Coastal Benthic Optical Properties of Coral Environments: ROV/AUV Imaging

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LONG-TERM GOALS

The deconvolution, quantification, and interpretation of the various components of water-leaving radiance in shallow coastal waters with emphasis on coral environments are the long-term goals of the project.

OBJECTIVES

In this project, objectives include the development of instrumentation and models to measure and predict the contribution of bottom reflectance to upwelling radiance in coastal waters. An underlying objective, then, is the development of the methodologies required to remotely classify bottom types in varying water depths. Intrinsic in this effort are the quantification of the optical properties of the water column and the need to perform rigorous data calibration/validation while working toward optical closure and to address the inherent problems of scale between in situ and remotely sensed data.

A collateral objective is to create a world-wide-web repository for data from the CoBOP project to enable investigators to efficiently explore the large and diverse data set.

APPROACH

In the first funding year of the CoBOP project (FY96), transects over coral bottoms in the Dry Tortugas were laid out and mapped by divers and by the Fluorescence Imaging Laser Line Scanner (FILLS). Instrumentation aboard our Remotely Operated Vehicle (ROV) and Autonomous Underwater Vehicle (AUV) platforms were used to determine the color and intensity of bottom elements from different altitudes (Costello et al., 1997). The goal was to correct imagery for path radiance and attenuation, providing bottom albedo estimates for the dominant bottom types/features, to image bottom fluorescence, and to measure the vertical spectral structure of the upwelling and downwelling light fields. The analyses required rigorous validation, calibration, and modeling efforts. Simultaneously, effort was expended toward developing simple, relatively low-cost methods that could exploit gross bottom reflectance signatures to yield useful data.
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In the 1998 funding year, a CoBOP field campaign was conducted from the Caribbean Marine Research Center (CMRC) located on Lee Stocking Island, Exuma Islands, Bahamas. Our responsibilities in the 1998 fieldwork were similar to those of the Dry Tortugas exercises with the addition of extensive atmospheric measurements and the inclusion of sediment, grassbed, and mixed bottom types in addition to coral environments.

In this funding year (FY1999) our approach was similar to our prior work with added effort toward rigorous instrument calibration and toward fruitful collaboration with other investigators.

WORK COMPLETED

Work during this period has consisted of reduction and modeling of CoBOP’98 data, the participation in the CoBOP’99 field campaign, and the construction of a data repository to serve the CoBOP project.

General efforts:
- Significant effort has been expended toward building a JAVA-based, data archive site for the CoBOP project team for interactive data exploration on the world wide web. Sample data sets have been obtained, a searchable heading format has been designed, and a prototype structure has been built which allows limited interactive plotting of geophysical data from a location of interest within the study area (Hou et al., 1998).
- A rigorous check of the geometric collection performance (cosine response) of USF-developed, 512-channel in situ irradiometers and of a LICOR-1800 has been performed (English et. al. 1998).
- A method has been described which utilized color video taken from the OV-II AUV to calculate the percent live sea-bottom cover (Renadette et. al. 1997, 1998; Hou et. al. 1999).
- A method developed to model and utilize downwelling irradiance spectra affected by wave focusing (Costello et. al. 1998a) has been extended to include the upwelling radiance light field and provide for the calculation of reflectance as a function of depth (Costello et. al. 1998b).
- A method to vicariously calibrate aircraft and satellite spectrometers using cloud shadows also corrects for atmospheric effects is applicable to NRL’s Coastal Ocean Imaging Spectrometer and PHILS, and NASA's AVIRIS (Reinersman et al., 1998).
- An analytical model was developed to predict the effect of internally reflected light over shallow, "patchy" bottoms (Costello and Carder, 1999).

CoBOP field efforts
- 700 Hyperspectral (512-channel) downwelling irradiance and upwelling radiance spectra were acquired during 46 vertical profiles performed using the ROSEBUD ROV. These are in addition to the 490 spectra acquired during 25 profiles in 1998.
- CTD, c-488, c-660, FL-685, FL-CDOM, HS-2 and Bb-830 data were acquired during 46 vertical profiles performed using the ROSEBUD ROV launched from the R/V Subchaser. (30 additional profiles in 1998)
- 6-channel, intensified bottom-albedo-video as well as NTSC-color-video bottom imagery were also obtained during each ROV deployment during each year.
- 91 JSD drop-package casts were performed from the R/V Suncoaster. The JSD recorded CTD, ac-9, 0.2 micron-filtered ac-9, 488-nm attenuation, 830 nm backscatter, 6-channel HS-6 backscatter, Flashpak CDOM fluorescence, and chlorophyll fluorescence. (47 additional casts in 1998)
- Sea surface Rrs, filter pad (pigment, detrital, and CDOM) absorption and fluorometric chlorophyll
were obtained at 49 stations. (44 stations in 1998)

- Color video bottom imagery was obtained during mapping transects in both years using the R/V Subchaser stern-mounted bottom camera. The imagery is overlaid with GPS position and time. The Subchaser ship computer simultaneously logs water depth and surface temperature, boat speed and heading, and data from the boat meteorological instrumentation.

- Atmospheric data were obtained (Reagan solar transmissometer, Licor, Micro-tops) daily as well as frequent Rrs measurements in support of the FILLS sensor flying aboard the AN-2 aircraft (C. Davis, NRL Washington).

RESULTS

- Water-Raman scattering and chlorophyll a fluorescence are extremely significant components of the upwelling light field at depths > 2 m and wavelengths > 520 nm over coraline environments and cannot be ignored in evaluating bottom-reflected (actively or passively) radiance.

- Solar-stimulated fluorescence at 685 nm from sediments due to benthic diatoms is ubiquitous on the Florida shelf, off the Florida Keys, and around Lee Stocking Island, Bahamas in sufficient intensity to allow the acquisition of narrow-band fluorescence bottom imagery (intensified video) from depths of 7 m to > 20 m.

- Animals (e.g. sponges) and man-made objects are readily apparent by their dark contrast with the bright, red, bottom fluorescence from benthic diatoms, coral symbionts, and macrophytes.

- Range to various components in an image greatly affects the 685-fluorescence signal since the e-folding depth through water is 2.5 m. Correction for range is critical for image interpretation (see Carder and Costello: N00014-96-1-5013).

- Wave focusing has a very significant spectral impact on the instantaneous downwelling light field on clear days providing red-rich irradiance in focal zones and blue-rich irradiance in divergence zones. Coral and vegetation fluorescence are spectrally and temporally dependent on the incident light field, and fluorescence “spill-over” may occur when photosynthetic reaction centers are full during wave focusing events but perhaps not for steady-state conditions providing the same time-averaged photon quality and quantity. Field measurements of IOPs and AOPs have allowed spectral model closure calculations to simulate the instantaneous spectral light field measurements. Increases in aerosols decrease these fluctuations due to wave focusing, stabilizing the light field (Costello et al., 1998a). In clear, shallow coastal waters, upwelling radiance can be significantly affected by bottom reflection of focused downwelling irradiance (Costello et al., 1998b).

- High-contrast, "patchy" bottoms in shallow waters can produce an increase in downwelling irradiance of up to 20% due to internal reflection of light beyond the critical angle (~48°) from sandy regions (Fig. 1). Furthermore, the increased irradiance changes as a function of depth convolved with the water column depth and the horizontal distance to contrasting "patches" (Costello and Carder, 1999). This large an effect indicates models assuming homogeneity in horizontal lightfields must be applied judiciously.
In our analysis of our hyperspectral light profile data sets, it soon became apparent that wave focusing and Raman scattering introduced significant complexity to models of the submarine light field. Moreover, modeling efforts toward addressing the complexities using Smith and Baker’s (1981) water absorption numbers were generally fruitless. Use of Pope and Fry (1997) numbers, modeled skylight and sunlight fields (Gregg and Carder, 1990) and focus/defocus of the sunlight contribution provided modeled light fields consistent with measurements. Fluorescence and primary production models need to consider the nonlinear aspects of this light field versus traditional time-averaged methods.

Variations in the 685 nm fluorescence yields, suggested by our observations, ranged from high for hard-bodied coral, medium for branching coral, to low for benthic diatoms. These differences suggest possible automatic classification schemes if adequate range information is available. Certainly, non-vegetative bottom features such as animals and man-made objects are sharply discernible when viewed at 685 nm, and path radiance due to backscattering does not reduce image contrast for fluorescence-dominated scenes.

Aircraft and space sensor calibrations change with vibration, temperature, and time. Recalibraton is critical since a small change in calibration can introduce large errors. For example, the atmosphere contributes 90% (or more) of the radiance received at a space-borne sensor. Just a 2% shift in calibration would, then, result in a 20% error in the calculated water-leaving radiance. Reinersman et al. (1998) provide a vicarious method to re-calibrate a sensor that simply depends on finding small, compact clouds in a scene.
Figure 1. Downwelling irradiance over a seagrass bed surrounded by sand, 3 meters total water depth. Contrary to expectations, the light level increases with depth due to the contribution from internally reflected light from adjacent, sandy bottom.

TRANSITIONS

The hyperspectral data acquired during this project has aided other projects (see RELATED PROJECTS section) in efforts toward the development and validation of algorithms for remote sensing of water constituents and bathymetry in coastal waters. Additionally, the Real-time Ocean Bottom Optical Topographer (ROBOT) module, an AUV-borne, laser-line-based, instrument system, first deployed during the CoBOP’98 field campaign, participated in Navy-sponsored underwater mine detection exercises in December, 1998.

RELATED PROJECTS

As part of the CoBOP Directed Research Initiative, this project is synergistic with numerous other CoBOP investigations and several multi-discipline investigations are underway. This project also provides significant data to and benefits from important instrumentation developed under “Optical Variability and Bottom Classification in Turbid Water” (ONR CODE 3220M).
Other collaborative projects:


ONR - A simulation analysis of the time-dependent roles of phytoplankton and CDOM in effecting the 3-dimensional structure of inherent optical properties on the West Florida shelf. PI - J.J.Walsh (USF)


NRL - Hyperspectral Modeling of Harmful Algal Blooms on the West Florida Shelf. PI - W. P. Bissett (Florida Environmental Research Institute)

NASA Project - Hyperspectral characterization of gelbstoff for application to remote sensing of carbon cycling in coastal regions. PIs - P.Coble and C.Castillo (USF)

NASA (EOS) - High spectral resolution MODIS algorithms for ocean chlorophyll in case II waters. PI - K. Carder

NASA (SIMBIOS) - Stray Light and Atmospheric Adjacency Effects for Large-FOV Ocean-Viewing Space Sensor. PI - K. Carder


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**PUBLICATIONS**


World Wide Web site: [http://iceman.marine.usf.edu](http://iceman.marine.usf.edu)