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**A Fuel Cell Propulsion System  
for a  
Mini - UAV**

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# Report Documentation Page

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# Presentation Outline

- **Introduction**
- **Mission specification**
- **Feasibility Study**
- **Preliminary Design (with AAA)**
- **Mini-UAV lay-out**
- **Conclusions**

# Introduction (1)

- **Mini-UAV propulsion : various**
- **Acoustic & IR --- > batteries**
- **RMA study : a stack of fuel cells integrated in the Mini-UAV (1.5 m spanwidth)**

# Introduction (2)

**Dragon Eye  
Mini-UAV  
(USA – US Navy)  
2001**



# Our starting point : Dragon Eye (US)

## Characteristics :

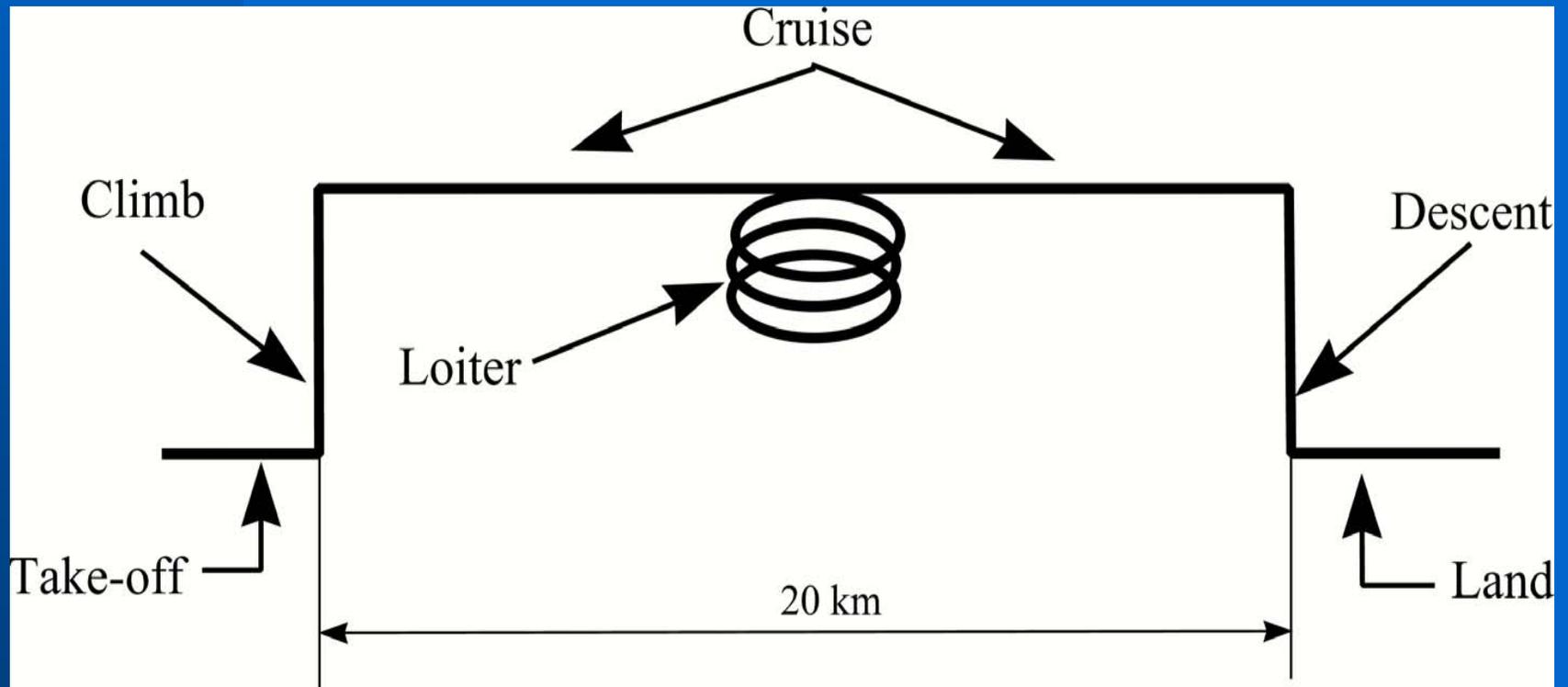
- Span : 1,14 m
- Speed : 18 m/s
- Endurance : 45 - 60 min
- Electric propulsion with batteries
- Propulsion system mass : 1350 g
- MTOGW : 2150 g
- Payload : ?



# Our mission specification

- **Payload : 1.0 kg (cam, nav, coms, PS)**
- **Engines : brushless DC motor with PEMFC**
- **Performance :**
  - **Max cruise speed : 16 - 18 m/s**
  - **Endurance : 50 - 60 minutes**
  - **Range : ~ 10 km**
  - **Direct climb to 1.000 ft**

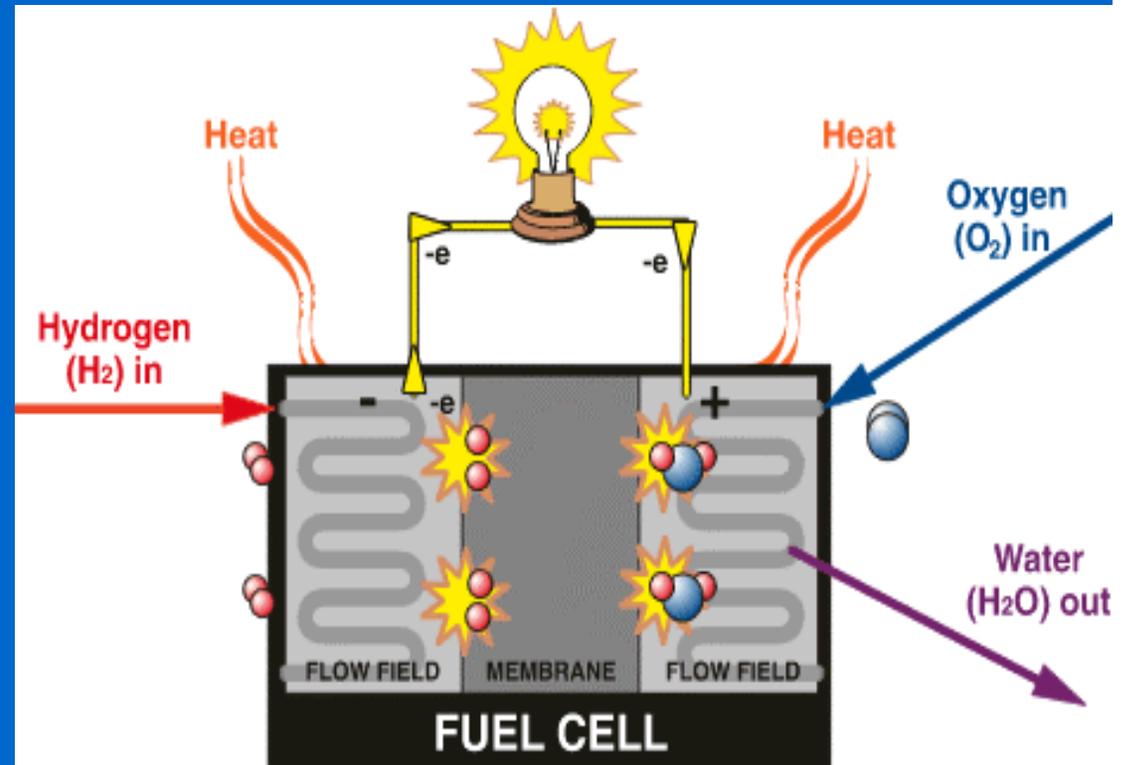
# Over the hill mission



# FC working principle

## Main elements :

- electrodes (+ / -)
- electrolyte
- reactants
- products



# Fuel Cells types

Types	SOFC Solide Oxyde Fuel Cell	MCFC Molten Carbonate Fuel Cell	PAFC Phosphoric Acide Fuel Cell	PEMFC Proton Exchange Membrane Fuel Cell	AFC Alcaline Fuel Cell	DMFC Direct Methanol Fuel Cell
<b>Electrolyte</b>	ZrO <sub>2</sub> /Y <sub>2</sub> O <sub>3</sub>	Li <sub>2</sub> (K <sub>2</sub> )CO <sub>3</sub>	H <sub>3</sub> PO <sub>4</sub>	membrane polymère	KOH	H <sub>2</sub> SO <sub>4</sub>
<b>Température</b>	800-1000°C	650°C	160- 210°C	50-100°C	70- 100°C	70°C
<b>combustible possible</b>	H <sub>2</sub> ,CO	H <sub>2</sub> ,CO,CH <sub>4</sub> ,mé thanol	H <sub>2</sub> ,CO	H <sub>2</sub>	H <sub>2</sub>	méthanol

## Ideal Selected configuration for tests

- PEMFC of 600 W

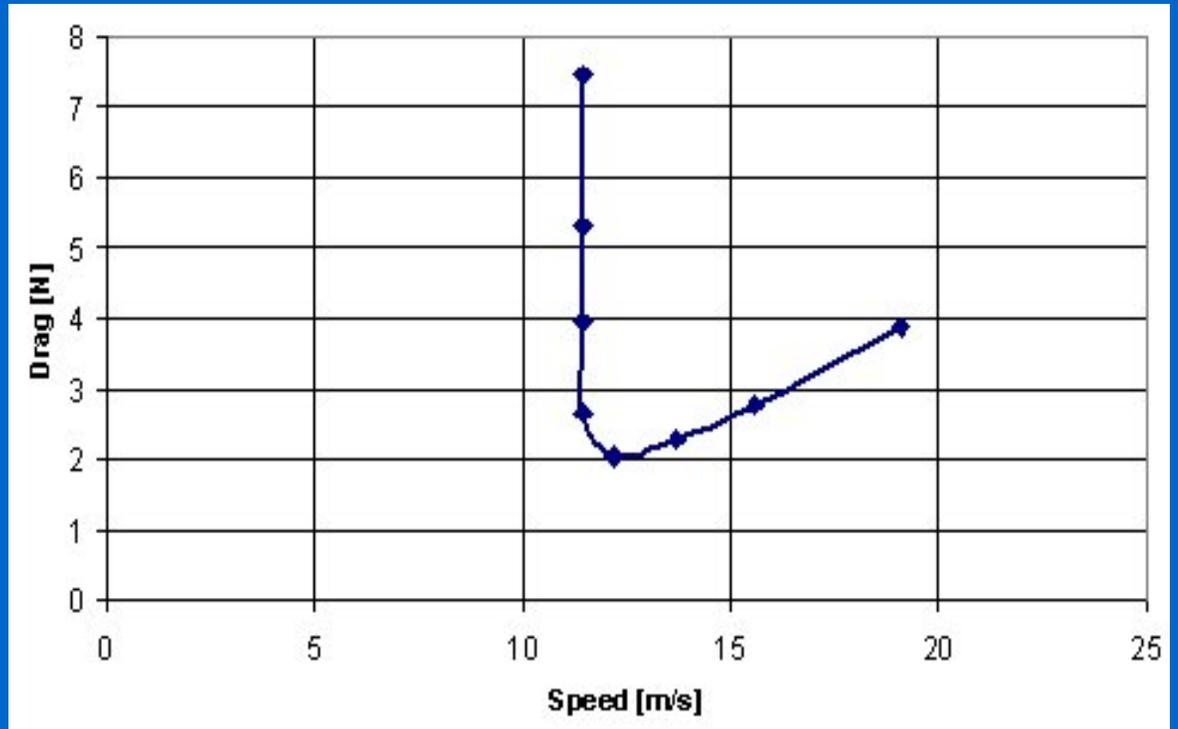
## Why ? Major arguments :

- Range of powers & power density & performance
- Fonctionnal temperature & start-up characteristics
- Fuel used (compactness)

# Feasibility Study (1)

## a/c drag :

- RMA data
- FX05 profile
- Mass estimation
- Power derived
- Wing area
- Stall speed



# Feasibility Study (2)

## Dimensions of FC :

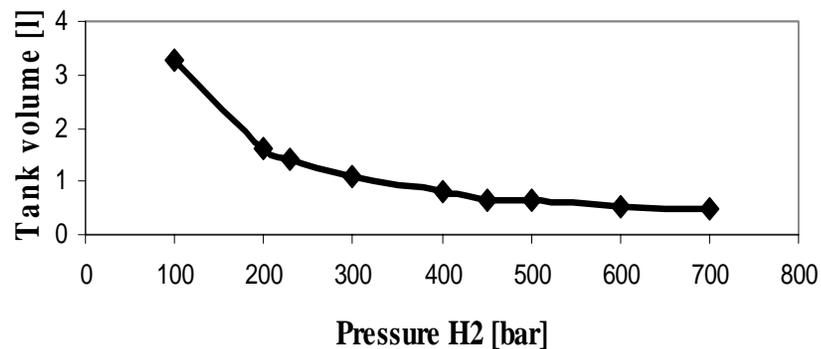
- D & V → required power ~ 400 W
- Power for utilities (10 W camera, 22 W for 24-12V and 13 W for 24-6 V DC-DC convertors) → 50 W
- 450 W PEMFC dim & mass estimation
- Motor voltage fixes the number of cells → length (30 cells x 3 mm + side plates) ~ 160 mm
- Power & Voltage → current (27 A)
- Current & density (.332 A/cm<sup>2</sup>) →  $\phi_i$  ~ 40 &  $\phi_o$  ~ 110 mm
- H<sub>2</sub> consumption determined ~ 23 g
- GH<sub>2</sub> at 300 b → composite tank (60 x 230) ~ 260 g

# Feasibility study (3) : Fuel Storage

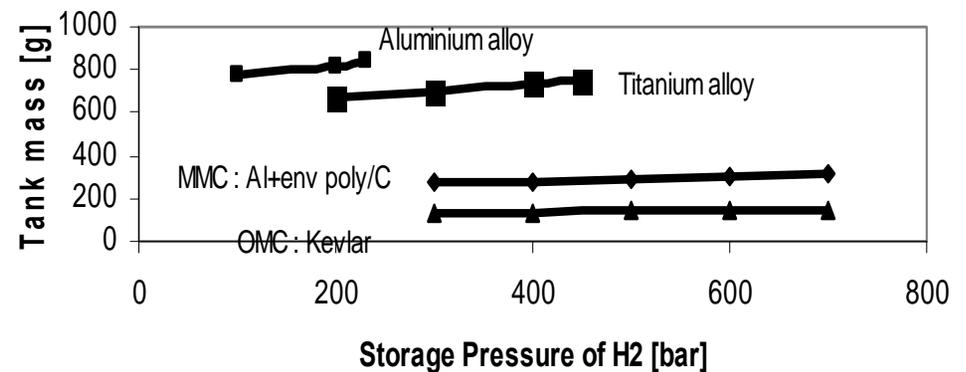
$\text{LH}_2$  or  $\text{GH}_2 \rightarrow \text{GH}_2 \text{ MP}$  (or other promising storage methods)

Tank size ?

Tank volume = f (pressure)  
for a one hour working



Tank mass evolution = f (pressure)  
for different materials



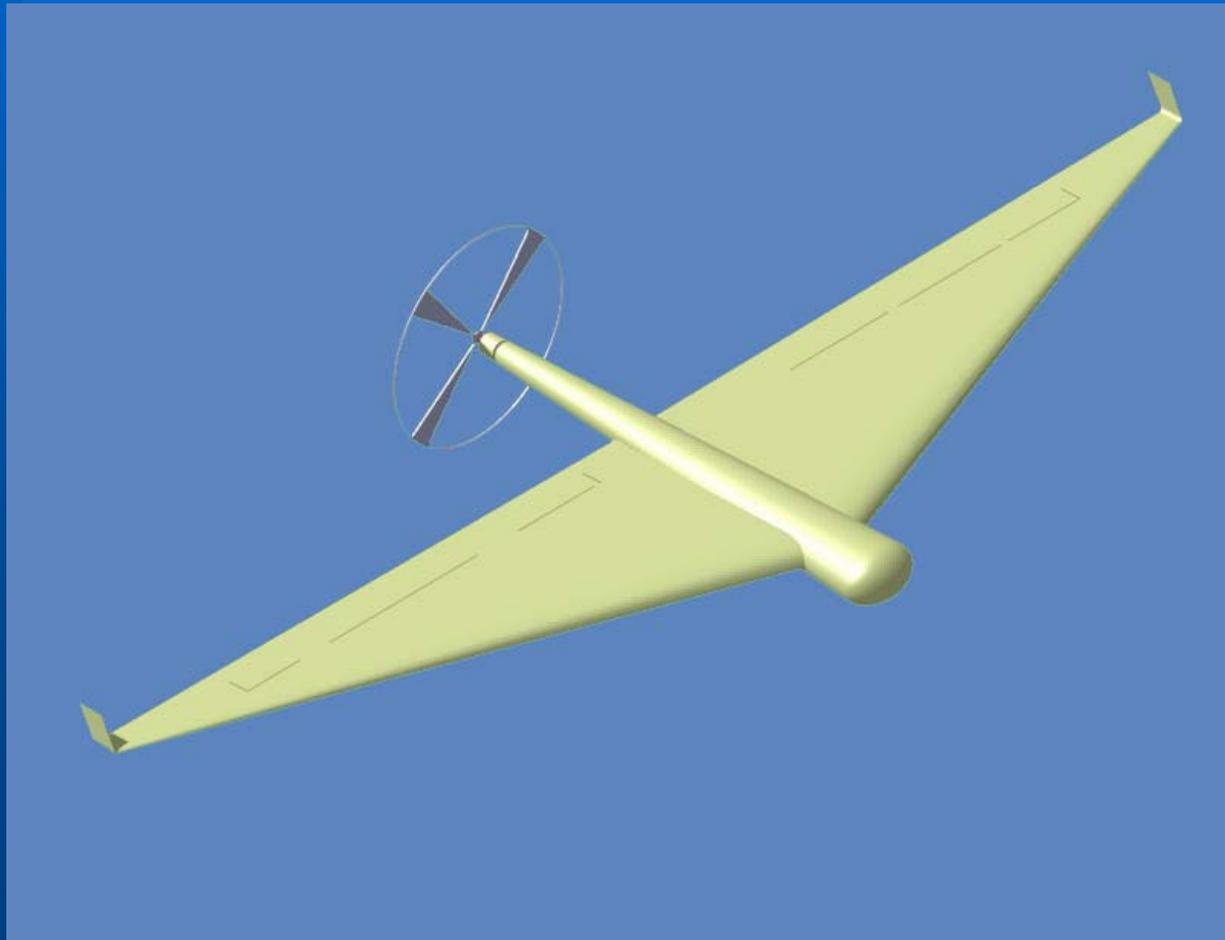
# Feasibility Study (4)

## Mass description :

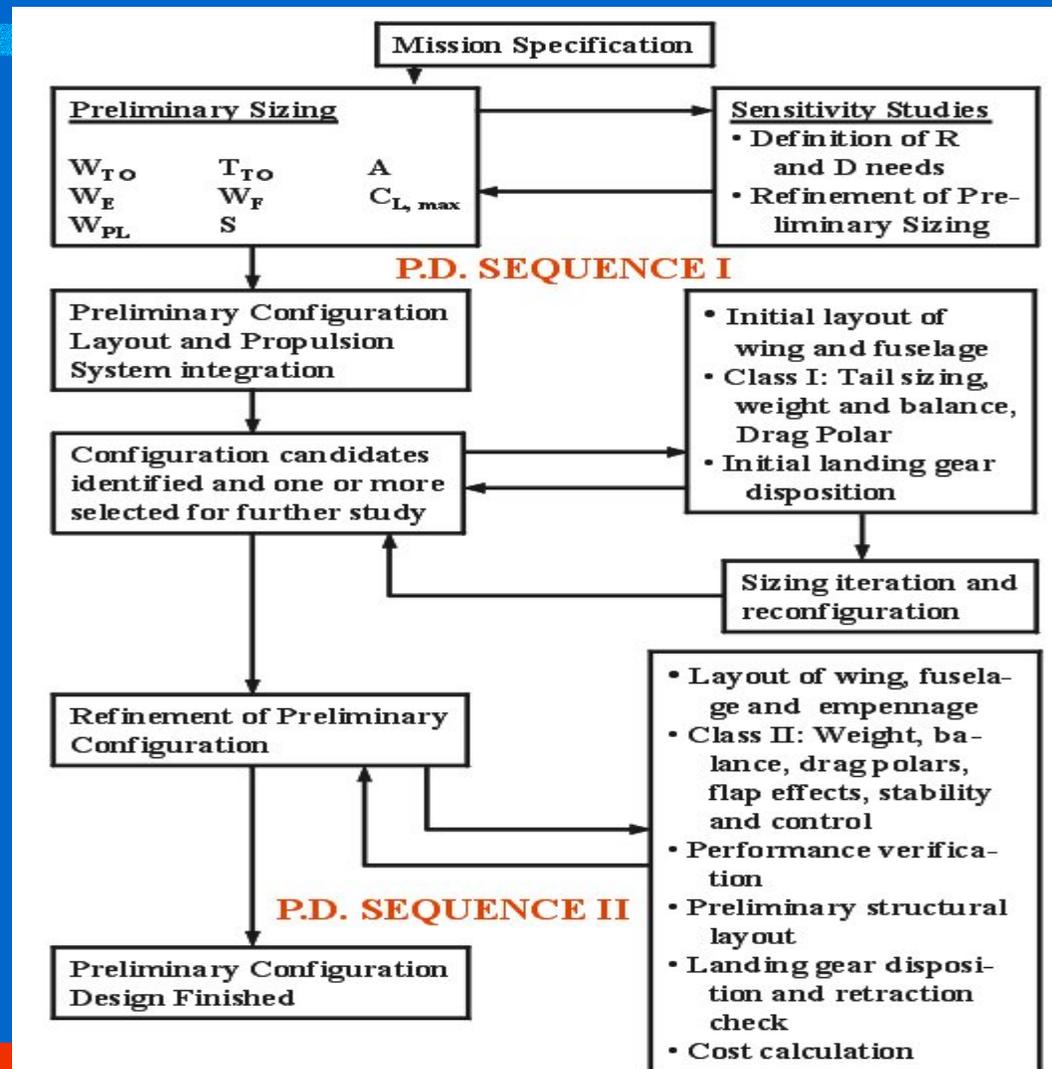
- Mass of PEMFC : 525 g
- Mass of H<sub>2</sub>-fuel : 25 g
- Mass of full fuel tank : 260 g
- Mass of complete prop syst : 2.160 g
- Mass of payload, fuselage, wings & acc : 950 g
- Total mass : 3,1 kg

# Mini-UAV

**Configuration : Flying Wing + winglets**



# Preliminary study (1): iterations !



# Preliminary Design (2)

Estimation of TOGW, OEW & MFW (generals of the iterative method) :

- $\text{TOGW} = \text{OEW} + \text{FW} + \text{Pay}$
- $\text{OEW} = \text{WE} + \text{TfoW} + \text{Crew}$
- Correlation :  $\log \text{TOGW} = A + B \log \text{WE}$
- If A & B known  $\rightarrow$  determine mission fuel fractions (Mff) & iterate
- With also :  $\text{FW} = (1 - \text{Mff}) (1 + \text{Mf, res}) \text{TOGW}$
- **Mff ??? A & B ???**

# Preliminary Design (3)

## Determination of $M_{ff}$ :

- Fuel fraction method for  $M_{ff}$  (x of the  $M_{ffi}$ )
- Fuel unintensive segments (statistical data)
- Fuel intensive segments (Breguet eq. for R & E)
- FC → Breguet eq N/A → hand calculation
- $M_{ff} = 0.9919$

# Preliminary Design (4)

## Determination of A & B :

- Correlation :  $\log \text{TOGW} = A + B \log \text{WE}$
- Problem : statistics N/A to UAV (mini !!)
- Own data base with electrical UAV & mini
- Small error for our PEMFC but PD 1
- $A = 0.1937$  &  $B = 1.0094$

# Preliminary Design (5)

## Results :

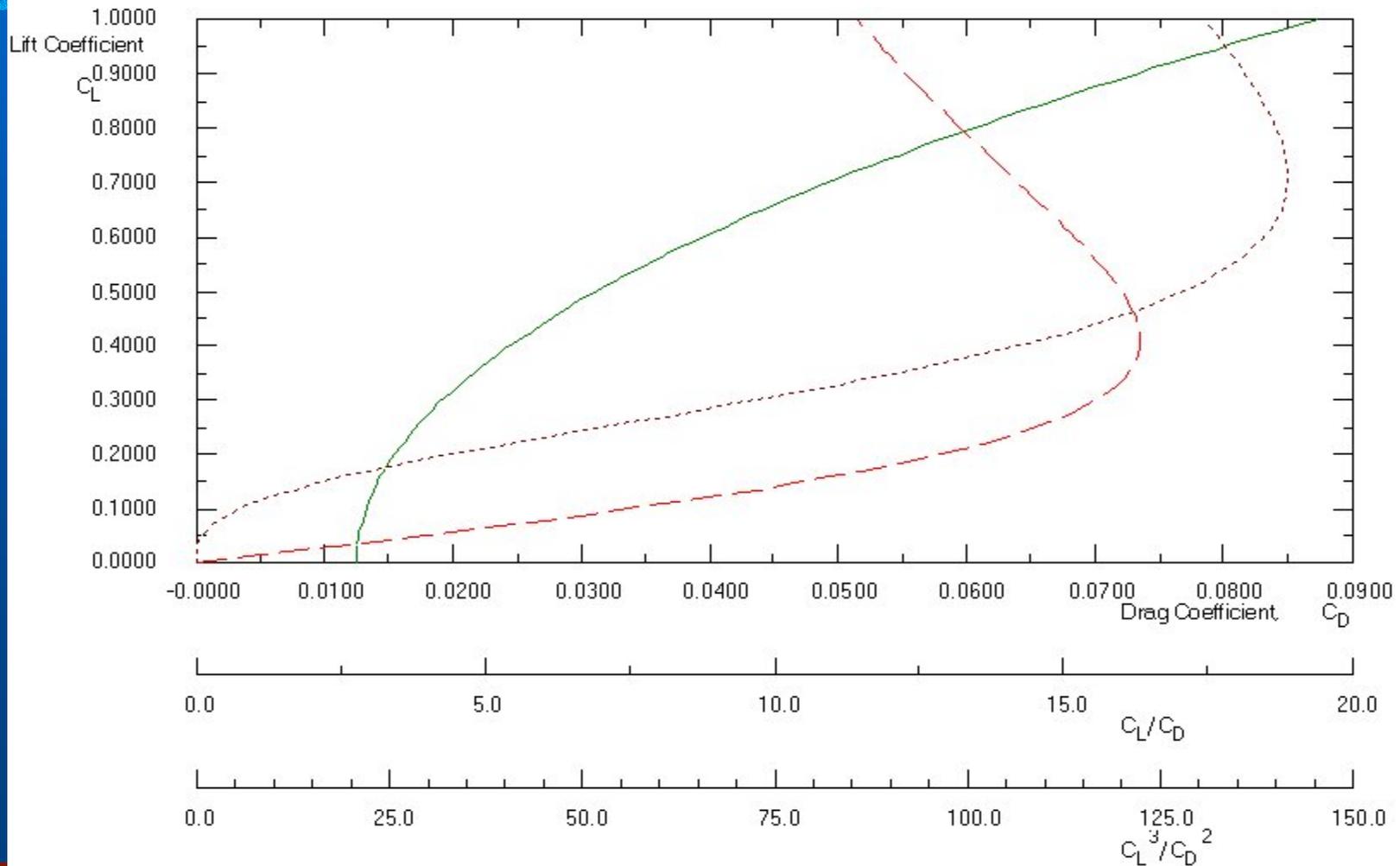
- TOGW = 3.97 kg
- WE = 2.92 kg
- FW = 32 g
- Compared with 3.1 kg, 2.1 kg and 23 g

# Preliminary Design (6)

## Estimation of the drag polar :

- $C_D = C_{D0} + \Delta C_{D0} + C_L^2 / (AR e \pi)$
- $C_{D0} = f / S_w$  (parasite area (f) method)
- Rationals :  $\log S_{wet} = c + d \log TOGW$  or  $\log f = a + b \log S_{wet}$  (a, b, c & d based on Cf)
- **AGAIN PROBLEM (due to FW configuration)**
- Other method : for FW,  $S_{wet}/S_w \sim 2.1$  (with SM)
- FW data  $\rightarrow AR = 5$  &  $e = 0.85$
- Try various  $S_w \rightarrow S_w = 0.45 \text{ m}^2 \rightarrow C_D$
- $C_D = 0.0125 + 0 + 0.0749 C_L^2$

# Preliminary Design (7)

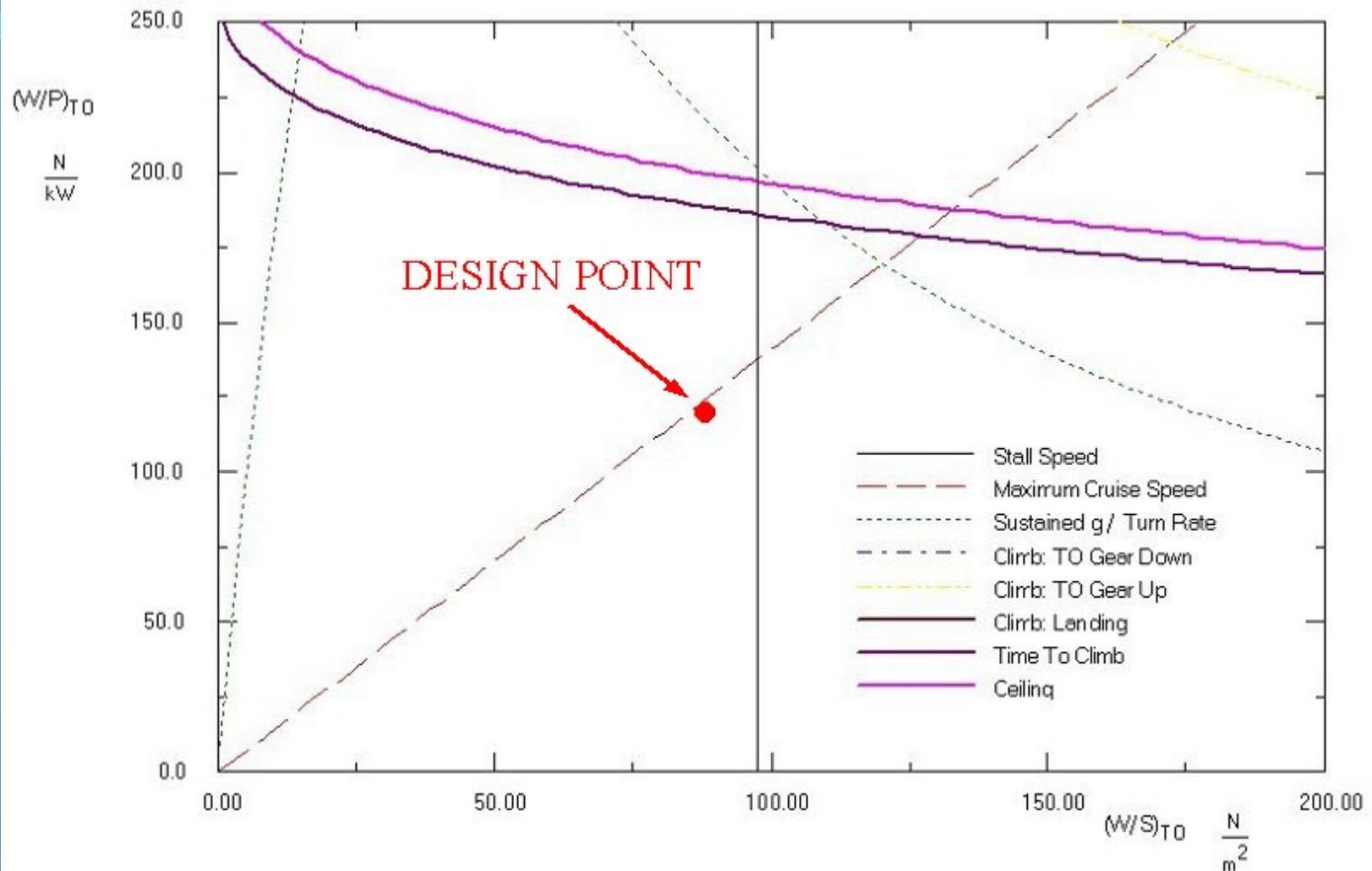


# Preliminary Design (8)

## Performance sizing :

- Restrictions on W/S at TO & W/P at TO
- Catapult launch & ventral or “net” ldg
- $V_s$  in cruise & MTOGW : 12.1 m/s
- Climb : grad (Mil Specs) & Tcib of 2'
- Max cruise speed at MTOGW
- Maneuvering distance :  $n_{max} = 2.0$  at MTOGW

# Preliminary Design (9)



# Preliminary Design (10)

## Performance sizing :

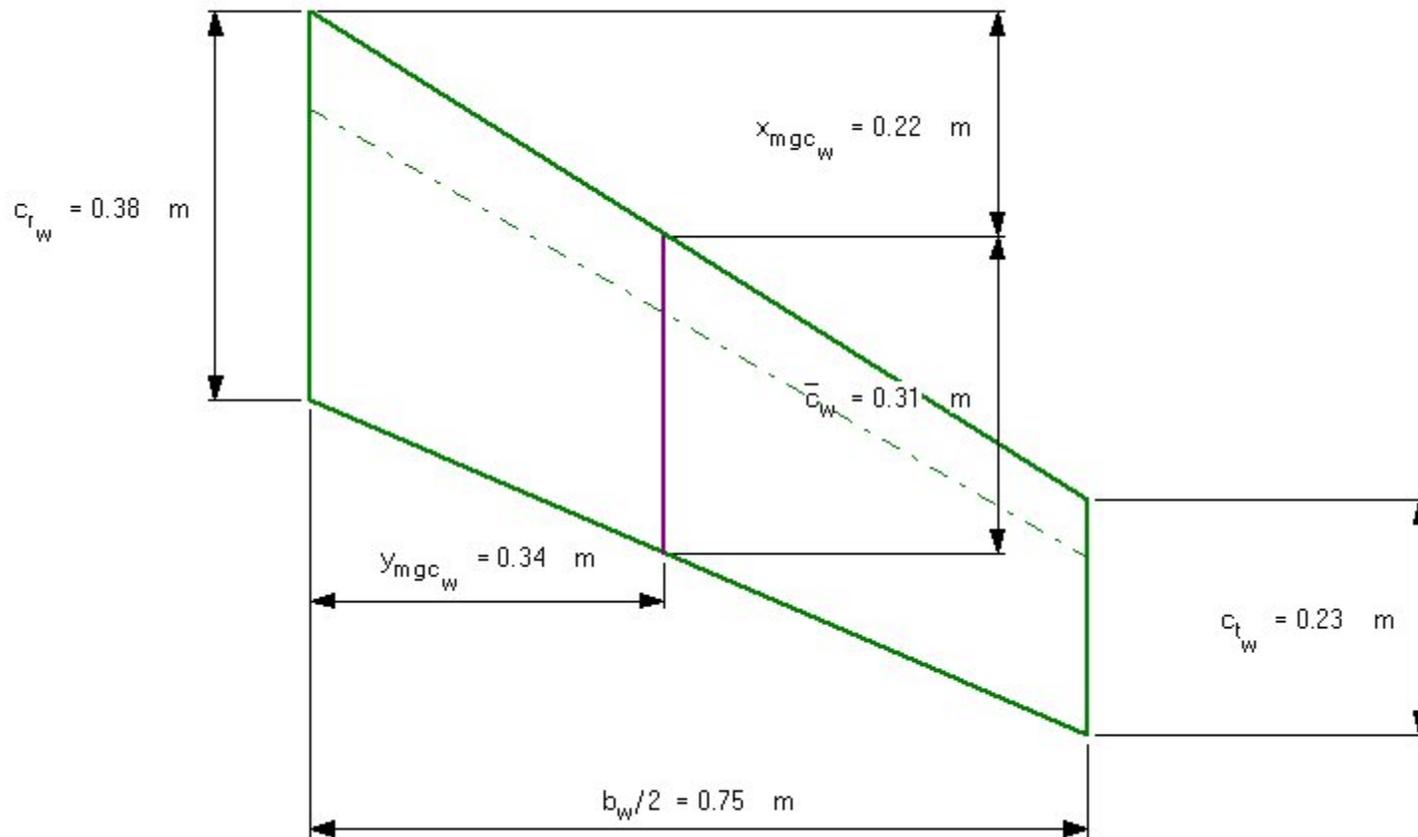
- Try different  $S_w$  in order to increase performance and minimize engine
- Final results :  $(W/S)_{TO} = 86 \text{ N/m}^2$  &  $(W/P)_{TO} = 120 \text{ N/kW}$
- Power of the PEMFC = 325 W + 50 for acc
- We had selected one of 450 W  $\rightarrow$  SF = 1.2

# Selection of the wing (1)

## Wing profile :

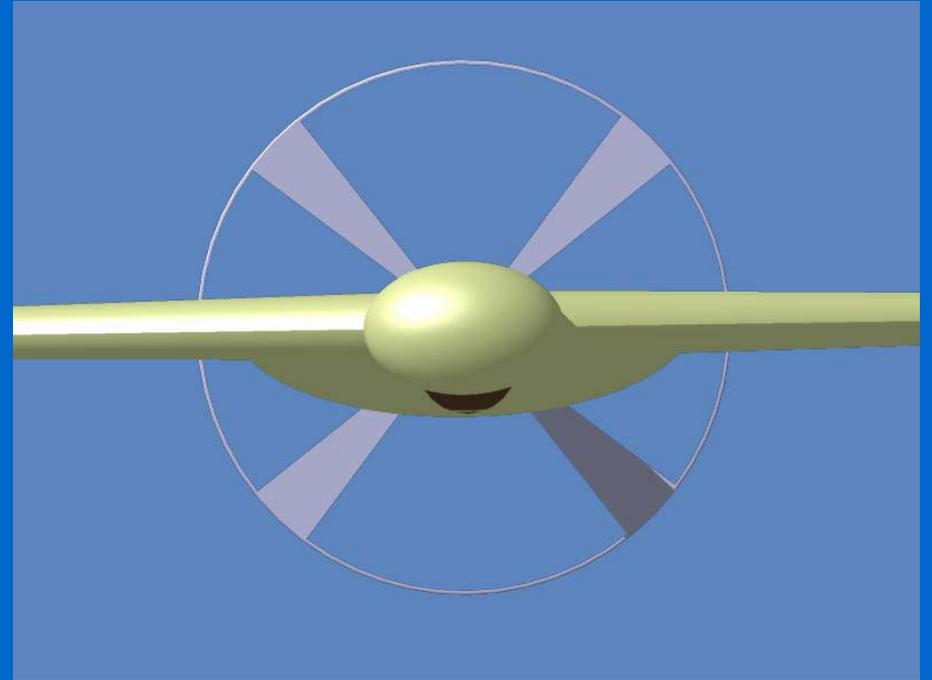
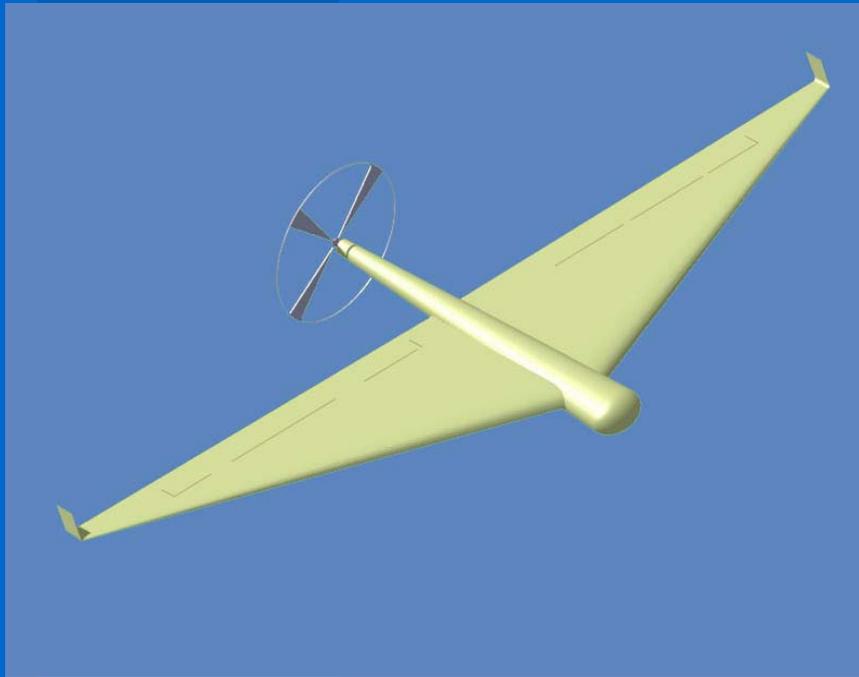
- Need of a fuselage (integrated in the planform)
- $C_{lmax}$  in accordance with sizing requirements
- $C_{lmax} \sim 1$
- High taper ratio in order to decrease trim drag but “neglectible” here
- $\frac{1}{4}$  chord sweep (stability with 2-cambered profile)
- Eppler 325,  $AR = 0.6$ ,  $\Lambda = 30^\circ$  ( $C_{lmax} = 0.96$ )

# Selection of the wing (2)

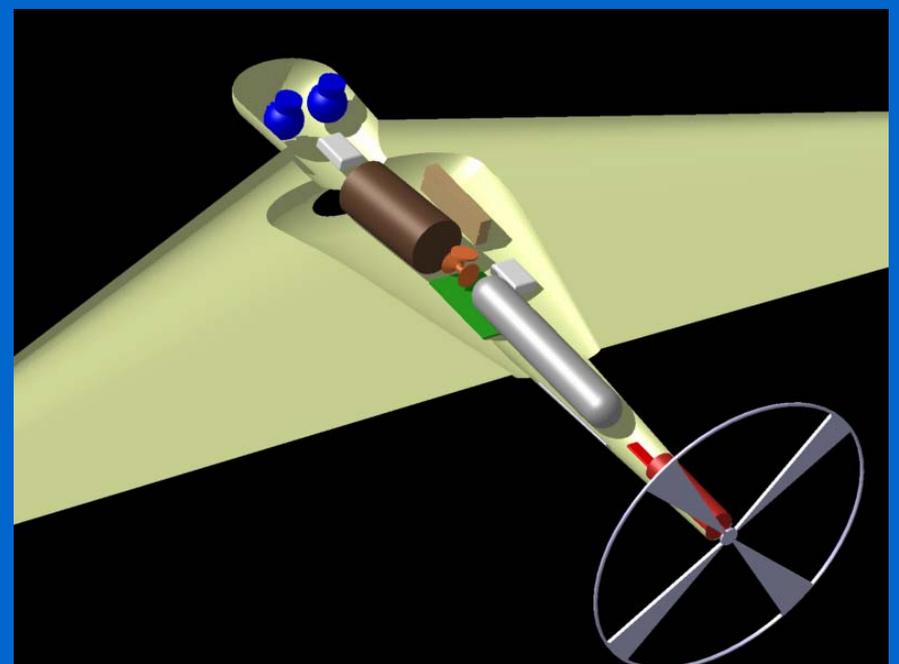
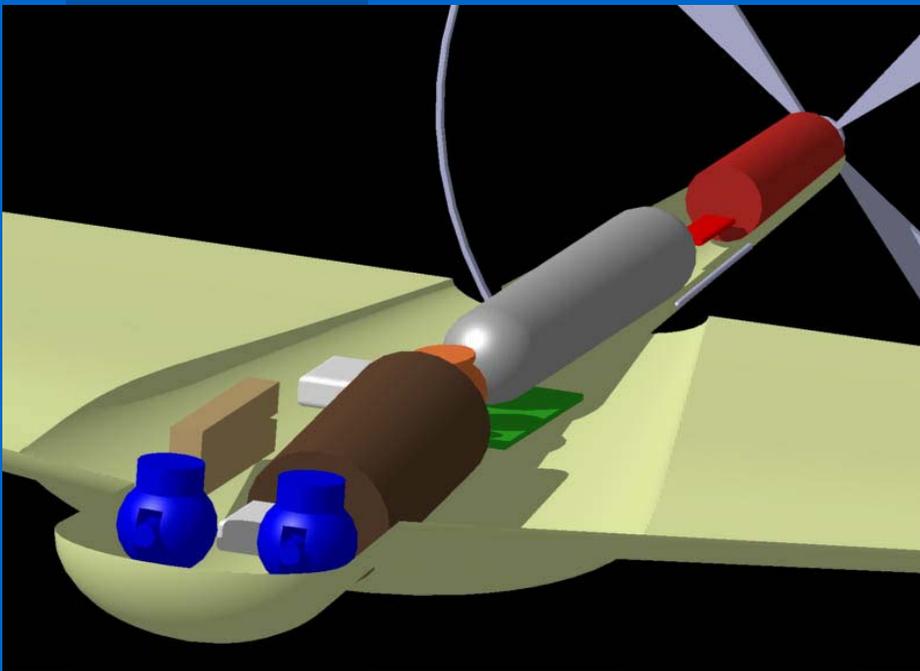
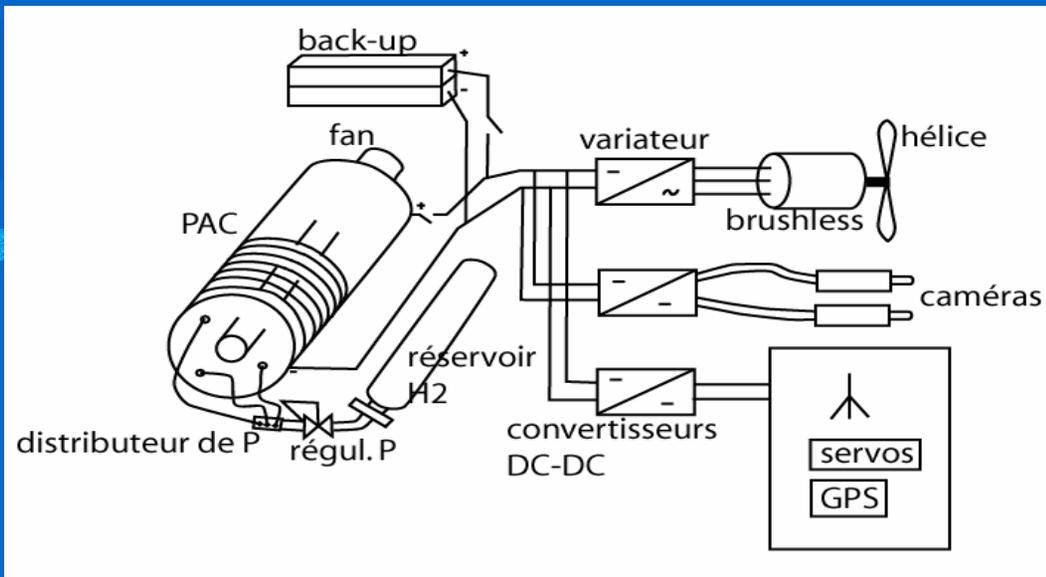


# Mini-UAV

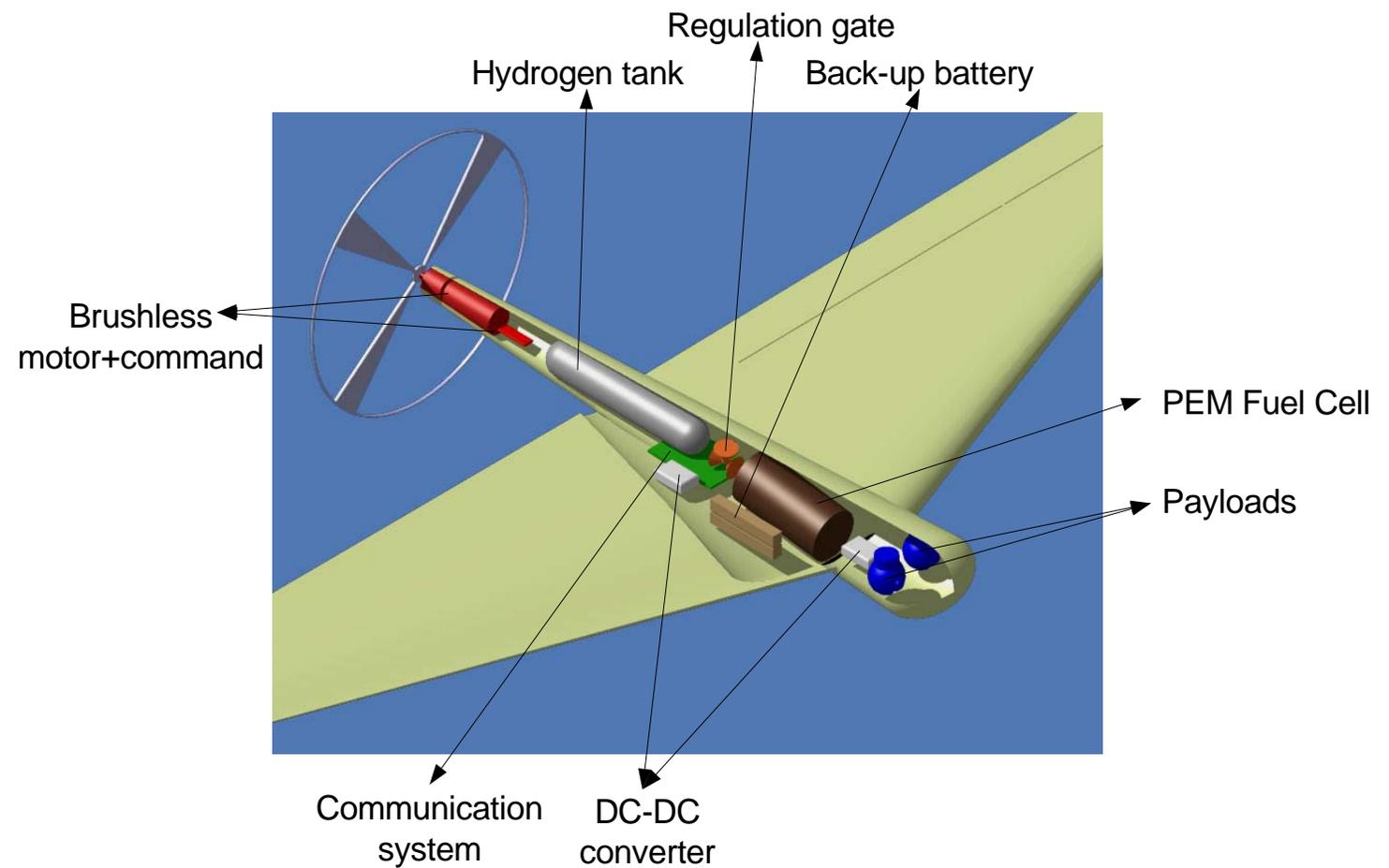
**Configuration : flying wing with winglets**



# Internal Elements : energy distribution

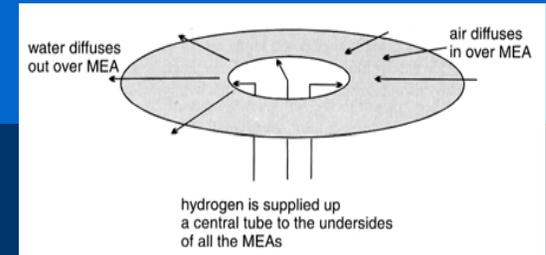


# Internal architecture



# PEMFC stack by Novars GmbH

- PEMFC of 600W
- $V_c = 0,6V$  ,  $V_{tot} = 24V$  (40 cells)
- mass = 780g
- $\varnothing = 110mm$
- $L = 200mm$  ↓



Special architecture

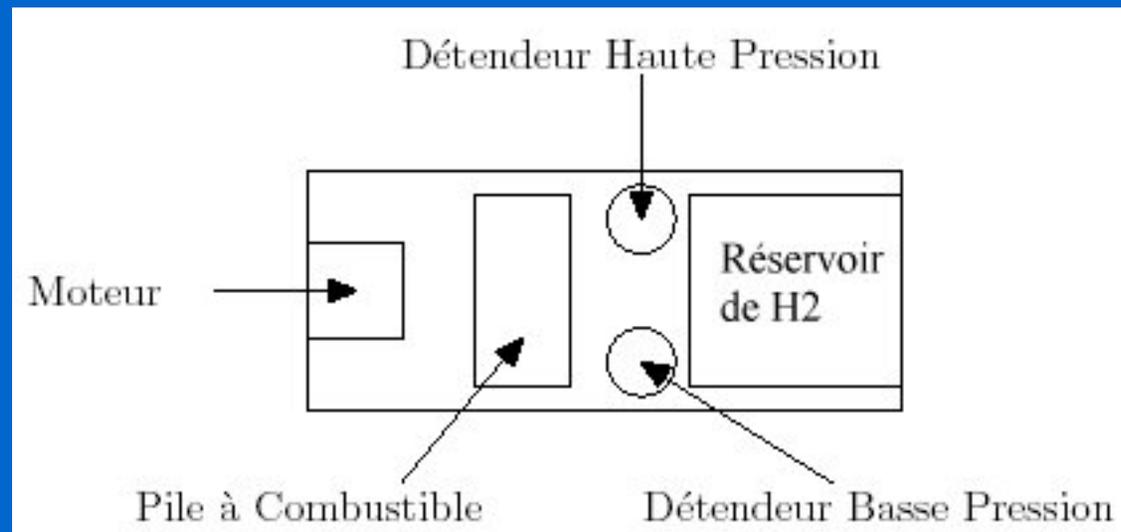


Complete system :  
220 Wh/kg energy density  
2,27 kg mass system

# Longitudinal Stability

**StM :**

- 4.8 cm
- 16.4 %

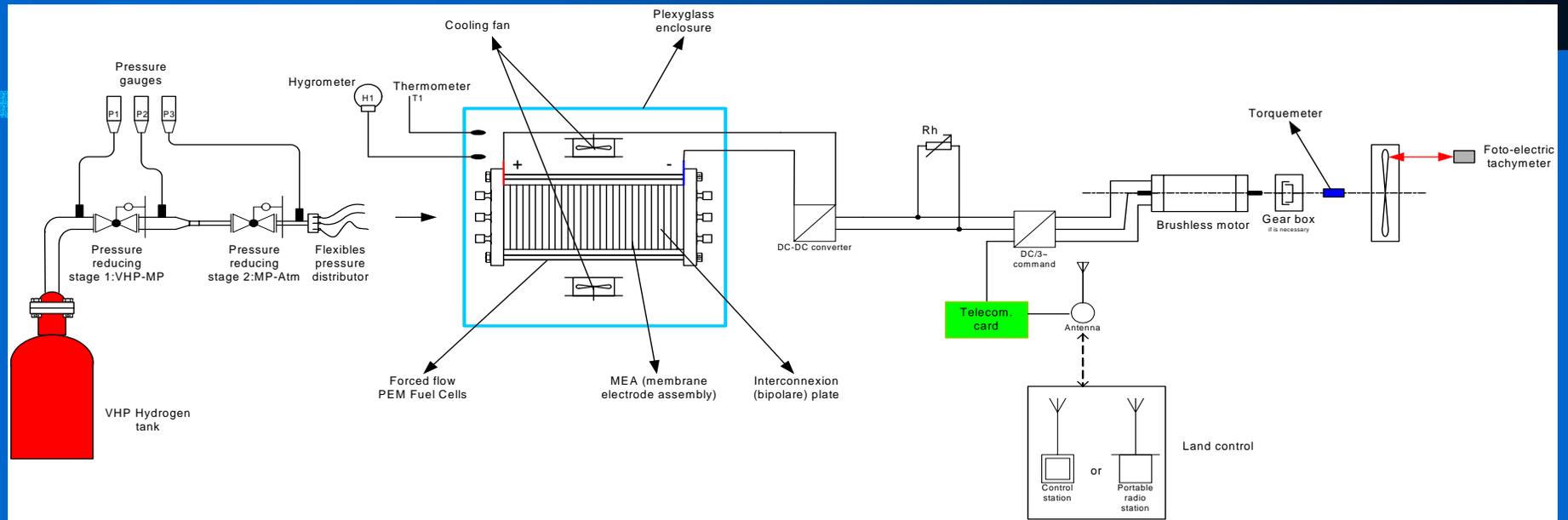


# Comparison with the Dragon Eye

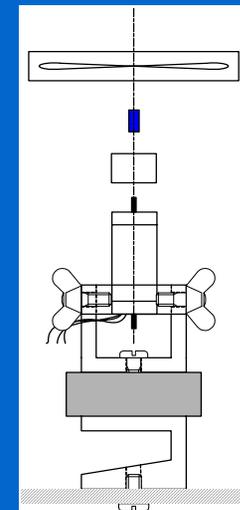
	Dragon Eye	MAV PAC
Wingspan [m]	1,14	1,5
Speed [m/s]	18	18 max
Range [min]	60	60
<b>Masses [g]</b>		
Propulsion System	1350	2620
Complete Aircraft	2150	3950
Power [W]	300	450

# The test bed at RMA

## ● Schematic



Thrust  
measurement  
system



# Our Fuel Cell

## Technical datas

PEMFC stack of 500 We

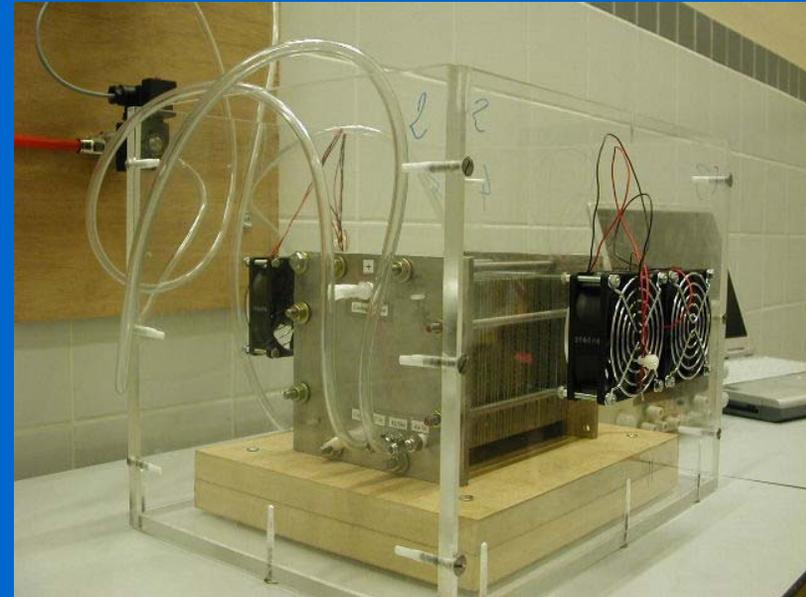
32 cells and  $V_c=0.625V$  so  
 $V_{tot}=20 V$

A current of 25A is available

The mass is about 6kg (power  
density 3 x lower)

Cooling system:

- <200We forced air by 4 fans
- >200We forced air+distilled water system



# Conclusions (1)

- **1st : Basic calculations in order to check the feasibility**
- **Compatible PEMFC are available (\$ !!)**
- **2nd : More detailed calculations (AAA)**
- **Planform determined & stability possible**
- **Test Bench : Acquire knowledge about small PEMFC in practice**

# Conclusions (2)

- **Improve current systems (fueling,storage,etc.) & control the required mass & volume of the whole propulsion system**
- **Miniaturise the complete propulsion system in a future exercise**
- **Increase the power density of complete FC propulsion system**
- **Future : other FC options**
- **Thanks to a few students from Fr & NI**

# Questions ?

