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Leveraging Open Source Software to Create Technical Animations of Scientific Data

John M. Vines
Computational and Information Sciences Directorate, ARL
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13. SUPPLEMENTARY NOTES

14. ABSTRACT

Open source animation software packages provide a means for which scientists, researchers, and engineers can develop technically correct animation at no cost. The U.S. Army Research Laboratory spends tens of thousands of dollars annually for software licenses for packages such as Maya, Houdini, and 3D Studio Max, while in many instances, an open source package such as Blender3D would suffice.

15. SUBJECT TERMS

- high performance computing; HPC; Python; scientific; visualization

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Figure 4. Blender3D rendered image, time step 500 (the last time step in data).................................5
1. Introduction

The objective of this technical report is to provide data about the use of open source software tools to create scientifically correct technical animations from scientific data. The packages used were Blender 3D, blender3d.org, and the Visualization Toolkit (VTK), www.vtk.org. Television and movie industry animation packages, such as Maya¹, Houdini², Lightwave³ or 3D Studio Max¹, are very powerful and very costly. These programs are very good at importing, animating, and rendering the millions of polygons created by large scientific data sets. My objective was to see if we could employ an open-source package with the same or nearly the same results as using a professional package.

2. Discussion

The first place that I started when reviewing Blender3D was the number of polygons supported; at present, version 2.42 supports as many as 2 billion faces per scene. A face can be comprised of quadrilateral or triangular polygons. On average, a scientific data set may encompass 500,000 to 1,000,000 cells or polygons; larger data sets contain well over 1,000,000 and approach 1,000,000,000 cells or polygons. The data that I am using have at most 750,000 polygons; therefore, Blender3D will have no problems with the data.

At the very heart of Blender3D is the Python⁴ programming language. Python is a high-level programming language designed by Guido van Rossum in 1990. It is a dynamically typed, object-oriented language, which makes it similar to Perl⁵, Ruby, Scheme, Smalltalk⁶, and Tcl. Python runs on Windows⁷, Linux⁸ or UNIX⁹, Palm Handhelds and is the primary programming language for Nokia mobile phones. It was developed as an open-source project, under the Python Software Foundation. Its versatility allows for many different uses in many different areas. National Aeronautics and Space Administration uses it to streamline communication with Oracle’s databases for space shuttle missions, the New York Stock Exchange uses it to create

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²Houdini is a registered trademark of Side Effects Software, Inc.
³Lightwave is a registered trademark of NewTek, Inc.
⁴Python is a trademark of Python Software Foundation.
⁵Perl is a trademark of The Perl Foundation.
⁶SmallTalk is a trademark of Active Information Corporation.
⁷Windows is a trademark of Microsoft Corporation.
⁸Linux is a registered trademark of Linus Torvalds.
⁹UNIX is a registered trademark of The Open Group.
graphical user interfaces (GUIs) for the real-time equity trading system, and Industrial Light and Magic use Python to “glue” together the thousands of computers and hundreds of software components in its computer graphics pipeline.

By default, Blender3D does not provide an interface for color-per-vertex shading. We needed to find a way to map scalar values from the data to the vertices, or nodes, of the polygonal data. I was able to accomplish this through the use of VTK and a new Python module, VTKBlender.py, written at the University of Alberta. VTK is an open source, freely available software system for three-dimensional (3-D) computer graphics, image processing, and visualization. VTK is a true visualization program, meaning that it does not just allow for simple geometry visualization but for a wide variety of algorithms that include scalar, vector, tensor, texture, and volumetric methods. It also allows for advanced modeling techniques such as implicit modeling, polygon reduction, mesh smoothing, cutting, contouring, and Delaunay triangulation.

The VTKBlender Python module was written at the University of Alberta's Academic Information and Communication Technology center. The module converts vtkPolyDataMapper’s to Blender3D polygonal meshes, with color-per-vertex information, and converts Blender3D meshes to vtkPolyData.

VTKBlender.PolyDataMapperToBlender(pmapper, me=None)

If the function is run with only one argument, this function takes a vtkPolyDataMapper pmapper and returns a new blender mesh with the converted polydata. A second optional argument, which takes a pre-existing blender mesh, may be provided, causing the existing mesh to be overwritten with the polydata. Please note that the new mesh is not added to the scene and can be added afterwards via

```python
sc = Blender.Scene.GetCurrent()
ob = Blender.Object.New('Mesh')
ob.link(me)
sc.link(ob)
```

The reason why the function takes a vtkPolyDataMapper object as an argument (instead of a vtkPolyData object) is because the vtkPolyDataMapper can also contain a look-up table to color the data, in which case, the blender mesh will have vertex colors set accordingly.

VTKBlender.BlenderToPolyData(me)

This function takes a blender mesh and returns a vtkPolyData object that contains the geometry contained in the mesh.

(https://www.ualberta.ca/CNS/RESEARCH/Vis/VTKBlender/index.html)

Blender 3D is an open-source software package used for 3-D modeling and animation developed as an in-house application by the Dutch animation studio NeoGeo and Not a Number Technologies
Blender is available for use on many operating systems, including FreeBSD\textsuperscript{10}, IRIX\textsuperscript{11}, GNU/Linux, Windows, Mac OSX, Solaris\textsuperscript{12}, SkyOS, and MorphOS. Recent additions to Blender support for 2 billion faces per scene, user interface enhancements and support for third party ray-tracing packages have brought its capabilities close to those of “high end” 3-D software, such as XSI, 3D Studio Max, and Maya, all professional programs used by Hollywood studios such as Pixar.

The user interface for Blender3D is highly customizable and configurable by the user. A typical “scripting” setup will have an OpenGL\textsuperscript{13} showing the data, a text editing window showing the Python script, and application windows at the bottom of the screen comprised of rendering options, directory information, animation options and hierarchical data.

The Python program shown in figure 1 imports, animates, and renders the time-variant data on a local file system.

All polygonal objects in Blender3D are considered meshes. The VTKBlender module, “VTKBlender.py,” provides the interface between the VTK data and Blender3D creating the polygonal mesh and applying the color-per-vertex information “on the fly”.

The data represented here are of an experimental armature for an electromagnetic weapon system. The rendered data show the electromagnetic forces in the X axial direction. In the completed animation, I was able to move the camera around the data showing multiple views of the data. The areas of interest (and showing where the forces are the greatest) are in red. The completed animation presents a complete picture of the performance of the candidate armature, presenting the color-per-vertex scientific data in a manner that is easily understood by the viewing audience. Figures 2, 3, and 4 show time-variant electromagnetic data rendered in Blender3D.

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\textsuperscript{11}IRIX is a trademark of Silicon Graphics, Inc. (SGI).
\textsuperscript{12}Solaris is a trademark of Sun Microsystems, Inc.
\textsuperscript{13}OpenGL is a registered trademark of SGI.
Figure 1. Blender3D user interface.

Figure 2. Blender3D rendered image, time step 1.
3. Conclusions

In the past, I have used animation packages such as Maya, Lightwave, 3D Studio Max, and Houdini to present and render scientific data. All these animation packages are tremendous at what they do, but there is a cost associated with each package and in some cases, it may be in the range of tens of thousands of dollars each year. Employing an open-source software package such as Blender3D to render photographic quality images and technical animations at no cost would save ARL and the Department of Defense tens of thousands of dollars each year in fees associated with software licenses and maintenance.
The incorporation of a Python interpreter at the very core of Blender3D provides an application programming interface to the data, thus providing a means to read and manipulate the data in a highly scientific manner.
4. References

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Appendix A. Blender Python Script Importing and Animating Time Variant Data

```python
#!/BPY

""
Name: 'ANIMATE XDMF'
Blender: 241
Group: 'Animation'
""
import os,sys,string
import Blender
from Blender.Scene import Render
try:
    import VTKBlender as VB
except:
    print 'Problem importing VTKBlender module...'
import vtk as V
#from Xdmf import *
from XFrameWork.io import XdmfVtk as X

class Data:
    iteration = 0
    datadir = None
    name = None
    ext = None
    me = None
    ActiveScalar = 'FX'
    location = [(0,0,0)]

    def __init__(self):
        """reads XDMF files from directory"""
        pass

    def ComputeAverageDistance(self):
        x_vector = 255
        dx = x_vector / 18.0
        print 'Computing average distance...', dx
        x = 0
        for i in range(18):
            loc = [ x + dx, 0, 0]
            self.location.append( loc )
            x = x + dx
            print 'X: ', x
        del x_vector
        del dx

    def ImportTimesteps(self):
        """Checks to see if we have multiple timesteps, if so import them into Blender"""
        if self.iteration != 0:
            self.XdmfDataFiles.sort()
            for file in self.XdmfDataFiles:
                path = self.datadir + '/' + file
                self.Import_Xdmf( self.XdmfDataFiles.index( file ), path )

    def Import_Xdmf(self, cntr, xdmf_file):
        print 'XDMF file: ', xdmf_file
        Blender.Window.WaitCursor(1)
        reader = X.vtkXdmfReader()
        reader.SetFileName( xdmf_file )
```
reader.UpdateInformation()
reader.EnableAllGrids()
reader.EnableAllArrays()
reader.Update()

surface = V.vtkDataSetSurfaceFilter()
surface.SetInput( reader.GetOutput() )
surface.SetPieceInvariant( 1 )
surface.Update()

cells = surface.GetOutput().GetNumberOfCells()

lut = V.vtkLookupTable()
lut.SetNumberOfColors( 256 )
lut.SetHueRange( 0.667, 0.0 )
lut.Build()

m = V.vtkPolyDataMapper()
m.SetInput( surface.GetOutput() )
m.SetScalarModeToUsePointData()
m.GetInput().GetPointData().SetActiveScalars( self.ActiveScalar )
min, max = m.GetInput().GetScalarRange()
if min < 0.0:
    min = 0.0
print 'Scalar min: %f  max: %f ' % ( min, max )
m.SetLookupTable( lut )
m.GetLookupTable().SetTableRange( min, max )
m.Update()

self.name, self.ext = os.path.splitext( os.path.basename( xdmf_file ) )
scn = Blender.Scene.GetCurrent()

if cntr == 0:
    self.me = VB.PolyDataMapperToBlender( m )
ob = Blender.Object.New('Mesh', self.name)
ob.link(self.me)   #tell object to use new mesh
scn.link(ob)    #link object to current scene
else:
    self.u_me = VB.PolyDataMapperToBlender( m, self.me )
c_ob = scn.getActiveObject()
scn.unlink( c_ob )
ob = Blender.Object.New('Mesh', self.name)
ob.link(self.u_me)   #tell object to use new mesh
scn.link(ob)    #link object to current scene

cam = Blender.Object.Get('Camera')
grp1 = Blender.Object.Get('armature_guides')
grp2 = Blender.Object.Get('payload')
lamp1 = Blender.Object.Get('Lamp')
lamp2 = Blender.Object.Get('Lamp.001')
ob.makeParent( [cam, grp1, grp2, lamp1, lamp2] )
ob.setLocation( self.location[cntr] )
ob.sel = 1

bcn = context.blenderScene
bcn.update()
Blender.Window.RedrawAll()
decl scn

def RenderScene(self, cntr):
    context = Blender.Scene.GetCurrent().getRenderingContext()
    context.saveRenderedImage( "%s.%04d.jpg" % ( self.ActiveScalar, cntr ) )
    context.setImageType(Render.JPEG)
    context.enableExtensions(1)
    context.render()

decl context

def Main(self):
    self.ComputeAverageDistance()
    for i in range(1):
file = './home/jvines/Devel/Coupling_05/EM_Dyna3D_COUPLING/TEST/Coupled_PROBED_%04d.xmf' % i
self.Import_Xdmf( i, file )
    self.RenderScene( i )

if __name__=='__main__':
    d = Data()
    d.Main()
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