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Integrated Strategy for Autonomous Drive, Connected Vehicle and Robotics

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24 August 2010

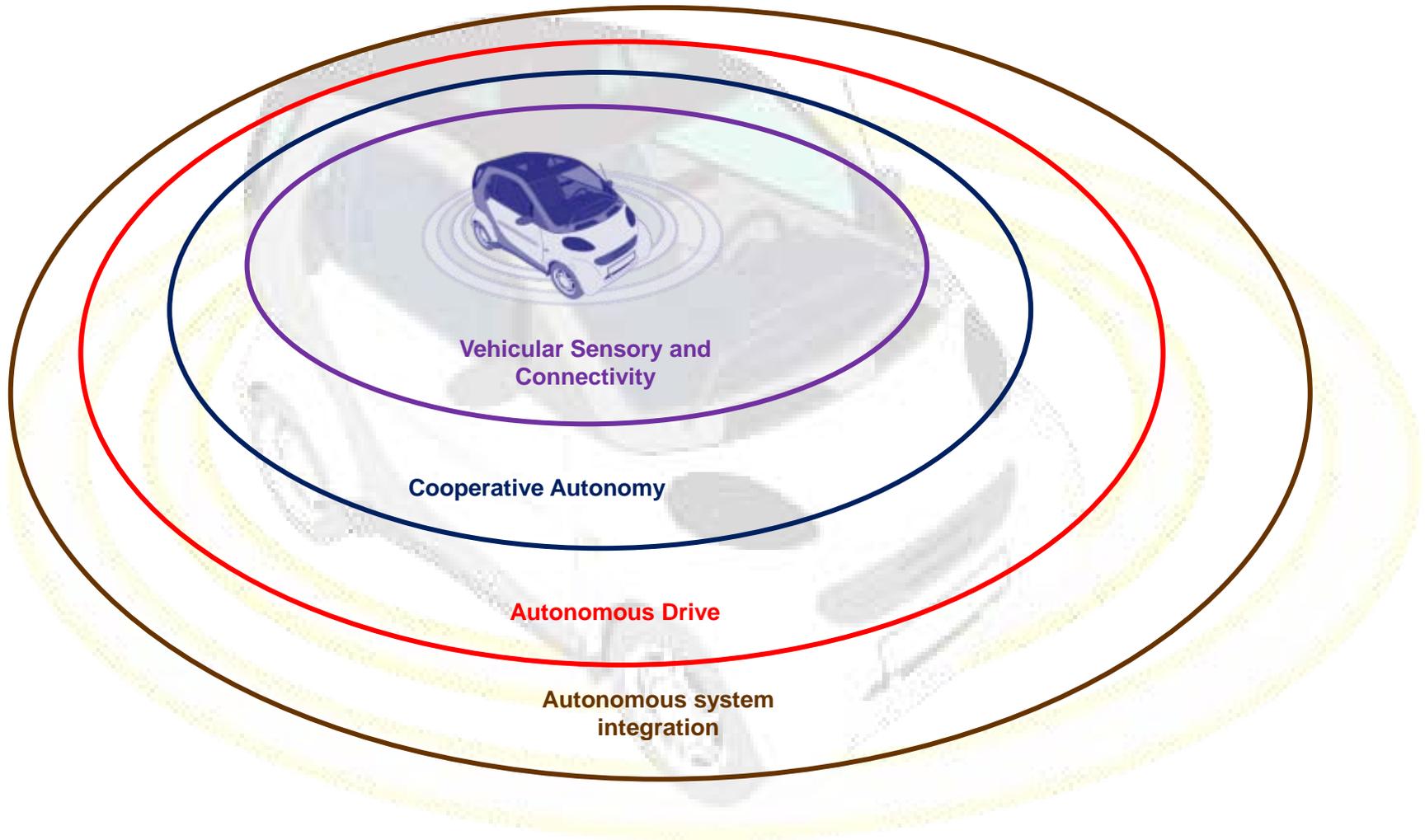
Report Documentation Page

Form Approved
OMB No. 0704-0188

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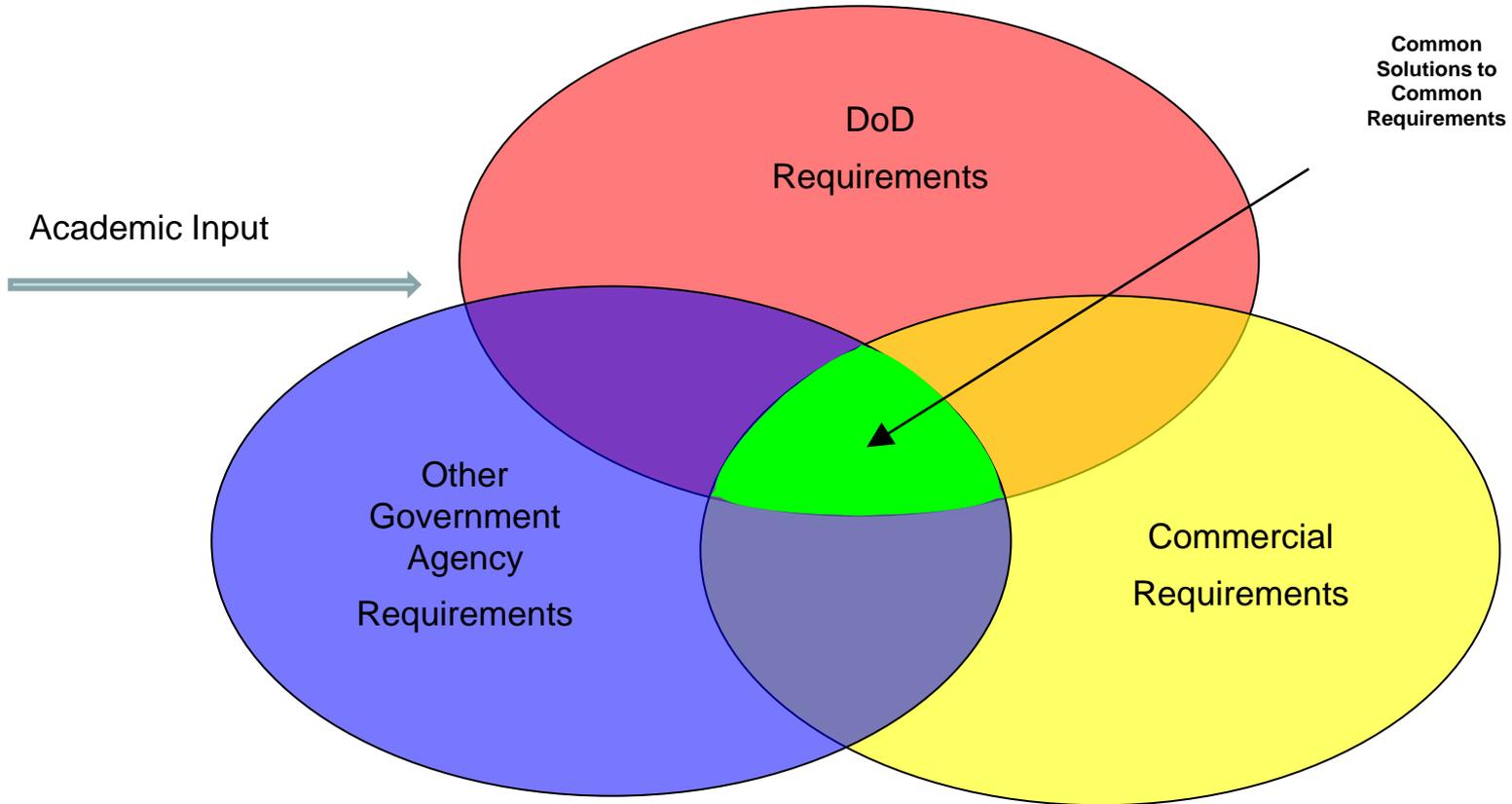
1. REPORT DATE 24 AUG 2010	2. REPORT TYPE N/A	3. DATES COVERED -			
4. TITLE AND SUBTITLE Integrated Strategy for Autonomous Drive, Connected Vehicle and Robotics		5a. CONTRACT NUMBER			
		5b. GRANT NUMBER			
		5c. PROGRAM ELEMENT NUMBER			
6. AUTHOR(S) David Thomas		5d. PROJECT NUMBER			
		5e. TASK NUMBER			
		5f. WORK UNIT NUMBER			
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) US Army RDECOM-TARDEC 6501 E 11 Mile Rd Warren, MI 48397-5000, USA		8. PERFORMING ORGANIZATION REPORT NUMBER 21014RC			
		10. SPONSOR/MONITOR'S ACRONYM(S) TACOM/TARDEC			
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES) US Army RDECOM-TARDEC 6501 E 11 Mile Rd Warren, MI 48397-5000, USA		11. SPONSOR/MONITOR'S REPORT NUMBER(S) 21014RC			
		12. DISTRIBUTION/AVAILABILITY STATEMENT Approved for public release, distribution unlimited			
13. SUPPLEMENTARY NOTES The original document contains color images.					
14. ABSTRACT					
15. SUBJECT TERMS					
16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT SAR	18. NUMBER OF PAGES 7	19a. NAME OF RESPONSIBLE PERSON
a. REPORT unclassified	b. ABSTRACT unclassified	c. THIS PAGE unclassified			

- **Synchronize** the **activities** of **Government**, **industry**, and **academia** to develop technologies, encourage policies, shape investments, and establish leadership in anticipation of transportation needs for the 21st century and beyond



- **Vehicular Sensory and Connectivity** In vehicle enabling infrastructure
Examples: composition, fusion, “geography”, road-map, control, networking
- **Cooperative Autonomy** Intra vehicle network, communications, rules and behaviors/actions/reactions
Examples: fused networks, autonomous connectivity architecture, autonomous communications protocols, roadway/ITS cooperation, cooperative control applications, cooperative safety
- **Autonomous Drive** Driver and passenger
Examples: Human Machine Interface, proactive destruction, autonomous vehicle design, semi autonomous, assisted driving, proactive safety
- **Autonomous system integration** The autonomous vehicle and its environment
Examples: Mixed use, transportation systems, infotainment, navigation, standards

- Improved competitive position in world's marketplace
- Increased economic and national security
- Reduced fatalities
- Reduced congestion
- Improved fuel efficiency
- Improved commerce efficiency





- Autonomous Drive, Connected Vehicle and Robotics will continue to grow in capabilities and acceptance in the coming decade.
- Cooperation between each of these thrusts is critical to overcome technical, regulatory and funding constraints.
- The Autonomous Drive, Connected Vehicle and Robotics coordination white paper will be the coordination document identifying gaps and opportunities.