ENERGY METHODS FOR NONLINEAR HYPERBOLIC
VOLterra INTEGRODIFFERENTIAL EQUATIONS
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We use energy methods to study global existence, boundedness, and asymptotic behavior as $t \to \infty$, of solutions of the two Cauchy problems (and related initial-boundary value problems)

\[
\begin{align*}
\text{(HF)} & \quad \begin{cases}
u_t(t,x) = \int_0^t a(t - \tau) \sigma(u(x,t)) \, d\tau + f(t,x) & (0 < t < \infty, x \in \mathbb{R}) \\
u(0,x) = u_0(x) & (x \in \mathbb{R}),
\end{cases} \\
\text{(VE)} & \quad \begin{cases}
u_{tt}(t,x) = \sigma(u_t(x,t)) + \int_0^t a'(t - \tau) \sigma(u(x,t)) \, d\tau + g(t,x) & (0 < t < \infty, x \in \mathbb{R}) \\
u(0,x) = u_0(x), \quad u_t(0,x) = u_1(x) & (x \in \mathbb{R})
\end{cases}
\end{align*}
\]

with suitably "small" data $u_0, u_1, f, g$; (HF) and (VE) are mathematical models for nonlinear one-dimensional heat flow in a material with "memory" and nonlinear one-dimensional viscoelastic motion, respectively. Here $a: [0, \infty) \to \mathbb{R}$, $\sigma: \mathbb{R} \to \mathbb{R}$, $f, g: [0, \infty) \times \mathbb{R} \to \mathbb{R}$, $u_0, u_1: \mathbb{R} \to \mathbb{R}$ are given, sufficiently smooth functions; the subscripts $x$ or $t$ denote partial derivatives. If $a(0) = 1$ formal differentiation with respect to $t$ reduces (HF) to (VE) with $g(t,x) = f(t,x)$ and $u_1(x) = f(0,x)$. But, since (HF) and (VE) have different physical origins, the corresponding natural assumptions concerning $a(\cdot)$ are drastically different and, therefore, the two problems are studied separately.

A previous study of (HF) and (VE) rests on the concept of Riemann invariant and is restricted to one space dimension. The energy method is simpler in principle and yields more widely applicable results.

AMS (MOS) Subject Classifications: 45K05, 47H15, 47H10, 45M99, 35L60

Key Words: nonlinear Volterra partial integrodifferential equations (of hyperbolic type), energy method, smooth solutions, local and global existence and uniqueness, boundedness, asymptotic behavior, energy estimates, resolvent kernels, nonlinear heat flow, nonlinear viscoelastic motion, materials with memory

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This paper is devoted to a study of the two initial value problems (and some closely related boundary-initial value problems):

\[
\begin{align*}
\begin{cases}
  u_t(t,x) &= \int_0^t a(t - \tau) \sigma(u_x(t,x)) \, d\tau + f(t,x) & (0 < t < \infty, x \in \mathbb{R}) \\
  u(0,x) &= u_0(x) & (x \in \mathbb{R}), \\
  u_{tt}(t,x) &= \sigma(u_x(t,x))_x + \int_0^t a'(t - \tau) \sigma(u_x(t,x))_x \, d\tau + g(t,x) & (0 < t < \infty, x \in \mathbb{R}) \\
  u(0,x) &= u_0(x), u_t(0,x) = u_1(x) & (x \in \mathbb{R})
\end{cases}
\end{align*}
\]

for suitably "small" data \(u_0', u_1', f, g\). Here \(a : [0,\infty) \to \mathbb{R}, \sigma : \mathbb{R} \to \mathbb{R}, f, g : [0,\infty) \times \mathbb{R} \to \mathbb{R}, u_0, u_1 : \mathbb{R} \to \mathbb{R}\) are given real functions, and \(a' = \frac{da}{dt}\). (HF) and (VE) are mathematical models for nonlinear heat flow in a material with memory and for nonlinear viscoelastic motion respectively. If \(a(0) = 1\) formal differentiation of (HF) with respect to \(t\) reduces (HF) to (VE) with \(g(t,x) = f_0(t,x), u_1(x) = f(0,x)\). However, the different physical origins of the two problems, imply drastically different assumptions on the kernel \(a(\cdot)\) for each, and therefore, the two problems are studied separately.

Problems (HF) and (VE) cannot in general be solved explicitly, even in the linear case \(\sigma(r) = c^2r, c\) a constant; here the main interest is in more complicated nonlinear problems, e.g. \(\sigma(r) = c^2r + r^2\), since these provide more accurate mathematical models of physical situations. To suggest some of the difficulties consider the case \(a(t) = 1\) for which both (HF) and (VE) reduce to a nonlinear undamped wave equation (W) \(u_{tt} = \sigma(u_x) + g\). It is known that (W), with the forcing term \(g \equiv 0\), has the property that its solutions develop singularities in the first derivatives at some finite time \(t\), no matter how smooth one takes the initial data; such solutions are called "shocks". Therefore, the initial value problem for (W) does not in general possess global, smooth solutions in time.

We use energy methods to establish the global existence, uniqueness, boundedness, and the decay as \(t \to \infty\) of smooth solutions of (HF) and (VE), under physical reasonable assumptions concerning the "memory function" \(a(\cdot)\), for smooth and suitably "small" data. One interpretation of our global existence results is that the presence of the integrals in (HF) and (VE) provides a damping mechanism which precludes the development of "shocks". The boundedness and decay results are relatively easy by products of the global existence results.

Due to the complexity of the equations under study any method of analysis will necessarily be quite technical. However, the energy method developed in this paper is simple, at least in principle, and it yields more general results for (HF) and (VE) than were obtained in a previous study by the method of Riemann invariants. For this reason our approach is not restricted to one space dimension, as we illustrate by outlining a two-dimensional version of (HF).

The responsibility for the wording and views expressed in this descriptive summary lies with MRC, and not with the authors of this report.
ENENERGY METHODS FOR NONLINEAR HYPERBOLIC VOLterra INTEGRODIFFERENTIAL EQUATIONS

C. M. Dafermos (1), (2), (3) and J. A. Nohel (1), (4)

1. Introduction. In this paper we use energy methods to study global existence, boundedness, and asymptotic behavior, as \( t \to +\infty \), of solutions of two initial value problems:

\[
\begin{align*}
\text{(HF)} & \quad \begin{cases}
\frac{\partial u}{\partial t}(t,x) = \int_0^t a(t - \tau) \frac{\partial u}{\partial x}(\tau,x) \, d\tau + f(t,x), & 0 < t < \infty, \ x \in \mathbb{R} \\
\frac{\partial u}{\partial x}(0,x) = u_0(x), & x \in \mathbb{R}.
\end{cases} \\
\text{(VE)} & \quad \begin{cases}
\frac{\partial^2 u}{\partial t^2}(t,x) = \sigma \frac{\partial u}{\partial x}(t,x) + \int_0^t a'(t - \tau) \frac{\partial u}{\partial x}(\tau,x) \, d\tau + g(t,x), & 0 < t < \infty, \ x \in \mathbb{R} \\
\frac{\partial u}{\partial x}(0,x) = u_0(x), \ u_x(0,x) = u_1(x), & x \in \mathbb{R}
\end{cases}
\end{align*}
\]

with suitably "small" data. Here \( a : [0,\infty) \to \mathbb{R} \), \( \sigma : \mathbb{R} \to \mathbb{R} \), \( f, g : [0,\infty) \times \mathbb{R} \to \mathbb{R} \), \( u_0, u_1 : \mathbb{R} \to \mathbb{R} \) are given functions; subscripts \( x \) or \( t \) denote corresponding partial derivatives; a prime ('') denotes the derivative of functions of a single variable.

Problem (HF) represents a mathematical model for heat flow in unbounded one-dimensional bodies of material with memory while (VE) is a model for the equation of motion of an unbounded one-dimensional nonlinear viscoelastic body. The corresponding initial-boundary value problems for bounded bodies have been studied by MacCamy [7], [8]; we also refer to [7], [8] for a sketch of the derivation of the equations from physical principles. Here we are dealing primarily with the initial value problem but in Section 6 we show that our methods apply equally well to certain initial-boundary value problems.

About \( \sigma(\cdot) \) we make the assumptions

\( (0) \quad \sigma \in C^3(\mathbb{R}), \ \sigma(0) = 0, \ \sigma'(0) > 0 \)

the first for technical reasons and the other two on physical grounds (in the linear

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versions of (HF) and (VE) \( \sigma(u_x) = u_x \). Concerning the forcing terms we assume

\[
\begin{align*}
f, f', f''', f_x, f', f't, f'x, f''t, f'xx, f', f'tt, f'tx, f'txx, f'xxx & \in L^2([0,\infty); L^2(R)), \\
g, g', g''t, g'x, g''tx, g'xx & \in L^2([0,\infty); L^2(R))
\end{align*}
\]

meaning that \( f, g \) and their (distributional) derivatives are endowed with some smoothness and decay sufficiently rapidly at infinity. The initial datum \( u_0(x) \) in both (HF) and (VE) will be assumed to satisfy

\[
\begin{align*}
u_0, u_0', u_0'', u_0''' & \in L^2(R) \\
u_0, u_0', u_0'', u_0''' & \in L^2(R)
\end{align*}
\]

while \( u_1(x) \) in (VE) will satisfy

\[
\begin{align*}
u_1, u_1', u_1'', u_1''' & \in L^2(R) \\
u_1, u_1', u_1'', u_1''' & \in L^2(R)
\end{align*}
\]

We shall postpone to Section 2 the precise assumptions on the kernels \( a(t) \). For the moment it suffices to know that \( a(t) \) is \( C^3 \) smooth and, without loss of generality, \( a(0) = 1 \).

Formal differentiation of (HF) with respect to \( t \) reduces this problem to (VE) with \( g(t,x) = f_t(t,x) \) and \( u_1(x) = f(0,x) \). However, since (HF) and (VE) have different physical origins, the corresponding natural assumptions on \( a(\cdot) \) are drastically different (see Section 2) and as a result the above problems have to be studied separately.

If \( a(t) = 1, t \in [0,\infty) \), both (HF) and (VE) reduce to a nonlinear undamped wave equation \( u_{tt} = \sigma(u_x) + g \). For the latter (take \( g \equiv 0 \)) it is known [4] that the initial value problem does not generally have global smooth solutions, no matter how smooth the initial data are. However, for the wave equation with "frictional" damping, \( u_{tt} + u_t = \sigma(u_x) \), Nishida [11] shows that when the initial data are "small", the dissipation precludes the development of shocks, and as a result global smooth solutions to the initial value problem exist. The proof rests heavily on the concept of Riemann invariants and is strictly "one-space-dimensional". In the aforementioned papers [7], [8], MacCamy shows that, under natural assumptions on the kernels \( a(t) \), the memory terms in (HF) and (VE) induce dissipative mechanisms that guarantee the
existence of global smooth solutions when the initial data and the forcing term are "small". The proof combines certain energy integrals with Nishida's Riemann invariants argument and consequently is "one-space-dimensional". For corrections of certain misprints and oversights in [7], [8] see Section 2. The question of obtaining the existence and uniqueness of a suitable local solution for (HF) and (VE), to be continued with the aid of a priori estimates, is not discussed in [7], [8], but this gap can be filled by the method outlined in Nohel [12]. For the multi-space-dimensional nonlinear wave equation with frictional damping and "small" data Matsumura [9], [10] establishes the existence of global smooth solutions by a method that is based exclusively on "energy" estimates. (We are grateful to Professor Nishida for explaining this method to us.) The object of this paper is to study (HF) and (VE) by a similar approach. We are restricting our attention to the one-space-dimensional situation for clarity - the method seems to work in any number of space dimensions; a two-dimensional version of (HF) is discussed briefly in Section 7.

Our procedure can be outlined as follows: In Section 2 we reduce, similar to [7], [8], both (HF) and (VE) to the equivalent form

\[
\begin{cases}
\displaystyle u_{tt}(t,x) + \frac{3}{2t} \int_0^t k(t-\tau)u_t(t,x)\,d\tau = \sigma(u_x(t,x))_x + \phi(t,x), & 0 < t < \infty, \ x \in \mathbb{R} \\
u(0,x) = u_0(x), \ u_t(0,x) = u_1(x), & \ x \in \mathbb{R}
\end{cases}
\]

(1.1)

where \( k(t) \) is the resolvent kernel associated with \( a'(t) \) (see Section 2) and \( \phi(t,x) \), determined by \( k(t) \) and \( f(t,x) \) or \( g(t,x) \), satisfies

\[
\begin{align*}
\phi, \phi_t, \phi_x, \phi_{tx}, \phi_{txx} \in & \ L^2([0,\infty); L^2(\mathbb{R})) \\
\end{align*}
\]

for problem (HF), and some additional conditions for (VE) (see conditions (\( \psi \)), Section 2). In Section 3 we prove with the help of the Banach fixed point theorem an existence and uniqueness theorem of a local solution to (1.1) that applies both to (HF) and (VE). In Sections 4 and 5 we establish for (HF) and (VE), respectively, "energy" estimates that allow the extension of the local solution, constructed in Section 3, into a global solution. These estimates have the form
\[ E(t) - E(0) \leq -\int_0^t \mathcal{Q}[u, u] \, dt + \int_0^t \mathcal{P}[u, u] \, dt + \int_0^t \mathcal{R}[u, \psi] \, dt \]

where \( E(t) \) is an "energy" that controls the growth of the solution; \( \mathcal{Q}[u, u] \), the dissipation term induced by the memory term, is a positive definite quadratic form in a set of derivatives of \( u(t, x) \); \( \mathcal{P}[u, u] \), the remainder term due to the nonlinearity of the problem, is a quadratic form in the same derivatives as \( \mathcal{Q}[u, u] \) and with coefficients that are small whenever the "energy" \( E \) is small; finally, \( \mathcal{R}[u, \psi] \) is a bilinear form in the set of derivatives of \( u(t, x) \) involved in \( \mathcal{Q}[u, u] \) and in \( \psi(t, x) \) and some of its derivatives. The idea now is that for as long as \( E(t) \) is small, \( \mathcal{P}[u, u] \) is dominated by \( -\mathcal{Q}[u, u] \). Moreover, the Cauchy-Schwarz inequality allows us to dominate the \( u \)-part in \( \mathcal{R}[u, \psi] \) by \( -\mathcal{Q}[u, u] \). Then, if \( E(0) \) and \( \psi \) are "small", \( (1.2) \) shows that \( E(t) \) remains small and the cycle closes.

Finally, we note that both problems (HF) and (VF) are of the abstract form

\[
\begin{cases}
\dot{u}(t) + A(t)u(t) + \int_a^b a'(t - \tau)A(u(\tau)) \, d\tau = F(t), & 0 < t < \infty \\
u(0) = u_0, \quad u'(0) = u_1
\end{cases}
\]

where \( A \) is a nonlinear maximal monotone operator in a Hilbert space \( H \), \( F(t) \) takes values in \( H \) while \( u(t) \) takes values in a reflexive Banach space \( W \) dense in \( H \).

The global existence problem for (A) was extensively studied by S. O. Londen [5], [6] for a class of kernels \( a(\cdot) \) which are positive, smooth, decreasing, convex on \( [0, \infty) \) and which satisfy the crucial condition \( a'(0+) = -\infty \). Unfortunately, this last condition is not satisfied by most memory functionals arising in heat flow theory or in visco-elasticity.
2. Properties of Resolvent Kernels and Transformation of Problems (HF) and (VE). We first show how (HF) and (VE) can be brought to the form (1.1). We define the resolvent kernel $k(\cdot)$ associated with $a'(\cdot)$ via the equation

\[(k)\quad k(t) + (a'_*k)(t) = -a'(t), \quad 0 \leq t < \infty,\]

where, throughout, the * will denote the convolution, i.e.,

\[(a'_*k)(t) = \int_0^t a'(t - \tau)k(\tau)d\tau.\]

By standard Volterra equations theory, if $a \in C^3$ smooth, $k(\cdot)$ is uniquely defined and is $C^2$ smooth on $[0,\infty)$ (see, e.g., Bellman and Cooke [2, Thm. 7.4]). Moreover, for any $\psi \in L^1_{\text{loc}}(0,\infty)$, the unique solution of the Volterra equation

\[(2.1)\quad y(t) + (a'_*y)(t) = \psi(t), \quad 0 \leq t < \infty,
\]

is given by

\[(2.2)\quad y(t) = \psi(t) + (k*\psi)(t), \quad 0 \leq t < \infty.\]

We now visualize the equation in (VE) as a Volterra equation of the form (2.1) with $y = \sigma(u_X)_X$ so that (2.2) yields

\[(2.3)\quad u_{tt}(t,x) + (k*u_{tt})(t,x) = \sigma(u_X)_X + g(t,x) + (k*g)(t,x).\]

An integration by parts with respect to $t$ in the convolution term on the left-hand side of (2.3) shows that (VE) is equivalent to (1.1) with

\[(2.4)_Y\quad \Phi(t,x) = g(t,x) + (k*g)(t,x) + k(t)u_1(x).\]

Problem (HF) is treated in a similar way. First we differentiate the equation in (HF) with respect to $t$ thus bringing it to the form

\[u_{tt}(t,x) = \sigma(u_x)_X + (a'_*\sigma(u_x)_X)(t,x) + f_t(t,x);\]

then we use (2.2) to get

\[u_{tt}(t,x) + (k*u_{tt})(t,x) = \sigma(u_x)_X + f_t(t,x) + (k*f_t)(t,x)\]

and, finally, we integrate by parts with respect to $t$ in the convolution terms to arrive at (1.1) with

\[(2.4)_H\quad \Phi(t,x) = f_t(t,x) + k(0)f(t,x) + (k*f_t)(t,x), \quad 0 \leq t < \infty, \quad x \in \mathbb{R}
\]

\[(2.5)_H\quad u_1(x) = f(0,x), \quad x \in \mathbb{R}.\]
We note that, on account of assumptions \( (f) \), \( u_1(x) \), given by \( (2.5)_H \), satisfies assumption \( (u_1) \).

We now state for each case, separately, the assumptions on the kernels \( a(t) \) and we derive the induced properties of the associated resolvent kernels.

I. Heat Flow Equation

We assume

\[
\begin{align*}
(a_H) & \quad (i) \ a(t) \in C^3[0,\infty), \ a(t), a'(t), a''(t), a'''(t) \text{ are bounded on } [0,\infty) \\
& \quad (ii) \ a(0) = 1, \ a'(0) < 0 \\
& \quad (iii) \ t^j a^{(m)}(t) \in L^1(0,\infty), \quad j = 0, 1, 2, 3, \ m = 0, 1, 2, 3 \\
& \quad (iv) \ \Re \tilde{a}(m) > 0, \ n \in \mathbb{R}, \text{ where } \tilde{a}(s) = \int_0^{\infty} e^{-st}a(t)dt.
\end{align*}
\]

We note that there is no loss of generality in assuming \( a(0) = 1 \), provided \( a(0) > 0 \).

If \( a(0) \neq 1 \), equation (k) is modified to:

\[
a(0)k(t) + (a'k)(t) = -\frac{a'(t)}{a(0)}; \quad (2.2)
\]

and all subsequent equations involving \( k \) are not affected by this change in an essential way. The following proposition summarizes properties of the resolvent kernel \( k(t) \) associated with \( a'(t) \).

**Lemma 2.1.** Assume that \( (a_H) \) are satisfied and let \( k(t) \) be the resolvent kernel associated with \( a'(t) \). Then

\( (i) \ k(t) \in C^2[0,\infty); \ k(t), k'(t), k''(t) \) are bounded on \( [0,\infty) \).

\( (ii) \ k(t) = k_0 + K(t); \ k_m = \frac{1}{a(0)} > 0; \ K^{(m)}(t) \in L^1(0,\infty), \ m = 0, 1, 2. \)

\( (iii) \ For \ any \ T > 0 \ there \ is \ a \ number \ a > 0 \ such \ that\)

\[
\int_0^T \dot{v}(t) \frac{d}{dt}(k*v)(t)dt \geq a \int_0^T v^2(t)dt.
\]

Assertion (iii) of Lemma 2.1 is the manifestation of the dissipative character of the memory term and will play a central role in Section 4. For the (harmonic analysis) proof of Lemma 2.1 we refer to [7, Lemma 3.1]. We note that our assumptions
(a_n) are weaker than the corresponding assumptions (a_m) in [7], the reason being that our method does not require that moments of K and K' be in L^1(0,\infty) (see [7, Lemma 3.1, assertion (ii)]). The reader of the proof of Lemma 3.1 in [7] should be aware of the following misprints: Formula (3.5) should read

\[ \tilde{\kappa}(s) = \frac{\tilde{\alpha}(s) - \tilde{\alpha}(0)}{s\tilde{\alpha}(s)\tilde{\alpha}(0)} - \frac{1}{\tilde{\alpha}(0)} . \]

Moreover, the assumption in [7] that a(t) \in C^2[0,\infty) is insufficient since it only yields \( o\left(\frac{1}{s^2}\right) \) for the error term in [7, eq. (3.8)] rather than \( o\left(\frac{1}{s^3}\right) \), as it is needed. It is for this reason that we are assuming here a(t) \in C^3[0,\infty). The proof of (iii) can be accomplished more simply by the technique of [13, Theorem 1] than that of [7]; the same comment applies to the proof of (2.11) below.

We note that assumption (f) together with k''(t) \in L^m(0,\infty) and k'(t), k''(t) \in L^1(0,\infty) (Lemma 2.1) yield that \( \Phi(t,\tau) \), as defined by (2.4), satisfies condition (4) recorded in Section 1.

II. Viscoelasticity Equation

We make the following assumptions concerning the kernel a(t) in (VE):

\[ \begin{align*}
(a_n) & \quad (i) \quad a(t) \in C^3[0,\infty), \quad a(t), a'(t), a''(t), a'''(t) \text{ are bounded on } [0,\infty) \\
                     & \quad (ii) \quad a(t) = a_n + \lambda(t), \quad a_n > 0, \quad a(0) = 1 \\
                     & \quad (iii) \quad (-1)^m \lambda^m(t) > 0, \quad 0 < t < \infty, \quad m = 0, 1, 2; \quad \lambda'(t) \neq 0 \\
                     & \quad (iv) \quad \lambda^j \lambda^m(t) \in L^1(0,\infty), \quad j = 0, 1, 2, 3, \quad m = 0, 1, 2, 3 .
\end{align*} \]

We note that \((a_n)(iii)\) implies \((a_m)(iv)\) by a standard result [13, Cor. 2.2]. The difference between \((a_m)\) and \((a_n)\) that has a major effect on the properties of the corresponding resolvent kernels is that in the former \( a(\infty) = 0 \) while in the latter \( a(\infty) = a_n > 0 \). In the place of Lemma 2.1 we now have

Lemma 2.2. Assume that \((a_n)\) are satisfied and let k(t) be the resolvent kernel associated with a'(t). Then

\[ \begin{align*}
(i) & \quad k(t) \in C^2[0,\infty); \quad k(t), k'(t), k''(t) \text{ are bounded on } [0,\infty) . \\
(ii) & \quad k^m(t) \in L^1(0,\infty), \quad m = 0, 1, 2. \\
(iii) & \quad \text{For any } T > 0 \text{ and every } v(t) \in L^2(0,T), \\
                  & \quad \int_0^T v(t) \frac{d}{dt} (kvv)(t) dt \geq 0 .
\end{align*} \]
For a proof of Lemma 2.2 see [8, Lemma 3.1].

We note that assumption (g) together with \( k''(t) \in L^\infty(0,\infty) \) and \( k(t), k'(t), k''(t) \in L^1(0,\infty) \) imply that \( \Phi(t,x) \), defined by (2.4), satisfies

\[
(\Phi_x) \quad \begin{align*}
\Phi, \Phi_t \in L^1([0,\infty); L^2(\mathbb{R})), \quad \Phi_x, \Phi_{tt}, \Phi_{tx} \in L^2([0,\infty); L^2(\mathbb{R})) .
\end{align*}
\]

namely conditions that imply (\( \Psi \)) of Section 1.

In contrast to \( (2.6)_H, (2.6)_V \) only indicates a weak dissipative mechanism. Indeed, the dissipative mechanism for the viscoelasticity equation is quite subtle and it will reveal itself through a device of MacCamy [8] that involves still another form of (VE).

We define a function \( r : [0,\infty) \to \mathbb{R} \) by

\[
(\Psi) \quad r(t) = \beta + k(t) + \beta \int_0^t k(\tau) d\tau
\]

where \( \beta > 0 \) is a constant to be specified below and \( k(t) \) is the resolvent kernel associated with \( a'(t) \). It is easily verified that the solution \( y(t) \) of the Volterra equation (2.1) satisfies

\[
y(t) + \beta \int_0^t y(\tau) d\tau = \phi(t) + (r\psi)(t), \quad 0 \leq t < \infty .
\]

Since \( y = \sigma(u_x)_x \) in (VE) satisfies an equation of the form (2.1) we obtain from (2.7)

\[
(2.8) \quad u_{tt}(t,x) + (r*u_{tt})(t,x) = \sigma(u_x(t,x))_x + \beta \int_0^t \sigma(u_x(\tau,x))_x d\tau + \sigma(t,x) + (r*q)(t,x) .
\]

Thus (VE) is equivalent to the problem

\[
(2.9) \quad \begin{cases}
  u_{tt}(t,x) + (r*u_{tt})(t,x) = \sigma(u_x(t,x))_x + \beta \int_0^t \sigma(u_x(\tau,x))_x d\tau + \Psi(t,x), \\
  u(0,x) = u_0(x), \quad u_x(0,x) = u_1(x), \quad x \in \mathbb{R}
\end{cases}
\]

where

\[
(2.10) \quad \Psi(t,x) = g(t,x) + (r*\sigma)(t,x) .
\]

The justification for considering the complicated variant (2.9) of (VE) is provided by the following proposition:
Lemma 2.3. Assume that assumptions \((a_n)\) are satisfied and let \(r(t)\) be defined by (r). Then

(i) \(r(t) \in C^2(0,\infty), r(t), r'(t), r''(t)\) are bounded on \([0,\infty)\).

(ii) \(r(t) = r_m + R(t); \quad r_m = \beta/a_m; \quad R^{(m)}(t) \in L^1(0,\infty), \quad m = 0,1,2.\)

(iii) For any \(T > 0\) there are constants \(\gamma, q > 0, \) with \(bq < 1,\) such that

\[
(2.11) \quad q \int_0^T v(t) \frac{d}{dt} \left( r*v(t) \right) dt - \int_0^T v(t) (R*v)(t) dt \geq (1 + \gamma) \int_0^T v^2(t) dt
\]

for every \(v(t) \in L^2(0,T).\)

It is (2.11) that reveals the dissipative mechanism induced by the memory term in the viscoelasticity equations. This estimate will play a crucial role in Section 5.

For the proof of Lemma 2.3 we refer to [8, Lemma 3.2]. For the benefit of the reader we record here the following corrections in the proof of [8, Proposition 4.1]:

Equation (4.16) should read

\[-q \eta \text{Im}(i\nu) - \text{Re}(i\nu) = \Gamma(q, \beta, n) + 1, \quad n \in \mathbb{R};\]

equation (4.26) should read

\[
\frac{1}{q} - \beta q = \frac{m(n)q^2 + n(n)}{q(n(n) - q)}
\]

and the sentence following this equation should read: "Given \(\tilde{q}, \tilde{q}, 0 < \tilde{q} < \tilde{q} < \infty,\) there exists an \(\tilde{\epsilon} > 0, \tilde{\epsilon} = \epsilon(q, \tilde{q}),\) such that for every \(\tilde{q} < q < \tilde{q}\) (4.27) holds".

Note also that \(\frac{1}{q_k} - \beta q_k\) tends to \(-\hat{a}(0)\) (and not to \(-\hat{a}(0)/q^2\)). In the concluding argument of the proposition one needs to choose \(0 < \epsilon < \min(\epsilon(q, \tilde{q}), \epsilon(q, \tilde{q}))\) in order to carry through the proof, since \(\gamma(q, \beta, n) + q \beta - 1 - \hat{a}(0)q\) and \(0 < \frac{1}{q} - \beta \epsilon < \frac{\epsilon}{2},\)

by the choice of \(q\) and \(\beta.\)

We close this section by noting that on account of (2.10), assumption (g) and \(r'(t), r''(t) \in L^1(0,\infty)\) (Lemma 2.3), the forcing term \(V(t,x)\) in (2.9) satisfies

\[
(V, V) \quad V_t \in L^1([0,\infty); L^2(\mathbb{R})), \quad V_{tt}, \quad V_{tx} \in L^2([0,\infty); L^2(\mathbb{R})).
\]
1. Local Existence Theorem. We discuss here existence and uniqueness of local solutions to problem (1.1), applicable to both (HF) and (VE). Throughout this section we will be assuming that the initial data satisfy conditions \((u_0), (u_1)\) and the forcing term satisfies \((\Phi)\). As regards the kernel \(k(t)\), we only require that \(k'(t), k''(t) \in C[0,\infty) \cap L^1(0,\infty)\) so that our analysis covers both the (HF) and the (VE) cases. On the other hand, since the local solution will not be necessarily "small", for the well-posedness of the problem we have to replace \((\Phi)\) by the stricter assumption

\[(\sigma) \quad \sigma \in C^3(\mathbb{R}); \sigma(0) = 0; \sigma'(w) \geq p_0 > 0, \ w \in (-\infty, \infty).
\]

This assumption will be dropped in Sections 4 and 5 where we will limit ourselves to "small" solutions.

The main result of this section is

Theorem 3.1. Let the assumptions \((\sigma^*), (\Phi), (u_0), (u_1)\), and \(k', k'' \in C[0,\infty) \cap L^1(0,\infty)\) be satisfied. There is a unique solution \(u(t,x) \in C^2((0,T_0) \times \mathbb{R})\) of (1.1) defined on a maximal interval \([0,T_0), T_0 \leq \infty\), such that, for \(T \in [0,T_0)\),

\[(3.1) \quad u_t, u_x, u_{tt}, u_{tx}, u_{xx}, u_{xxx}, u_{xxxx} \in L^2([0,T]; L^2(\mathbb{R})).
\]

Furthermore, if \(T_0 < \infty\), then

\[(3.2) \quad \int_0^T \left[ u^2_t(t,x) + u^2_x(t,x) + u^2_{tt}(t,x) + u^2_{tx}(t,x) + u^2_{xx}(t,x) + u^2_{ttt}(t,x) \right] dx < \infty, \ t \to T_0.
\]

The proof of the above proposition will be based on an application of the Banach fixed point theorem. We begin with some preparation.

For positive \(M\) and \(T\) we let \(X(M,T)\) denote the set of functions \(u(t,x) \in C^2([0,T] \times \mathbb{R})\), with initial conditions \(u(0,x) = u_0(x), u_t(0,x) = u_1(x)\), which satisfy (3.1), and

\[(3.3) \quad \sup_{[0,T]} \int [u^2_t + u^2_x + u^2_{tt} + u^2_{tx} + u^2_{xx} + u^2_{ttt} + u^2_{txx} + u^2_{xxx}] dx \leq M^2.
\]

Note that \(X(M,T)\) is nonempty if \(M\) is sufficiently large. Also observe that for
\[ u(t,x) \in X(M,T) \quad (3.3) \] easily yields

\[ \sup_{[0,T] \times \mathbb{R}} \{ |u_t(t,x)|, |u_x(t,x)|, |u_{tt}(t,x)|, |u_{tx}(t,x)|, |u_{xx}(t,x)| \} \leq M \]

\[ (3.4) \quad \left( \int_{-\infty}^{\infty} \left[ u_t^2(t,x) \right] \, dx \right)^{\frac{1}{2}} \leq 2 \left( \int_{-\infty}^{\infty} |u_t(t,x)| \, dx \right) \left( \int_{-\infty}^{\infty} |u_{tx}(t,x)| \, dx \right) \leq M^2, \]

and similarly for the others).

We now construct a map \( S : X(M,T) \to C(0,T] \times \mathbb{R} \) which carries \( v(t,x) \in X(M,T) \) into the solution \( u(t,x) \) of the linear initial value problem

\[
\begin{align*}
 & u_{tt}(t,x) + k(0)u_t(t,x) = \sigma'(v_x(t,x))u_{xx}(t,x) + \theta(t,x) - (k'*v)(t,x), \\
 & u(0,x) = u_0(x), \quad u_t(0,x) = u_1(x), \quad x \in \mathbb{R}.
\end{align*}
\]

(3.5)

Our goal is to show that \( S \) has a unique fixed point in \( X(M,T) \) since the desired solution of (1.1) is such a fixed point (note that

\[
\frac{3}{\delta t} (k*u_t)(t,x) = k(0)u_t(t,x) + (k'*u_t)(t,x).
\]

Lemma 3.1. If \( M \) is sufficiently large and \( T \) sufficiently small, then \( S \) maps \( X(M,T) \) to itself.

Proof. We have to show that the solution of (3.5) satisfies (3.1), (3.3), provided that \( M \) is large and \( T \) is small. To this end we establish below a number of a priori "energy" estimates for solutions of (3.5).

Let us assume, temporarily, that \( \sigma(x), k(t), u_0(x), u_1(x), \theta(t,x) \) and \( v(t,x) \) are \( C^\infty \) smooth on the corresponding domains of definition and that \( u_0(x), u_1(x), \theta(t,x) \) and \( v(t,x) \) are compactly supported on \( \mathbb{R} \). Then the solution \( u(t,x) \) of (3.5) will be \( C^\infty \) smooth on \([0,\infty) \times \mathbb{R} \) and \( u(t,\cdot) \) will have compact support in \( \mathbb{R} \) for \( t \geq 0 \).

Multiplying the equation in (3.5) by \( u_t(t,x) \) and integrating over \([0,s] \times \mathbb{R}, 0 \leq s \leq T \), we obtain, after an integration by parts with respect to \( x \) and other straightforward calculations (for simplicity we omit the arguments of functions whenever no confusion arises from doing so in this and subsequent calculations),
To aid the reader we indicate a calculation contained in (3.6); similar calculations are involved in (3.7)–(3.10) as well as in Sections 4, 5, 6, 7. Integrating by parts with respect to \( x \) one has

\[
\int_0^S \int \sigma'(v)_x u_x u_t \, dx \, dt = - \int_0^S \int \sigma'(v)_x u_x u_t \, dx \, dt - \int_0^S \int \sigma''(v)_x u_x u_t \, dx \, dt.
\]

Observing that \( u_{tt} = \frac{3}{2}\frac{d}{dt} u_x^2 \) and integrating the first integral on the right side by parts with respect to \( t \) yields

\[
\int_0^S \int \sigma'(v)_x u_x u_t \, dx \, dt = - \int_0^S \int \sigma'(v)_x u_x u_t \, dx \, dt - \int_0^S \int \sigma''(v)_x u_x u_t \, dx \, dt,
\]

which, together with the other terms resulting from multiplying (3.5) by \( u_t \) and integrating, easily gives (3.6).

We next differentiate the equation in (3.5) with respect to \( t \) obtaining

\[
u_{ttt} + k(0) u_{tt} = \sigma'(v)_x u_{xt} + \sigma''(v)_x u_{xx} + \frac{d}{dt} - k'(0) v_t - (k''v)_t(t,x).
\]

We multiply this equation by \( u_{tt}(t,x) \), and following the procedure used in the derivation of (3.6) we obtain
We now differentiate the equation in (3.5) with respect to $x$, we multiply by $u_{tx}(t,x)$ and we follow the above standard procedure to get

\[
\frac{1}{2} \int_{-\infty}^{\infty} u_{tt}^2(s,x) \, dx + \frac{1}{2} \int_{-\infty}^{\infty} \sigma'(v_x(s,x)) u_{x}^2(s,x) \, dx - \frac{1}{2} \int_{-\infty}^{\infty} u_{tx}^2(0,x) \, dx \\
- \frac{1}{2} \int_{-\infty}^{\infty} \sigma'(v_x(0,x)) u_{xx}^2(0,x) \, dx = - \int_{-\infty}^{\infty} k(0) u_{tt}^2 \, dxdt + \int_{-\infty}^{\infty} \frac{1}{2} \sigma''(v_x) v_{x} u_{xx}^2 \, dxdt \\
- \int_{-\infty}^{\infty} \sigma''(v_x) v_{x} u_{xx} u_{tx} \, dxdt + \int_{-\infty}^{\infty} \sigma''(v_x) v_{x} u_{tx} \, dxdt + \int_{-\infty}^{\infty} \phi u_{tt} \, dxdt \\
- \int_{-\infty}^{\infty} k'(0) v_{tx} u_{tx} \, dxdt - \int_{-\infty}^{\infty} (k''v_x) u_{tt} \, dxdt .
\]

We now differentiate the equation in (3.5) with respect to $t$ and then multiplying by $u_{ttt}(t,x)$. In the present case note from the equation preceding (3.7) that $\frac{d}{dt}(k''v_x)(t,x) = k''(t)v_x(0,x) + (k''v_x)(t,x)$. The result of the calculation is

\[
\frac{1}{2} \int_{-\infty}^{\infty} u_{tt}^2(s,x) \, dx + \frac{1}{2} \int_{-\infty}^{\infty} \sigma'(v_x(s,x)) u_{x}^2(s,x) \, dx - \frac{1}{2} \int_{-\infty}^{\infty} u_{tx}^2(0,x) \, dx \\
- \frac{1}{2} \int_{-\infty}^{\infty} \sigma'(v_x(0,x)) u_{xx}^2(0,x) \, dx = - \int_{-\infty}^{\infty} k(0) u_{ttt}^2 \, dxt + \int_{-\infty}^{\infty} \frac{1}{2} \sigma''(v_x) v_{x} u_{xx}^2 \, dxt \\
+ \int_{-\infty}^{\infty} \frac{1}{2} \sigma''(v_x) v_{x} u_{xx} u_{ttt} \, dxt - \int_{-\infty}^{\infty} \sigma''(v_x) v_{x} u_{ttt} \, dxt \\
+ \int_{-\infty}^{\infty} 2\sigma''(v_x) v_{tx} u_{ttt} \, dxt + \int_{-\infty}^{\infty} \sigma''(v_x) v_{tx} u_{xxx} \, dxt \\
+ \int_{-\infty}^{\infty} \frac{1}{2} \sigma''(v_x) v_{tx} u_{xxx} u_{ttt} \, dxt .
\]

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The final estimate is obtained by taking the second derivative of the equation in (3.5) with respect to $t$ and $x$ and multiplying by $u_{ttx}(t,x)$. We thus obtain

$$(3.10) \quad \frac{1}{2} \int_0^s u_{ttx}^2(s,x)dx + \frac{1}{2} \int_0^s \sigma'(\nu_x(s,x))u_{ttx}^2(s,x)dx - \frac{1}{2} \int_0^s u_{ttt}(0,x)dx$$

and so forth.

We now observe that $u_{tt}(0,x)$, $u_{ttx}(0,x)$ and $u_{tttx}(0,x)$ can be expressed through (3.5) in terms of $u_{0x}(x)$, $u_{0xx}(x)$, $u_{0xxx}(x)$, $u_1(x)$, $u_{1x}(x)$, $u_{1xx}(x)$, $\phi(0,x)$, $\phi_x(0,x)$ and $\phi_{xx}(0,x)$. It follows that, since $u(t,x)$ is smooth, $u(t,x) \in C(M,T)$ provided that $M$ is sufficiently large and $T$ is sufficiently small. We shall use (3.6)-(3.10) to estimate $M$ and $T$ independently of our provisional smoothness assumptions. To this end, using (3.3), (3.4) and the Cauchy-Schwarz inequality, we majorize each integral on the right-hand side of (3.6)-(3.10) by a fixed constant (i.e. independent of $M$) plus $M^2T$ times a constant depending on $M$. For example, in (3.9),

$$\int_0^s 2\sigma''(\nu_x)u_{ttt}u_{ttx}dxdt \leq \max(|\sigma''(\nu_x)\nu_x|) \int_0^s (u_{ttt}^2 + u_{ttx}^2)dxdt \leq (M \max |\sigma''(\cdot)|)M^2T,$$

$$\int_0^s \frac{1}{2} u_{ttx}^2(s,x)dx \leq \frac{1}{2} M^2T,$$

$$\int_0^s \frac{1}{2} \sigma'(\nu_x(s,x))u_{ttx}^2(s,x)dx \leq \frac{1}{2} M^2T,$$

$$\int_0^s \frac{1}{2} k'(0)u_{ttt}^2dx \leq \frac{1}{2} M^2T.$$
\[
\int_0^s \int_{\mathbb{T}} u_{ttt} \, dx \, dt \leq \int_0^s \int_{\mathbb{T}} u_{tt}^2 \, dx \, dt + \int_0^s \int_{\mathbb{T}} u_{tt}^2 \, dx \, dt \leq \int_0^s \int_{\mathbb{T}} \phi_{ttt}^2 \, dx \, dt + M^2 T,
\]
\[
- \int_0^s \int_{\mathbb{T}} (k^*v_{tt})u_{ttt} \, dx \, dt \leq \int_0^s \int_{\mathbb{T}} (k^*v_{tt})^2 \, dx \, dt + \int_0^s \int_{\mathbb{T}} u_{tt}^2 \, dx \, dt 
\]
\[
\leq \left( \int_0^s \|k^*(t)\|_d \right)^2 + 1M^2 T.
\]

Since \( u_{xxx}(t,x) \) does not appear on the left-hand side of any of the estimates (3.6)-(3.10), we have to express it in terms of other derivatives via
\[
(3.11) \quad \sigma'(v_x)u_{xxx} = u_{txx} + k(0)u_{tx} - \sigma''(v_x)v_{xx}u_x - \phi_x + (k'v_x_{tx})
\]
which is obtained by differentiating (3.5) with respect to \( x \). On account of \( (\sigma)^* \), (3.3), (3.4) and in conjunction with (3.8), (3.10), equation (3.11) yields an upper estimate for \( \int_{\mathbb{T}} u_{xxx}^2(t,x) \, dx \) by a fixed constant plus \( M^2T \) times a constant depending on \( M \).

Combining all the above estimates we obtain
\[
(3.12) \quad \int_0^s \int_{\mathbb{T}} [u_t^2(t,x) + u_x^2(t,x) + u_{tx}^2(t,x) + u_{xx}^2(t,x) + u_{tt}^2(t,x) + u_{txx}^2(t,x)] \, dx \leq A(u_0, u_1, \phi) + B(M)M^2 T, \quad 0 \leq t \leq T.
\]
The constant \( A \) can be estimated solely in terms of the \( L^2(\mathbb{T}) \)-norms of \( u_0^x, u_{0xx}, u_{0xxx}, u_1^x, u_{1xx} \), the \( L^2([0,T]; L^2(\mathbb{T})) \) norms of \( \phi, \phi', \phi'', \phi_{tx}, \phi_{txx}, \phi_{txxx} \), and \( \sigma'(\cdot), \sigma''(\cdot) \), \( k'(\cdot), k''(\cdot) \), \( k'(\cdot), k''(\cdot) \), \( k'(\cdot), k''(\cdot) \) and \( k'(\cdot), k''(\cdot) \). The constant \( B \) can be estimated solely in terms of \( M \) and bounds on \( \sigma'(\cdot), \sigma''(\cdot), k'(\cdot), k''(\cdot) \). It follows that, even though (3.12) was established under supplementary smoothness conditions, its validity can be extended by a simple density argument to the standing assumptions of this section.

We now select \( M \geq [2A(u_0, u_1, \phi)]^{1/2} \) and then \( T \leq [2B(M)]^{-1} \) in which case the right-hand side of (3.12) is dominated by \( M^2 \). It follows that with this selection of \( M \) and \( T, S \) maps \( X(M,T) \) into itself. The proof of Lemma 3.1 is complete.
We now equip \( X(M, T) \) with the metric
\[
\rho(u, v) = \max_{[0, T]} \left\{ \int_0^T \left[ (u_t(t, x) - u_t(t, x))^2 + (u_x(t, x) - u_x(t, x))^2 \right] dx \right\}^{1/2}.
\]

Using the lower semicontinuity property of norms under weak convergence in Banach space, it is easily verified that \( X(M, T) \) becomes a complete bounded metric space. We now have

**Lemma 3.2.** For \( M \) sufficiently large and \( T \) sufficiently small the map
\( S : X(M, T) \rightarrow X(M, T) \) is a contraction.

**Proof.** Let \( v(t, x), \bar{v}(t, x) \in X(M, T) \). We set \( u = Sv, \bar{u} = S\bar{v}, \bar{v} = v - \bar{v}, U = u - \bar{u} \).

Then \( U(t, x) \) is a solution of the initial value problem
\[
\begin{align*}
U_{tt}(t, x) + k(0)U_t(t, x) &= \sigma'(v_x(t, x))U_x(t, x) + \chi(t, x)\bar{v}_x(t, x)V_x(t, x) - (k'\bar{v}_t)(t, x), \\
U(0, x) &= 0, \quad U_t(0, x) = 0, \quad x \in \mathbb{R}
\end{align*}
\]
(3.14)

where \( \chi(t, x) \) is the bounded continuous function
\[
\chi(t, x) = \begin{cases} 
\frac{\sigma'(v_x(t, x)) - \sigma'(\bar{v}_x(t, x))}{v_x(t, x) - \bar{v}_x(t, x)} & \text{if } v_x(t, x) \neq \bar{v}_x(t, x) \\
\sigma''(v_x(t, x)) & \text{if } v_x(t, x) = \bar{v}_x(t, x).
\end{cases}
\]
(3.15)

Multiplying (3.14) by \( U_t \) integrating over \( [0, s] \times \mathbb{R} \), \( 0 < s < T \), and after an integration by parts we obtain
\[
\frac{1}{2} \int_0^s \int_{\mathbb{R}} U_t^2(s, x) dx + \frac{1}{2} \int_0^s \int_{\mathbb{R}} \sigma'(v_x(s, x)) U_x^2(s, x) dx
\]
\[
= - \int_0^s \int_{\mathbb{R}} k(0)U_t^2 dx dt + \int_0^s \int_{\mathbb{R}} \frac{1}{2} \sigma''(v_x) v_{xx}^2 U_x^2 dx dt
\]
\[
- \int_0^s \int_{\mathbb{R}} \sigma''(v_x) v_{xx}^2 U_x^2 dx dt + \int_0^s \int_{\mathbb{R}} \chi U_x V_x U_t dx dt
\]
\[
- \int_0^s \int_{\mathbb{R}} (k'\bar{v}_t)U_t dx dt.
\]
(3.16)

We minorize the left-hand side of (3.16), using \((\sigma)^*\), and we majorize each integral on the right-hand side using (3.4) and the Cauchy-Schwarz inequality thus obtaining
\[ (3.17) \quad \int_0^T \left[ H_t^2(s,x) + H_x^2(s,x) \right] ds \]

\[ \leq \int_0^T \int \left[ H_t^2(t,x) + H_x^2(t,x) \right] dx dt + \int_0^T \left[ \int \left[ H_t^2(t,x) + H_x^2(t,x) \right] dx \right] dt, \quad (0 \leq s \leq T) \]

where \( u \) depends solely on \( N, \max \left| o'(\cdot) \right|, \max \left| o''(\cdot) \right|, P_0, k(0), \) and \( \int \left| k'(t) \right| dt. \]

Applying Gronwall's lemma to (3.17) yields

\[ (3.18) \quad \max_{[0,T]} \int \left[ H_t^2(t,x) + H_x^2(t,x) \right] dx \leq \frac{1}{4} \int_{[-M,M]} \left( H_t^2(t,x) + H_x^2(t,x) \right) dx. \]

We now fix \( N \) sufficiently large and, subsequently, we pick \( T \) so small that on the one hand \( S \) maps \( X(M,T) \) into itself (Lemma 3.1) and on the other \( \frac{T}{e^T} \leq \frac{1}{4} \). This implies that

\[ (3.19) \quad \rho(Sv,Sw) \leq \frac{1}{2} \rho(v,v), \quad \text{for } v, \bar{v} \in X(M,T). \]

The proof of Lemma 3.2 is complete.

**Proof of Theorem 3.1.** From Lemma 3.2 and the Banach fixed point theorem we deduce the existence of a unique fixed point of \( S \) in \( X(M,T) \), for some \( N > 0, T > 0 \), which will be a solution of (1.1) on \([0,T] \times \mathbb{R}\). Let \( T_0 \leq \) be the maximal interval of existence of a solution \( u(t,x) \) of (1.1) which satisfies (3.1) for all \( T < T_0 \). Then \( u(t,x) \) is locally and hence also globally unique as the fixed point of a contraction.

If \( T_0 \leq \) and (3.2) is not satisfied, we can extend \( u(t,x) \) up to \( t = T_0 \) so that \( u(t,x) \in C([0,T_0] \times \mathbb{R}) \) and, by weak convergence in \( L^2(\mathbb{R}), u_x(T_0,x), u_{xx}(T_0,x), u_{xxx}(T_0,x), u_{tx}(T_0,x), u_{txx}(T_0,x) \in L^2(\mathbb{R}). \) But then \( u(t,x) \) can be extended as a solution on a small interval \([T_0,T_0 + \epsilon]\) beyond \( T_0 \) which is a contradiction. This completes the proof of Theorem 3.1.

As \( o(\cdot), k(t), \) and the data \( u_0(x), u_1(x) \) and \( \Phi(t,x) \) get smoother, the solution becomes smoother. We record below a regularity result that will be used in Sections 4 and 5.
Theorem 3.2. Let the assumptions of Theorem 3.1 be satisfied. Under the additional assumption

\[ \begin{align*}
\sigma(\cdot) & \in C^4(\mathbb{R}) \\
u_{0xxx} & \in L^2(\mathbb{R}) \\
u_{1xxx} & \in L^2(\mathbb{R}) \\
_{ttttt} & \in L^2([0,T); L^2(\mathbb{R})),
\end{align*} \]

the solution \( u(t,x) \) of (1.1), established by Theorem 3.1, also has the property

\[ u_{tttt}, u_{ttxxx}, u_{ttxxx}, u_{xxx}, u_{xxxx} \in L^\infty([0,T); L^2(\mathbb{R})) \]

for every \( T < T_0 \), where \([0,T_0)\) is the maximal interval of existence.

Sketch of proof. For positive \( M, N, T \), we denote by \( Y(M,N,T) \) the set of functions \( u(t,x) \in C([-1,1] \times \mathbb{R}) \), with initial conditions \( u(0,x) = u_0(x), u(0,x) = u_1(x), \) which satisfy (3.1), (3.3), (3.21) and

\[ \begin{align*}
\sup_{[0,T]} & \int [u_x^2 + u_t^2 + u_{tt}^2 + u_x^2 + u_{ttt}^2 + u_{tx}^2 + u_{xxxx}^2 + u_{tttt}^2 \\
& + u_{txxx}^2 + u_{ttxxx}^2 + u_{xxx}^2 + u_{xxxx}^2] \ dx \leq N^2.
\end{align*} \]

We consider again the map \( S \) that carries \( v(t,x) \) to the solution \( u(t,x) \) of (3.5) and we try to show that it has a fixed point in \( Y(M,N,T) \), for appropriate values of \( M, N, T \). We proceed as in the proof of Lemma 3.1. To the set of "energy" integrals (3.6)-(3.10) we append another integral obtained by forming the third derivative of (3.5), with respect to \( t, t \) and \( x \), and then multiplying by \( u_{ttxx} \). This allows the estimation of \( \int u_{tttx}(t,x) \ dx \) and \( \int u_{ttxx}(t,x) \ dx \). These estimates together with (3.5) yield estimates for \( \int u_{tttt}(t,x) \ dx, \int u_{ttxx}(t,x) \ dx \) and \( \int u_{xxxx}(t,x) \ dx \).

Combining all above estimates we obtain, as in the proof of Lemma 3.1, the following analog of (3.12):

\[ \begin{align*}
\int [u_t^2(t,x) + u_t^2(t,x) + u_t^2(t,x) + u_x^2(t,x) + u_t^2(t,x) + u_{ttt}^2(t,x) \\
+ u_x^2(t,x) + u_{xx}^2(t,x) + u_{ttt}^2(t,x) + u_{txx}^2(t,x) \\
+ u_{txxx}^2(t,x) + u_{xxx}^2(t,x)] \ dx \leq A^*(u_0, u_1, \phi) + B^*(M) N^2.
\end{align*} \]
The crucial observation is that $B^*$ depends on $M$ but not on $N$. The reason is that in deriving (3.23) the integrals to be majorized are at most quadratic in the highest order derivatives (whence the term $N^2$) with coefficients that depend on derivatives of $v(t,x)$ of order at most two and are thus bounded, in view of (3.4), solely by functions of $M$. Similarly, we recall that $\mu$, in (3.18), depends on $M$ but not on $N$. It follows that the maximal interval of existence of the smoother solutions is controlled solely by $M$, i.e., (3.21) will be satisfied for any $T$ for which (3.1) is satisfied.

This concludes the sketch of the proof of Theorem 3.2.
4. Global Existence and Asymptotic Behavior of Solutions of the Heat Flow Equation. In this section we consider problem (HF) and we prove that if the initial data and the forcing term are "small" then the maximal interval of existence of the solution constructed in Section 3 is \([0,\infty)\) and that the solution decays to zero, as \(t \to \infty\). Our strategy is to show that the dissipative mechanism induced by assumptions (a, H) overrides the growth tendencies of the solution caused by the nonlinearity of \(\sigma(t)\). Conclusion (2.6)_{H} of Lemma 2.1 (iii), which was not used in Section 3, plays a crucial role in this argument. The precise form of the result is

**Theorem 4.1.** Let \((\gamma), (a_{H}), (f)\) and \((u_{0})\) be satisfied. If the \(L^{2}(0,\infty)\) norms of \(u_{0}, u_{x}, u_{xx}, u_{xxx}\) and the \(L^{2}(\mathbb{R})\) norms of \(u_{0x}, u_{0xx}, u_{0xxx}\) are sufficiently small, then there is a unique global solution \(u(t,x) \in C^{2}(0,\infty) \times \mathbb{R}\) of (HF) and

\[
\begin{align*}
&u_{t} - \sum u_{x} u_{tt} u_{tx} u_{xx} u_{ttt} u_{txx} u_{xxx} \in L^{2}(0,\infty) \times L^{2}(\mathbb{R}), \\
&u_{x} - \sum u_{tt} u_{tx} u_{ttt} u_{txx} u_{xxx} \in L^{2}(0,\infty) \times L^{2}(\mathbb{R}), \\
&u_{xx} - \sum u_{t} (t,\cdot), u_{tt} (t,\cdot), u_{tx} (t,\cdot), u_{x} (t,\cdot) - 0, \ t \to \infty, \ \text{in} \ L^{2}(\mathbb{R}), \\
&u_{xxx} - \sum u_{t} (t,x), u_{tt} (t,x), u_{tx} (t,x), u_{xx} (t,x) - 0, \ t \to \infty, \ \text{uniformly on} \ \mathbb{R}.
\end{align*}
\]

**Remark 4.1.** It follows from the proof of Theorems 3.1 and 4.1 that the solution \(u\) of (HF) has a finite speed of propagation.

**Proof.** We will work with form (1.1) of problem (HF) with \(f(t,x)\) and \(u_{1}(x)\) given by (2.4)_{H} and (2.5)_{H}, respectively. In order to make sure that the problem is well-posed, we have to restrict the range of \(u_{1}(t,x)\) to the set on which \(\sigma'(t) > 0\). To this end we introduce a constant \(c_{0} > 0\) such that

\[
\sigma'(w) \geq p_{0} > 0, \ \ w \in [-c_{0},c_{0}].
\]

At this point it is convenient to define

\[
W(w) = \int_{0}^{w} \sigma(t) dt
\]

and to note that, on account of (4.5),

\[
W(w) \geq \frac{1}{2} p_{0} w^{2}, \ \ w \in [-c_{0},c_{0}].
\]
We will say that a quantity is "controllably small", if it can be made arbitrarily small by selecting the initial data and the forcing term appropriately small. For example, on account of (f), Lemma 2.1 (ii), (2.4)$_H$ and (2.5)$_H$, the $L^2((0,\infty); L^2(\mathbb{R}))$ norms of $\phi$, $\phi_t$, $\phi_x$, $\phi_{tt}$, $\phi_{tx}$ and the $L^2(\mathbb{R})$ norms of $u_1$, $u_x$, $u_{xx}$ are controllably small.

Our strategy is to show that there is a small positive number $\mu < c_0$, depending solely upon $\alpha$ (the constant appearing in (2.6)$_H$), $p_0$, bounds of $|\sigma'(\cdot)|$ and $|\sigma''(\cdot)|$ on $[-c_0, c_0]$, and the $L^1(0,\infty)$ norm of $k'(t)$, such that if the local solution $u(t,x)$ of (1.1), in the sense of Theorem 3.1, satisfies

\begin{equation}
|u_x(t,x)|, |u_{tx}(t,x)|, |u_{xx}(t,x)| \leq \mu, \quad 0 \leq t < T, \quad x \in \mathbb{R},
\end{equation}

then certain functionals of the solution are controllably small.

We begin by multiplying the equation in (1.1) by $u_t(t,x)$ and integrating each term over $[0,s] \times \mathbb{R}$, $0 < s < T$. We integrate the term

\begin{equation}
\int_0^s \int_0^\infty \sigma(u_t(t,x)) u_x(t,x) \, dx \, dt
\end{equation}

by parts with respect to $x$ and use (4.6); we then use (2.6)$_H$ to estimate the term

\begin{equation}
\int_0^s \int_0^\infty u_t(t,x) \frac{1}{\alpha} \int_0^t k(t-\tau) u_x(t,x) \, d\tau \, dx \, dt,
\end{equation}

and we thus obtain the estimate

\begin{equation}
\frac{1}{2} \int_0^\infty u_t^2(s,x) \, dx + \int_0^\infty W(u_x(s,x)) \, dx + \alpha \int_0^s \int_0^\infty u_x^2 \, dx \, dt
\end{equation}

\begin{equation}
\leq \frac{1}{2} \int_0^\infty u_t^2(0,x) \, dx + \int_0^\infty W(u_x(0,x)) \, dx + \int_0^s \int_0^\infty \phi_t \, dx \, dt.
\end{equation}

We note that each term on the right-hand side of (4.9) either is controllably small or can be majorized by the sum of a quantity that is controllably small and a quantity that is dominated by the dissipation term, such as

\begin{equation}
\int_0^s \int_0^\infty \phi_t \, dx \, dt \leq \frac{1}{\alpha} \int_0^s \int_0^\infty \phi^2 \, dx \, dt + \frac{\alpha}{4} \int_0^s \int_0^\infty u_x^2 \, dx \, dt.
\end{equation}
Thus, for as long as (4.8) is satisfied with \( u < c_0' \), (4.9), (4.10), together with (4.7), yield that \( \int_0^s u^2_t(s,x)dx \), \( \int_0^s u^2_x(s,x)dx \) and \( \int_0^s u^2_tdxdt \) are controllably small, uniformly on \((0,T)\).

We now derive two additional estimates, the first by differentiating the equation in (1.1) with respect to \( t \) and then multiplying by \( u_t(t,x) \), the second by differentiating (1.1) with respect to \( x \) and then multiplying by \( u_x(t,x) \). Following the procedure in the derivation of (4.9), and noting that

\[
\frac{3}{2} (k^* u_t)(t,x) = \frac{3}{2} (k^* u_x^t)(t,x) + k'(t) u_4(x) ,
\]

we obtain

\[
\int_0^s \frac{1}{2} \int u^2_{tt}(s,x)dx + \frac{1}{2} \int u^2_{tx}(s,x)dx + \int_0^s \frac{1}{2} \int u^2_tdxdt
\]

\[
- \frac{1}{2} \int u^2_{tx}(0,x)dx + \frac{1}{2} \int u^2_{tx}(0,x)dx + \frac{1}{2} \int \frac{1}{2} (u_x^3) dx + \int_0^s \frac{1}{2} \int \frac{1}{2} u_{\phi}\phi u^2_{\phi} dx dt
\]

\[
+ \int_0^s \phi u^2_{\phi} dx dt - \int_0^s k'(t) u_4 dx dt ,
\]

and

\[
\int_0^s \frac{1}{2} \int u^2_{tx}(s,x)dx + \frac{1}{2} \int u^2_{xx}(s,x)dx + \int_0^s \frac{1}{2} \int u^2_{tx}dxdt
\]

\[
- \frac{1}{2} \int u^2_{tx}(0,x)dx + \frac{1}{2} \int u^2_{tx}(0,x)dx + \frac{1}{2} \int \frac{1}{2} u^3_{\phi} \phi u^2_{\phi} dx dt
\]

\[
+ \int_0^s \phi u_{\phi} dx dt .
\]

We add up (4.12), (4.13) and we claim that in the resulting inequality, and as long as (4.8) is satisfied with \( u \) sufficiently small, each term on the right-hand side is either controllably small or can be majorized by the sum of a quantity that is controllably small and a quantity that is dominated by the dissipation term. Indeed, the \( L^2(R) \) norm of \( u_{tt}(0,x) \) is controllably small since

\[
u_{tt}(0,x) = \sigma(u_{0x}(x)) + \phi(0,x) - k(0)u_1(x) ;
\]

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space-time integrals are majorized in the pattern of the following representative samples:

\[
\begin{align*}
(4.15) & \quad \int_0^s \int_0^t u_{tt} dx dt \leq \frac{1}{a} \int_0^s \int_0^t \phi^2 dx dt + \frac{a}{4} \int_0^s \int_0^t u_{tt}^2 dx dt, \\
(4.16) & \quad -\int_0^s \int_0^t k'(t)u_{tt} u_{tt} dx dt \leq \frac{1}{a} \sup_{t \leq t \leq T} \int_0^s |k'(t)| dt \int_0^s u_1^2(x) dx + \frac{a}{4} \int_0^s \int_0^t u_{tt}^2 dx dt, \\
(4.17) & \quad \frac{1}{2} \int_0^s \int_0^t \sigma''(u_x) u_x u_{xx}^2 dx dt \leq \frac{1}{2} \max_{[-c_0, c_0]} \int_0^s \sigma''(\cdot) \int_0^s u_{xx}^2 dx dt, \\
(4.18) & \quad \frac{1}{2} \int_0^s \int_0^t \sigma''(u_x) u_x u_{xx}^2 dx dt \leq \frac{1}{2} \max_{[-c_0, c_0]} \int_0^s \sigma''(\cdot) \int_0^s u_{xx}^2 dx dt.
\end{align*}
\]

To estimate the integral on the right-hand side of (4.18), we express \( u_{xx}(t,x) \) in terms of other derivatives by

\[
(4.19) \quad \sigma''(u_x) u_x u_{xx}(t,x) = u_{tt}(t,x) + k(0)u_x(t,x) + (k'u_x)(t,x) - \phi(t,x),
\]

which yields

\[
(4.20) \quad p_0^2 \int_0^s \int_0^t u_{xx}^2 dx dt \leq 4 \int_0^s \int_0^t u_{xx}^2 dx dt + 4 k^2(0) \int_0^s \int_0^t u_{tt}^2 dx dt + 4 \int_0^s \int_0^t \phi^2 dx dt.
\]

The restrictions imposed on \( u \) are expressed in terms of parameters fixed a priori. For example, (4.17) imposes the restriction \( \max_{[-c_0, c_0]} |\sigma''(\cdot)| \leq \frac{a}{4} \). The combination of (4.12), (4.13) and (4.20) yields that, as long as (4.8) is satisfied, \( \int_0^s u_{xx}^2(s,x) dx, \int_0^s u_{xx}^2(s,x) dx, \int_0^s u_{tt}^2 dx dt, \int_0^s u_{tt}^2 dx dt \) are controllably small, uniformly on \([0,T]\).

To get the final set of estimates we assume temporarily that the additional hypothesis (3.20) is satisfied. Thus, by Theorem 3.2, \( u(t,x) \) enjoys the additional smoothness property (3.21). We form the second derivative of the equation in (1.1) with respect to \( t \) and we multiply by \( u_{ttt}(t,x) \); also the second derivative of the equation in (1.1) with respect to \( t \) and \( x \) and we multiply by \( u_{ttt}(t,x) \). Following
the procedure used in the derivation of the previous estimates we obtain

\[ \frac{1}{2} \int_0^\infty u_{ttt}^2(s,x)dx + \frac{1}{2} \int_0^\infty \sigma'(u_x(s,x))u_{txx}^2(s,x)dx + \alpha \int_0^\infty u_{ttt}^2 dxdt \]

\[ \leq \frac{1}{2} \int_0^\infty u_{ttt}^2(0,x)dx + \frac{1}{2} \int_0^\infty \sigma'(u_x(0,x))u_{txx}^2(0,x)dx + \int_0^\infty \frac{1}{2} \sigma''(u_x)u_{txx}^2 dxdt \]

\[ + \int_0^\infty \int_0^\infty 2\sigma''(u_x)u_{tx}u_{txx} dxdt + \int_0^\infty \int_0^\infty \sigma'''(u_x)u_x^2 u_{tx} dxdt \]

\[ + \int_0^\infty \int_0^\infty \int_0^\infty \sigma''(u_x)u_{txx} u_{txxx} dxdt + \int_0^\infty \int_0^\infty \sigma'''(u_x)u_x^2 u_{txx} dxdt \]

\[ + \int_0^\infty \int_0^\infty \int_0^\infty \int_0^\infty k''(t)u_x^2 u_{txx} dxdt + \int_0^\infty \int_0^\infty \int_0^\infty \int_0^\infty k''(t)u_x^2 u_{txx} dxdt \]

\[ (4.21) \]

\[ \frac{1}{2} \int_0^\infty u^2_{txx}(s,x)dx + \frac{1}{2} \int_0^\infty \sigma'(u_x(s,x))u_{txx}^2(s,x)dx + \alpha \int_0^\infty u_{txx}^2 dxdt \]

\[ \leq \frac{1}{2} \int_0^\infty u_{txx}^2(0,x)dx + \frac{1}{2} \int_0^\infty \sigma'(u_x(0,x))u_{txx}^2(0,x)dx + \int_0^\infty \frac{1}{2} \sigma''(u_x)u_{txx}^2 dxdt \]

\[ + \int_0^\infty \int_0^\infty \sigma''(u_x)u_x^2 u_{txx} dxdt + \int_0^\infty \int_0^\infty \sigma'''(u_x)u_x^2 u_{txx} dxdt \]

\[ + \int_0^\infty \int_0^\infty \int_0^\infty \int_0^\infty k''(t)u_x^2 u_{txx} dxdt \]

We add (4.21), (4.22) and we claim that, as long as (4.8) is satisfied for a sufficiently small \( u \), then each term in the resulting inequality is either controllably small or is majorized by the sum of a quantity that is controllably small and a quantity that is dominated by the dissipation term. The \( L^2(\mathbb{R}) \) norms of \( u_{ttt}(0,x) \) and \( u_{txx}(0,x) \) are controllably small since

\[ u_{ttt}(0,x) = \sigma'(u_{0x}(x))u_{1xx}(x) + \sigma''(u_{0x}(x))u_{1x}(x) + \phi(0,x) \]

\[ - k(0)u_{ttt}(0,x) - k'(0)u_{1x}(x) \]

\[ (4.23) \]

\[ u_{txx}(0,x) = \sigma'(u_{0x}(x))u_{0xxx}(x) + \sigma''(u_{0x}(x))u_{0xx}(x) + \phi(0,x) - k(0)u_{1x}(x) \]

\[ (4.24) \]
Whenever $u_{txx}(t,x)$ or $u_{xxx}(t,x)$ appear on the right-hand side, they should be estimated in terms of derivatives for which dissipation information is available with the help of

\begin{align}
(4.25) \quad \sigma'(u_x(t,x))u_{txx}(t,x) &= u_{tttt}(t,x) - \sigma''(u_x(t,x))u_{ttx}(t,x) - \Phi(t,x) \\
&+ k(0)u_{tt}(t,x) + k'(0)u_{t}(t,x) + (k''u_{x})(t,x),
\end{align}

\begin{align}
(4.26) \quad \sigma'(u_x(t,x))u_{xxx}(t,x) &= u_{txx}(t,x) - \sigma''(u_x(t,x))u_{txx}(t,x) - \Phi(t,x) \\
&+ k(0)u_{txx}(t,x) + (k'u_{tx})(t,x).
\end{align}

Beyond that the estimations follow the usual pattern, e.g.,

\begin{align}
(4.27) \quad \int_0^s \int_0^t \phi u_{tttt} dx dt < \frac{1}{a} \int_0^s \int_0^t \phi^2 dx dt + \frac{3}{4} \int_0^s \int_0^s u^2_{ttt} dx dt,
\end{align}

\begin{align}
(4.28) \quad \int_0^s \int_0^t \sigma''(u_x)u_{tt}^2 u_{ttt} dx dt < \frac{1}{2} \max_{[-c_0,c_0]} |\sigma''(\cdot)| \int_0^s \int_0^t (u_{tx}^2 + u_{ttt}^2) dx dt,
\end{align}

\begin{align}
(4.29) \quad - \int_0^s \int_0^t k''(t)u_{ttx} dx dt < \frac{1}{a} \sup_{0 < a} |k''(t)| \int_0^s |k''(t)| dt \int_0^s u_{ttt}^2 dx dt + \frac{3}{4} \int_0^s \int_0^s u_{ttt}^2 dx dt.
\end{align}

Combining (4.21), (4.22), (4.25) and (4.26) we deduce that

\begin{align*}
\int_0^s \int_0^t u_{ttt}^2(s,x) dx dt, \\
\int_0^s \int_0^t u_{ttt}^2(s,x) dx dt, \\
\int_0^s \int_0^t u_{ttt}^2(s,x) dx dt, \\
\int_0^s \int_0^t u_{ttt}^2(s,x) dx dt, \\
\int_0^s \int_0^t u_{ttt}^2(s,x) dx dt, \\
\int_0^s \int_0^t u_{ttt}^2(s,x) dx dt, \\
\int_0^s \int_0^t u_{ttt}^2(s,x) dx dt
\end{align*}

are controllably small, uniformly on $[0,T)$. Moreover, we observe that the estimates involved depend solely on parameters depending on the standing assumptions of the theorem and not on the additional assumptions (3.20). Therefore, by a straightforward density argument, we may remove these extraneous assumptions.

We now put together the information we have collected on controllably small quantities in all of our estimates, and we select initial data and forcing term so "small" that, as long as (4.8) is satisfied,
\[ (4.30) \int_0^s \left[ u_t^2(s,x) + u_x^2(s,x) + u_{tt}^2(s,x) + u_{xx}^2(s,x) + u_{xt}^2(s,x) + u_{tx}^2(s,x) + u_{ttt}^2(s,x) \right] \, dx \\
+ \int_0^s \left[ u_t^2(s,x) + u_{xx}^2(s,x) + u_{xxx}^2(s,x) \right] \, dx \\
\leq \int_0^s \left[ u_t^2 + u_x^2 + u_{tt}^2 + u_{xx}^2 + u_{ttt}^2 + u_{tx}^2 + u_{xxx}^2 \right] \, dx \, dt \leq u^2, \]

where \( 0 \leq s < T \). However, (4.30) implies, in return, (4.8) and the cycle closes. Once (4.30) has been established, Theorem 3.1 yields that the maximal interval of existence of \( u(t,x) \) is \([0,\infty)\) and (4.30) is satisfied for \( 0 \leq s < \infty \). In particular, (4.1) and (4.2) are satisfied.

Statement (4.3) is an immediate corollary of (4.1), (4.2) while (4.4) is a corollary of (4.3) and (4.1). The proof is complete.
5. Global Existence and Asymptotic Behavior of Solutions of the Viscoelasticity Equation. We show here that when the initial data and the forcing term are "small" problem (VE) admits a unique, globally defined, solution which decays to zero as $t \to \infty$.

We note that the solution $u$ of (VE) has a finite speed of propagation (see Remark 4.1). The estimate (2.11) of Lemma 2.3 (iii) plays a crucial role in the analysis. The result is given by

**Theorem 5.1.** Let $(a), (a_0), (g), (u_0)$ and $(u_1)$ be satisfied. If the $L^1((0,\infty); L^2(R))$ norms of $g, g', g't, g 'tx$ and the $L^2(R)$ norms of $u_0x', u_0xx', u_0xxx', u_1, u_1x', u_1xx$ are sufficiently small, then there is a unique global solution $u(t,x) \in C^2((0,\infty) \times R)$ of (VE) and

(5.1) \[ u_t, u_x, u_{tt}, u_{tx}, u_{xx}, u_{ttt}, u_{txx}, u_{txxx}, u_{xxx} \in L^\infty((0,\infty); L^2(R)) \]

(5.2) \[ u_{tt} (t, \cdot), u_{tx}(t, \cdot), u_{xx}(t, \cdot) \to 0, t \to \infty, \text{ in } L^2(R) \]

(5.3) \[ u_t(t, x), u_x(t, x), u_{tt}(t, x), u_{tx}(t, x), u_{xx}(t, x) \to 0, t \to \infty, \text{ unif. on } R. \]

**Proof.** As in the proof of Theorem 4.1, we will work here with form (1.1) of our problem. We introduce again $c_0$ by (4.5) and $W(w)$ by (4.6) noting (4.7). We again consider a local solution $u(t,x)$ of (1.1), in the sense of Theorem 3.1, which satisfies (4.8) for some $T, 0 < T < \infty$, and a small positive $\nu, \nu < c_0$, to be specified later.

To get the first estimate, we multiply the equation in (1.1) by $u_t(t,x)$, we integrate over $[0,s] \times R, 0 < s < T$, integrating by parts with respect to $x$, and we use (2.6), thus obtaining

(5.5) \[ \frac{1}{2} \int_0^s u_t^2(s,x)dx + \int_0^s W(u_x(s,x))dx = \frac{1}{2} \int_0^s u_t^2(0,x)dx + \int_0^s W(u_x(0,x))dx + \int_0^s \phi u_t dx dt. \]

Noting that

(5.6) \[ \int_0^s \phi u_t dx dt \leq \frac{1}{4} \max_{[0,s]} \int_0^s u_t^2(t,x)dx + \left( \int_0^s (\int_0^s \phi dx)^{1/2} dt \right)^2 \]

and using (4.7), we deduce from (5.5)
\[ (5.7) \quad \frac{1}{2} \int_0^s u_t^2(s,x) \, dx + P_0 \int_0^s u_x^2(s,x) \, dx \]

\[ \leq \int_0^s u_1^2(x) \, dx + 2 \int_0^s W(u_{0x}(x)) \, dx + 2 \left( \int_0^s (\int_0^s \phi^2 \, dt)^{1/2} \right)^2, \quad 0 \leq s \leq T. \]

It is easily seen that, on account of (2.4), the \( L^1([0,\infty); L^2(\mathbb{R})) \) norm of \( \phi \) is controllably small, so that it follows from (5.7) that \( \int_0^s u_t^2(s,x) \, dx \) and \( \int_0^s u_x^2(s,x) \, dx \) are controllably small, uniformly on \([0,T)\).

In the following estimates we seek to take advantage of the dissipative mechanism which manifests itself through Lemma 2.3 (iii). To this end, we shall use the equivalent form (2.9) of our problem (VE).

We differentiate (2.9) with respect to \( t \) and we multiply the resulting equation, first by \( u_{tt}(t,x) \) and then by \( u_t(t,x) \). Integrating over \([0,s] \times \mathbb{R}, 0 < s < T\), integrating by parts with respect to \( x \), etc., we end up with the following two equations:

\[ (5.8) \quad \frac{1}{2} \int_0^s u_{tt}^2(s,x) \, dx + \frac{1}{2} \int_0^s \sigma'(u_x(s,x)) u_{tx}^2(s,x) dx + \int_0^s \int_0^s u_t(r^* u_{tt}) \, dx \, dt \]

\[ - B \int_0^s \int_0^s \sigma'(u_x) u_{tx}^2 dx \, dt = \frac{1}{2} \int_0^s u_{tt}^2(0,x) \, dx + \frac{1}{2} \int_0^s \sigma'(u_x(0,x)) u_{tx}^2(0,x) \, dx \]

\[ + \int_0^s \int_0^s \frac{1}{2} \sigma''(u_x) u_{tx}^3 dx \, dt - B \int_0^s \sigma(u_x(0,x)) u_{tx}(s,x) dx + B \int_0^s \sigma(u_x(0,x)) u_{tx}(0,x) dx \]

\[ + \int_0^s \int_0^s \sigma''(u_x) \sigma'(u_x) u_{tx}^2 dx \, dt. \]

\[ (5.9) \quad \frac{B}{2a} \int_0^s u_t^2(s,x) \, dx + \frac{B}{a} \int_0^s W(u_x(s,x)) \, dx - \int_0^s \int_0^s u_t (R u_{tt}) \, dx \, dt \]

\[ - \int_0^s \int_0^s u_t^2 \, dx \, dt + \int_0^s \sigma'(u_x) u_{tx}^2 \, dx \, dt = \frac{B}{2a} \int_0^s u_t^2(0,x) \, dx + B \int_0^s W(u_x(0,x)) \, dx \]

\[ - \int_0^s u_t(s,x) u_{tt}(s,x) dx + \int_0^s u_t(0,x) u_{tt}(0,x) dx \]

\[ - \int_0^s u_t(s,x) (R u_{tt})(s,x) dx + \int_0^s \Psi u_t \, dx \, dt. \]
We now multiply (5.8) by \( q \) (see Lemma 2.3) and we add it to (5.9). Using (2.11) we obtain
\[
\frac{\delta}{2a} \int_{-\infty}^{\infty} x^2 f(x)dx + \delta \int_{-\infty}^{\infty} W(u_x(s,x))dx + \frac{q}{2} \int_{-\infty}^{\infty} u_t^2 (s,x)dx + \frac{q}{2} \int_{-\infty}^{\infty} u_x^2 (s,x)dx
\]
\[
+ \gamma \int_{0}^{\infty} \int_{-\infty}^{\infty} u_t^2 (s,x)dxdt + (1 - q\delta) \int_{0}^{\infty} \int_{-\infty}^{\infty} u_x^2 (s,x)dxdt
\]
\[
\leq \frac{\delta}{2a} \int_{-\infty}^{\infty} u_t^2 (0,x)dx + \delta \int_{-\infty}^{\infty} W(u_x(0,x))dx + \frac{q}{2} \int_{-\infty}^{\infty} u_t^2 (0,x)dx
\]
\[
+ \frac{q}{2} \int_{-\infty}^{\infty} u_x^2 (0,x)dx - \int_{-\infty}^{\infty} u_t (s,x)u_x (s,x)dx + \int_{-\infty}^{\infty} u_t (0,x)u_x (0,x)dx
\]
\[
- q\delta \int_{-\infty}^{\infty} u_x (s,x)u_x (s,x)dx + q\delta \int_{-\infty}^{\infty} u_x (0,x)u_x (0,x)dx
\]
\[
- \int_{-\infty}^{\infty} u_t (s,x)(Ru_t (s,x))dx + \frac{q}{2} \int_{0}^{\infty} \frac{1}{a} (u_x^2 (s,x)dxdt
\]
\[
+ \int_{0}^{\infty} \int_{-\infty}^{\infty} u_t^2 (s,x)dxdt + q \int_{0}^{\infty} \int_{-\infty}^{\infty} u_t^2 (s,x)dxdt .
\]

We claim that each term on the right-hand side of (5.10) is either controllably small, as long as (4.8) is satisfied with sufficiently small \( u \), or it can be majorized by the sum of a controllably small quantity and a quantity dominated by the left-hand side of (5.10). Thus, for example, the \( L^2(\mathbb{R}) \) norm of \( u_t (0,x) \) is controllably small in view of (4.14). Also
\[
\int_{-\infty}^{\infty} u_t (s,x)u_t (s,x)dx \leq \frac{1}{q} \int_{-\infty}^{\infty} u_t^2 (s,x)dx + \frac{q}{4} \int_{-\infty}^{\infty} u_t^2 (s,x)dx
\]
\[
\int_{-\infty}^{\infty} u_t (s,x)(R(u_t (s,x)))dx \leq \int_{0}^{\infty} R^2 (s,x)(s,x)\int_{0}^{\infty} u_t^2 (s,x)dx + \int_{0}^{\infty} u_t^2 (s,x)dx
\]
\[
\leq \frac{1}{\gamma} \sup_{R(t)} |R(t)| \int_{0}^{\infty} |R(t)|dt + \frac{1}{\gamma} \int_{0}^{\infty} u_t^2 (s,x)dx + \frac{1}{\gamma} \int_{0}^{\infty} u_t^2 (s,x)dx
\]
\[
q \int_{0}^{\infty} \int_{-\infty}^{\infty} \frac{1}{2} (u_x^2 (s,x)dxdt \leq \max_{\alpha \in [-c_0, c_0]} \int_{0}^{\infty} u_x^2 (s,x)dxdt .
\]
After the above estimations (5.10) yields that \( \int_0^s \int_0^s \int_0^t \nu_t \, \mathrm{d}x \, \mathrm{d}t \leq \frac{1}{4} \max \int_0^s \int_0^s \nu_t^2(t,x) \, \mathrm{d}x \),

\[ \int_0^s \int_0^s \int_0^t \nu_t^2(t,x) \, \mathrm{d}x + \left( \int_0^T \nu_t^2(t,x) \, \mathrm{d}t \right)^2, \]

\( q \int_0^s \int_0^s \int_0^t \nu_t \, \mathrm{d}x \, \mathrm{d}t \leq \frac{q^2}{2} \int_0^s \int_0^s \nu_t^2 \, \mathrm{d}x \, \mathrm{d}t + \frac{1}{4} \int_0^s \int_0^s \nu_t^2 \, \mathrm{d}x \, \mathrm{d}t. \)

After the above estimations (5.10) yields that \( \int_0^s \int_0^s \int_0^t \nu_t (s,x) \, \mathrm{d}x \, \mathrm{d}t \leq \frac{q^2}{2} \int_0^s \int_0^s \nu_t^2 \, \mathrm{d}x \, \mathrm{d}t + \frac{1}{4} \int_0^s \int_0^s \nu_t^2 \, \mathrm{d}x \, \mathrm{d}t. \)

\( \sigma'(u(x,t))u_x (x,t) = u_{ttt}(t,x) + k(t)u_1(x) + (k* u_{tt})(t,x) - \Theta(t,x), \)

we deduce that also \( \int_0^s \int_0^s \nu_t (s,x) \, \mathrm{d}x \, \mathrm{d}t \) and \( \int_0^s \int_0^s \nu_t \, \mathrm{d}x \, \mathrm{d}t \) are controllably small, uniformly on \([0,T], \) of course always as long as (4.8) is satisfied for a sufficiently small \( u \) (from (5.13), \( u \) \( \max \left| \sigma''(\cdot) \right| \leq (1 - qB)p_0 \)). Using (4.19) which we rewrite, after an integration by parts, in the form

\[ \sigma'(u(x,t))u_{xx}(x,t) = u_{ttt}(t,x) + k(t)u_1(x) + (k* u_{tt})(t,x) - \Theta(t,x), \]

we deduce that also \( \int_0^s \int_0^s \nu_t (s,x) \, \mathrm{d}x \, \mathrm{d}t \) and \( \int_0^s \int_0^s \nu_t \, \mathrm{d}x \, \mathrm{d}t \) are controllably small, uniformly on \([0,T]. \)

To get the next estimate we assume temporarily that condition (3.20) holds, so that \( u(t,x) \) is smoother, we take the second derivative of (2.9) with respect to \( t \) and \( x \) and then multiply the resulting equation first by \( u_{xxx}(t,x) \) and then by \( u_{xx}(t,x) \). We integrate over \( [0,s] \times \mathbb{R}, \) \( 0 \leq s \leq T, \) and after a long computation we arrive at the following two equations:

\[ \frac{1}{2} \int_0^s \int_0^s \nu_t^2(t,x) \, \mathrm{d}x \, \mathrm{d}t + \frac{1}{2} \int_0^s \int_0^s \nu_x^2(t,x) \, \mathrm{d}x \, \mathrm{d}t + \int_0^s \int_0^s \nu_{ttt}(t,x) \, \mathrm{d}x \, \mathrm{d}t, \]

\[ - \frac{1}{2} \int_0^s \int_0^s \nu_x^2(t,x) \, \mathrm{d}x \, \mathrm{d}t = \frac{1}{2} \int_0^s \int_0^s \nu_{tt}(0,x) \, \mathrm{d}x \, \mathrm{d}t + \frac{1}{2} \int_0^s \int_0^s \nu_x^2(0,x) \, \mathrm{d}x \, \mathrm{d}t \]

\[ - \frac{1}{2} \int_0^s \int_0^s \nu_x^2(t,x) \, \mathrm{d}x \, \mathrm{d}t = \frac{1}{2} \int_0^s \int_0^s \nu_x^2(0,x) \, \mathrm{d}x \, \mathrm{d}t + \frac{1}{2} \int_0^s \int_0^s \nu_x^2(0,x) \, \mathrm{d}x \, \mathrm{d}t \]

\[ + \int_0^s \int_0^s \nu_x^2(t,x) \, \mathrm{d}x \, \mathrm{d}t + \int_0^s \int_0^s \nu_x^2(t,x) \, \mathrm{d}x \, \mathrm{d}t. \]
\[-\int_0^s \int_0^t \sigma''(u_x)u_{tx}u_{txx}u_{xxx} \, dx \, dt - \int_0^s \int_0^t \sigma'''(u_x)u_{txx}u_{txx} \, dx \, dt\]

\[+ \beta \int_0^s \int_0^t \sigma''(u_x)u_{tx}u_{txx}u_{txx} \, dx \, dt + \int_0^s \int_0^t \gamma u_{txx} \, dx \, dt,\]

\[\text{(5.18)} \quad \frac{\delta}{2\alpha} \int_0^s u_x^2(s,x) \, dx + \frac{\theta}{2} \int_0^s \sigma'(u_x(s,x))u_{xx}^2(s,x) \, dx - \frac{\delta}{2} \int_0^s u_{txx} \, dx \, dt\]

\[-\int_0^s \int_0^t u_{tx}^2 \, dx \, dt + \int_0^s \int_0^t \sigma''(u_x)u_{xx}^2 \, dx \, dt = \frac{\delta}{2\alpha} \int_0^s u_x^2(0,x) \, dx\]

\[+ \frac{\delta}{2} \int_0^s \sigma'(u_x(0,x))u_{xx}^2(0,x) \, dx - \int_0^s u_{tx}(s,x)u_{txx}(s,x) \, dx + \int_0^s u_{tx}(0,x)u_{txx}(0,x) \, dx\]

\[-\int_0^s u_{txx}(s,x)(R \ast u_{txx})(s,x) \, dx - \int_0^s \int_0^t u_{txx} \, dx \, dt\]

Multiplying (5.17) by \(q\) then adding it to (5.18) and using (2.11), we obtain

\[\text{(5.19)} \quad \frac{\delta}{2\alpha} \int_0^s u_x^2(s,x) \, dx + \frac{\theta}{2} \int_0^s \sigma'(u_x(s,x))u_{xx}^2(s,x) \, dx + \frac{\theta}{2} \int_0^s u_{txx} \, dx \, dt\]

\[+ \frac{\delta}{2} \int_0^s \sigma'(u_x(s,x))u_{xx}^2(s,x) \, dx + \gamma \int_0^s \int_0^t u_{txx}^2 \, dx \, dt\]

\[+ (1 - q\delta) \frac{\theta}{2} \int_0^s \sigma'(u_x(s,x))u_{xx}^2 \, dx + \frac{\theta}{2} \int_0^s \sigma'(u_x(0,x))u_{xx}^2(0,x) \, dx\]

\[+ \frac{\theta}{2} \int_0^s u_{txx}(0,x) \, dx + \frac{\theta}{2} \int_0^s \sigma'(u_x(0,x))u_{xx}^2(0,x) \, dx - \int_0^s u_{tx}(s,x)u_{txx}(s,x) \, dx\]

\[+ \frac{\theta}{2} \int_0^s u_{tx}(s,x)u_{txx}(s,x) \, dx - \int_0^s u_{tx}(0,x)u_{txx}(0,x) \, dx - \int_0^s \int_0^t u_{txx} \, dx \, dt\]

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\[ + q \int_0^S \int_0^{\frac{1}{2} \sigma'(u_x)} u_x^2 \, dx \, dt + q \int_0^S \sigma''(u_x) u_x^2 u_{xx} t \, dx \, dt \]

\[ - q \int_0^S \int_0^{\sigma''(u_x) u_x u_{xx} u_{xxx}} \, dx \, dt - q \int_0^S \sigma''(u_x) u_x^2 u_{xxx} t \, dx \, dt \]

\[ + 8q \int_0^S \sigma''(u_x) u_x u_{xx} u_{xxx} \, dx \, dt - \int_0^S \sigma''(u_x) u_x u_{xx} u_{xxx} \, dx \, dt \]

\[ + \frac{8}{2} \int_0^S \sigma''(u_x) u_x^2 \, dx \, dt + \int_0^S u_{xx} u_{xxx} \, dx \, dt + q \int_0^S \psi u_{xxx} \, dx \, dt . \]

As long as (4.8) is satisfied with \( u \) sufficiently small, each term on the right-hand side of (5.19) is either controllably small or it can be estimated by the sum of a controllably small quantity and a quantity dominated by the left-hand side of (5.19).

To show that the \( L^2(R) \) norm of \( u_{ttx}(0,t) \) is controllably small, we use (4.24). To estimate \( u_{xxx} \), we express it, with the help of (4.26), in terms of derivatives on which we already have information. The remaining steps of the estimation follow the by now familiar pattern. For example,

\[ (5.20) \quad - \int u_{tx}(s,x)u_{ttx}(s,x) \, dx < \frac{1}{q} \int u_{tx}(s,x) \, dx + \frac{1}{4} \int u_{ttx}(s,x) \, dx , \]

\[ (5.21) \quad - \int u_{tx}(s,x) (R u_{tttx})(s,x) \, dx \]

\[ < \frac{1}{q} \sup |R(t)| \int |R(t)| \, dt \int u_{tx}^2(s,x) \, dx + \frac{1}{4} \int u_{ttx}^2 \, dx , \]

\[ (5.22) \quad q \int \int \sigma''(u_x) u_x u_{xx} u_{xxx} \, dx \, dt \leq \frac{u^2}{2} \max_{[-c_0,-c_0]} \sigma''(\cdot) \int \int u_{txx}^2 + u_{ttx}^2 \, dx \, dt , \]

\[ (5.23) \quad q \int \int \psi u_{ttx} \, dx \, dt \leq \frac{u^2}{10} \int \int \psi^2 \, dx \, dt + \frac{1}{4} \int \int u_{ttx}^2 \, dx \, dt . \]

Thus, (5.19) yields that, as long as (4.8) is satisfied with \( u \), \( \int u_{ttx}^2(s,x) \, dx \), \( \int u_{txx}^2(s,x) \, dx \), and \( \int u_{ttx}^2 \, dx \) are controllably small, uniformly

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on \([0, T]\). We now discard, with the help of a density argument, the extraneous hypothesis (3.20). Using again (4.26) we conclude that \(\int_0^T \int_{\mathbb{R}^3} u_{xxx}^2 \, dx \, dt\) are controllably small, uniformly on \([0, T]\). Finally, using (4.25), after rewriting it in the form

\[
(5.24) \quad u_{ttt}(t, x) = \sigma'(u_t(t, x))u_{txx}(t, x) + \sigma''(u_x(t, x))u_{tx}(t, x)u_{xx}(t, x)
\]

we deduce that \(\int_0^T u_{ttt}^2(s, x) \, ds \, dx\) and \(\int_0^T u_{ttt}^2 \, ds \, dt\) are also controllably small, uniformly on \([0, T]\).

Combining the above information, we select initial data and forcing term so small that, as long as (4.8) is satisfied,

\[
(5.25) \quad \int_0^T \int_{\mathbb{R}^3} \left[ u_t^2(s, x) + u_x^2(s, x) + u_{xx}^2(s, x) + u_{xxx}^2(s, x) + u_{txx}^2(s, x) + u_{tx}^2(s, x) + u_{tx}^2 \right] \, dx \, dt \leq \epsilon^2,
\]

\(0 \leq \epsilon \leq T\). Since, in return, (5.25) implies (4.8), we conclude with the help of Theorem 3.1 that the maximal interval of existence of \(u(t, x)\) is \([0, \omega]\) and that (5.25) is satisfied for \(s \in [0, \omega]\). In particular, (5.1), (5.2) hold. Assertion (5.3) follows from (5.1), (5.2) and (5.4) is a corollary of (5.1) and (5.3). The proof is complete.

Remark 5.1. If \(a(t) = \frac{1}{2} \left(1 + e^{-t}\right)\), (VE) is easily shown to be equivalent to the Cauchy problem

\[
\begin{align*}
&u_{ttt} + u_{tt} = \sigma(u_t) + \frac{1}{2} \sigma(u_x) + g + g_t, \\
&u(0, x) = u_0(x), \quad u_t(0, x) = u_1(x), \quad u_{tt}(0, x) = \sigma(u_0(x)),
\end{align*}
\]

that was studied by J. Greenberg [3]. We note that our Theorem 5.1 applies to this problem.
6. Boundary Value Problems. In this section we make a few remarks on initial-boundary value problems for the heat flow and the viscoelasticity equations. We assume that the configuration of the body is the interval $[0,1]$ and we impose homogeneous boundary conditions of the Neumann type. For the heat flow equation these boundary conditions mean that the boundary is thermally insulated, while for the viscoelasticity equation they mean that the end points are free. In the place of (HF) and (VE) we now have

\begin{align*}
\text{(HF)}^* & \quad \begin{cases} 
  u_t(t,x) = \int_0^t a(t-\tau) \sigma(u(x,\tau)) \, d\tau + f(t,x), & 0 < t < \infty, \ 0 < x < 1, \\
  u(0,x) = u_0(x), & 0 \leq x \leq 1, \\
  u_x(t,0) = u_x(t,1) = 0, & 0 < t < \infty,
\end{cases} \\
\text{(VE)}^* & \quad \begin{cases} 
  u_{tt}(t,x) = \sigma(u_x(t,x)) + \int_0^t a'(t-\tau) \sigma(u_x(\tau,x)) \, d\tau + g(t,x), & 0 < t < \infty, \ 0 < x < 1, \\
  u(0,x) = u_0(x), \ u_x(0,x) = u_1(x), & 0 \leq x \leq 1, \\
  u_x(t,0) = u_x(t,1) = 0, & 0 < t < \infty.
\end{cases}
\end{align*}

The proper replacements of assumptions (f), (g), (u_0) and (u_1) are

\begin{align*}
(f)^* & \quad f, f_t, f_x, f_{tt}, f_{tx}, f_{xx}, f_{ttt}, f_{txx} \in L^2([0,\infty); L^2(0,1)), \\
(g)^* & \quad g, g_t \in L^1([0,\infty); L^2(0,1)), g_x, g_{tt}, g_{tx} \in L^2([0,\infty); L^2(0,1)), \\
(u_0)^* & \quad \begin{cases} 
  u_{0x}^x, u_{0xxx}^x, u_{0xxx} \in L^2(0,1) \\
  u_{0x}(0) = u_{0x}(1) = 0
\end{cases} \\
(u_1)^* & \quad \begin{cases} 
  u_{1x}^x, u_{1xxx} \in L^2(0,1) \\
  u_{1x}(0) = u_{1x}(1) = 0
\end{cases}
\end{align*}

For problems (HF)^* and (VE)^* propositions analogous to Theorems 4.1 and 5.1 hold, namely,

**Theorem 6.1.** Let $(\alpha), (\alpha'), (f)^*$ and $(u_0)^*$ be satisfied. If the $L^2([0,\infty); L^2(0,1))$ norms of $f, f_t, f_x, f_{tt}, f_{tx}, f_{xx}, f_{ttt}, f_{txx}$ and the $L^2(\mathbb{R})$ norms of $u_{0x}, u_{0xx}, u_{0xxx}$ are sufficiently small, then there is a unique global solution.
Theorem 6.2. Let \( (a), (a_j), (g), (u_0) \) and \( (u_j) \) be satisfied. If the \( L^1(0,\infty); L^2(\mathbb{R}) \) norms of \( g, q, q_t, q_{tx}, q_{xxx} \) and the \( L^2(\mathbb{R}) \) norms of \( u, u_t, u_{xx}, u_{xxx} \) are sufficiently small, then there is a unique global solution \( u(t, x) \in C^2((0,\infty) \times [0,1]) \) of (HE) and
\[
\begin{align*}
&u(t,x) \in C^2((0,\infty) \times [0,1]) \quad \text{of } \text{(HE)} \quad \text{and} \\
&\frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left( \frac{\partial}{\partial x} \right) u, \quad 0 < t < \infty, \quad \text{unif. on } (0,1).
\end{align*}
\]

The proofs of Theorems 6.1 and 6.2 are identical to the proofs of Theorems 4.1 and 5.1, respectively. Indeed, virtually all equations of Sections 3-5 are valid also for the Neumann boundary value problem, provided that integration with respect to \( x \) over \( (-\infty, \infty) \) be replaced by integration over \( (0,1) \). In particular the crucial estimates (3.6)-(3.10), (4.9), (4.12), (4.13), (4.21), (4.22), (5.5), (5.8), (5.9), (5.17), (5.18) are valid. The reason is that the assumed Neumann boundary conditions annihilate the boundary contribution when, in the derivation of the estimates, we integrate by parts with respect to \( x \).

The same observation holds if we replace the Neumann by Dirichlet boundary conditions,
\[
\begin{align*}
\frac{\partial u}{\partial x}(t, 0) &= 0, \quad 0 < t < \infty, \\
\frac{\partial u}{\partial x}(t, 1) &= 0, \quad 0 < t < \infty,
\end{align*}
\]
provided we impose on the forcing terms the condition
\[
\begin{align*}
&f(t, 0) = f(t, 1) = 0, \quad 0 < t < \infty, \\
&q(t, 0) = q(t, 1) = 0, \quad 0 < t < \infty.
\end{align*}
\]
so that boundary contributions are again annihilated when, in the derivation of the estimates, we integrate by parts with respect to $x$. We also note that for the Dirichlet boundary-initial value versions of (HF) and (VE) we can also conclude that $u(t,x) \to 0$, uniformly for $x \in [0,1]$, as $t \to \infty$. If one imposes boundary conditions (6.7) but without (6.8) and (6.9) the problem can be solved but the estimates need certain modifications that we shall not discuss here.

Finally, we remark that MacCamy [7], [8] studies the initial-boundary value problems for (HF) and (VE) only for the case of Dirichlet boundary conditions, and that his assumptions on the boundary values of the data, see assumptions $(u_0^1)$, $(f_3)$ of [7] and $(U_2^1)$, $(F_4)$ of [8], are different and more restrictive than ours.
7. Two-Dimensional Heat Flow with Memory. In this section we outline the applicability of the energy method to the initial value problem (compare with (HF)):

\[
\begin{cases}
\frac{\partial u}{\partial t}(t,x_1,x_2) + \int_0^t a(t-\tau)Au(t,x_1,x_2)d\tau = f(t,x_1,x_2) \\
(0 < t < \infty, x = (x_1,x_2) \in \mathbb{R}^2), \\
\frac{\partial u}{\partial t}(0,x_1,x_2) = u_0(x_1,x_2) \\
A u = -\left(\frac{\partial}{\partial x_1} \left[ \psi \left( \frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} \right) u \right] + \frac{\partial}{\partial x_2} \left[ \psi \left( \frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} \right) u \right] \right).
\end{cases}
\]

We assume that the function \( \psi : \mathbb{R}^+ \to \mathbb{R} \) satisfies

\( \psi \in C^4(\mathbb{R}^+) \) and \( \psi(0) > 0 \).

The problem (7.1) represents a mathematical model for heat flow in an unbounded two-dimensional body of material with memory.

Proceeding as in Section 2 we differentiate (7.1) with respect to \( t \), we define the resolvent kernel \( k \) of \( a' \) by equation (k) (we assume for the moment that \( a \) satisfies \( (a_H) \), and that \( f \) is smooth), and we apply the procedure of Section 2 to arrive at the following equivalent form of (7.1) (compare with (1.1))

\[
\begin{cases}
\frac{\partial^2 u}{\partial t^2}(t,x) + \frac{\partial}{\partial t} \int_0^t k(t-\tau)u(\tau,x)d\tau = -Au(t,x) + \phi(t,x), \quad 0 < t < \infty, \quad x \in \mathbb{R}^2 \\
u(0,x) = u_0(x), \quad u_t(0,x) = u_1(x) = f(0,x), \quad x \in \mathbb{R}^2 \\
\phi(t,x) = f_t(t,x) + k(0)f(t,x) + \int_0^t k'(t-\tau)f(\tau,x)d\tau, \quad 0 < t < \infty, \quad x \in \mathbb{R}^2.
\end{cases}
\]

We shall use (7.2) to obtain global results for (7.1) in a manner analogous to the way (1.1) is used in the proof of Theorem 4.1. Since (7.1) and (7.2) have two space dimensions, the energy method requires that we obtain estimates of various partial derivatives of \( u \) up to order four in \( L^\infty(0,\infty) \cap L^2(\mathbb{R}^2) \) and in \( L^2([0,\infty); L^2(\mathbb{R}^2)) \) (rather than up to order three for (HF) in one space dimension). This means that for technical reasons the kernel \( k \) and the function \( \phi \) in (7.2) have to be correspondingly smoother, in order to permit the additional differentiations of (7.2). To be precise we replace assumptions \( (a_H) \) regarding the kernel \( a \) in (7.1) by (compare with Section 2):
One then easily has the following strengthening of Lemma 2.1.

Lemma 7.1. Let the assumptions (aH) be satisfied and let k(t) be the resolvent kernel of a'(t). Then

(i) k(t) ∈ C^3[0,∞); k(t), k'(t), k''(t), k'''(t) are bounded on [0,∞).

(ii) k(t) = k_m + K(t); k_m = \frac{1}{a(0)}, k_m(t) ∈ L^1(0,∞), m = 0,1,2,3.

(iii) The inequality (2.6) holds for some α > 0 and for every v ∈ L^2(0,T).

With the aid of Lemma 7.1 (i), (ii) one readily verifies that if f in (7.1) satisfies the assumptions

(f) \quad f, f_t, f_{x_j}, f_{x_j}^2, f_{x_j}^3, f_{x_j x_j}, f_{x_j x_j x_j}, f_{x_j x_j x_j x_j}, f_{x_j x_j x_j x_j} ∈ L^2([0,∞); L^2(\mathbb{R}))

i,j,ℓ = 1,2,

then the function Φ in (7.2) has the property

(Φ) \quad Φ, Φ_t, Φ_{x_j}, Φ_{x_j}^2, Φ_{x_j}^3, Φ_{x_j x_j}, Φ_{x_j x_j x_j}, Φ_{x_j x_j x_j x_j} ∈ L^2([0,∞); L^2(\mathbb{R})), \quad i,j = 1,2

(compare with (f), (Φ) in Section 1).

Concerning the initial datum u_0 we assume

(\hat{u}_0) \quad u_{0x_j} u_{0x_j x_j} u_{0x_j x_j x_j} u_{0x_j x_j x_j x_j} ∈ L^2(\mathbb{R}^2), \quad i,j,ℓ,m = 1,2.

Our global result for (7.1), analogous to Theorem 4.1 for (HF) is:

Theorem 7.1. Let the assumptions (Ψ), (aH), (f), (\hat{u}_0) be satisfied. If the L^2([0,∞); L^2(\mathbb{R})) norms of f and its partial derivatives in (f) and the L^2(\mathbb{R}^2) norms of the partial derivatives of u_0 in (\hat{u}_0) are sufficiently small, then there is a unique global solution u(t,x) ∈ C^2([0,∞) × \mathbb{R}^2) of (7.1) and

\begin{align}
\begin{cases}
\quad u_t u_{x_j}, u_{tt} u_{x_j}^2, u_{ttt} u_{x_j}^3, u_{tttt} u_{x_j}^4, u_{tx_j} u_{x_j x_j}, u_{tx_j u_{x_j x_j}}, u_{tx_j x_j} u_{x_j x_j}, u_{tx_j x_j x_j} u_{x_j x_j x_j}, u_{tx_j x_j x_j x_j} u_{x_j x_j x_j x_j}, u_{tx_j x_j x_j x_j x_j} u_{x_j x_j x_j x_j x_j} ∈ L^\infty([0,∞); L^2(\mathbb{R}^2)), \quad i,j,ℓ,m = 1,2,
\end{cases}
\end{align}
\[
\begin{align*}
\begin{cases}
\frac{\partial^4 u}{\partial t^4} - \sum_{i,j=1}^2 \frac{\partial^2 u}{\partial t^2 \partial x_i \partial x_j} &= 0, & t \in (0, +\infty), \ x \in \mathbb{R}^2, \\
\frac{\partial u}{\partial t} - \sum_{i=1}^2 \frac{\partial u}{\partial x_i} &= \sum_{i,j=1}^2 \int_{\mathbb{R}^2} \frac{\partial^2 u}{\partial x_i \partial x_j} \ dx_1 \ dx_2 
\end{cases}
\end{align*}
\]
(7.8) \[
\sup_{[0,T] \times \mathbb{R}^2} \left( |u_t(t,x)|, |u_{x_1}(t,x)|, |u_{tt}(t,x)|, |u_{tx_1}(t,x)|, |u_{x_1x_1}(t,x)| \right) \\
\leq M \quad (i,j = 1,2),
\]
(7.9) \[
\begin{align*}
&u_{tt}(t,x) + k(0)u_t(t,x) = \psi \left( \sqrt{v_{x_1}^2 + v_{x_2}^2} \right) [u_{x_1} u_{x_1} + u_{x_2} u_{x_2}] \\
&+ \phi'(t,x) - (k' v_e)(t,x) \quad (0 \leq t < a, x \in \mathbb{R}^2) \\
&u(0,x) = u_0(x), \quad u_t(0,x) = u_1(x) = f(0,x) \quad (x \in \mathbb{R}^2).
\end{align*}
\]

One arrives easily at analogues of Theorems 3.1, 3.2 for the existence, uniqueness, and regularity of the (generally) local solution \( u(t,x) \in C^2([0,T_0) \times \mathbb{R}^2) \) of the Cauchy problem (7.2) on a maximal interval \([0,T_0), T_0 < \infty\), such that for \( T \in [0,T_0) \)

\[
\begin{align*}
&\left\{ u_{tt} x_1, u_{tt} t x_1, u_{tt} t x_1 x_1, u_{tt} t x_1 x_2, u_{tt} t x_1 x_2 x_2, \ldots, u_{ttt t t t} \right\} \\
&\in L^\infty([0,T]; L^2(\mathbb{R}^2)),
\end{align*}
\]
for \( i, j, m = 1,2 \) (compare with 3.2); moreover, if \( T_0 < \infty \), then the integral in (7.7) \(+\) as \( t \rightarrow T_0^-\). We omit the details.

To complete the proof of Theorem 7.1 one proceeds to obtain energy estimates for derivatives of \( u \) as in Section 4 (however, to obtain the \( L^\infty([0,\infty); L^2(\mathbb{R}^2)) \) and the \( L^2([0,\infty); L^2(\mathbb{R}^2)) \) estimates of the fourth derivatives of \( u \) in (7.3), and (7.4), it is now necessary to differentiate (7.2) up to three times, as opposed to up to twice).

Similar to the proof of Theorem 4.1 we have to restrict the range of \( u_{x_1}(t,x) \) and \( u_{x_2}(t,x) \) to the set on which \( A \) is elliptic in order that (7.2) be a well posed problem. We choose a constant \( c_0 > 0 \) such that
We define $W(w) = \int_0^w \xi \phi(l) dl$ and we note that

\begin{equation}
W(w) \geq \frac{1}{2} p_0 w^2, \quad w \in [0,c_0).
\end{equation}

As in Section 4 the aim is to show that there exists a number $u$, $u < c_0$, such that if the local solution $u(t,x)$ of (7.2) satisfies (compare with (4.8))

\begin{equation}
\sup_{[0,T] \times \mathbb{R}^2} \left( |u_{x_1}^i(t,x)|, |u_{tx_1}^i(t,x)|, |u_{x_1 x_1}^i(t,x)| \right) \leq u, \quad (i,j = 1,2),
\end{equation}

then certain functionals of the solution $u$ are controllably small.

To obtain the first set of estimates we multiply (7.2) by $u_{tx}$ and integrate each term over $[0,s] \times \mathbb{R}^2$, $0 < s < T < T_0$. We make use of (2.6) in Lemma 7.1 (iii), an integration by parts (compare with (4.9)), and we obtain

\begin{equation}
\frac{1}{2} \int_0^s \int_{\mathbb{R}^2} u_{t}^2(s,x) dx_1 dx_2 + \int_0^s \int_{\mathbb{R}^2} \left( \frac{u_{x_1}^2(s,x)}{x_1^2} + \frac{u_{x_2}^2(s,x)}{x_2^2} \right) dx_1 dx_2
\end{equation}

\begin{align*}
&+ \int_0^s \int_{\mathbb{R}^2} u_{tx}^2(t,x) dx_1 dx_2 dt + \frac{1}{2} \int_0^s \int_{\mathbb{R}^2} u_{t}^2(0,x) dx_1 dx_2
\end{align*}

\begin{align*}
&+ \int_0^s \int_{\mathbb{R}^2} \left( \frac{u_{x_1}^2(0,x)}{x_1^2} + \frac{u_{x_2}^2(0,x)}{x_2^2} \right) dx_1 dx_2 + \int_0^s \int_{\mathbb{R}^2} \phi(t,x) u_{tx}^2(t,x) dx_1 dx_2 dt.
\end{align*}

By an argument similar to that following (4.9) one obtains that

\begin{align*}
\int_0^s \int_{\mathbb{R}^2} u_{t}^2(s,x) dx_1 dx_2, \int_0^s \int_{\mathbb{R}^2} u_{x_1}^2(s,x) dx_1 dx_2 (i = 1,2), \int_0^s \int_{\mathbb{R}^2} u_{tx}^2(t,x) dx_1 dx_2 dt
\end{align*}

are controllably small, uniformly on $[0,T]$.

We omit the derivation of the remaining, technically involved, energy estimates which follow the pattern of those in Section 4. We only remark that for most of these calculations it is convenient to write $A u$ in the form

\begin{equation}
A u = -\left( \frac{\sqrt{u_{x_1}^2 + u_{x_2}^2}}{u_{x_1} x_1 + u_{x_2} x_2} \right) \left( \frac{u}{\sqrt{u_{x_1}^2 + u_{x_2}^2}} \right) + \frac{\phi}{\sqrt{u_{x_1}^2 + u_{x_2}^2}} \left( u_{x_1} u_{x_1} x_1 + 2 u_{x_1} u_{x_2} x_2 + u_{x_2} u_{x_2} x_2 \right).
\end{equation}
Once we have obtained the $L^2([0, T) ; L^2(\mathbb{R}^2))$ and $L^2([0, T) ; L^2(\mathbb{R}^2))$ estimates of derivatives of $u$ up to order four, we can select initial data and forcing term so "small" that, for as long as (7.13) is satisfied, one has (compare with (4.30))

$$
\int_0^T \int\left( u_{ttt}^2 + u_{tt}^2 + u_t^2 + u_{tt}^2 + \sum_{i=1}^2 \left( u_{xx_i}^2 + u_{tx_i}^2 + u_{txx_i}^2 + u_{txx_i}^2 \right) + \sum_{i,j=1}^2 \left( u_{xx_i}^2 + u_{xx_j}^2 + u_{xx_i}^2 + u_{xx_j}^2 \right) + \sum_{i,j,l=1}^2 \left( u_{xx_i}^2 + u_{xx_j}^2 + u_{xx_l}^2 + u_{xx_l}^2 \right) \right) dx \, dt \leq \nu^2,
$$

and one concludes the proof of Theorem 7.1 exactly as that of Theorem 4.1.
REFERENCES


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INTEGRALDIFFERENTIAL EQUATIONS

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**Abstract:**
We use energy methods to study global existence, boundedness, and
asymptotic behavior as $t \to \infty$, of solutions of the two Cauchy problems (and
related initial-boundary value problems)
20. ABSTRACT (cont'd.)

\begin{equation}
\begin{aligned}
\begin{cases}
\frac{u_t(t,x)}{x} = \int_0^t a(t - \tau) \sigma(u_x(\tau,x)) \, d\tau + f(t,x) & (0 < t < \infty, x \in \mathbb{R}) \\
\quad u(0,x) = u_0(x) & (x \in \mathbb{R}),
\end{cases}
\end{aligned}
\end{equation}

\begin{equation}
\begin{aligned}
\begin{cases}
\frac{u_{tt}(t,x)}{x} = \sigma(u_x(t,x)) + \int_0^t a'(t - \tau) \sigma(u_x(\tau,x)) \, d\tau + g(t,x) & (0 < t < \infty, x \in \mathbb{R}) \\
\quad u(0,x) = u_0(x), u_t(0,x) = u_1(x) & (x \in \mathbb{R}),
\end{cases}
\end{aligned}
\end{equation}

with suitably "small" data \( u_0, u_1, f, g \); \( (HF) \) and \( (VE) \) are mathematical models for nonlinear one-dimensional heat flow in a material with "memory" and nonlinear one-dimensional viscoelastic motion, respectively. Here \( a : [0,\infty) \to \mathbb{R}, \sigma : \mathbb{R} \to \mathbb{R}, f, g : [0,\infty) \times \mathbb{R} \to \mathbb{R}, u_0, u_1 : \mathbb{R} \to \mathbb{R} \) are given, sufficiently smooth functions; the subscripts \( x \) or \( t \) denote partial derivatives. If \( a(0) = 1 \) formal differentiation with respect to \( t \) reduces \( (HF) \) to \( (VE) \) with \( g(t,x) = f_t(t,x) \) and \( u_1(x) = f(0,x) \). But, since \( (HF) \) and \( (VE) \) have different physical origins, the corresponding natural assumptions concerning \( a(\cdot) \) are drastically different and, therefore, the two problems are studied separately.

A previous study of \( (HF) \) and \( (VE) \) rests on the concept of Riemann invariant and is restricted to one space dimension. The energy method is simpler in principle and yields more widely applicable results.