

# ***Methods to Optimize for Energy Efficiency***



**Developed by  
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**Air Vehicles Directorate  
U.S. Air Force Research Laboratory**

***Presented by:  
José Camberos & John Doty***

***Thermodynamics: Can Macro Learn from Nano?  
22- 15 May 2011, Sweden***

Cleared for Public Release: 88ABW-2008-1174

## Report Documentation Page

*Form Approved*  
*OMB No. 0704-0188*

Public reporting burden for the collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing the collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden, to Washington Headquarters Services, Directorate for Information Operations and Reports, 1215 Jefferson Davis Highway, Suite 1204, Arlington VA 22202-4302. Respondents should be aware that notwithstanding any other provision of law, no person shall be subject to a penalty for failing to comply with a collection of information if it does not display a currently valid OMB control number.

1. REPORT DATE <b>MAY 2011</b>	2. REPORT TYPE <b>N/A</b>	3. DATES COVERED <b>-</b>			
4. TITLE AND SUBTITLE <b>Methods to Optimize for Energy Efficiency</b>		5a. CONTRACT NUMBER			
		5b. GRANT NUMBER			
		5c. PROGRAM ELEMENT NUMBER			
6. AUTHOR(S)		5d. PROJECT NUMBER			
		5e. TASK NUMBER			
		5f. WORK UNIT NUMBER			
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) <b>Air Vehicles Directorate U.S. Air Force Research Laboratory</b>		8. PERFORMING ORGANIZATION REPORT NUMBER			
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES)		10. SPONSOR/MONITOR'S ACRONYM(S)			
		11. SPONSOR/MONITOR'S REPORT NUMBER(S)			
12. DISTRIBUTION/AVAILABILITY STATEMENT <b>Approved for public release, distribution unlimited</b>					
13. SUPPLEMENTARY NOTES <b>See also ADA553749. Thermodynamics: Can Macro Learn from Nano? Held in Sjobo, Sweden on May 23-25, 2011. Approved for public release; distribution is unlimited. U.S. Government or Federal Purpose Rights License., The original document contains color images.</b>					
14. ABSTRACT					
15. SUBJECT TERMS					
16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT <b>SAR</b>	18. NUMBER OF PAGES <b>33</b>	19a. NAME OF RESPONSIBLE PERSON
a. REPORT <b>unclassified</b>	b. ABSTRACT <b>unclassified</b>	c. THIS PAGE <b>unclassified</b>			

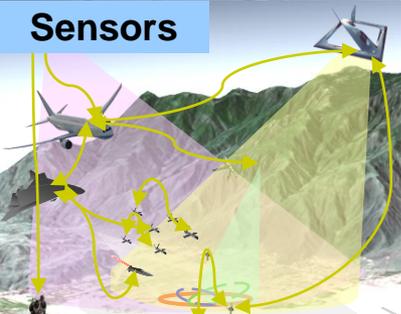
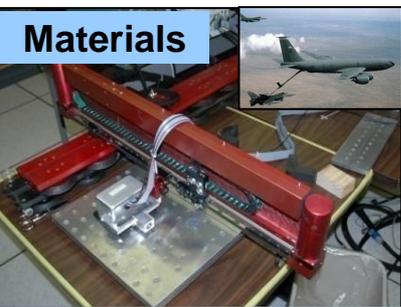
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is the birthplace, home and future of aerospace



- On base organizations; missions ranging from acquisition & logistics management to research & development, education, flight operations and many other defense related activities
- Wright-Patterson Air Force Base (WPAFB) is the home of
  - U. S. Air Force Research Laboratory
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  - ...

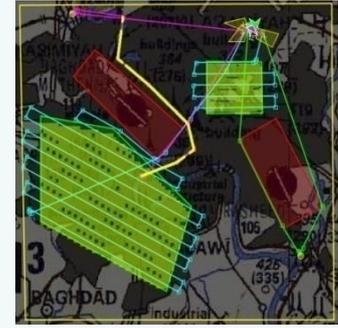
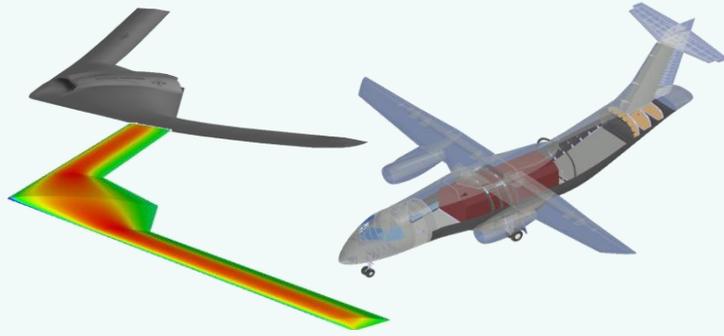
# U. S. Air Force Research Laboratory



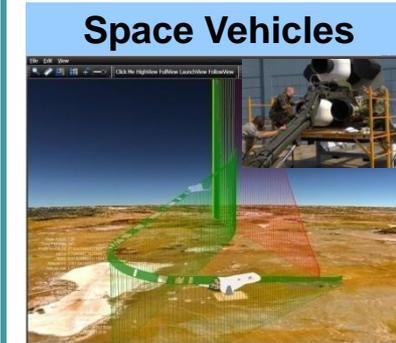
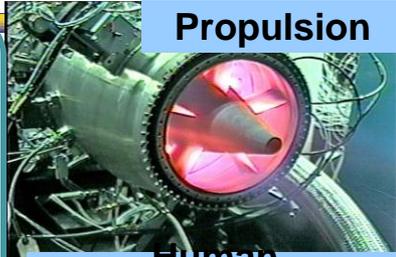
**AERONAUTICAL SCIENCES**

**STRUCTURES**

**CONTROL SCIENCES**



***Air Vehicles Directorate***

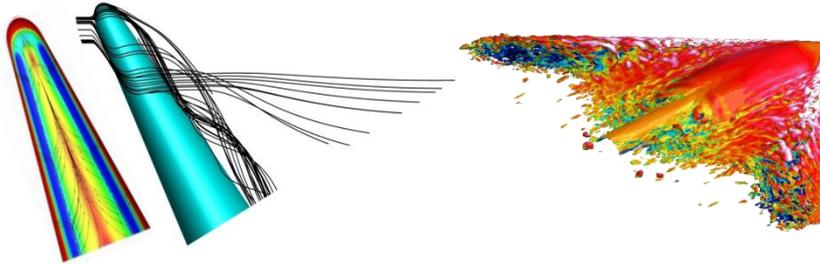


***AFOSR – Basic Research***

# Air Vehicles Directorate

## Core Technical Competencies

### Aeronautical Sciences



Hypersonics

- ★ High Fidelity Computational Simulation
- ★ Advanced Air Vehicle Concepts

### Control Sciences

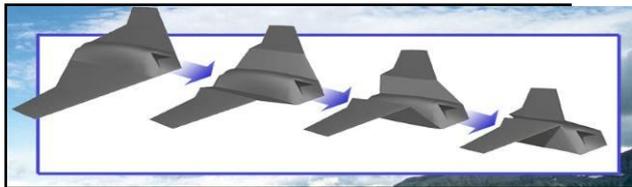
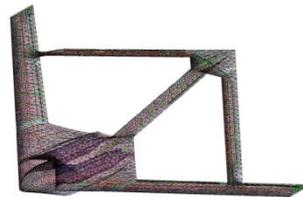
Collision avoidance



UAS range & endurance via aerial refueling

- ★ Cooperative and Adaptive Control
- ★ Autonomous and Advanced Control

### Structures

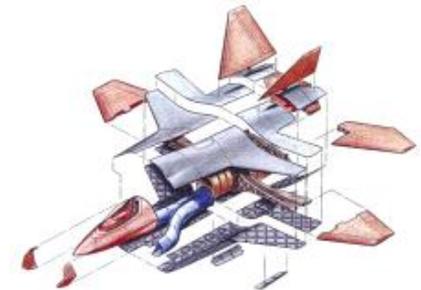


- ★ Advanced Structural Concepts
- ★ Multidisciplinary Structural Design & Analysis

### Integration



Lightweight, Survivable Inlets



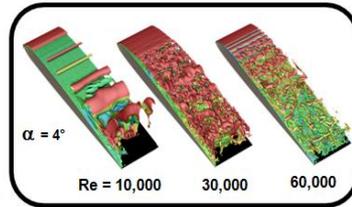
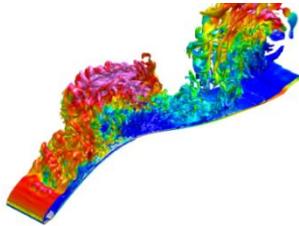
- ★ Modeling and Simulation
- ★ Quantitative Technology Assessment
- ★ Experimental Validation

# Air Vehicles Directorate Research Centers

## Computational Sciences



Micro Air Vehicles



Low-Re Flow

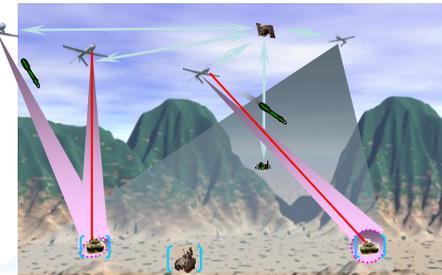
Dr. Jack Benek (ST)  
Director, CS Center

- High Fidelity Computational Simulation

## Control Sciences



Sense And Avoid



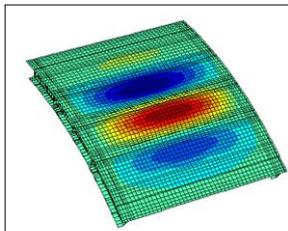
Dr. Siva Banda (ST)  
Director, CS Center

- Cooperative and Adaptive Control

## Structural Sciences

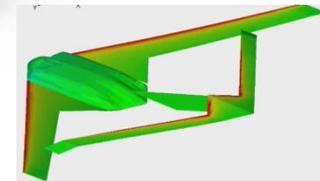
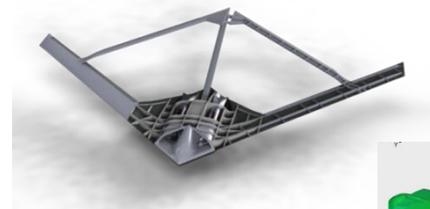


Dr. Ravi Chona (ST)  
Director, SS Center



- Combined Extreme Environments

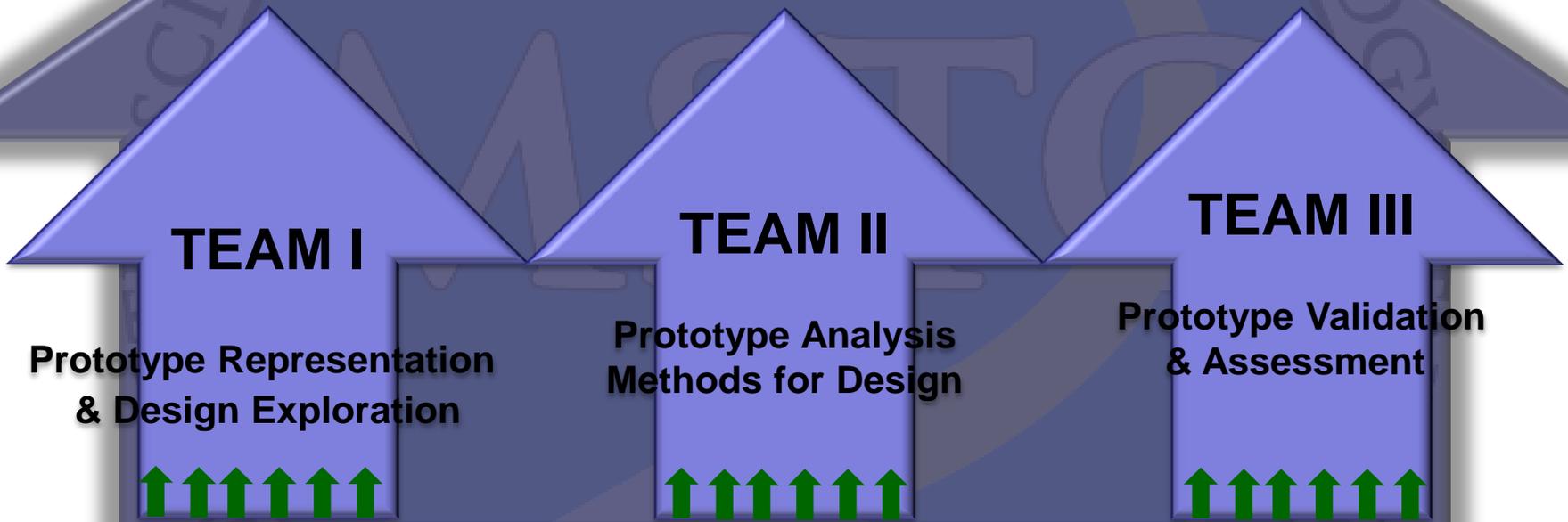
## Multidisciplinary Science & Technology



Dr. Ray Kolonay,  
Acting Director  
MSTC Center

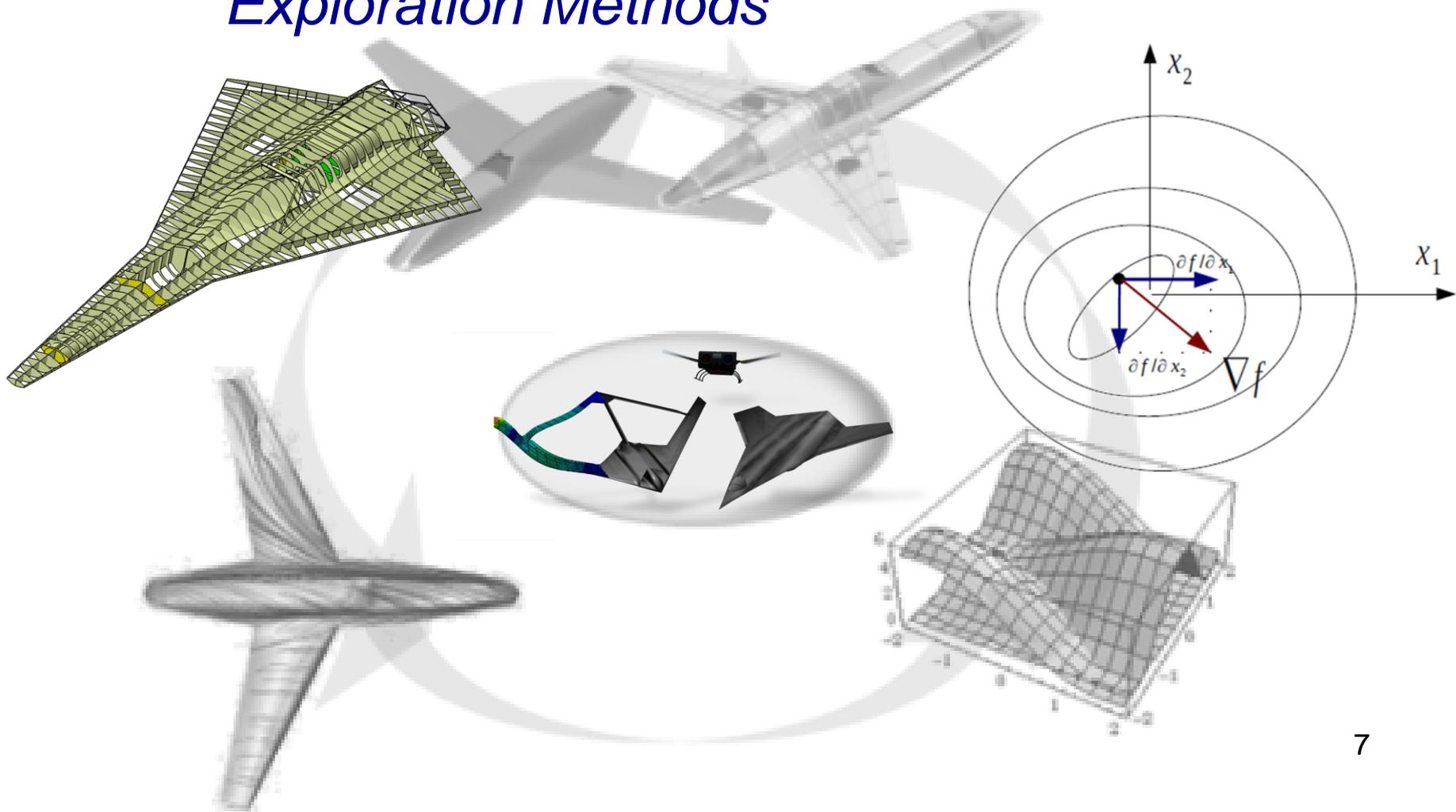
- Multidisciplinary Analysis & Design  
Space Exploration

DISCIPLINARY SCIENCE & TECHNOLOGY



*Shared Activities*  
*Unified Computational Framework (SORCER, MODEL Center)*

## – Prototype Representation & Design Exploration Methods





Feature Presentation

# EXERGY-BASED METHODS

# Energy-Based Design Methods Background

## Historically:

- Energy always an *implicit* consideration, e.g:
  - Breguet Range Equation ~ Energy to overcome Drag
  - Trajectory Optimization → trade Potential & Kinetic Energy

## Problem:

- Energy Considerations are Only Implicit & unrelated.
- Aircraft Subsystems are ‘Optimized’ as Separate Components.
- “Integration” accomplished, but often with incompatible objectives

*Need Common Metrics for Analysis and a Design Framework to  
Apply at All Levels*

# Evolutionary vs. Revolutionary

***“Polishing Old Methods Can Only Give Incremental Improvement, But New Methods Can Open the World”***

## ASSESS CUSTOMER REQUIREMENTS

EVOLUTIONARY SOLUTION

OR

REVOLUTIONARY

PRE-EXISTING DATA

(Physical ~ even with approximations  
Validated with FLIGHT DATA!!)

THEORETICAL MODELS

VALIDATED TOOLS



WHAT TOOLS ??

EXISTING MDO PROCESS



ALLOW FLEXIBILITY

IMPROVE ‘COMPONENTS’  
and/or INNOVATE



INVENTION, with PHYSICS

**INCREMENTAL IMPROVEMENT  
CAN BE VERY GOOD OR ??**

**FIRST TIME CAPABILITY  
IS VERY GOOD**

# Customer and Overhead Work

- Define specific energy as kinetic + potential energies per unit mass:

$$E = h + \frac{1}{2g} U^2$$

- Customer work rate – includes generating specific payload energy & overcoming drag and power requirements:

$$\frac{dw_c}{dt} = W_p \frac{dE_w}{dt} + P_p + D_p U$$

- Overhead work – Sum of work consumed and drag caused by every component of the system:

$$\frac{dw_o}{dt} = \sum \left( W_i \frac{dE}{dt} + P_i + D_i U \right)$$

**Design Problem → Minimize Overhead Work (Loss)**

Develop Thermodynamics Laws into common currency for system optimization, e.g. hypersonic airframe/propulsion integration

Develop energy-minimizing algorithms based on consumption, so every subsystem component is optimized to system-level metrics

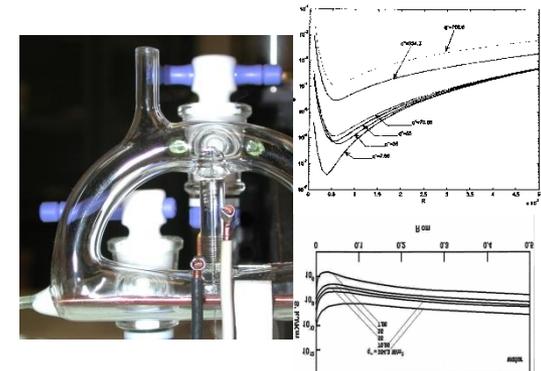
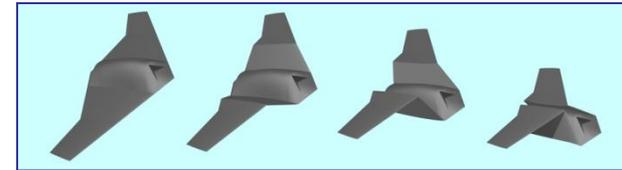
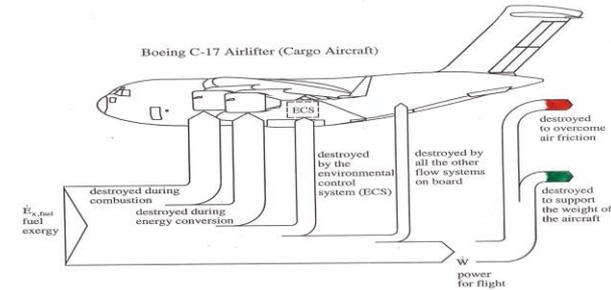
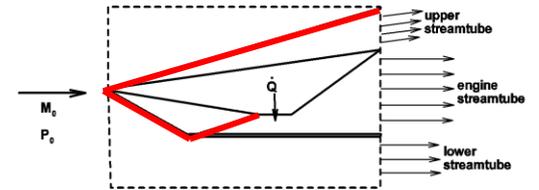
Develop topology and mechanization to enable energy-efficient adaptive structures for fully morphing aircraft concepts

Develop methodologies for entropy generation minimization and optimization of thermal components

Additional tasks:

Understand and develop energy harvesting

High fidelity computation of entropy generation



# Exergy-Based Design Methods:

*Specify all vehicle design requirements as work potential (exergy destruction, entropy production)*

## **Multidisciplinary Design:**

- Decompose system into energy subsystems
- Design all components to optimize system to minimize loss

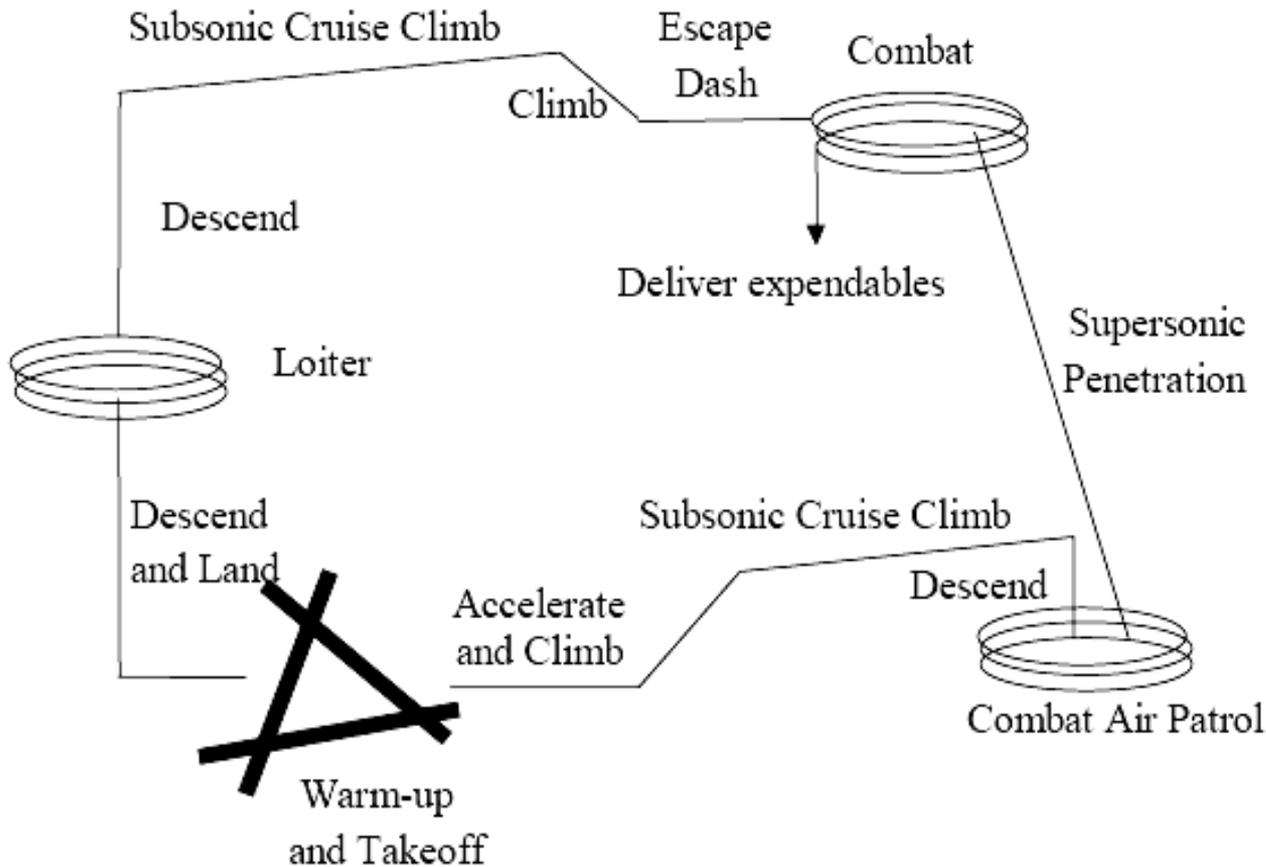


Example

# MISSION LEVEL OPTIMIZATION

# Mission Level Optimization

Mission for an Advanced Aircraft Fighter (AAF):  
PS, ECS, and AFS-A



Mission Segments	
Io.	Name
1	Warm-up
2	Take-off acceleration
3	Take-off rotation
4	Accelerate
5	Climb
6	Subsonic cruise climb 1
7	Combat air patrol
8	Supersonic penetration
9	Combat turn
10	Combat acceleration
11	Escape dash
12	Subsonic cruise climb 2
13	Loiter
14	Descend and Landing

Source: Mattingly et. al., 1987



# Optimal Vehicles Predicted for Four Optimization Metrics



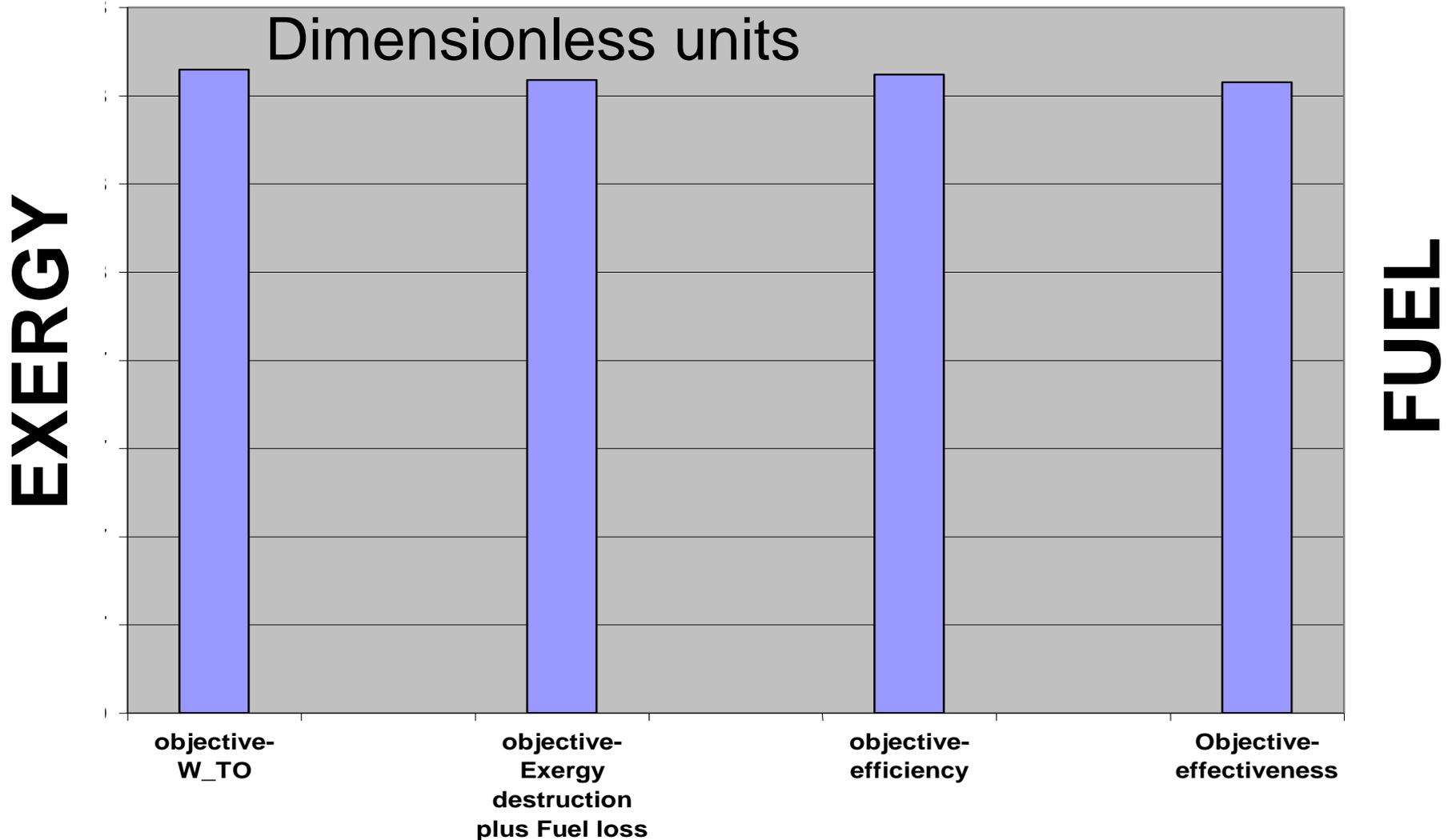
## Traditional:

- Minimize Gross Takeoff Weight

## Exergy Methods:

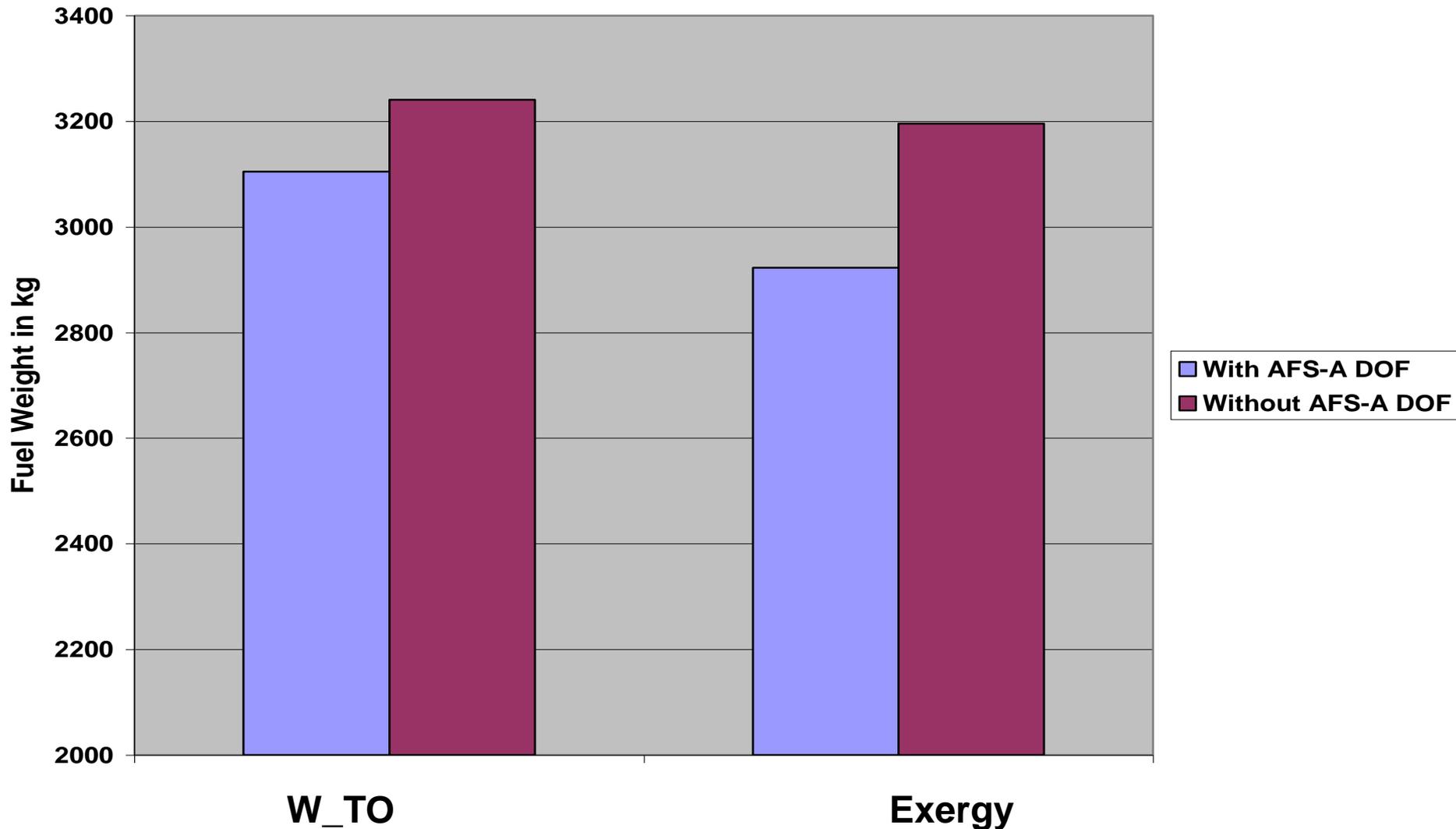
- Maximize Thrust Efficiency = thrust divided by fuel mass flow  $\times$  heating value
- Maximize Thermo Effectiveness = thrust divided by max thrust if no irreversibilities
- Minimize Exergy Destruction

# Optimal Vehicles Predicted for Four Optimization Metrics



***Optimization Metric Makes Little Difference ~~~ SO ????***

# Optimum Vehicles Including Aero Design Variables





Example

# MORPHING WING MISSION ANALYSIS

# Morphing Wing Mission Analysis

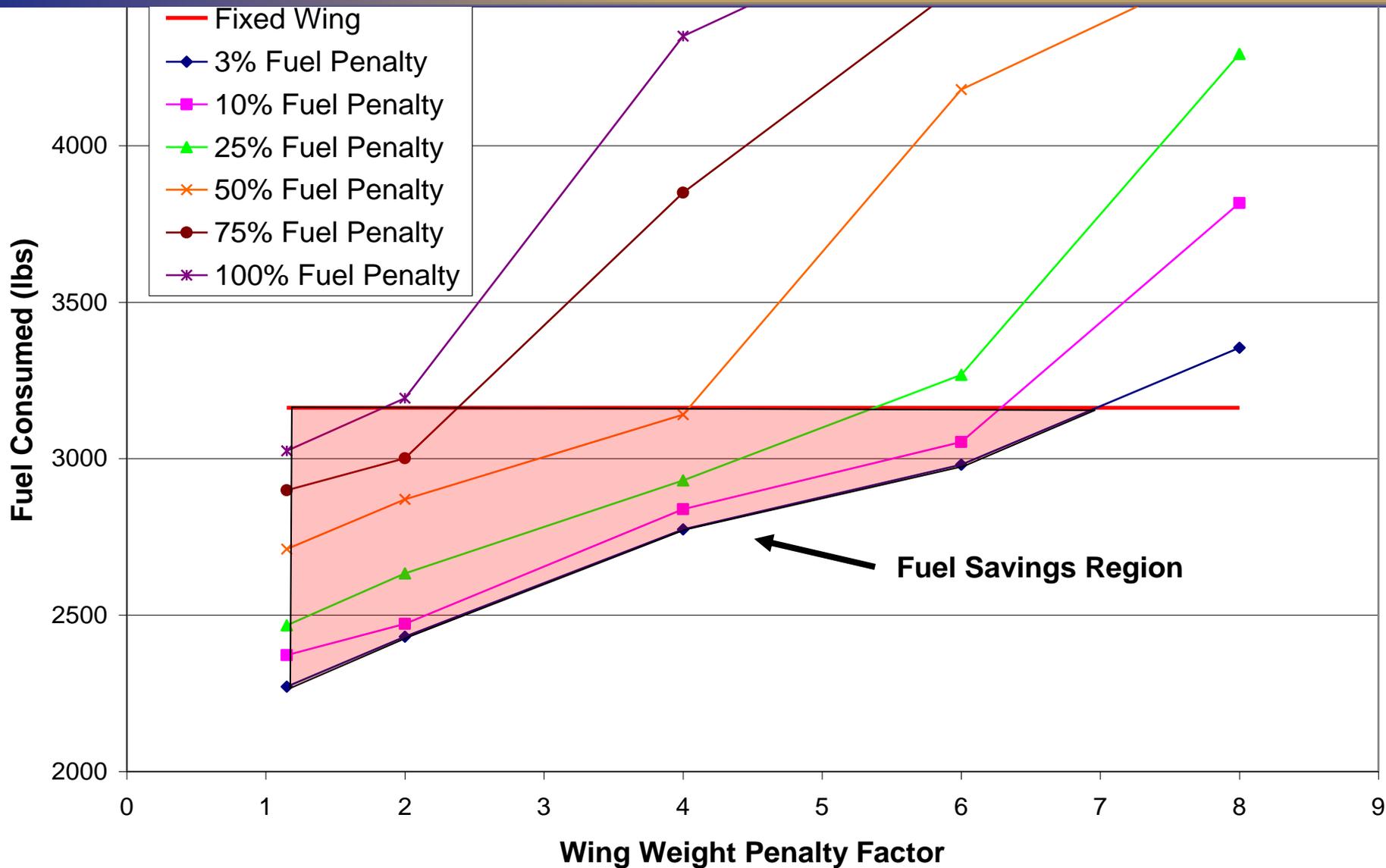
## Wing Optimization Details:

- Wing sweep, wing length, root and tip chord lengths (2D geometries) are morphed, mission optimized by segment
- Wing twist and camber changes (3-D geometries) are not morphed
- 15% weight penalty factor > varied up to 9 x baseline weight
- 3% fuel penalty factor > varied up to double baseline mission fuel

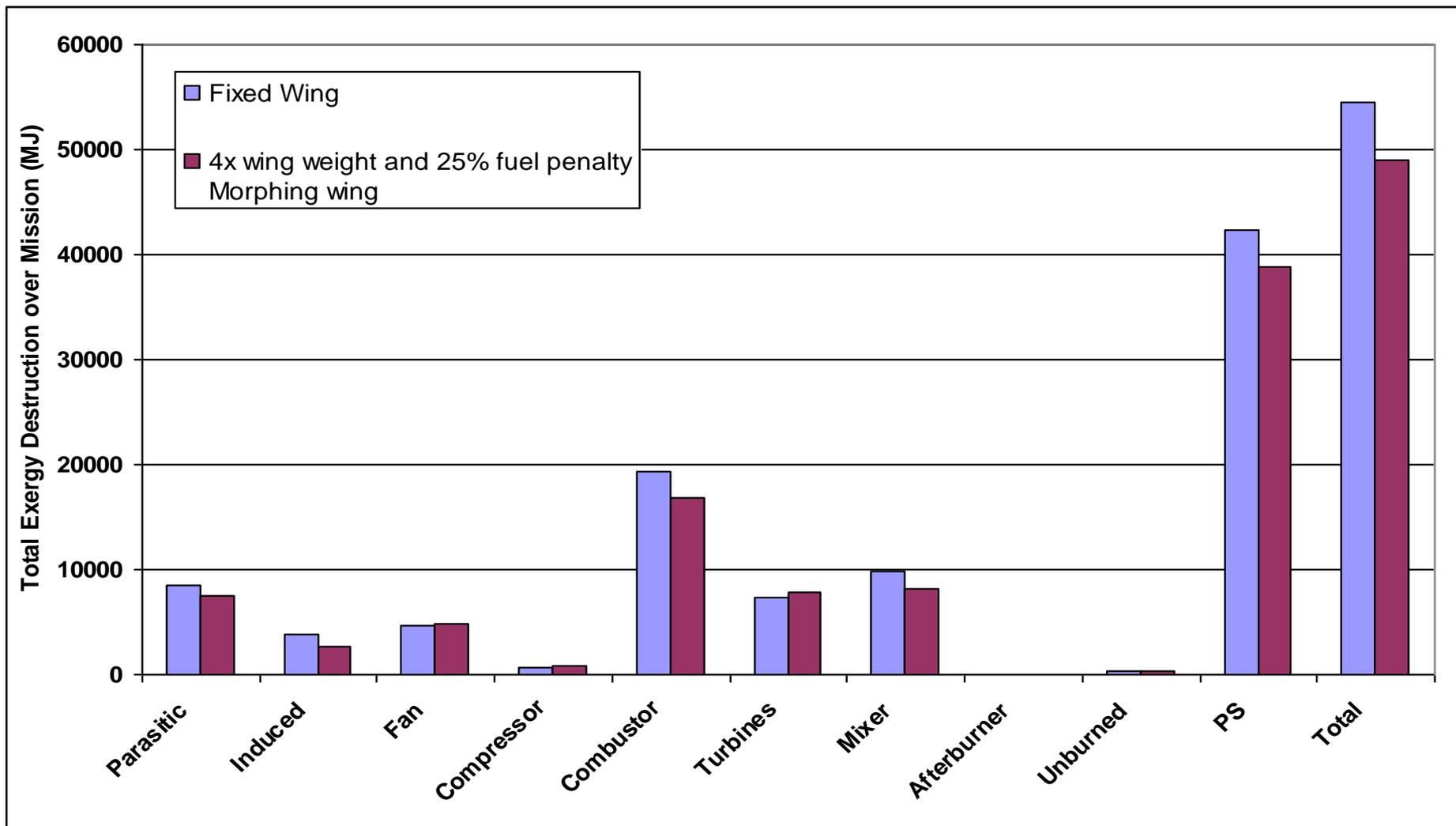
## Model Characteristics

- Turbojet propulsion subsystem (PS)
- Airframe subsystem
- Genetic algorithm (QMOO)
- Investigated mission effects of using morphing wing technology on supersonic fighter aircraft

# Effect of Morphing Wing on Exergy Destruction



# Exergy Destruction Distributions



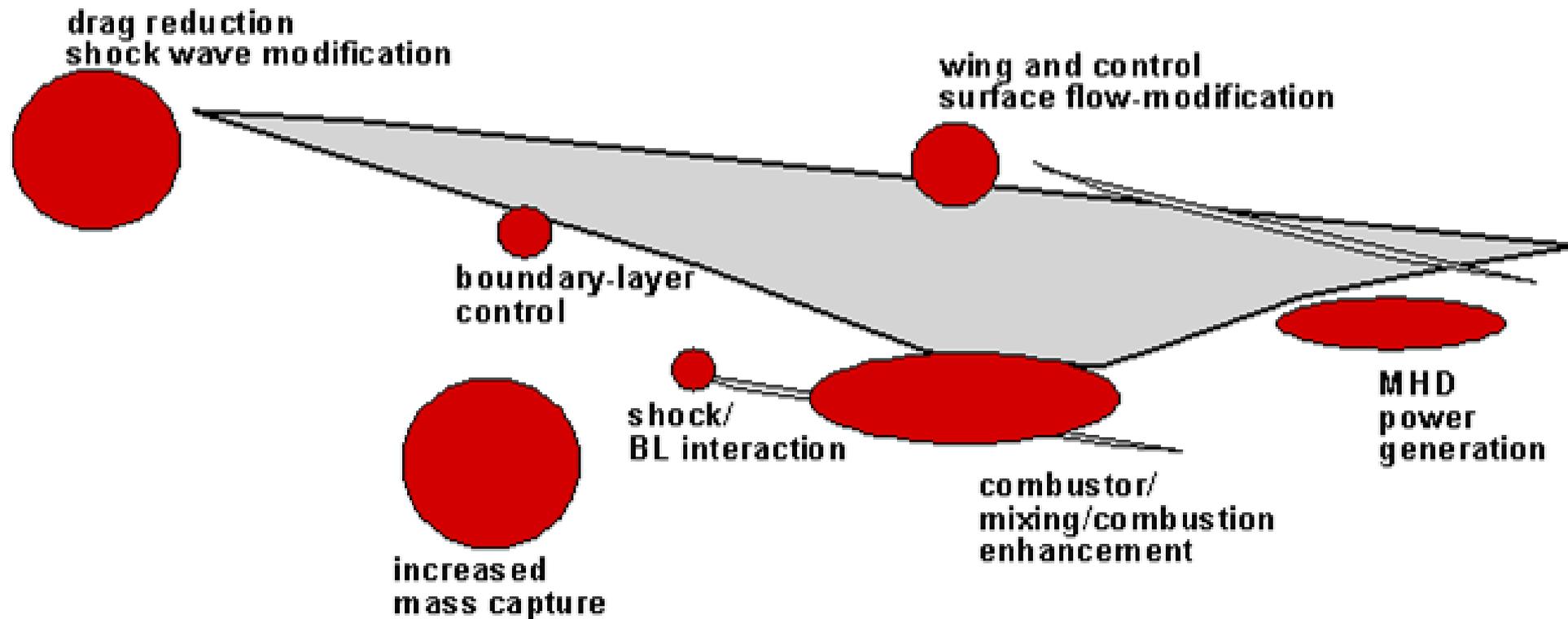
# Effect on Different Mission Segments

Mission Segment	Morphing Wing		Fixed Wing	
	Cruise	Supersonic Penetration	Cruise	Supersonic Penetration
Wing length (ft)	35.50	29.09	41.4301	
Wing sweep (deg)	13.16	43.63	41.7168	
Root Chord Length (ft)	4.04	4.00	5.0138	
Tip Chord Length (ft)	1.53	1.68	2.6809	
Fuel Consumption (lbm)	76.8	712.2	210.1	662.2
Percent Decrease	63.4%	-7.55%	Baseline	

Example

# ENERGY DEPOSITION

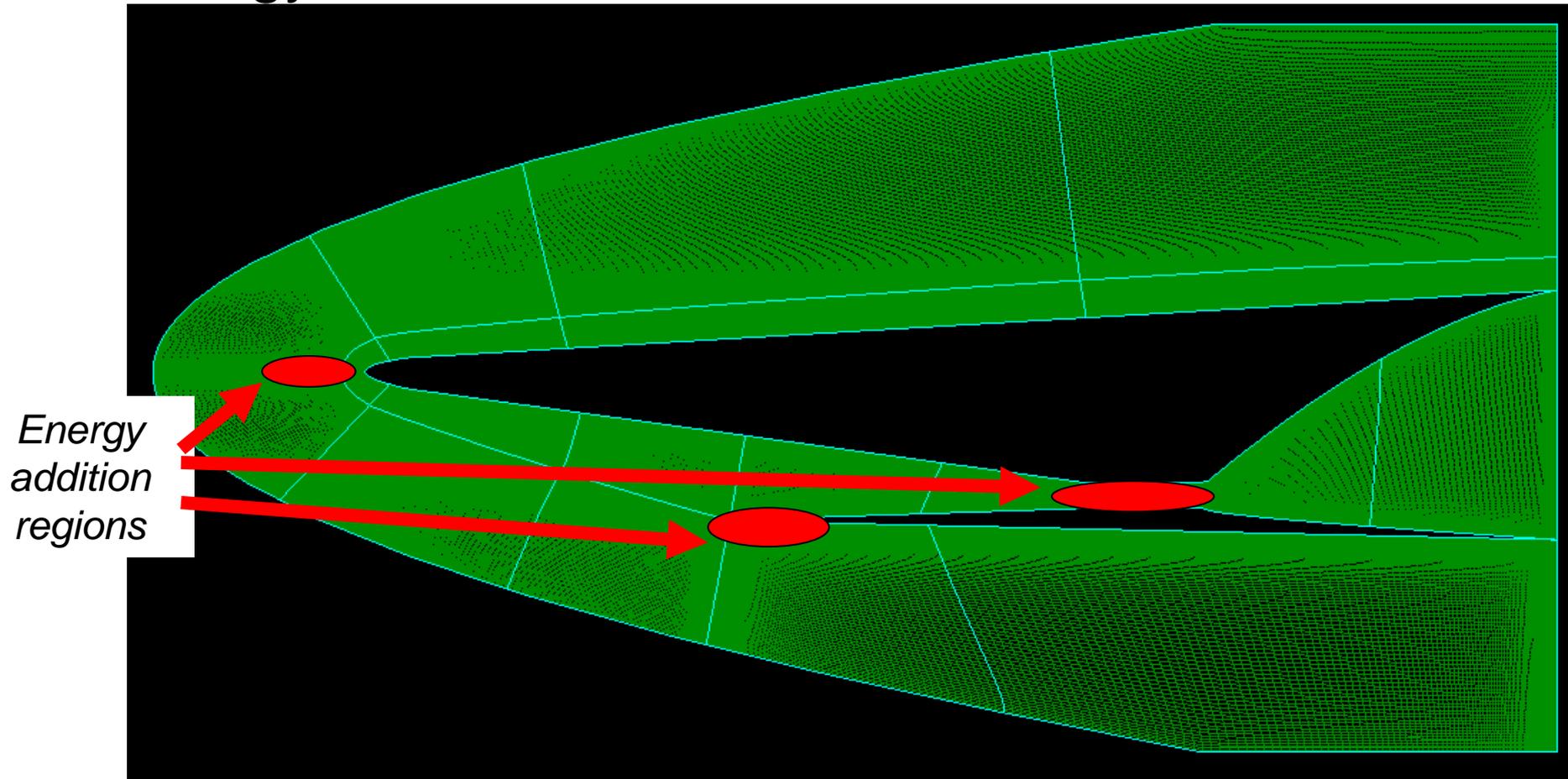
# Potential Areas of System Usage for On-board Energy



*Requires Accurate & Consistent  
Second-Law-Based, System-Level Performance  
and Optimized Fuel Usage*

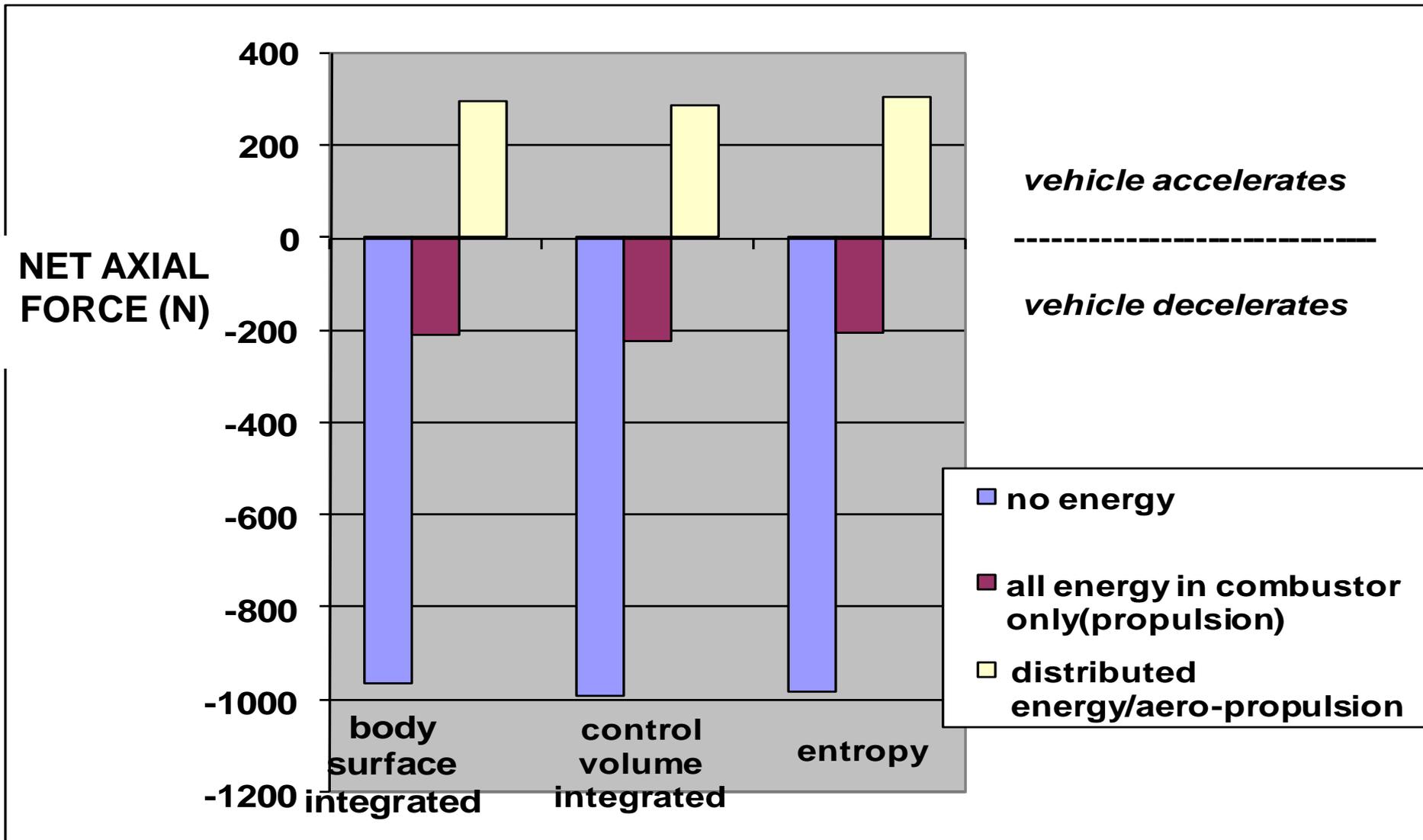
# 2-D Vehicle Study

- Used VULCAN “ignition sub-blocks” to add energy into discrete locations in the flow-field



# 2-D Vehicle Force Summary

## Mach 10

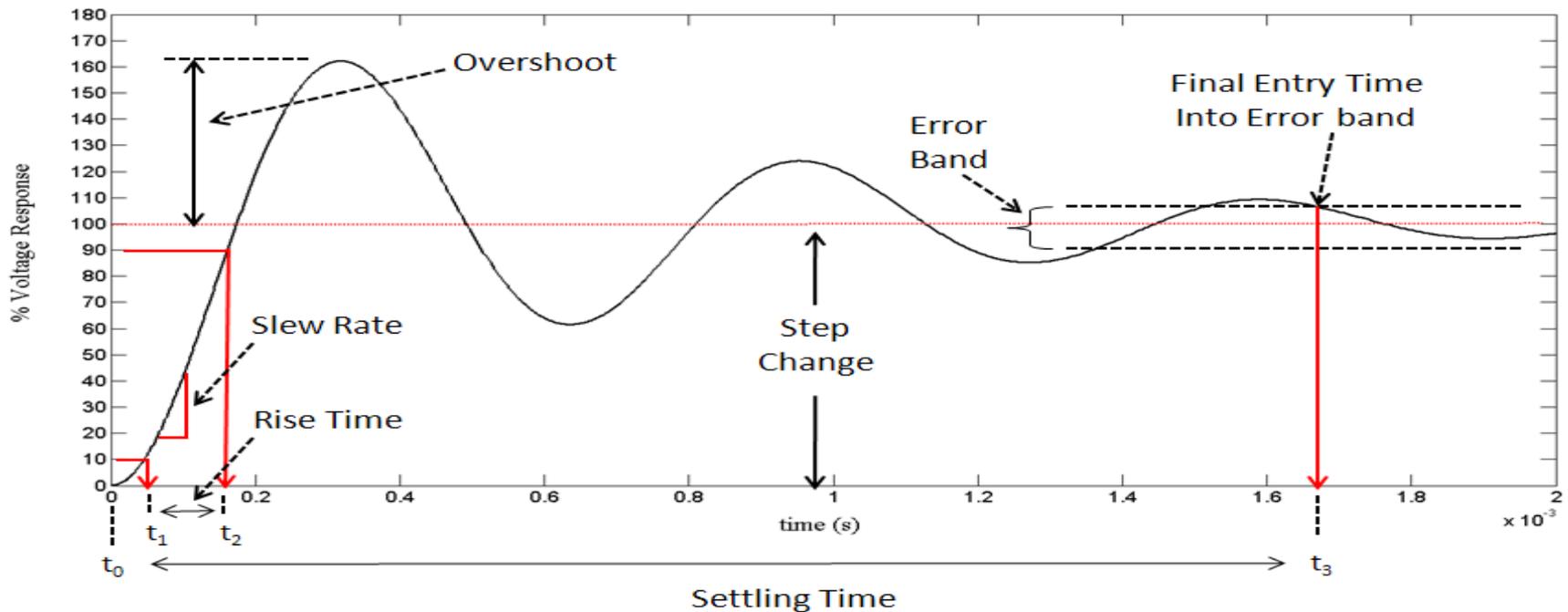
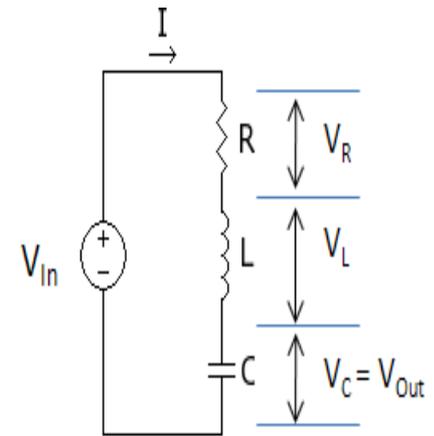


Example

# ENTROPY GENERATION MINIMIZATION & MAXIMUM SYSTEM PERFORMANCE

# System Dynamics

- Step input change in source voltage ( $V_C$ ):
  - *Rise time*: Time for ( $V_C$ ) 10% to 90% of *step change*
  - *Slew rate*: Maximum ( $V_C$ ) change rate
  - *Overshoot*: Maximum normalized ( $V_C$ )
  - *Settling time*: Elapsed time for meta-stability

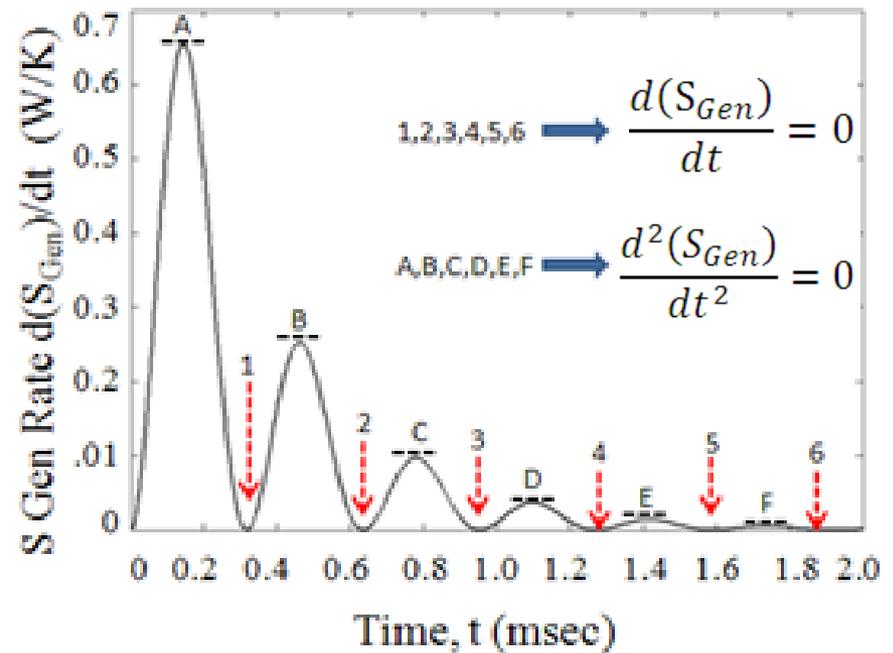
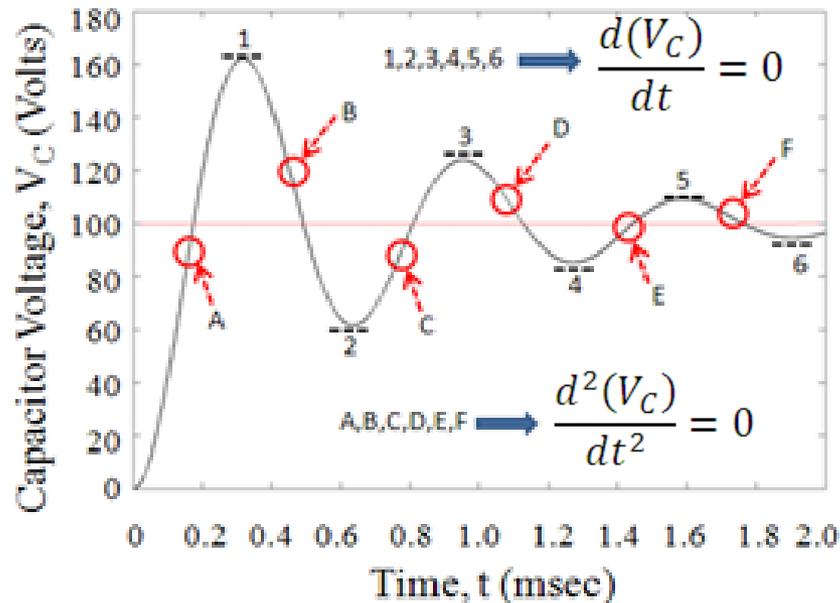


# Dynamic Response

## 1<sup>st</sup> & 2<sup>nd</sup> Law Comparison

★ 1<sup>st</sup> Law ( $V_C$ ) →  $\frac{d(V_C)}{dt} = 0$

★ 2<sup>nd</sup> Law (Entropy) →  $\frac{d^2(S_{Gen})}{dt^2} = 0$

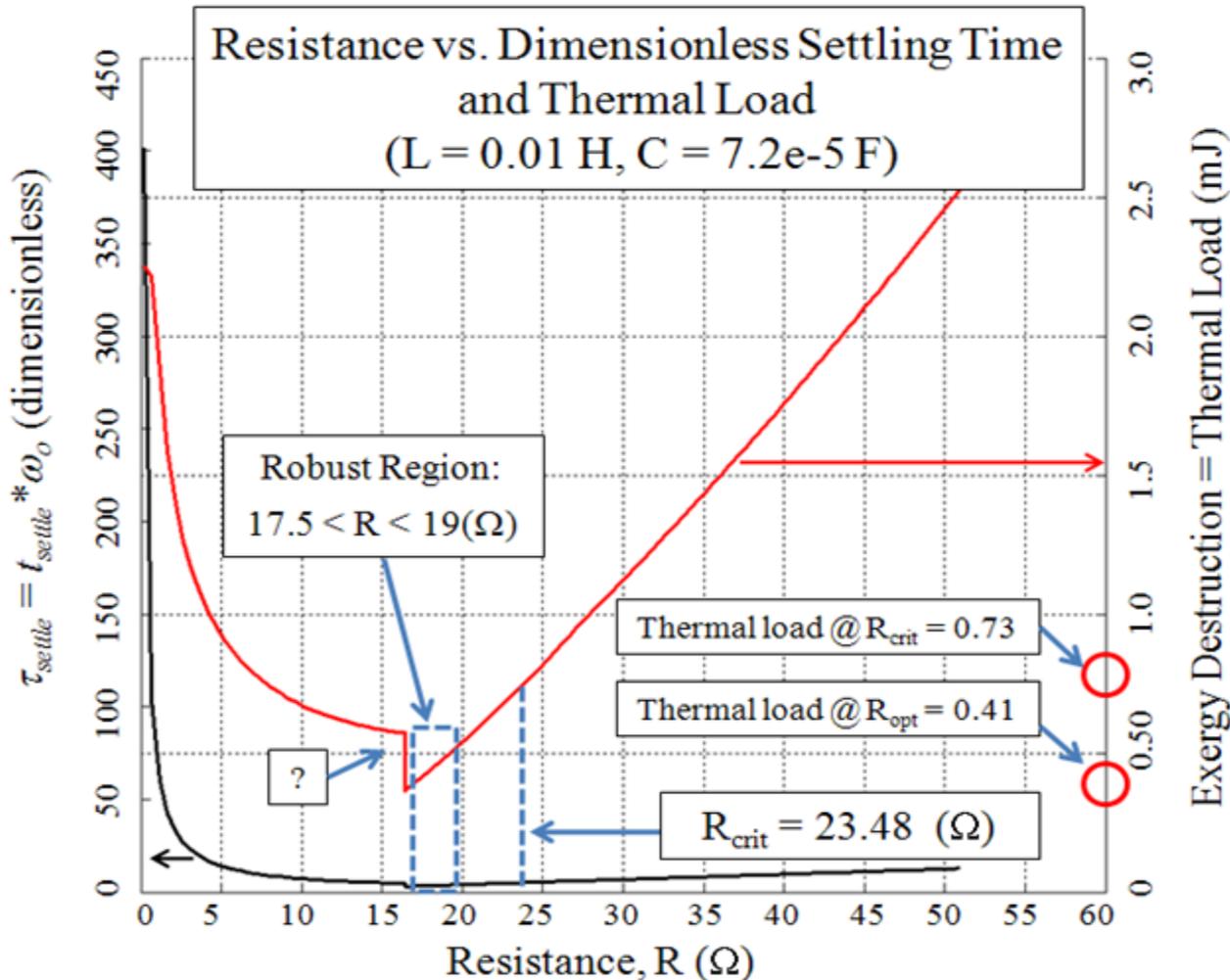


**SAME PHYSICS; BUT DIFFERENT INTERPRETATION:**

1<sup>st</sup> & 2<sup>nd</sup> LAW → STATIONARY POINTS, → EQUILIBRIUM OR NOT?

# Interpretation

## Dynamics AND Exergy Destruction



~29% lower Rise Time & Settling Time, with ~43% reduction in Thermal Load; 2% Overshoot

**“Anomaly” in exergy destruction due to settling time definition**

|

**DYNAMIC BEHAVIOR CAPTURED VIA STATIONARY INPUTS**

MIN THERMAL LOAD & MIN EXERGY DESTRUCTION → ~INCREASED PERFORMANCE

# Exergy-Based Design Methods

## Summary:



- Optimization metric options are equivalent for propulsion + power components
- Adding airframe component → optimizing to minimize exergy destruction saved 6% fuel
- Morphing wing → significant system benefits
- Net thrust demonstrated with strategic energy deposition, using work potential loss

*Exergy-Based Design Methods MUST be used to enable truly integrated, system/mission-level analysis and design optimization*

# Research Questions

- What are relevant time scales for dynamic systems?
- How to incorporate dramatically different timescales into cohesive system?
- How to appropriately define system and its relevant boundaries such that interactions properly captured?
- How to properly pose the physical problem such that the models are more correctly developed
- How to validate models with physical experiments?