II. SEDIMENT PENETRATION

The following section describes the model for scattering from and out of the bottom with sand ripples. This work is based on the second order perturbation theory of scattering from sand ripples. It assumes that the scattering into the sediment is approximately described by Snell’s law for angles above the critical angle, and by second order perturbation theory below the critical angle. This section ignores the effects of small-scale roughness and volume inhomogeneities.

Let $\theta_i$ be the grazing angle of the incident field, and $\phi$ be the azimuthal angle between the incident field and the direction of the ripple field. Neglecting small-scale roughness, the scattering into the sediment is composed of five terms. The first is the coherent component due to Snell’s law. The remaining components are the lowest order terms for Bragg diffraction of sound into the sediment by the ripple structure. It is these last remaining terms that play the dominant role of scattering into the sediment for sub-critical grazing angles.

This section assumes the sinusoidal surface is of the following form.

$$z = h_s \cos(k_s x)$$

The incident wave vector is of the following form, where we assume the ripples are oriented along the x-axis.

$$k_{i,s} = k_i \cos(\theta_i) \cos(\phi)$$

$$k_{i,r} = k_i \cos(\theta_i) \sin(\phi)$$

$$k_{i,t} = k_i \sin(\theta_i)$$

(2.2)

Here, $k_i$ and $k_s$ are the angular wavenumber in the fluid and the sediment, respectively.
**Title**: High Frequency Images of Proud and Buried 3D-Targets

**Performing Organization**: Coastal Systems Station

**Address**: R21 6703 West Highway 98 Panama City, Florida 32407-3560

**Distribution/Availability Statement**: Approved for public release, distribution unlimited

The horizontal wavenumber of the incident field is of the following form.

\[ q_{x, y} = k_i \cos(\vartheta) \cos(\varphi) \]
\[ q_{x, y} = k_i \cos(\vartheta) \sin(\varphi) \]  

(2.3)

The vertical wavenumber in the upper and lower media are given by the following functions of the horizontal wavenumber, where the branch cut is chosen such that the imaginary component of the wavenumber on the physical sheet is positive.

\[ h_i(\vec{q}) = i \sqrt{q^2 - k_i^2} \]  
\[ h_\perp(\vec{q}) = i \sqrt{q^2 - k_i^2} \]  

(2.4)

The plane wave reflection coefficient is given by the following expression in terms of the vertical wavenumber and the ratio of the density of the sediment to that of seawater.

\[ R(\vec{q}) = (\rho h_i(\vec{q}) - h_\perp(\vec{q})) / (\rho h_i(\vec{q}) + h_\perp(\vec{q})) \]  

(2.5)

The following vector gives the horizontal wavenumber of the ripple field.

\[ q_{x, y} = \frac{2\pi}{L_n} \]
\[ q_{x, y} = 0 \]  

(2.6)

To second order in perturbation theory, Bragg scattering through a sinusoidal surface consists of 5 rays whose horizontal wavenumber are of the following form, where \( n \) ranges from –2 to +2.

\[ \vec{q}_i = \vec{q} + n\vec{k}_s \]  

(2.7)

Define the following quantities taken from Moe1.

\[ a = 1 - \frac{k_i^2}{\rho k_s^2} + \left(1 - \frac{\vec{q}_i \cdot \vec{q}}{k_i^2} \right) \]
\[ b = (\rho - 1) \frac{h_i(\vec{q}_i)h_\perp(\vec{q}_i)}{k_i^2} \]
\[ H_{i x}(\vec{q}_i, \vec{q}) = \frac{k_i}{2i h_i(\vec{q}_i)} \{ a(1 + R(\vec{q}_i))(1 + R(\vec{q})) \} \]
\[ -b(1 + R(\vec{q}_i))(1 - R(\vec{q})) \} \]  

(2.10)

\[ G_{i x}(\vec{q}_i, \vec{q}_i, \vec{q}) = \]
\[ \frac{1}{2} \left( \frac{k_i^2}{k_i^2} - 1 \right) \{ (1 + R(\vec{q}_i))(1 - R(\vec{q})) \} \]
\[ h_i(\vec{q}_i)h_\perp(\vec{q}_i) \}
\[ - (1 - R(\vec{q}_i))(1 + R(\vec{q})) \} \]
\[ + \frac{i k_i H_{i x}(\vec{q}_i, \vec{q}_i)}{h_i(\vec{q}_i)} \{ (\vec{q}_i \cdot \vec{q}_i) - 1 \}(1 + R(\vec{q}_i)) \}
\[ - h_i(\vec{q}_i)h_\perp(\vec{q}_i) \}
\[ k_i \}

(2.11)

\[ G_{i x}(\vec{q}_i, \vec{q}_i, \vec{q}) = G_{i x}(\vec{q}_i, \vec{q}_i, \vec{q}) \]
\[ - h_i(\vec{q}_i)h_\perp(\vec{q}_i) \}
\[ k_i \}
\[ + \frac{2i k_i H_{i x}(\vec{q}_i, \vec{q}_i)}{h_i(\vec{q}_i)} \{ \}
\[ \frac{2i h_i(\vec{q}_i)H_{i x}(\vec{q}_i, \vec{q}_i)}{k_i} \}
\[ k_i \}

(2.13)

The T-matrix for the 5 Bragg waves diffracted into the sediment is given by the following expressions.

\[ T_{i x}(\vec{q}_i, \vec{q}_i) = \]
\[ (1 + R(\vec{q}_i)) + \frac{1}{2} \frac{k_i h_i \vec{q}_i}{k_i} \{ G_{i x}(\vec{q}_i, \vec{q} - \vec{q}_s, \vec{q}) + G_{i x}(\vec{q}_i, \vec{q} + \vec{q}_s, \vec{q}) \} \]
\[ T_{i x}(\vec{q}_i - \vec{q}_s, \vec{q}_i) = \frac{k_i h_i \vec{q}_i}{2} H_{i x}(\vec{q}_i - \vec{q}_s, \vec{q}) \]
\[ T_{i x}(\vec{q}_i + \vec{q}_s, \vec{q}_i) = \frac{k_i h_i \vec{q}_i}{2} H_{i x}(\vec{q}_i + \vec{q}_s, \vec{q}) \]
\[ T_{i x}(\vec{q}_i + 2\vec{q}_s, \vec{q}_i) = \frac{k_i h_i \vec{q}_i}{2} G_{i x}(\vec{q}_i + 2\vec{q}_s, \vec{q} + \vec{q}_s, \vec{q}) \]
\[ T_{i x}(\vec{q}_i - 2\vec{q}_s, \vec{q}_i) = \frac{k_i h_i \vec{q}_i}{2} G_{i x}(\vec{q}_i - 2\vec{q}_s, \vec{q} - \vec{q}_s, \vec{q}) \]  

(2.14)
Reciprocity yields the following expression for the outgoing T-matrix in terms of the incoming T-matrix:

\[ T_{zi}(-\tilde{q}, -\tilde{q}_i) = \frac{h_i(\tilde{q}_i)}{\rho h_i(\tilde{q})} T_{zi}(\tilde{q}_i, \tilde{q}) \] (2.15)

The pressure field of the Bragg waves scattered into the sediment is given by the following expression in terms of the incoming T-matrix, where \( z \) is the depth into the sediment.

\[ p = T_{zi}(\tilde{q}_i + n\tilde{q}_s, \tilde{q}_i) \exp[+ih_i(\tilde{q}_i + n\tilde{q}_s)z] \] (2.16)

Similarly, the pressure field scattered from the sediment into the water column is given by the following expression.

\[ p = T_{zi}(-\tilde{q}, -(\tilde{q}_i + n\tilde{q}_s)) \exp[+ih_i(\tilde{q}_i + n\tilde{q}_s)z] \]
\[ = \frac{h_i(\tilde{q}_i + n\tilde{q}_s)}{\rho h_i(\tilde{q})} T_{zi}(\tilde{q}_i + n\tilde{q}_s, \tilde{q}_i) \exp[+ih_z(\tilde{q}_i + n\tilde{q}_s)z] \] (2.17)

The travel time of the individual paths are estimated from the vertical wavenumber in the sediment by the following expression.

\[ t = \frac{\text{Re}(k_z)z}{\text{Re}(h_i)c_z} \] (2.18)

Here \( c_z \) is the speed of sound in the sediment and \( z \) is the burial depth.

**III SAMPLE CALCULATIONS**

This section contains sample calculations of the images of buried and partially buried 3D targets. This section uses the combination of the Kirchhoff approximation and Geometric Theory of Diffraction described by Sammelmann\(^2\) to compute the scattered field given the incoming and outgoing eigen-rays.

Figure 1 depicts the image of a buried cylinder at broad side incidence taken by the Low Frequency Synthetic Aperture Sonar (LFSAS) during SAX99\(^7\). The center frequency of the sonar is 20 kilohertz with a bandwidth of 10 kilohertz. The elements are 15 cm in length with a vertical beam width of 25 degrees. The sonar is a synthetic aperture sonar with a resolution of 7.5 cm x 7.5 cm. The cylinder is buried approximately 35 cm from the center of the cylinder. The cylinder is 2 meters in length and 0.50 meters in diameter. The target is located at a range of 25 meters from the sonar, which is operating at an altitude of 4 meters. The incident grazing angle at the target is approximately 10 degrees, which is well below the critical grazing angle of medium sand. The measured signal-to-noise ratio of the target is approximately 20 decibels.

Figure 2 depicts a synthetic image of a similar target buried 36 cm at a range of 20 meters for the LFSAS as computed by PC SWAT 8.0 using the methods outlined in the previous section. The altitude of the sonar is 4 meters with a depression angle of 5 degrees. The center frequency of the sonar is 20 kilohertz with a bandwidth of 10 kilohertz. Both the projector and receiver are 15 cm in length with a vertical beam-width of 25 degrees. The ripple height is 2 cm with a ripple wavelength of 25 cm as opposed to the 75 cm wavelength reported for SAX99. In the case the ripple wavelength is 75 cm, the target is not discernible above the background. The shorter ripple wavelength produces a more vertically oriented Bragg diffracted wave. Qualitatively the two images are similar, but the signal-to-noise ratios between the two cases are greatly different. The signal-to-noise ratio in Figure 2 is approximately 15 decibels. Sediment penetration is largely due to Bragg scattering. The difference between the two images is likely due to the fact that higher order Bragg scattering terms are responsible for the signal in Figure 1, resulting in a propagation path that is
more vertical than that predicted by the second order Bragg scattering term.

Figure 2. PCSWAT image of buried cylinder.

When the wavelength of the ripple is much greater than that of the incident field the effect of higher order terms in perturbation theory is to introduce terms with a horizontal wave number of the following form.

\[ k_x = k_{i,x} - nk_R \]
\[ k_y = k_{i,y} \]  

(3.1)

Here, \( n \) is an integer. In the case \( k_R << k_{i,x} \), increasing the integer \( n \) results in a smaller horizontal wave number corresponding to a wave that is more nearly vertically directed. This trend continues up to a critical value for \( n \), beyond which the wave begins to propagate in the backward direction and becomes more nearly horizontal. Those higher order terms that are more vertically oriented, travel less distance in the sediment and are less affected by the attenuation in the sediment. In the case of first order perturbation theory, Bragg scattering consists of the terms \( n = -1, +1 \). In the case of second order perturbation theory, Bragg scattering consists of the terms \( n = -2, 0, +2 \).

Figure 3 depicts a plot of the two-way transmission loss for a medium sand bottom at a frequency of 20 kilohertz in the presence of sand ripples in the case the incident field is oriented at 0, 45, and 90 degrees relative to the sand ripples. The wave height of the ripple is 2 cm and the wavelength is 75 cm. Bragg scattering from the ripples significantly increases sediment penetration past the critical angle at broadside incidence (0 degrees). Sediment penetration below the critical angle for an incident field parallel to the ripple field (90 degrees) is due to the evanescent field and the random, small-scale roughness of the surface.

Figure 3. Transmission loss versus orientation relative to the ripple field.

Figure 4 depicts a comparison of two-way transmission loss as a function of grazing angle for first and second order perturbation theory at 20 kilohertz for a target buried 10 cm. The ripple height is 2 cm and the ripple wavelength is 25 cm. Decreasing the ripple wavelength has significantly increased the sediment penetration at low grazing angles.

Figure 4. Comparison of two-way transmission loss

Figure 5 depicts an image of a partially buried 81 mm mortar shell at the top of the image, a buried sphere 8 inches in diameter in the middle of the image, and a partially buried 100 mm artillery shell at the bottom of the image. The center frequency of the sonar is 45 kilohertz with a bandwidth of 20 kilohertz. Both the projector and receiver are conical elements with a diameter of 8 cm. The altitude of the sonar is 2 m with a depression angle of 25 degrees. The targets are approximately 2.5 to 3.5 meters from the sonar. Both the mortar and artillery shell are near broad side incidence. In the case of the mortar shell, the fins of the mortar shell are in evidence in

Figure 5. PCSWAT image of buried targets.
the image. The image is plotted on a 50 decibels logarithmic scale, where the units on the axes are meters.

Figure 5. Image of partially buried and buried UXO.

Figure 6 depicts a simulated image of a partially buried 81 mm mortar shell and 100 mm artillery shell computed by PC SWAT 8.0. The image is plotted on a 50 decibels logarithmic scale. The axes are labeled in meters. Figure 7 depicts a blow up of the image of the area around the mortar shell. The head and fins of the mortar shell are in evidence in the simulated image. Figure 8 depicts a blown up image of the area around the 100 mm artillery shell. Figure 9 depicts an outline of the shape of the mortar shell used in PC SWAT. Figure 10 depicts an outline of the 100 mm artillery shell used in PC SWAT.

Figure 6. Simulated image of partially buried mortar and artillery shell.

Figure 7. Blown up image of simulated mortar shell.

Figure 8. Blown up image of simulate 100 mm artillery shell.

Figure 9. Outline of shape of 81 mm mortar shell.
V SUMMARY

Bragg diffraction of sound into the sediment is the dominant mechanism for sound penetrating the interface at sub-critical grazing angles. However, first and second order perturbation theory are inadequate to reproduce the measured signal-to-noise levels observed in the SAX99 experiment. Higher order terms are needed to account for Bragg scattering in the near vertical directions.

A better alternative than using higher order perturbation theory is to use the small slope approximation to describe sediment penetration from the ripple field. In the small wave height limit, the small slope approximation reduces to perturbation theory. However, the first order small slope approximation is proportional to the Kirchhoff approximation, which includes all orders of Bragg scattering.
ACKNOWLEDGEMENTS

This work was jointly sponsored by SERDP (Strategic Environmental Research and Development Program) and code 32MIW of the Office of Naval Research.

REFERENCES


