_{12} \) is called admissible if it can be written in the form

\[
K_{12} = \hat{K}_{12} H_{12},
\]

where \( \hat{K}_{12} \) is an admissible operator and \( H_{12} \) is an appropriate function (for the KP, \( H_{12} = H(y_1, y_2) \)).

**EXAMPLE.**

The function \( \hat{M}_{12} \delta_{12} \triangleq \delta q_{12}^{\perp} \delta_{12} + \delta^{-1} q_{12}^{\perp} \delta_{12} \) is an admissible function since the operator \( \hat{M}_{12} \) depends only on \( q_{12}^{\perp} \), and \( \delta_{12} = \delta(y_1 - y_2) \).

It is easy to compute its directional derivative:

\[
(\hat{M}_{12}^{\delta_{12}}) d[\sigma_{12}] = Dq_{12}^{\delta_{12}} + q_{12}^{\delta_{12}} - q_{12}^{\delta_{12}} + q_{12}^{\delta_{12}},
\]

where \( q_{12}^{\perp} F_{12} \triangleq \int_R d\gamma_3 (\sigma_{13}^{f_1} f_{32} = \sigma_{32}^{f_1} f_{13}) \). Hence \( (\hat{M}_{12}^{\delta_{12}}) d[\sigma_{12}] = 2D\sigma_{12} \).

### 3.3. Isospectral problems yield hereditary operators.

Using the same methods as in 1+1, it can be shown that if the extended gradient \( (G_{\lambda})_{12} \) of the eigenvalue \( \lambda \) of an isospectral problem satisfies

...
then $\phi_{12} \ast \phi_{12}^*$ is a hereditary operator. (One must again assume completeness, a proof of which should follow a two dimensional version of the method developed in [6]).

**EXAMPLE.**

Consider the isospectral problem

$$V_{1_{xx}} + (\check{q}_1 - \lambda)V_1 = 0. \tag{3.32}$$

Taking the directional derivative of the above it follows that

$$(D^2 + \check{q}_1 - \lambda)V_1 = (\check{q}_1 - \lambda)\frac{\partial}{\partial d}V_1^+ + (\check{q}_d)_d[f_{12}] = 0. \tag{3.33}$$

Multiplying the above by $V_1^+$, where $V_1^+$ satisfies the adjoint of (3.32), integrating with respect to $dx$ $dy$, and assuming $\int_{R^2} dx$ $dy$ $V_1$ $V_1^+ = 1$, we obtain

$$\check{q}_d[f_{12}] = \langle \text{grad}_{12}, f_{12} \rangle = \int_{R^2} dx$ $dy$$V_1^+ \check{q}_d[f_{12}] V_1.$

Using (3.26) to evaluate $\check{q}_d[f_{12}]$ it follows that

$$(G_{\lambda})_{12} \ast \text{grad}_{12}^* = V_1 V_2^+. \tag{3.34}$$

It is easy to show that $\phi_{12}^*$ as defined by (3.7) satisfies

$$\phi_{12}^* V_1 V_2^+ = 4\lambda V_1 V_2^+. \tag{3.35}$$

Hence $\phi_{12}$ is a hereditary operator.
Remark 3.2.

Konopelchenko and Dubrovsky [29] were the first to establish the importance of working with $V(x, y_1)V^*(x, y_2)$, as opposed to $V^*(x, y_1)V(x, y_2)$. They also found a linear equation satisfied by $V_1V_2$. However, they failed to recognize that this equation could actually yield the recursion operator of the entire associated hierarchy of nonlinear equations. Indeed, they used the above equation to obtain "local" recursion operators. Thus the question of studying the remarkably rich structure of these recursion operators in particular its connection to symmetries, conservation laws, and bi-Hamiltonian operators were not even posed.

3.4 Starting Symmetries.

The theory of symmetries for equations in 1+1 is based on the existence of "starting" symmetries $K^0$, which via $\delta$ generate infinitely many symmetries. For example, for the KdV $K^0 = q_x$. For equations in 2+1 we find that the starting symmetries $K_{12}^0$ has the following important properties: (i) Can be written in the form $K_{12}^0 H_{12}$, where $K_{12}^0$ is an admissible operator and $H_{12}$ is an appropriate function. (ii) The starting operators $K_{12}^0$ have simple commutator properties with respect to $h_{12} = h(y_1, y_2)$. (iii) The Lie algebra of the starting operator $K_{12}^0$ acting on functions $H_{12}$ is closed. (iv) Using (iii) and the fact that $\delta_{12}$ also admits a simple commutator relationship with $h_{12}$, it can be shown that $\delta_{12} x_k K_{12}^0 \cdot 1 = \sum_{\xi=0}^{n} b_{n, \xi} x_k K_{12}^0 \cdot 1_{12}$, where $b_{n, \xi}$ are appropriate constants; hence $\delta_{12} x_k K_{12}^0 \cdot 1$ are admissible functions. It is thus clear that in 1+1 one considers the Lie algebra of functions $K^0$, while in 2+1 one considers the Lie algebra of operators $K_{12}^0$. This
richer algebraic structure of equations in 2+1 can be exploited in a
variety of ways. For example different choices of \( H_{12} \) yield both time-
independent and time-dependent symmetries. Furthermore, all these
symmetries correspond to gradient functions.

We now discuss (i)-(iv) above for the concrete case of the KP:

It should be first noted that given an operator \( \tilde{S}_{12} \) there exists an
algorithmic way of finding its starting symmetries: One looks for
operators \( \hat{S}_{12} \) such that \( \hat{S}_{12}H_{12} = 0 \) but \( \phi_{12}\hat{S}_{12}H_{12} \neq 0 \). It can
be shown that if a starting symmetry is constructed in the above way
and \( \phi_{12} \) is hereditary then \( \phi_{12} \) is a strong symmetry for this starting
symmetry.

(i) For the KP there exist two starting symmetries:

\[
\dot{M} \equiv Dq_{12} - q_{12}D^{-1}q_{12}, \quad \dot{N} \equiv q_{12}, \quad H_{12} \equiv H(y_1, y_2) \tag{3.35}
\]

corresponding to \( \hat{S}_{12} = D \) and \( \hat{S}_{12} = D(q_{12})^{-1}D \) respectively.

(ii) The following operator equations are valid:

\[
[\hat{M}_{12} , h_{12}] = 2\alpha Dh_{12}, \quad [\hat{N}_{12} , h_{12}] = 0. \tag{3.36}
\]

(iii) The Lie algebra of \( \hat{M}_{12} , \hat{N}_{12} \) is given by

\[
[\hat{N}_{12}H(1)_{12}, \hat{N}_{12}H(2)_{12}]_d = -\hat{N}_{12}H(3)_{12}, \quad [\hat{N}_{12}H(1)_{12}, \hat{M}_{12}H(2)_{12}]_d = -\hat{M}_{12}H(3)_{12}. \tag{3.37}
\]

\[
[\hat{M}_{12}H(1)_{12}, \hat{M}_{12}H(2)_{12}]_d = -\phi_{12}\hat{N}_{12}H(3)_{12},
\]

where

\[
[K^{(1)}_{12} , K^{(2)}_{12}]_d = K^{(1)}_{12} [K^{(2)}_{12}] - K^{(2)}_{12} [K^{(1)}_{12}], \tag{3.38}
\]
\[ H_{12}^{(3)} = [H_{12}^{(1)}, H_{12}^{(2)}]_I = \int_R dy_3 (H_{13}^{(1)} H_{32}^{(1)} - H_{13}^{(2)} H_{32}^{(2)}). \]  

Let us derive (3.37a):

\[ q_{12} [q_{12}^{(1)} H_{12}^{(2)}]_{H_{12}^{(1)}} = \int_R dy_3 dy_3' (q_{13}^{(1)} H_{32}^{(2)} - q_{33}^{(2)} H_{32}^{(1)}) H_{32}^{(1)} - H_{13}^{(1)} (q_{33}^{(2)} H_{32}^{(1)} - q_{33}^{(2)} H_{32}^{(1)}) \]

\[ = \int_R dy_3 dy_3' (H_{13}^{(1)} [q_{12}^{(1)} - \alpha(D_1 + D_3)] H_{13}^{(2)} - H_{13}^{(1)} [q_{32}^{(2)} - \alpha(D_3 + D_2)] H_{13}^{(2)}). \]

Hence

\[ [q_{12}^{(1)} H_{12}^{(1)}, q_{12}^{(2)} H_{12}^{(2)}]_I = -i[q_{12}^{(1)} - \alpha(D_1 + D_3)] [H_{12}^{(1)}, H_{12}^{(2)}]_I. \]

**Remark 3.3.**

The bracket (3.39) can also be traced back to the integral representation of \( \hat{q}_1 \) (see [27]).

**(iv)** Equations (3.36) and the operator equation (see (3.11))

\[ \{:h_{12}^{(1)}, h_{12}^{(1)}:\} = 4 \alpha h_{12}^{(1)} \]  

\[ (3.40) \]

imply

\[ \{ :h_{12}^{(1)}, h_{12}^{(1)}: \} = \frac{n}{\pi} (-4 \alpha) \sum_i \frac{i}{i+1} \sum_{i=1}^n (-4 \alpha)^i (-i+1)^2. \]

\[ (3.41) \]

\[ \{ :h_{12}^{(1)}, h_{12}^{(1)}: \} = \frac{n}{\pi} \sum_{i=1}^n \sum_{i=1}^n (-4 \alpha)^i (-i+1)^2. \]

\[ (3.42) \]

Let us indicate how the above equations can be derived: Introducing an operator \( D \), which commutes with all admissible operators \( \hat{h}_{12}^{(1)} \) and which
has the property that

\[ D \cdot h_{12} = h'_{12}, \]

it follows that

\[
\delta_{12}^{n} \hat{\alpha}_{12}^{n} \cdot 1 = (\varepsilon_{12}^{4aD})^{n} \delta_{12}^{n} \hat{\alpha}_{12}^{n} \cdot 1 = (\varepsilon_{12}^{4aD})^{n} \hat{\alpha}_{12}^{n} \cdot \delta_{12}^{n} = \\
= \sum_{i=1}^{n} (-4a)^{i} \hat{\alpha}_{12}^{n} \cdot \delta_{12}^{n}.
\]

To derive equation (3.42) note that

\[
\delta_{12}^{n} \hat{\alpha}_{12}^{n} \cdot 1 = (\varepsilon_{12}^{4aD})^{n} \delta_{12}^{n} \hat{\alpha}_{12}^{n} \cdot 1 = (\varepsilon_{12}^{4aD})^{n} (\hat{\alpha}_{12}^{n} \cdot \delta_{12}^{n} - 2a) - \delta_{12}^{n+1}. \quad (3.43)
\]

The next step is to express \( \hat{\alpha}_{12}^{j} \) in terms of \( \hat{\alpha}_{12}^{j+1} \), where \( j, j' \) are integers. This can be achieved as follows: It can be shown that

\[ \hat{\alpha}_{12}^{n+1} \cdot 1 = \hat{\alpha}_{12}^{n} \hat{\alpha}_{12} \cdot 1. \]

This equation implies

\[ \hat{\alpha}_{12}^{n+1} \cdot h_{12} = \sum_{j=0}^{n} (2a)^{j} \hat{\alpha}_{12}^{n-j} \hat{\alpha}_{12} \cdot h_{12}; \quad \hat{h}_{12}^{j} \cdot \frac{d\hat{h}_{12}}{dy} \cdot h_{12}. \quad (3.44) \]

For example, multiplying \( \hat{\alpha}_{12}^{j} \cdot h_{12} \cdot 1 = \hat{\alpha}_{12}^{j} \cdot h_{12} \cdot 1 \) by \( h_{12} \), it follows that

\[ (\varepsilon_{12}^{4aD})^{j} h_{12} \cdot 1 = (\hat{\alpha}_{12}^{n} \cdot h_{12}), \] or \( \hat{\alpha}_{12}^{j} \cdot h_{12} = \hat{\alpha}_{12}^{n} \cdot h_{12}. \)

Similarly

\[ \hat{\alpha}_{12}^{n+1} \cdot 1 = \hat{\alpha}_{12}^{n} \hat{\alpha}_{12} \cdot 1 \] implies \( \hat{\alpha}_{12}^{n} \cdot h_{12} = \hat{\alpha}_{12}^{n} \hat{\alpha}_{12} \cdot h_{12} + 2a\hat{\alpha}_{12} \cdot h_{12}, \)

etc. Using (3.44) into (3.43) yields (3.42).
3.5. Basic Notions and Results

We consider exactly solvable evolution equations in the form

\[ q_t = K(q), \quad q(x,y,t), \] on a normed space \( M \) of vector-value functions on \( \mathbb{R} \); \( K \) is a suitable \( C^\infty \) vector field on \( M \). We assume that the space of smooth vector fields on \( M \) is some space \( S \) of \( C^\infty \) functions on the plane vanishing rapidly as \( x, y \to \infty \). The above equation is a member of a hierarchy generated by \( \phi_{12} \), hence more generally we shall study

\[ q_t = K^{(n)}(q). \]

Fundamental in our theory is to write these equations in the form

\[ q_t = \int_R dy_2 \cdot K^{(n)}_1 = K^{n} \quad (3.45) \]

(in the matrix case, \( I \) is replaced by the identity matrix \( I \)), where

\[ K^{(n)}_1(q_1, q_2) \] belongs to a suitably extended space \( \hat{S} \), and \( \hat{S}^* \) denotes the dual of \( \hat{S} \). In the extended spaces \( S \) and \( S^* \) we define the new directional derivative (3.28) and the new bilinear form (3.18); the notions of the adjoint and of a gradient are well defined with respect to (3.18) (see (3.19), (3.23), (3.24)). In analogy with definition 2.1 we have:

**Definition 3.1.**

(i) A function \( c^{12} \in \hat{S} \) is called an extended symmetry if

\[ q_{1t} = \int_R dy_2 \cdot K^{12} = K^{11} \quad (3.46) \]

iff

\[ \frac{d}{dt} c^{12}_1 = \{ c^{12}_1 \} - (K^{12}_1) c^{12} = 0. \quad (3.47) \]

(ii) A function \( \gamma^{12} \in \hat{S}^* \) is called an extended conserved gradient (i.e. it is the extended gradient of a conserved functional \( I \)).
of (3.46) iff
\[
\frac{\partial \gamma_{12}}{\partial t} + \gamma_{12} f + (\delta_{12} K_{12}) \gamma_{12} = 0, \quad \gamma_{12} = \gamma_{12}^*.
\] (3.48)

Functions which satisfy (3.48a) are called extended conserved
covariants.

(iii) An operator valued function \( \phi_{12} : \tilde{S} \rightarrow \tilde{S} \), is a recursion operator
for (3.46) (or it is a strong symmetry for \( K_{12} \)) iff
\[
\phi_{12} f + [\phi_{12}, (\delta_{12} K_{12}) f] = 0.
\] (3.49)

(iv) An operator valued function \( \phi_{12} : \tilde{S} \rightarrow \tilde{S} \), is a hereditary operator
(or Nijenhuis or regular) iff
\[
\phi_{12} \left[ \phi_{12}, \phi_{12} \right] w_{12} - \phi_{12} \phi_{12} \left[ v_{12}, \phi_{12} \right] w_{12} \text{ is symmetric w.r.t. } v_{12}, w_{12}.
\] (3.50)

(v) An operator valued function \( \Theta_{12} : \tilde{S} \rightarrow \tilde{S} \) is a Hamiltonian operator
iff it is skew symmetric, i.e. \( \Theta_{12} = -\Theta_{12}^* \), and it satisfies
\[
\epsilon a_{12} \Theta_{12} \left[ 0 b_{12}, c_{12} \right] = \text{cyclic permutation} = 0.
\] (3.51)

(vi) Equation (3.46) is a Hamiltonian system iff it can be written in
the form
\[
q_{1t} = \int_R dy_2 \Theta_{12} f_{12}^*.
\] (3.52)

where \( \Theta_{12} \) is a Hamiltonian operator and \( f_{12} \) is an extended gradi-
ent function, i.e. \( f_{12}^* = f_{12}^* \). Associated with (3.52) we define
the following Poisson bracket
\[
\{ 1, H \} = \text{grad}_{12} 1 \cdot \Theta_{12} \text{grad}_{12} H^*.
\] (3.53)
In the above, subscripts \( f \) and \( d \) denote total Fréchet (see (3.29)) and directional (see (3.28)) derivatives respectively.

**Remark 3.4.**

(i) Equation (3.47) can also be written as

\[
\frac{\partial c_{12}}{\partial t} + [\sigma_{12}, \delta_{12} K_{12}]_d = 0,
\]

since \( \sigma_{12} [\delta_{12} K_{12}] = \sigma_{12} [K] \). Similarly \( \phi_{12} [K] = \phi_{12} [\delta_{12} K_{12}] \).

(ii) Some of the above notions are well defined only if \( (\delta_{12} K_{12})_d \) is well defined. However, for equations (3.45)

\[
\delta_{12} K_{12}^{(n)} = \delta_{12} \phi_{12}^{n} K_{12}^{0} \cdot 1 + \sum_{k=0}^{n} b_{n, k} \phi_{12}^{n-k} K_{12}^{0} \cdot \delta_{12}^{k}.
\]

Furthermore, by construction \( \phi_{12} \) and the starting operators \( K_{12}^{0} \) depend on the basic operators \( q_{12}^{z} \). Hence \( (\delta_{12} K_{12}^{(n)})_d \) is well defined.

In analogy with the basic results in 1+1:

**Theorem 3.1.**

(i) If \( \phi_{12} \) is a recursion operator for (3.46) then \( \phi_{12} \) maps extended symmetries onto extended symmetries and \( \phi_{12}^{*} \) maps extended conserved covariants onto extended conserved covariants.

(ii) If (3.46) is a Hamiltonian system then \( \sigma_{12} = 0_{12}^{0} \).

(iii) If \( \phi_{12} \) is a hereditary operator and a recursion operator for \( K_{12}^{0} \cdot 1 \) then \( \phi_{12} \) is a recursion operator for \( q_{12}^{z} = \int_{t}^{t+1} dy_{2} \phi_{12}^{n} K_{12}^{0} \cdot 1 \).

(iv) If \( \phi_{12} = c_{12}^{z} (\sigma_{12}^{(1)})^{-1} \), where \( c_{12}^{(1)} + c_{12}^{(2)} \) is a Hamiltonian operator
for all values of the constant $v$ and $\gamma^{(1)}$ is invertible, then $\gamma^{(1)}$ is hereditary.

(v) If $\phi_{12}$ as in (iv) and $\gamma_{12} \neq (\phi_{12})^{-1} \gamma_{12} \cdot 1$ is an extended gradient function then all $\gamma_{12}^m \phi_{12}^0$ are extended gradient functions.

**EXAMPLE.**

The hereditary operator $\phi_{12}$ of the KP equation is factorizable in terms of the Hamiltonian operators $D$ and $D_{12}$. Hence each member of the KP hierarchy is a bi-Hamiltonian system, with respect to the following two Poisson brackets

$$
\{ I, H \} = \{ \text{grad}_{12} I, \gamma^{(1)}_{12} \text{grad}_{12} H \}, \quad i = 1, 2
$$

$$
\{ I_{12}, \gamma_{12} \} = D_{12} = D^j - q_{12}^j + Dq_{12}^j + q_{12}^{j-1}q_{12}^j.
$$

3.6. Extended Symmetries.

**Lemma 3.1.**

(i) Let $\phi_{12}$ be hereditary, then

$$
\{ \phi_{12}^m, \phi_{12}^n \} = \phi_{12}^{m+n} [k^{(1)}_{12}, k^{(2)}_{12}] + \phi_{12}^m \phi_{12}^n \sum_{r=1}^{n-r} \phi_{12}^r [s^{(1)}_{12}, \phi_{12}^{r-1} k^{(2)}_{12}]
$$

$$
- \phi_{12}^n \phi_{12}^m [s^{(1)}_{12}, \phi_{12}^{r-1} k^{(2)}_{12}],
$$

where

$$
\phi_{12}^n \phi_{12}^m = \phi_{12}^m [k^{(1)}_{12}] + [\phi_{12}^n, k^{(1)}_{12}],
$$

$m, n$ are non-negative integers.
(ii) $\sigma_{12}^{(r)}$ is a time-dependent extended symmetry of order $r$ of equation (3.46) iff

$$
\sigma_{12}^{(r)} = \sum_{j=0}^{r} \mathcal{J}_1^{(j)}(j), \quad \mathcal{J}_1^{(j)}(j) = -\frac{i}{2} \left[ \zeta_{12}^{(j-1)}, \zeta_{12}^{(j)} K_{12} \right]_d, \quad j = 1, \ldots, r,
$$

$$
\left[ \zeta_{12}^{(r)}, \zeta_{12}^{(j)} K_{12} \right]_d = 0. \tag{3.56}
$$

Proof.

See [28].

We propose the following constructive approach to extended symmetries: Given an isospectral problem construct a recursion operator $\phi_{12}$. This operator must be hereditary (see §3.3). Then construct its starting symmetries operators, say $M_{12}$, $N_{12}$. The operator $\phi_{12}$ is a strong symmetry of $M_{12}$, $N_{12}$ (see [27]). Compute the commutators of $M_{12}$, $N_{12}$ with $\phi_{12}$. Use the commutator relationships to derive

$$
\delta_{12}^{(j-1)} K_{12} = \left[ b_n, \right]^{n-j} \left[ K_{12}^{(j)} \right] = \left[ K_{12}^{(j-1)} \right]_d = M_{12}, \quad n = 0, 1, 2, \ldots
$$

Finally compute the Lie algebra of $M_{12}$, $N_{12}$. This Lie algebra together with (3.54)-(3.56) yield infinitely many time-independent and time-dependent extended symmetries.

EXAMPLE.

1. $\phi_{12}^{m} M_{12}, \phi_{12}^{m} N_{12}$ are extended symmetries of the KP hierarchy, $q_{12} = \int_R dy_2 \phi_{12}^{m} M_{12}, \phi_{12}^{m} N_{12}$, $\phi_{12}^{m} M_{12}, \phi_{12}^{m} N_{12}$ are defined in (3.35).
\[
[\delta_{12}^n \hat{M}_{12}, 1, \hat{M}_{12}, H_{12}]_d = \sum_{\ell=0}^{n} b_{n, \ell} \left( \delta_{12}^{n-\ell} \hat{M}_{12}, H_{12} \right)_d = \sum_{\ell=0}^{n} b_{n, \ell} \left( \delta_{12}^{n-\ell} \hat{M}_{12}, H_{12} \right)_d = \sum_{\ell=0}^{n} b_{n, \ell} \left( \delta_{12}^{n-\ell} \hat{M}_{12}, H_{12} \right)_d,
\]

where we have used (3.54) (\(\delta_{12}\) is hereditary and it is also a strong symmetry for \(M_{12} H_{12}\), thus \(S_{12}^{(i)} = 0\)), and (3.37c). Taking \(H_{12} = 1\) and using

\[
[\delta_{12}, 1]_t = 0,
\]

equation (3.57) implies \([\delta_{12}^n \hat{M}_{12}, 1, \hat{M}_{12} H_{12}]_d = 0\), i.e.

\(\hat{M}_{12} H_{12} = 1\) is an extended symmetry of the KP hierarchy. Similarly for \(\hat{N}_{12} H_{12} = 1\), since

\(\hat{M}_{12} H_{12} = 1\) is an extended symmetry of the KP hierarchy. Similarly for

\(\hat{N}_{12} H_{12} = 1\), since

\[
\Sigma^{(2j-1)}_{12} = \sum_{s \leq 1} \nu(r, 2j-1, s) \hat{M}_{12}^{(m+2j-1)n+1-2s, s+1} H_{12}^{r-2j-1, 2s, s+1},
\]

2. \(\hat{M}_{12} H_{12} = 1\) and \(\hat{N}_{12} H_{12} = 1\) are extended symmetries of the hierarchy

\[
\Sigma^{(0)}_{12} = \hat{M}_{12}^{(m)}, H_{12}^{(r)}, \quad H_{12}^{(r)} = (y_1 + y_2)^r.
\]

3. The KP hierarchy admits two hierarchies of \(t\)-dependent symmetries of order \(r\) given by (3.56) where

the summation \(\Sigma\) is over \(s_1, s_2, \ldots, s_j\), from zero to \(P_n\). \(P_n = (n-1)/2\) if \(n\) is odd, \((n-2)/2\) if \(n\) is even.
and

\[ \Sigma_{12}^0 = \hat{M}(m) \cdot H(r) \]

\[ \Sigma_{12}^{2j} = \Sigma \nu(r, 2j, s) M_{12}^{(m+2jn+j - \sum_{\ell=1}^{2j} 2s_\ell + 1)}, \]

\[ \Sigma_{12}^{(2j-1)} = \Sigma \nu(r, 2j-1, s) \hat{N}_{12}^{(m+(2j-1)n+j - \sum_{\ell=1}^{2j-1} 2s_\ell + 1)}, \]

with \( j \geq 1, \ b_{n, \ell} = \frac{\xi}{\ell} (\ell-s) (n-s) = (-4\alpha)^{\ell} \xi^2 (\ell-s) \) and

\[ \nu(r, j, s) \triangleq \frac{(-2)^j}{j!} \sum_{\ell=1}^{j} b(r - \sum_{\ell=1}^{2s_\ell + 1})(\sum_{\ell=1}^{2s_\ell + 1} (r - \sum_{\ell=1}^{2s_\ell + 1})) \]

For.

Equation (3.56) implies that constructing a symmetry of order \( r \) is equivalent to finding a function \( \Sigma_{12}^0 \) with the property that its \((r+1)\)st commutator with \( \Sigma_{12}^0 \) is zero. This can be easily achieved by using suitable \( H_{12} \)'s. For example, let \( H_{12} = y_1 + y_2 \), then (3.57) implies:

\[ [\delta_{12}^m \hat{M}_{12}^m, (y_1 + y_2)] = \sum_{i=0}^{n} b_{n, i} \delta_{12}^m \hat{M}_{12}^{m+n+i+1} \hat{N}_{12}^{2\ell+1}, \]

since

\[ [\delta_{12}^m, y_1 + y_2] = 2\delta_{1, \ell} \] where \( \delta_{1, \ell} = 0 \) if \( \ell \neq 1 \) or 1 if \( \ell = 1 \).

Thus, using the fact that \([\delta_{12}^m, \delta_{1, \ell}] = 0\) it follows that \( \delta_{12}^m \hat{M}_{12}^m (y_1 + y_2) \) generates first order time-dependent symmetries

\[ \delta_{12}^m \hat{M}_{12}^m (y_1 + y_2) - 2b_{n, 1} \delta_{12}^m \hat{N}_{12}^{2\ell+1}. \]

Similarly, to generate \( r \)-order time-dependent symmetries use \( \delta_{12}^m \hat{M}_{12}^m (y_1 + y_2)^r \).
since the commutator of \((y_1^* y_2)^r\) with \(\delta_{12}^r\) produces \((y_1^* y_2)^{r-1}\) and hence the \(r\)th commutator of \((y_1^* y_2)^r\) with \(\delta_{12}^r\) produces 1 which commutes with \(\delta_{12}^r\):

\[
\left[\delta_{12}^r, (y_1^* y_2)^r\right] = (1-(-1)^S)\delta(r-s)\frac{r!}{(r-s)!} (y_1^* y_2)^{r-s},
\]

where \(\delta(r-s)\) denotes the Heaviside function.

4. The hierarchy \(q_1 = \int_R dy_3 \delta_{12}^{r_n} n_{12} \cdot 1\) admits two hierarchies of \(t\)-dependent symmetries of order \(r\) given by (3.56) where

\[
\theta_{12}^{(0)} = N_{12}^r \cdot H_{12}^r
\]

\[
\theta_{12}^{(j)} = \psi(r,j,s)N_{12}^r \cdot H_{12}^r \cdot \delta_{12}^l (m+jn-\frac{j}{2}s+1).H (r-\frac{j}{2}s+1),
\]

and by

\[
\theta_{12}^{(0)} = M_{12}^r \cdot H_{12}^r
\]

\[
\theta_{12}^{(j)} = \psi(r,j,s)M_{12}^r \cdot H_{12}^r \cdot \delta_{12}^l (m+jn-\frac{j}{2}s+1).H (r-\frac{j}{2}s+1),
\]

where the summation \(\Sigma\) is over \(s_1, s_2, \ldots, s_j\) from zero to \(P_n\), \(j \geq 1\), \(P_n = (n-1)/2\) if \(n\) is odd and \((n-2)/2\) if \(n\) is even. Also

\[
b_{n,\xi} = (-4\alpha)^{\frac{n}{\xi}}.
\]

The above extended symmetries, under the reduction \(y_2 = y_1\) yield symmetries. This follows from the following theorem (see [27]).
Theorem 3.2.

Assume that the admissible operators \( \dot{\xi}_{12}, K_{12}, \) satisfy

\[
[\dot{\xi}_{12}, \xi_{12}] = -\delta \xi_{12},
\]

\[
[K_{12}, \dot{\xi}_{12}] = -\delta \xi_{12} \dot{\xi}_{12},
\]

where \( \delta, \dot{\delta} \) are constants and \( \xi_{12} \) is such that \( \xi_{12} \{ \cdot \} \varphi_{12} = 0 \). Then

(i) If \( \xi_{12} \) is an extended symmetry of (3.45), \( \varphi_{12} \) is a symmetry of (3.45).

(ii) If \( \xi_{12} \) is an extended symmetry of (3.45) then \( \varphi_{12} = (q_1, q_1) = 0 \) is an auto-Bäcklund transformation of (3.45), where \( q_1 \) and \( q_2 \) are viewed as two different solutions of (3.45).

(iii) If \( \gamma_{12} \) is an extended conserved covariant of (3.45), \( \gamma_{12} \) is a conserved covariant of (3.45).

(iv) If \( \gamma_{12} \) is an extended gradient function then \( \gamma_{12} \) is a gradient function.

EXAMPLE.

Consider the extended symmetry of the KP

\[
\dot{M}_{12} \cdot 1 = q_1 x + q_2 x + (q_1 - q_2)D^{-1}(q_1 - q_2) + D^{-2}(q_1 y_1 - q_2 y_2).
\]

Clearly \( \{ M_{12} \cdot 1 \} = 2q_1 x \) which is a symmetry of the KP. Also \( \dot{M}_{12} \cdot 1 = 0 \) is a well known auto-Bäcklund transform of the KP.

Remark 3.5.

(i) It is quite interesting that both symmetries and Bäcklund transformations of an equation in 2+1 come from the same basic entity,
the extended symmetry. Indeed, when \( a = 0 \) the recursion operator \( \phi_{12} \) for the KP equation reduces to an operator that Calogero and Degasperis have introduced \([30]\) and which generates the auto-Bäcklund transformations of the KdV equation.

(ii) Using the interpretation that \( \partial_b \# \partial_q : bq, q, b \) matrices, the recursion operator of the KP becomes the operator generating auto-Bäcklund transformations for the equations associated with the \( N \times N \) matrix Schrödinger problem in one dimension (studied by Calogero and Degasperis \([30]\)). This important connection is explained from the fact that certain 2+1 dimensional systems can be viewed as reductions of certain evolution equations non-local in \( y \). These equations are directly connected to matrix evolution equations \([28]\), \([31]\).

3.7. Extended Conserved Gradients.

Lemma 3.2.

Assume that \( \phi_{12} \) is a Hamiltonian operator. Then,

\[
\left[ \phi_{12}, \phi_{12}^* \right] = \phi_{12} \text{grad}_{12} \phi_{12}^* + \phi_{12}^* \text{grad}_{12} \phi_{12} + \phi_{12} \left( \phi_{12}^* \right)^* - \left( \phi_{12}^* \right)^* \phi_{12}.
\]  \hspace{1cm} (3.58)

Proof.

See \([28]\).

One way of proving that \( \phi_{12}^* \) generates gradient functions is to use Theorem 3.1, (v). However, this requires that \( \phi_{12}^* \) is factorizable in terms of Hamiltonian operators. Alternatively, we propose the following constructive approach, which only uses one Hamiltonian operator.
Construct the Lie algebra of the starting operators, say $\hat{M}_{12}, \hat{N}_{12}$. Then use this algebra and (3.58) to prove that all $\hat{e}^{m}_{12} = 1, 0 \times H_{12}$ are gradients, provided that $\hat{e}^{1, 0}_{12} H_{12}$ is a gradient, where $K_{12}^0$ is $M_{12}$ or $N_{12}$.

Finally use Theorem 3.2 to show that $(c_{12}^{-1, 0} H_{12})_{11}$ are gradients.

**EXAMPLE.**

Consider the operators $\hat{M}_{12}, \hat{N}_{12}$ associated with the KP. Then

\[
D^{-1} \phi_{12}^{n+1} \hat{M}_{12} H^{(3)} = \text{grad} \cdot \phi_{12}^{n} \hat{M}_{12} H^{(1)}, \quad D^{-1} \phi_{12}^{n+1} \hat{N}_{12} H^{(2)}, \quad (3.59)
\]

\[
D^{-1} \phi_{12}^{n} \hat{N}_{12} H^{(3)} = \text{grad} \cdot \phi_{12}^{n} \hat{N}_{12} H^{(1)}, \quad D^{-1} \phi_{12}^{n} \hat{M}_{12} H^{(3)}, \quad (3.60)
\]

For.

It is easy to verify that $D^{-1} \hat{M}_{12} H_{12}$ is an extended gradient.

Then (3.58) and (3.37c) imply that $D^{-1} \hat{N}_{12} H_{12}$ is an extended gradient.

Equation (3.37b) implies

\[
[\phi_{12}^{n} \hat{M}_{12} H^{(1)}, \phi_{12}^{n} \hat{M}_{12} H^{(2)}] = \phi_{12}^{n+1} \hat{M}_{12} H^{(3)}.
\]

Since $D^{-1} \phi_{12}^{n} \hat{N}_{12} H^{(3)}, D^{-1} \phi_{12}^{n} \hat{M}_{12} H^{(3)}$ are extended gradients, the above equation with $n = 0$ and (3.58) imply that $D^{-1} \phi_{12}^{n} \hat{M}_{12} H_{12}$ is an extended gradient.

Similarly $D^{-1} \phi_{12}^{n} \hat{N}_{12}$ is an extended gradient. Equation (3.60) follows in a similar manner using (3.37c).

**Remark 3.6.**

It was shown in §3.6 that time-dependent symmetries of order $r$ are generated via $\phi_{12}^{m} \hat{M}_{12} H_{12}, \phi_{12}^{m} \hat{N}_{12} H_{12}$ with $H_{12} = (y_{1, 2})^r$. The above results shows that $D^{-1} \phi_{12}^{m} \hat{M}_{12} H_{12}, D^{-1} \phi_{12}^{m} \hat{N}_{12} H_{12}$ are gradient functions for
arbitrary \( H_{12} \). Hence the time-dependent symmetries correspond to gradient functions. However, the time-dependent symmetries are closely related to master-symmetries \( T \) (see §2). Hence the master-symmetries \( T \) correspond to gradient functions.


Lemma 3.3.

Assume that the hereditary operator \( \phi_{12} \) satisfies \( \phi_{12} G_{12} = \theta_{12} T_{12} \), where \( \theta_{12} \) is a Hamiltonian operator (if \( \phi_{12} \) is factorizable, then this equation follows). Assume for simplicity that \( \theta_{12} = 0 \). Then

\[
\phi_{12} \phi_{12}^{-1} = \phi_{12} (T_{12} + \theta_{12} T_{12} \partial_{12}^{-1}) + \sum_{r=1}^{\infty} T_{12} \partial_{12}^{r-1} \phi_{12} \partial_{12}^{-1},
\]

(3.61)

where

\[
\partial_{12} \phi_{12} = \partial_{12} [T_{12}] + [T_{12} \partial_{12}],
\]

(3.62)

Proof.

See [28].

The results of Lemmas 3.1-3.3 can be used to obtain non-gradient master-symmetries \( T_{12} \). Such master-symmetries are explicitly related to recursion operators \( \phi_{12} \). Indeed given \( \phi_{12} \) one computes \( T_{12} \) and given \( T_{12} \) one computes \( \phi_{12} \). These formulae are the two dimensional analogues of the formulae given in §2.1. The basic idea is to find a \( T_{12} \) such that

\[
T_{12} + \theta_{12} T_{12} \theta_{12}^{-1} = 0 \quad \text{and} \quad S_{12}^* = C \cdot 1, \ C \text{constant}.
\]
EXAMPLE.

A master-symmetry of the KP hierarchy is given by $z_{12}^{2}$. Indeed

$$\phi_{12} = e((z_{12}^{2}d_{12})^d + D(z_{12}^{2}d_{12})d + 1), \quad e \text{ constant}$$

(3.63)

$$\phi_{12}^{n+1} \cdot M_{12} = \phi_{12}^{n} [\phi_{12}^{2}d_{12}^d + 1, \phi_{12}^{2}d_{12}^d], \quad \phi_{12}^{n} \text{ constant}$$

(3.64)

$$D^{-1} \phi_{12}^{m+n-1} \cdot M_{12} = \text{grad}_{12} \phi_{12}^{n} [\phi_{12}^{2}d_{12}^d + 1, \phi_{12}^{2}d_{12}^d]$$

(3.65)

For,

$\phi_{12}$ and $M_{12}$ are given by (3.8), (3.35a), $\phi_{12} = D_{12}$. Let $T_{12} = \phi_{12}$.

Then $T_{12}d + \phi_{12}^{-1} = 0$ and $S_{12} = 4$ (see (3.62)). Thus, equation (3.61) with $m=2$ implies (3.63).

To derive equation (3.64) use Lemma 5.1 with $\phi_{12} = M_{12} - 1$,

$\phi_{12}^{n}[M_{12}^{2} - 1, \phi_{12}^{2}d_{12}^d + 4n\phi_{12}^{n+1}d_{12}^d] = \phi_{12}^{n+2}[M_{12}^{2} - 1, \phi_{12}^{2}d_{12}^d + 4n\phi_{12}^{n+1}d_{12}^d]$.

However, $\phi_{12}^{n}[M_{12}^{2} - 1, \phi_{12}^{2}d_{12}^d]$ is proportional to $\phi_{12}^{n+1}d_{12}^d$, hence the above implies (3.64).

To derive equation (3.65), use Lemmas 3.1-3.3 to obtain the following general result: If $\phi_{12}$ is a hereditary operator such that it is a strong symmetry for $M_{12}$ and $\phi_{12}^{O_{12}} = O_{12} \phi_{12}$, where $\phi_{12}$ is a constant invertible Hamiltonian operator then

$$\phi_{12}^{n} \left( \sum_{r=1}^{n} \phi_{12}^{r-1}S_{12}^{r-1} \phi_{12}^{r-1} \right)M_{12} + \left( \sum_{r=1}^{n} \phi_{12}^{r-1}S_{12}^{r-1} \phi_{12}^{r-1} \right)M_{12} + \phi_{12}^{n+1}M_{12}^{-1} \cdot M_{12} =$$

$$= \phi_{12}^{n-1} \cdot n \cdot M_{12}^{2} - \phi_{12}^{n} \left( \phi_{12}^{n} \cdot \phi_{12}^{n} \cdot \phi_{12}^{n} \right) \cdot M_{12}^{2}$$
where

\[ S_{12} = \phi_{12d} \left[ T_{12} \right] + \left[ \phi_{12d}^{*} T_{12d} \right], \quad S_{12}^{*} = \phi_{12d}^{*} \left[ T_{12} \right] + \left[ T_{12d}^{*} \phi_{12d}^{*} \right]. \]

Using \( T_{12} = \delta_{12} \) in the above and noting that \( S_{12} = S_{12}^{*} = 4 \),

\[ T_{12d}^{-1} + \phi_{12d} T_{12d}^{-1} = 0, \quad \phi_{12d}^{*} [M_{12d}, \delta_{12}] \]

is proportional to \( \phi_{12d}^{n+m-1} M_{12d} \cdot 1 \),

we obtain (3.65).

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