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3 SMALL VEHICLE LAUNCH PLATFORM

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5 STATEMENT OF GOVERNMENT INTEREST

6 The invention described herein may be manufactured and used
7 by or for the Government of the United States of America for
8 governmental purposes without the payment of any royalties
9 thereon or therefor.

10
11 BACKGROUND OF THE INVENTION

12 (1) Field of the Invention

13 The present invention relates to marine vehicles and more
14 particularly to marine vehicle launch systems.

15 (2) Brief Description of the Prior Art

16 Underwater missiles and torpedoes are currently launched
17 from either off the side of a manned ship or from the torpedo
18 tube of a manned submarine. The current method of deploying
19 undersea weapons requires the actual presence of the ship and/or
20 submarine at the deployment site, thereby posing a number of
21 dangers, including (1) exposure of personnel and ships to enemy
22 fire in a danger zone, and (2) detection of ships and submarines
23 in shallow water.

1 Various arrangements are described in the prior art for
2 launching a weapon or other device from an unmanned vehicle.
3 U.S. Patent No. 3,513,750 to Penza, for example, discloses a
4 missile launcher including an elongate buoyant keel structure
5 adapted to float upright in a body of water. The keel is
6 provided with an azimuth and elevation sensing mechanism which
7 controls a series of propulsive devices also placed on the keel
8 and which give the launcher and an attached missile the desired
9 launch elevation and azimuth positioning.

10 U.S. Patent No. 5,076,192 to Tegel et al. discloses an
11 unmanned submarine which is guided to the surface of the water in
12 order to launch an air rocket contained therein and which is
13 provided in its walls with closeable openings for the discharge
14 of the rocket recoil gases into the surrounding water to conduct
15 the impinging recoil gases of a launched air rocket directly out
16 of the submarine. To create a lock for the recoil gas discharge
17 openings which withstands high water pressures and is easily
18 opened in the starting phase of the air rocket, the openings are
19 disposed in the surfaces where the recoil gases impinge on the
20 wall of the submarine, each opening is closed by a cover which is
21 pressed out of the opening by the impinging gases, the seat for
22 the cover in the opening is configured as an inwardly tapered
23 conical surface, and the cover is held in the opening by a

1 transport safety which is released by the action of the pressure
2 of the recoil gases or the cover.

3 U.S. Patent No. 5,542,333 to Hagelberg et al. discloses an
4 undersea vehicle storage and ejection system including a capsule
5 having a cavity therein adapted to store and launch a vehicle.
6 The capsule has an opening at one end for passage of the vehicle
7 therethrough. A closure member is suitably adapted to be
8 mateable with the housing at the opening to seal the cavity. A
9 rocket unit is incorporated within the capsule to remove the
10 closure member at launch. The closure member includes a sealing
11 arrangement for withstanding the hydrostatic pressure when the
12 system is in the undersea environment of use and block the entry
13 of seawater into the cavity. The rocket unit, when ignited,
14 rapidly builds up pressure within the capsule to a level
15 exceeding the external hydrostatic pressure on the cover, thereby
16 removing the cover so that the vehicle may be launched.

17 U.S. Patent No. 5,786,545 to Hillenbrand discloses a vehicle
18 known as an unmanned undersea vehicle (UUV). The UUV includes a
19 weapon compartment and a control means. Within the weapon
20 compartment are a weapon and a buoyancy chamber positioned axi-
21 symmetrically therein. The buoyancy chamber is initially empty
22 and has sufficient capacity so that it can be loaded with
23 seawater whose mass approximates mass of the weapon. The weapon

1 compartment further includes controllable valve means for
2 enabling seawater surrounding the vehicle to fill the buoyancy
3 chamber. The control means controls the deployment of the weapon
4 by expelling the weapon from the weapon compartment and
5 thereafter controls the firing of the weapon. The control means
6 further controls the valves during weapon deployment to enable
7 filling of the buoyancy chamber to maintain a predetermined
8 distribution of mass as the weapon is deployed, which filling-of-
9 the-chamber acts with bilateral symmetry on opposing sides of a
10 vertical reference plane through the vehicle's axis. The mother
11 vehicle generates command information for controlling the control
12 means and receives unmanned undersea vehicle status information
13 from the unmanned undersea vehicle and processes it for use in
14 generating the command information. The communication link
15 interconnects the unmanned undersea vehicle and the mother
16 vehicle to facilitate transfer of command information from the
17 mother vehicle to the unmanned undersea vehicle and to facilitate
18 transfer of unmanned undersea vehicle status information from the
19 unmanned undersea vehicle to the mother vehicle.

21 SUMMARY OF THE INVENTION

22 It is an object of the invention to allow a smaller UUV to
23 be launched or jettisoned from a larger or host UUV.

1 It is a further object to mount the smaller UUV's within the
2 same diameter as the host UUV.

3 Yet another object is allowing the host UUV to launch the
4 smaller UUV's without adversely affecting its buoyancy.

5 Accordingly, the undersea launch platform of the present
6 invention includes a host vehicle, which is preferably, a larger
7 UUV having a generally cylindrical hull. A cradle projection
8 extends from the hull of the host vehicle. A carried vessel,
9 which is preferably a small UUV, is mounted on the forward axial
10 cradle projection.

11 This launch platform would allow the larger UUV, preferably
12 with a tactical diameter of 21 inches, to significantly expand
13 its area of operation by carrying one or more small UUV's. The
14 small UUV's could be launched individually at any time during the
15 larger UUV's mission. The smaller UUV's, when equipped with
16 sensors, i.e., sonar, oceanographic instrumentation, etc., could
17 obtain data in their own region of operation and relay that
18 information, via submerged acoustic communications submerged or
19 surface radio communications, back to the larger UUV or another
20 vehicle. This deployment and operation technique would
21 substantially expand the area of coverage of the larger UUV.

1 section 16 on which there is mounted a stern propeller assembly
2 18. Also adjacent the converging stern section 16 there are
3 stern stabilizing fins 20, 22, 24 and 26. Extending forward from
4 the convex bow 14 there is a forward axial cradle 28, which
5 includes peripheral axial recesses 30, 32, 34 and 36. It will be
6 noted that in this embodiment these axial recesses are
7 peripherally positioned at about 90° from adjacent recesses. In
8 each of these axial recesses there is, respectively, mounted a
9 small UUV 38, 40, 42 and 44. Each of the UUV's as, for example,
10 small UUV 38 includes a cylindrical hull 46, a convex bow 48, a
11 converging stern section 50 and a stern propeller assembly 52.
12 UUV 38 also includes stern stabilizing fins 54, 56, 58 and 60.
13 The control and propulsion features of UUV 38 are conventional as
14 is, for example, disclosed in the aforesaid Hillenbrand patent.
15 It will be also understood that the other small UUV's 40, 42 and
16 44 typically identical to UUV 38.

17 A controller 37 is positioned within hull 12. Controller 37
18 is joined by a control line 39 to release mechanisms 41 joined
19 between cradle 28 and small UUV's 38, 40, 42 and 44.

20 Those skilled in the art will appreciate that release
21 mechanisms 41 can be a spring-loaded release pin with a lanyard
22 pull initiated by an actuator mechanism or an explosive squib
23 which breaks the attachment latching on the small UUV. Whatever

1 release mechanism is used, it is controlled by the host UUV's
2 control computer 37. Each release mechanism 41 joining a small
3 UUV is independent, allowing the small UUV's to be deployed
4 separately.

5 Referring particularly to FIG. 2, it will be seen that small
6 UUV 40 has a cylindrical hull 62 and stern stabilizing fins 64,
7 66, 68 and 70. Fins 58 on small UUV 38 and fins 64 on small UUV
8 40 slightly overlap so fins on its upper side continuously
9 overlap the periphery of the forward axial cradle 28. Small UUV
10 42 has a cylindrical hull 72 and stern stabilizing fins 74, 76,
11 78 and 80. It will also be noted that fin 70 on small UUV 40 and
12 fin 76 on small UUV 42 overlap so as to continuously overlap the
13 axial cradle 28 on one of its axial sides. Small UUV 44 also has
14 a cylindrical hull 82 and stern fins 84, 86, 88 and 90. It will
15 be observed that fin 74 on small UUV 42 and fins 88 on small UUV
16 44 overlap to continuously overlap the forward axial cradle 28 on
17 its lower side, and fin 60 on small UUV 38 and fin 86 on small
18 UUV 44 overlap to continuously overlap the forward axial cradle
19 28 on its other lateral side. It will also be observed that the
20 stern fins 54 and 56 on small UUV 38, fins 66 and 68 on small UUV
21 40, fins 76 and 80 on small UUV 42, and fins 84 and 90 on small
22 UUV 44 extend slightly beyond the periphery of the cylindrical
23 hull 12 of the host vehicle 10. The cylindrical hulls at

1 cylindrical hull 86 of the small UUV's 38, 40, 42 and 44 are,
2 however, confined within the diameter of the cylindrical hull 12
3 of the host vehicle 10 so as to allow torpedo tube and swimout
4 cage capability.

5 It will be appreciated that the launch of the small UUV can
6 be executed with several different techniques. The small UUV can
7 start its own propeller and swim away from the host at a greater
8 velocity than the host. The small UUV can also be jettisoned
9 from the host, either outboard or forward of the host UUV.
10 Jettison methods include actuators or springs, which push the
11 small UUV in the desired direction. After jettison, the small
12 UUV can power away on its own.

13 Another launch technique require deceleration of the host
14 UUV and simultaneously release of the small UUV allowing the
15 small UUV's inertia to carry it forward of the host UUV. The
16 small UUV then powers away.

17 Preferably, the small UUV's is packaged together on the
18 cradle in such a way as to not exceed the standard 21 inch
19 diameter of the host. This allows typical tube launch or cage
20 swimout. If the fins on the small UUV are required to be larger
21 for control purposes and extend beyond the standard 21 inch
22 diameter, they should be pop out fins which extend during the
23 small UUV's launch sequence.

1 Although the embodiment described above carries four small
2 UUV's, it will be understood that, depending on the size of the
3 small UUV's employed, greater or fewer numbers of UUV's can be
4 carried. It will also be understood that the cradle projection
5 does not need to be mounted on the bow, and in alternate
6 embodiments the cradle projection can be mounted anywhere on the
7 cylindrical hull. This option should incorporate the off-board
8 jettison launch technique described above.

9 The invention allows multiple UUV's to be launched
10 individually or together at any time. This operational technique
11 allows the host UUV to significantly expand its operational area.
12 These multiple UUV's can be networked together via acoustic or
13 other communications to effectively generate a UUV with
14 tremendous range and coverage for whatever mission is desired.

15 While the present invention has been described in connection
16 with the preferred embodiments of the various figures, it is to
17 be understood that other similar embodiments may be used or
18 modifications and additions may be made to the described
19 embodiment for performing the same function of the present
20 invention without deviating therefrom. Therefore, the present
21 invention should not be limited to any single embodiment, but
22 rather construed in breadth and scope.

23

1 Attorney Docket No. 79425

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SMALL VEHICLE LAUNCH PLATFORM

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ABSTRACT OF THE DISCLOSURE

6 A launch platform for a host vehicle. There is a cradle
7 having a cylindrical shape with peripheral axial recesses formed
8 therein and arranged around the cradle. A release mechanism is
9 positioned within the cradle. The release mechanism releasably
10 joins small cylindrical undersea vehicles positioned in said
11 peripheral axial recesses.

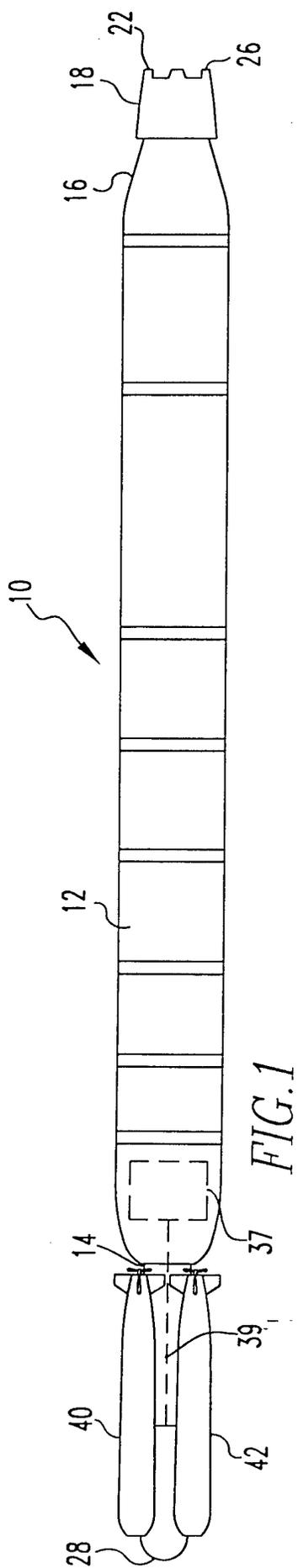


FIG. 1

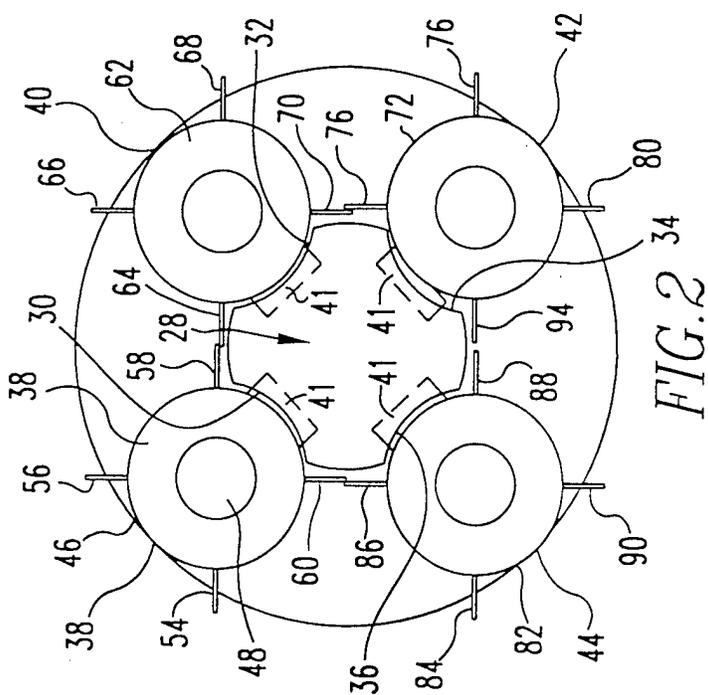
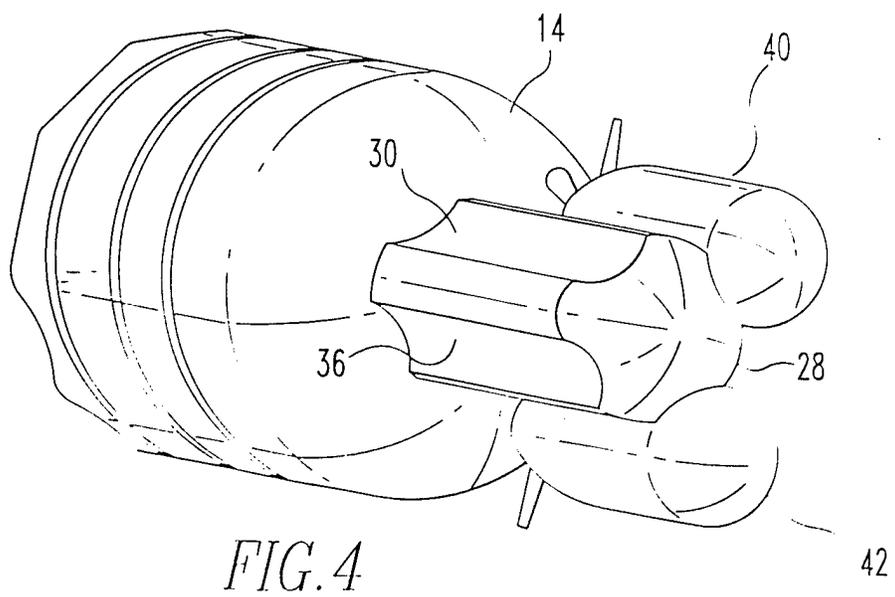
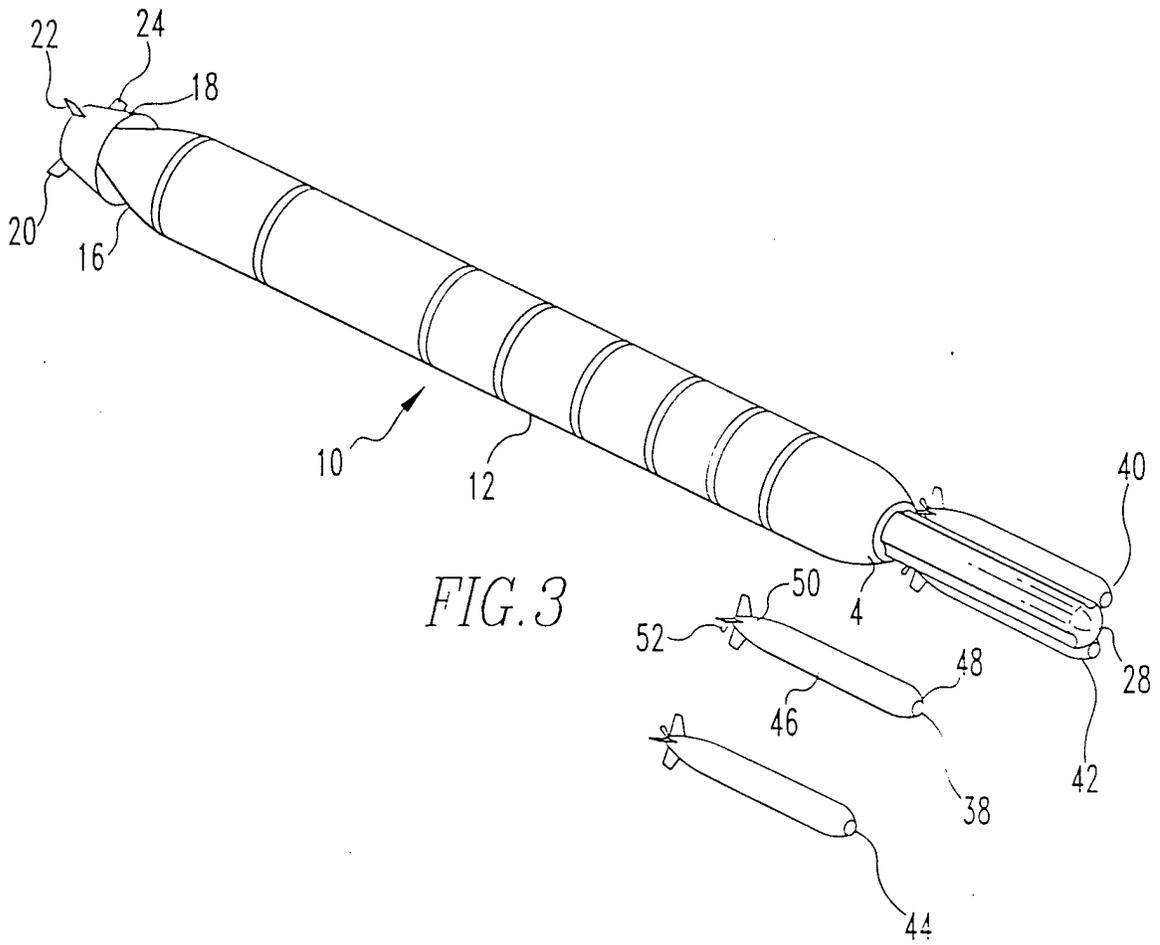


FIG. 2



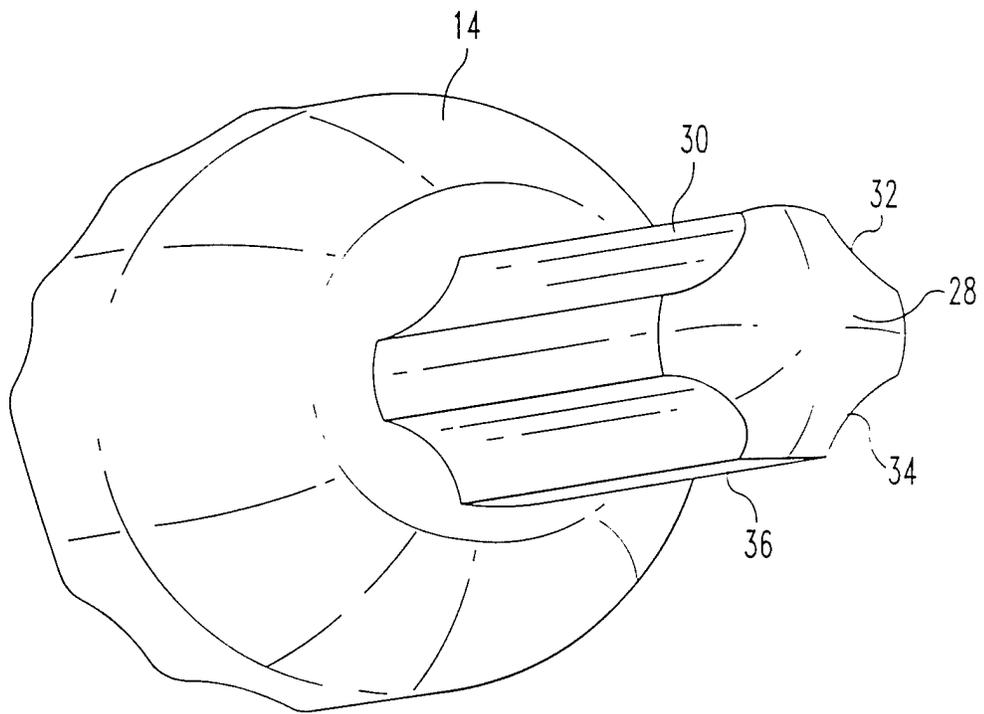


FIG. 5