

A Conceptual Framework to Support a Multi-level Planning Capability

Jitu Patel
DSTL UK

Michael C.
Dorneich
Honeywell USA

David Mott
IBM UK

Ali Bahrami
Boeing USA

Cheryl
Giammanco
ARL USA

Abstract - Over the years, military planning has attracted a lot of attention by researchers with the aim of providing automated planning support tools. There have been some successes (e.g., DART system which was used for movement during Gulf war) however, to-date, planning still remains a very human activity with little or no automated support tools. Why? A possible reason for this predicament is that researchers have not fully conceptualized the problem. For instance, a common approach has been to consider planning as a single process or a homogenous set of problems to be solved. Unfortunately, military planning is not a single activity but a set of heterogeneous but interrelated activities that are carried out by different set of planners working at different times and locations. These activities may be conceptually quite different. It is therefore proposed that military planning should be viewed as a *capability*, which consists of diverse activities aimed at producing a set of coordinated plans to achieve given high-level mission objectives. This perspective informs a human-centered approach where it is possible to identify the key areas where automated support is most beneficial. This paper proposes a conceptual framework for providing automated support for aspects of the planning capability. It will describe the complex nature of military planning and proposes a pragmatic approach to providing planning support tools. This work addresses the ITA research on collaborative shared understanding and problem solving over a network. Military Planning is an example of distributed collaborative problem solving that is dependent on shared understanding.

Keywords: military planning; problem solving; Collaborative Planning Model; shared understanding

I. INTRODUCTION

*“No matter how well one may fire a howitzer, plant a mine, manoeuvre a tank, pilot an aircraft or shape a ship’s course, if the equation is wrong at the top it will eventually fail to produce the desired results.”*C.

Military operations, like many other major enterprises, have two intertwined phases: planning and execution. The former is intellectually the most demanding, and if not properly thought

through, could seal the fate of the latter before it even commences.

Over the years, military planning has attracted considerable attention by researchers with the aim of providing automated planning support tools. For example, the ARPA/Rome Laboratory Planning Initiative was a large funded program which ran from 1989 to 1998 which demonstrated advanced concepts for planning and scheduling to support military crisis action planning C. This effort produced some notable successes including the DART system which was used for movement during Gulf war C. Unfortunately, these early successes have not spawned off more successful planning support tools. Currently, there is a dearth of planning support tools; the planning activity remains primarily manual supported by standard office automation tools which are used of generating written orders. Why?

Researchers have looked at planning as a single process or a homogenous set of problems to be solved, and attempted to provide automated solutions. Unfortunately, military planning is not a single activity but a set of interrelated activities that are carried out by different set of planners working at different times and locations C. These activities may be conceptually quite different (e.g., identifying the best location for a fuel dump, moving troops, deploying sensors, fire planning, determining courses of action). It is therefore best to view military planning as a *capability* which consists of different activities aimed at producing a set of coordinated plans to achieve given high-level mission objectives. This view informs a human-centered approach which results in a paradigm that looks to identify the key areas where automated support is most beneficial, but preserves the human contribution to the planning process that allows for maximum utilization of human knowledge, creativity, experience, and situation awareness while offering automated support to increase planning effectiveness.

In this paper we present a conceptual framework for developing a human-centric military planning capability. Though the framework is primarily focused on facilitating planning knowledge generation and management, it uses constructs that could be used by synthetic agents to support knowledge exploitation, particularly for dynamic planning and execution.

The paper will start with a description of some of the key characteristics of military planning. These characteristics

Report Documentation Page

Form Approved
OMB No. 0704-0188

Public reporting burden for the collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing the collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden, to Washington Headquarters Services, Directorate for Information Operations and Reports, 1215 Jefferson Davis Highway, Suite 1204, Arlington VA 22202-4302. Respondents should be aware that notwithstanding any other provision of law, no person shall be subject to a penalty for failing to comply with a collection of information if it does not display a currently valid OMB control number.

1. REPORT DATE

SEP 2010

2. REPORT TYPE

3. DATES COVERED

00-00-2010 to 00-00-2010

4. TITLE AND SUBTITLE

A Conceptual Framework to Support a Multi-level Planning Capability

5a. CONTRACT NUMBER

5b. GRANT NUMBER

5c. PROGRAM ELEMENT NUMBER

6. AUTHOR(S)

5d. PROJECT NUMBER

5e. TASK NUMBER

5f. WORK UNIT NUMBER

7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES)

U.S. Army Research Laboratory, 2800 Powder Mill Rd, Adelphi, MD, 20783

8. PERFORMING ORGANIZATION REPORT NUMBER

9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES)

10. SPONSOR/MONITOR'S ACRONYM(S)

11. SPONSOR/MONITOR'S REPORT NUMBER(S)

12. DISTRIBUTION/AVAILABILITY STATEMENT

Approved for public release; distribution unlimited

13. SUPPLEMENTARY NOTES

Presented at the Fourth Annual Conference of the International Technology Alliance, London, UK, September 15-16, 2010.

14. ABSTRACT

Over the years, military planning has attracted a lot of attention by researchers with the aim of providing automated planning support tools. There have been some successes (e.g., DART system which was used for movement during Gulf war) however, to-date, planning still remains a very human activity with little or no automated support tools. Why? A possible reason for this predicament is that researchers have not fully conceptualized the problem. For instance, a common approach has been to consider planning as a single process or a homogenous set of problems to be solved. Unfortunately, military planning is not a single activity but a set of heterogeneous but interrelated activities that are carried out by different set of planners working at different times and locations. These activities may be conceptually quite different. It is therefore proposed that military planning should be viewed as a capability, which consists of diverse activities aimed at producing a set of coordinated plans to achieve given high-level mission objectives. This perspective informs a human-centered approach where it is possible to identify the key areas where automated support is most beneficial. This paper proposes a conceptual framework for providing automated support for aspects of the planning capability. It will describe the complex nature of military planning and proposes a pragmatic approach to providing planning support tools. This work addresses the ITA research on collaborative shared understanding and problem solving over a network. Military Planning is an example of distributed collaborative problem solving that is dependent on shared understanding.

15. SUBJECT TERMS

16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT Same as Report (SAR)	18. NUMBER OF PAGES 7	19a. NAME OF RESPONSIBLE PERSON
a. REPORT unclassified	b. ABSTRACT unclassified	c. THIS PAGE unclassified			

Standard Form 298 (Rev. 8-98)
Prescribed by ANSI Std Z39-18

provide a good means of identifying requirements that potential planning support tools need to meet. In the following section we identify some of the broad requirements, which are used as the basis for the proposed conceptual framework. In the final section, we present our research on the Collaborative Planning Model (CPM) that has been developed as the enabling mechanism for the realization of the framework.

II. CHARACTERISTICS OF PLANNING

A. Collaboration

Military planning is a collaborative activity involving a large number of military staff working in teams on different aspects of the plan¹. Figure 1 shows how the combat and functional planning teams collaborate. These teams typically work in parallel. This way of working was first used by Napoleon, hence referred to as “Napoleonic Staff System” in which planners work collaboratively across functional areas and across echelons to ensure a coherent and synchronized set of plans C.

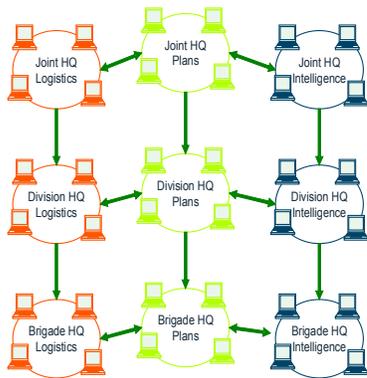


Figure 1: Collaborative Plan Development

The main battle (or maneuver) plan is developed by the *Plans* team who take inputs from the functional areas (e.g., *Logistics* and *Intelligence*). The functional areas will also produce their supporting plans. For example, for the combat plan to be realistic they would get estimate figures of the fuel and ammunition requirements from the logistics staff. While the combat plan is finalized, the logistics staff will start planning on how best to store and deliver necessary fuel and ammunition to their own troops wherever they are on the battlefield. Thus, these teams work in close collaboration to ensure synergy and consistency between their plans.

In order to generate timely and effective plans, there needs to be a shared understanding of the operational objectives and of the evolving plan between the Plans team, and the functional

planning teams at every echelon. A key aspect to achieving this shared understanding is an understanding of the reasoning of others as they go through the estimate process. Currently, there are at least two impediments to successful collaboration: the ever increasing distributed nature of the work and the natural human difficulty of sharing information without misunderstanding, and the content of a plan that is shared.

The Plans team and functional planning teams are usually working at different locations with communications (voice and data) links. The situation is compounded by the fact that the planning process involves the gathering of a large amount of information by each team, which in turn generates new information, only some of which is shared with other teams. Management and sharing of this information remains a challenge.

One of the possible reasons for less than optimal shared understanding between planners is the fact that plans are currently captured in static representation such as text or diagram C. Thus, what is shared between planners (and operators) are the outputs of the planning activity, which does not typically contain any information about the rationale, constraints or assumptions for the decisions. Associated research on possible causes of miscommunication in coalition operations has demonstrated that context plays an important role in fostering shared understanding C. In the planning case, the contextual information is embedded in the rationale, constraints and assumptions underlying the decisions.

B. Specialisation

Traditionally there are two ways to categorize military planning. One categorization scheme is in terms of when the planning activity is carried out (e.g., deliberate planning prior to deployment and crisis-action planning during operation C). Another categorization scheme is in terms of the level and type of decision made (e.g., strategic, operational and tactical). The two categorizations are not entirely dissimilar as one can map, for instance, tactical planning to crisis-action planning. A fundamental flaw in both categorizations is the implicit suggestion that the different phases are discrete and can be conducted independently. Unfortunately, this is not the case. The plans generated by the Plans team and the supporting functional planning teams needs to be coherent and synchronized. Therefore, there is a close link between plans generated at different command levels and the functional areas.

Figure 2 shows a high-level view of how the command is organized. Each node contains both the Plans team and supporting functional planning teams at that command level (the three horizontal teams in Figure 1). Planning needs to be carried out at different command levels and in a large number of functional teams and are required to process different types of information. Each of the cells (peer groups at the same level of command) depicted in Figure 1 requires specialist knowledge. For instance, the Engineers will produce a combat supporting plan for building bridges and runways for aircraft,

¹ At the top level there is only one campaign plan. This plan will have a number of annexes describing the different supporting plans. At the tactical level, there will be different detailed mission plans for the combat and the supporting plans. However, all the plans are supposed to be coherent and coordinated.

the Logistics unit will produce a plan for setting up maintenance areas and schedules for the provision of supplies in theatre.

There are at least two different type of information processing happening at the functional planning cells: provision of information for the combat estimate (e.g., there is sufficient ammunition to support a month’s supply needs and that it can be delivered to the suggested areas in theatre at by the prescribed times), and producing a plan and schedule for the delivery of supplies. The first is an analysis activity which feeds into the second, which is a planning activity.

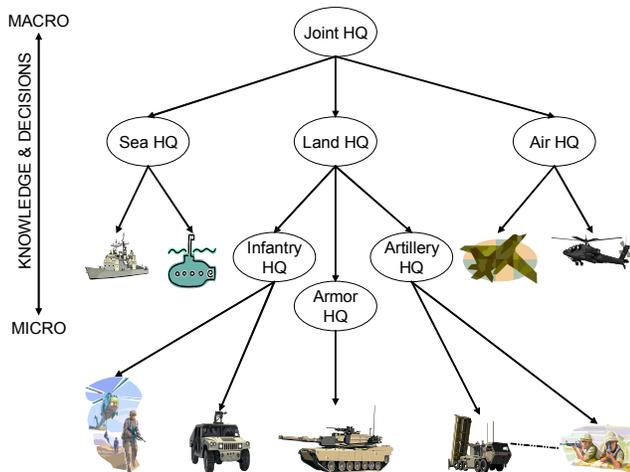


Figure 2: Knowledge and decisions levels in Command

While there is difference in specialization between peer groups, there is also a significant difference in the type of information the teams at different command levels (superior and subordinate nodes) use and the type of decisions made. At the higher command level, granularity of information processing and outputs are macro-level decisions (e.g. this will be primarily a ground operation with close-air support provided by the Navy). As planning progresses down the command-chain, the level of information processed is more detailed (e.g. the land assets to be used are identified and the objectives refined to greater granularity). For example, at the higher-level joint-level (where, for example the campaign plan is developed) one would look at terrain to decide force composition. At the lower-level battalion HQ, relevant battlefield terrain is examined for suitability for setting up maintenance areas, determining movement plans and locations to engage the enemy.

Figure 2 is an illustration of a typical hierarchical military structure. For the purpose of designing planning support tools one needs to understand the detailed information processing happening within the node and between the nodes. The planning teams (Plans team and supporting functions) working at the same command level use different domain knowledge. Therefore there a number of plans which collectively form a coherent set of synchronized activities aimed at achieving

higher-level objectives. These set of plans are then fleshed out in greater detail as planning goes down the command chain.

The implication for planning support tools is that they need to support the specialist functions of different planning cells. Furthermore, they should facilitate information management so the information gathered at higher-level is gradually built upon as one moves down the command hierarchy and more detailed information is gathered and incorporated.

C. Communication

Figure 3 illustrates the areas of responsibility of a Plans cell and an Operations cells. The Plans cell tends to look at the future plans, while the Operations focus on current plans and its execution.



Figure 3: Plans-Operations interactions

There are two key communication channels: between planning teams, and between planning teams and operations. The issues related to the former were discussed in the previous two subsections. The latter requires more attention as it is a human-centric process involving the transfer of plans from the Plans cell to the Operations cell. This hand-over process is often rushed due to time pressures (i.e., the paper copies of the plans are handed over without detailed background briefings on issues, constraints, and assumptions that were considered during the planning process).

When the plan requires amending, it is done by the Operations cell. Often this is where problems arise. The plans currently do not contain all of the background details such as rationale, assumptions and constraints. Also, since the Operations cells were not involved in the development of the plan, they would not have benefit of long deliberations that go into the plan formulation stage. Therefore, during the handover of the plan the planners need to provide a detailed and comprehensive brief to the Operations staff. Unfortunately, this is not always possible due to time pressures.

Effective transfer of knowledge from the Plans cell to the Operations cell is essential both the purpose of generating correct Operational Orders and doing the replanning² in light of a changing situation. As most of replanning occurs during the execution phase, the responsibility for making the necessary changes falls within the Operations Cell (Planning teams are

² Replanning is used here to refer to plan repair or amendment.

busy generating plans for the next phase of the battle). Thus, planning and replanning are generally done by different staff C.

Like planning, replanning is also a knowledge intensive activity and requires a lot of the underpinning information generated during the planning stage. A large proportion of this information is not transferred in the communicated plan. Currently, there are no proper mechanisms for providing this information in a way that it can be adequately utilized in the replanning process.

D. Changing Situation

The constantly changing situation is one characteristic that the planning community is acutely aware of. Indeed, the mantra that *plans are nothing, planning is everything* is used to emphasize the fact that the situation (your own, the enemy and the environment) is constantly changing as a result of your own and enemy actions. Therefore, this may require frequent updating if the plan is to stay current. Dynamic planning done manually (as is the case of planning itself) is not practical in theatre due to lack of both time and knowledgeable resources. According to General Rabin, “it would not do to wait for detailed planning to be completed before starting a move; such a delay is harmful and should not be tolerated.” C.

In order to effectively operate in constantly changing situation, the military planning process includes the development of contingency plans. Unfortunately, due to the open-ended nature of the problem, it is not possible to produce a contingency plan for every possible situation. When planning dynamically is reaction to a change of situation, the normal approach is to take the existing contingency plan closest to the needs of the situation and adapt it for execution. This is not the most efficient way of handling unpredictable situations. Furthermore, one finds that as situations unfold new goals emerge C, of which there may be no appropriate contingency plans available to exploit the opportunity or to deal with a change in focus. It is therefore not possible to produce a plan without some understanding of the goals. As a result execution involves improvisation and a lot of peer-to-peer coordination. For example, during the 1967 Arab-Israel conflict, of the four day campaign by the Southern command “only the first day was planned in detail, the remaining days were pure improvisations” C.

Replanning, like planning, is a complex cognitive task that requires both time and effort. Unfortunately, in theatre both of these are at premium hence improvisation is the norm. This is obviously very risky and could negatively impact operational effectiveness. Aitken et al. C have investigated the possibility of providing automated planning support tools to help dynamically replanning during execution. This approach, however, relies on the availability of necessary information from the planning stage.

III. HUMAN-CENTRIC FRAMEWORK

A. Requirements

From the planning characteristics described above we can distil the following requirements for planning support tools:

1. A tool must support coordinated activities carried out by different teams, which may not be co-located (collaboration, specialization)
2. A tool must support the diversity in the information requirements and processing done in each of the teams (collaboration, specialization)
3. A tool must support both planning and replanning³ which involve different types of information processing⁴ and is carried out by different staff, e.g., Planning or Operations (communication)
4. A tool must support replanning during the execution phase to account for the dynamic nature of the battlespace. Due to time constraints there is a need for automated support for replanning (changing situation)

B. Solution Options

Before looking at the possible options for type of planning support tools, it is assumed that all planning teams will be using some form of planning support tools⁵. The measure of usefulness of a solution approach is whether it is able to adequately meet the above requirements. The following are the main options:

- *Single Planning Tool* – the same tool is used by all planning teams. This is not a good option as it meets none of the requirements.
- *Common Planning Tools* – superior and subordinate planning teams use same planning tools, which are different for different functional areas. This is a possible option, but it will not adequately meet the second requirement. Also, if the common tools are used by superior and subordinate cells, there will be strong tendency over plan by the superior cells.
- *Different Planning Tools* – different planning teams use tailored tools to meet their needs. This approach only partially satisfies the above requirements, assuming tools are able to exchange data. It however falls short on addressing the issue of how one fosters shared understanding and ensures coherence in the plan generated by different teams.
- *Different Planning Tools Linked with a Common Representation* for planning concepts – different planning teams use tailored tools to meet their needs. This approach does satisfy the above requirements.

³ Replanning here refers to plan repair or modification in light of changed situation. This activity normally falls within the execution cycle.

⁴ Planning involves generation and selection of courses of action (COAs) whereas replanning will involve modification of the COA.

⁵ In this paper we have not differentiated planning support tools in terms of what functionality they provide. The assumption is that these tools will provide all necessary support to generate COAs and produce hard copies of Operational Plans.

C. Proposed Framework

It is proposed that for the generation of timely and quality plans human planning teams need to be supported by a network of planning support tools. These tools should be tailored to the needs of individual planning teams. The only requirement on the tools is that they use a common representation of the planning concepts⁶. The common representation can be the basis of the tool, or if an existing tools has its own semantics, then interoperability can be achieved by creating a mapping between the ontologies. So what is shared between teams are planning concepts, as illustrated in Figure 4.

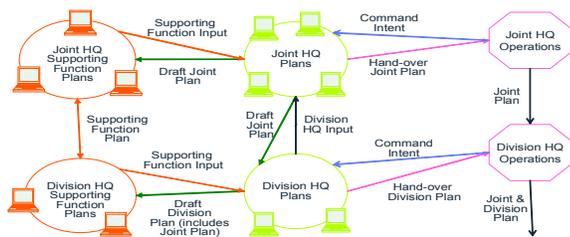


Figure 4: Flow of Plans

In the figure, “Joint Plan” includes all of the information that the Joint HQ Plans cell has generated during the planning process. This is held digitally so different planning teams are able to selectively visualize and amend the plan as necessary. As such, the plan is alive. In contrast, the current military planning process involves exchange of paper copies of “plans”, which consist of just the final abridged outputs from the planning process C.

The information flow process is as following. Once command intent is received, the Joint HQ Plans cell will generate a Joint plan, which is sent to the Supporting Functions cell and Division HQ for their inputs. Once the joint plan is finalized, it is handed over to the Joint Operations cell for execution. The plan flows down the command hierarchy, and at each level it is fleshed out with more details. This process continues until it is finally executed. However, as noted the previous section, plans are continually modified during the execution cycle. With a digital version of the plan it becomes feasible to employ synthetic agents to carry out plan modifications, particularly in time-constrained situations (e.g. dynamic planning and execution).

Example benefits of digitizing plans includes:

- increased shared understanding between planning teams, as they are now able to see significantly more underpinning information (e.g., assumptions, constraints, rationale) in the plans.

- Decrease in information load as synthetic agent technology can be used to quickly process information (e.g., route planning) leaving humans to focus on important tasks. This will improve timeliness for generating plans
- Improve plan quality by making it easier to verify and validate plans using modeling and simulation tools.

The proposed approach is based on the proposition that a comprehensive and reliable plan representation scheme can be developed. This is a research question and is the subject of ongoing research in the International Technology Program described in the next section. Other challenges include knowledge acquisition (how to get planning teams to encode their thought processes into the system), visualization (visualizing relevant parts of the plan), plan version control (as plans are continuously modified by different planning teams), sharing plans (exchanging only changes elements of the plan to reduce network traffic).

IV. PLAN REPRESENTATION USING THE CPM

There is a research strand within the International Technology Alliance program investigating how to improve shared understanding in distributed teams collaboratively solving a common problem over the network C. The research has taken Military Planning which is an example of collaborative problem solving.

One of the activities in the research strand is developing a representational scheme for military planning. This plan representation language is called the Collaborative Planning Model (CPM). The CPM is a representation ontology developed to support military planning by distinctly representing goals, plans, constraints, and human rationale associated with decisions made while creating the plan C. The CPM ontology is represented in a Web Ontology Language (OWL 1.1) and capable of representing planning concepts typically present in “static” documents (e.g., objectives, tasks, decision points, resources) as well as assumptions, constraints and human rationale associated with decisions made while creating plans C.

While a useful machine understandable representation, raw OWL is not a human friendly representation C. To address this we have taken two approaches. Firstly we have developed a human-readable Controlled Natural Language (Controlled English C) that can be mapped to and from OWL. Secondly we have explored plan-specific visualization by creating three independently-developed tools with the ability to create, edit, visualize and exchange plans in CPM : the IBM Visualiser, the Boeing Graphical Plan Authoring Language (GPAL) Tool, and the Honeywell PlanEditor. Two of the tools (Visualizer and PlanEditor) were developed explicitly for CPM, while one tool (GPAL) was developed with its own semantics and extended to allow for the exchange of plans in CPM. The tools provide a graphical representation of the spatial and non spatial aspects

⁶ Example of planning concepts include: Objectives, Tasks, Activities, Effects, Units, Agents and Main Effort.

of the plan, including a display of the plan on a map and the relationships between entities such as objectives and tasks; facilities for editing the plan including objectives, tasks, resource requests, and assignments; capabilities to import and export plans in CPM/OWL; and the display and capture of the rationale for properties of plan entities.

A. Initial CPM Evaluation – September 2008

Initial functionality of CPM was evaluated in September 2008 by three UK military officers C. A brigade level plan was produced on the Visualizer by one military officer. The plan was then forwarded to the battlegroup commanders (played by the other two officers). The battlegroup planning was done on two different laptops, one with Visualizer and other with the PlanEditor. The battlegroup plans were then merged on another laptop to identify resource conflicts. This exercise demonstrated the feasibility of using a common plan representation to collaborative problem solving using different tools C. However, since the tools used for this exercise were designed for CPM, the findings were deemed to be inconclusive.

B. Dry-run – March 2010

In preparation for a detailed evaluation of CPM's capability to represent collaborative human generated battle and functional plans at two levels of command of a joint US-UK operation, we carried out a dry-run with the help of two US and a UK military officers over one and half days in March 2010. This exercise suggested that CPM is able to represent most of the US planning concepts, and that at the conceptual level there was not any significant difference between US and UK⁷.

While not formally examine, we had the opportunity to develop and share plans between the Visualiser and GPAL. This finding was interesting considering that the G-PAL ontology is different from the CPM, but the G-PAL system can import and export CPM plans CC.

C. Future Challenges

Evaluations C of the CPM has highlighted potential challenges that must be met when achieving shared understanding in more complex multi-level collaborative planning, including issues of representational semantics, rationale, configuration management, visualization utilizing context and filtering, plan interoperability, and interfaces.

The continuing challenge in building the CPM is to ensure that it contains the representational semantics needed to capture all the relevant constructs within the planning process. Thus it must have both broad and deep semantics that can support the range of planning from pre-deployment to dynamic ad-hoc re-planning during execution. Ideally as plans are modified, there would be some from of audit trail to further enable someone to

uncover the history of the plan to better understand its current state.

Recent discussions with US planners during “dry run” planning session revealed that the rationale in the form of dependencies between tasks was important; in addition the presentation of draft plans was also accompanied by statements of rationale C. There are still many issues to be addressed in the construction of rationale in the CPM: the multiple sources of rationale information, structured vs unstructured rationale, the capture of rationale in formalisms like Controlled English, and the utility of context in creating and interpreting rationale.

Given the complexity of coalition plans, it is difficult, if not impossible, for every planner to understand all details of the entire plan. In fact, each plan participant has his or her own role in planning process, and therefore may only need to understand a small portion of the plan, along with additional contextual (including situational) information that is not necessarily included in the plan itself CC. This has implications for how to share plans or portions of plans between functional teams and between levels, how to visualize plans at different planning levels, and how to provide information during the planning process. In our approach, the same planning element will be used for every situation or context C. What changes from context to context is not the representation of specific planning elements but what attributes, features, or relationships should be represented Context aware representation speaks directly to the task-specific concerns and interests of specific group of users and, as such, it will selectively represent aspects of the plan and feature representations in which the user operates. Thus shared understanding may not require an understanding of the total plan, only those parts relevant to the planners task in hand.

Configuration management involves identifying plan revisions at given points in time, systematically controlling changes to the plan, and maintaining the integrity and traceability of the plan throughout the lifecycle C. Configuration management poses a challenge in multi-level planning environments. As the plan evolves and different versions of plans are generated, the problems worsen. Planning constraints and version restrictions can be encoded in CPM/OWL that can facilitate the sharing of knowledge about configurations, across various systems. Additionally, as more plans are created, it would be possible to create libraries of partial plans that could be used starting a new plan. How to archive and index such a partial plan library is another challenge to be addressed.

It will be necessary to reconcile different military vocabularies. Experience in discussion with military experts suggests that the terminology and concept definition in different nationalities and areas of planning can be conflicting and confusing. Traditionally, terms are introduced by defining them in terms of others, and we propose a similar approach. CPM seeks to define generic concepts, that are not necessarily one-to-one

⁷ Most of the identified differences were purely linguistic as suggested by C.

with military terminology (due to the confusions of the latter), but that have a logical meaning. We then propose to map key military terminology onto the more generic CPM concepts, thus different cultures could share understanding of the same underlying concepts.

Finally, interfaces must support all phases of the military mission, from pre-deployment planning through execution to post operation activities. While the CPM allows for entities and modeled concepts to follow a plan through all phases, there still remains the challenge of how to effectively capture data along the way to support the capture of rationale, planning alternatives considered and discarded, and other elements of the problem solving process.

ACKNOWLEDGMENTS

Research was sponsored by the U.S. Army Research Laboratory and the U.K. Ministry of Defence and was accomplished under Agreement Number W911NF-06-3-0001. The views and conclusions contained in this document are those of the authors and should not be interpreted as representing the official policies, either expressed or implied, of the U.S. Army Research Laboratory, the U.S. Government, the U.K. Ministry of Defence or the U.K. Government. The U.S. and U.K. Governments are authorized to reproduce and distribute reprints for Government purposes notwithstanding any copyright notation hereon.

REFERENCES

- [1] H Herwig - The Prussian Model and Military Planning Today, *JFQ*, Spring 1998
- [2] A Tate – Smart Planning, in A Tate (Ed) *Advanced Planning Technology: Technological Achievements of the ARPA/Rome Laboratory Planning Initiative*, AAAI Press, Menlo Park, California, 1996.
- [3] N Fowler III, S Cross, T Garvey and M Hoffman – The ARPA-Rome Laboratory Knowledge-Based Planning and Scheduling Initiative, in A Tate (Ed) *Advanced Planning Technology: Technological Achievements of the ARPA/Rome Laboratory Planning Initiative*, AAAI Press, Menlo Park, California, 1996.
- [4] A Aitken, T. Humiston & J Patel “Dynamic Planning and Execution”. In *Proceedings of the Fifth Knowledge Systems for Coalition Operations*. 2007 P. 37 – 42.
- [5] D. Alberts and R. Hayes – *Planning: Complex Endeavors*, CCRP Publications, 2007.
- [6] Poteet, S. et al (2009) “Miscommunications and Context Awareness”. paper submitted to the 3rd Annual Conference of the International Technology Alliance (ACITA), Maryland, USA, 2009
- [7] J. Moffatt – Command and control in the information age: representing its impacts, *TSO*, London, 2002.
- [8] G Klein – Flexicution as a Paradigm for Replanning, Part 1. In *IEEE Intelligent Systems*, Vol 22, No. 5, 2007.
- [9] M van Creveld – *Command in War*, Harvard University Press, Cambridge, MA., 1985.
- [10] NIS ITA Biennial Program Plan 2009 (BPP09)
- [11] Allen, J.A., Mott, D., Bahrami, A., Yuan, J., Giammanco, C., and Patel, J. "A Framework for Supporting Human Military Planning," Proceedings of the Second Annual Conference of the International Technology Alliance, London UK, September 2008.
- [12] Mott, D., Summary of Controlled English, ITACS, <https://www.usukitacs.com/?q=node/5424>, May 2010.
- [13] Dorneich, M.C., Mott, D., Patel, J. & Gentle, E. (2009). “Using a Structured Plan Representation to Support Multi-level Planning”. *Proceedings of the Knowledge Systems for Coalition Operations*, March 2009, Southampton, United Kingdom.
- [14] A. Bahrami, J. Yuan, D. Mott, C. D. Emele, D. Masato and T. J. Norman, “Collaborative And Context-Aware Planning,” MILCOM2008, 2008 Military Communication Conference, November 17-19 2008, San Diego California
- [15] Conceptual Mapping between GPAL-OWL and CPM. Mott, D., Bahrami, A, Yuan, J, Nov 2009, <https://www.usukitacs.com/?q=node/5046>
- [16] Dorneich, M.C., Mott, D., Bahrami, A., & Patel, J. (2009) “Improving Shared Understanding in Multilevel Planning”, Third Annual Conference of the International Technology Alliance, Maryland, September 23-24.
- [17] Mott, D., Giammanco, C., Dorneich, M.C., & Braines, D. (2010). “Hybrid Rationale for Shared Understanding” *The Fourth Annual Conference of the International Technology Alliance*. London, England. 13-17 September.
- [18] A. Bahrami, J. Yuan, D. Emele, D. Masato, T. J. Norman And D. Mott, “Collaborative And Context-Aware Planning,” Proc, Military Communication Conference, November 17-19 2008, San Diego California.