SUMMARY
OF
RESEARCH
2001

Department of Mechanical Engineering
Graduate School of Engineering and Applied Sciences

Terry R. Mc Nelley
Chair
Young Kwon
Associate Chair for Research

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Prepared for: Naval Postgraduate School
Monterey, CA 93943-5000
NAVAL POSTGRADUATE SCHOOL
Monterey, California

RADM David R. Ellison, USN
Superintendent

Richard Elster
Provost

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David W. Netzer
Associate Provost and
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### Summary of Research 2001, Department of Mechanical Engineering

**Faculty of the Naval Postgraduate School**

**Naval Postgraduate School**

Monterey, CA 93943-5000

This report contains project summaries of the research projects in the Department of Mechanical Engineering. A list of recent publications is also included, which consists of conference presentations and publications, books, contributions to books, published journal papers, and technical reports. Thesis abstracts of students advised by faculty in the Department are also included.
THE NAVAL POSTGRADUATE SCHOOL MISSION

Increase the combat effectiveness of the U.S. and allied forces and enhance the security of the U.S.A. through advanced education and research programs focused on the technical, analytical, and managerial tools needed to confront defense related challenges of the future.
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PREFACE

Research at the Naval Postgraduate School is carried out by faculty in the four graduate schools (School of International Graduate Studies, Graduate School of Operations and Information Sciences, Graduate School of Engineering and Applied Sciences, and Graduate School of Business and Public Policy) and three Research Institutes (The Modeling, Virtual Environments, and Simulation (MOVES) Institute, Institute for Information Superiority and Innovation (I2SI), and Institute for Defense System Engineering and Analysis (IDSEA)). This volume contains research summaries for the projects undertaken by faculty in the Department of Mechanical Engineering during 2001. The summary also contains thesis abstracts for those students advised by Mechanical Engineering faculty during 2001.

Questions about particular projects may be directed to the faculty Principal Investigator listed, the Department Chair, or the Department Associate Chair for Research. Questions may also be directed to the Office of the Associate Provost and Dean of Research. General questions about the Naval Postgraduate School Research Program should be directed to the Office of the Associate Provost and Dean of Research at (831) 656-2099 (voice) or research@nps.navy.mil (e-mail). Additional information is also available at the RESEARCH AT NPS website, http://web.nps.navy.mil/~code09/

Additional published information on the Naval Postgraduate School Research Program can be found in:

- **Compilation of Theses Abstracts:** A quarterly publication containing the abstracts of all unclassified theses by Naval Postgraduate School students.

- **Naval Postgraduate School Research:** A tri-annual (February, June, October) newsletter highlighting Naval Postgraduate School faculty and student research.

- **Summary of Research:** An annual publication containing research summaries for projects undertaken by the faculty of the Naval Postgraduate School.

This publication and those mentioned above can be found on-line at:
INTRODUCTION

The research program at the Naval Postgraduate School exists to support the graduate education of our students. It does so by providing military relevant thesis topics that address issues from the current needs of the Fleet and Joint Forces to the science and technology that is required to sustain the long-term superiority of the Navy/DoD. It keeps our faculty current on Navy/DoD issues, and maintains the content of the upper division courses at the cutting edge of their disciplines. At the same time, the students and faculty together provide a very unique capability within the DoD for addressing warfighting problems. Our officers must be able to think innovatively and have the knowledge and skills that will let them apply technologies that are being rapidly developed in both the commercial and military sectors. Their unique knowledge of the operational Navy, when combined with a challenging thesis project that requires them to apply their focused graduate education, is one of the most effective methods for both solving Fleet problems and instilling the life-long capability for applying basic principles to the creative solution of complex problems.

The research program at the Naval Postgraduate School consists of both reimbursable (sponsored) and institutionally funded research. The research varies from very fundamental to very applied, from unclassified to all levels of classification.

- Reimbursable (Sponsored) Program: This program includes those projects externally funded on the basis of proposals submitted to outside sponsors by the School’s faculty. These funds allow the faculty to interact closely with RDT&E program managers and high-level policymakers throughout the Navy, DoD, and other government agencies as well as with the private sector in defense-related technologies. The sponsored program utilizes Cooperative Research and Development Agreements (CRADAs) with private industry, participates in consortia with government laboratories and universities, provides off-campus courses either on-site at the recipient command, by VTC, or web-based, and provides short courses for technology updates.

- Naval Postgraduate School Institutionally Funded Research (NIFR) Program: The institutionally funded research program has several purposes: (1) to provide the initial support required for new faculty to establish a Navy/DoD relevant research area, (2) to provide support for major new initiatives that address near-term Fleet and OPNAV needs, (3) to enhance productive research that is reimbursably sponsored, and (4) to cost-share the support of a strong post-doctoral program.

In 2001, the level of research effort overall at the Naval Postgraduate School was 148 faculty work years and exceeded $48 million. The reimbursable program has grown steadily to provide the faculty and staff support that is required to sustain a strong and viable graduate school in times of reduced budgets. In FY2001, over 93% of the research program was externally supported. A profile of the sponsorship of the Naval Postgraduate School Research Program in FY2001 is provided in Figure 1.
INTRODUCTION

Figure 1. Profile of NPS Research and Sponsored Programs ($52M)

The Office of Naval Research is the largest Navy external sponsor. The Naval Postgraduate School also supports the Systems Commands, Warfare Centers, Navy Labs and other Navy agencies. A profile of external Navy sponsorship for FY2001 is provided in Figure 2.

Figure 2. Navy External Sponsors of NPS Research and Sponsored Programs ($29M)

These are both challenging and exciting times at the Naval Postgraduate School and the research program exists to help ensure that we remain unique in our ability to provide education for the warfighter.

DAVID W. NETZER
Associate Provost and Dean of Research

September 2002
DEPARTMENT OF
MECHANICAL ENGINEERING

TERRY MCNELLEY
CHAIR
DEPARTMENT SUMMARY

OVERVIEW:

The mission of the Department of Mechanical Engineering is to increase the combat effectiveness of U.S. and Allied armed forces and to enhance the security of the United States through advanced education that focuses on the ability to identify, formulate and solve technical and engineering problems in areas related to mechanical engineering and that spans issues of research, design, development, procurement, operation, maintenance and disposal of components and systems for Naval platforms.

RESEARCH MISSION:

The research mission of the Department of Mechanical Engineering is to increase the combat effectiveness of U.S. and Allied armed forces and to enhance the security of the United States through research in areas related to mechanical engineering and that spans the field from basic phenomena to engineering design, development, operation, maintenance and disposal of components and systems for Naval platforms.

CURRICULA SERVED:

The Mechanical Engineering Department serves the Naval and Mechanical Engineering Curriculum (570) and the Mechanical and Reactors Engineering Curriculum (571). Both curricula are in support of Navy needs for individuals having advanced technical education in mechanical engineering and related fields. The 570 Curriculum provides the educational component for the Engineering Duty Officer program and the research program in the Department is designed to support the requirement for Officers having the ability to identify, formulate and solve technical and engineering problems in areas related to mechanical engineering.

DEGREES GRANTED:

- Master of Science in Mechanical Engineering
- Mechanical Engineer
- Doctor of Philosophy
- Doctor of Engineering

RESEARCH THRUSTS:

There are five different disciplines of research thrusts such as Fluid Dynamics, Heat Transfer and Turbomachinery; Dynamics Systems, Controls and Robotics; Solid Mechanics, Vibrations, and Shock; Materials Science and Engineering; Total Ship Systems Engineering.

FACULTY EXPERTISE:

- Fluid Dynamics, Heat Transfer and Turbomachinery:
  Distinguished Professor Turgut Sarpkaya, Professor Matthew Kelleher, Associate Professor Knox Millsaps, Jr., Associate Professor Ashok Gopinath
- Dynamics Systems, Controls and Robotics:
  Professor Anthony Healey, Professor Morris Driels, Associate Professor Fotis Papoulias
- Solid Mechanics, Vibration, and Shock:
  Professor Young Shin, Professor Young Kwon, Associate Professor Joshua Gordis
- Materials Science and Engineering:
  Professor Terry McNeelley, Professor Alan Fox, Associate Professor Indranath Dutta
- Total Ship Systems Engineering:
  Professor Charles Calvano
DEPARTMENT SUMMARY

RESEARCH FACILITIES:

The Mechanical Engineering Laboratories are designed as complements to the educational mission and research interests of the department. In addition to extensive facilities for the support of student and faculty research, a variety of general use equipment is available. This includes equipment and facilities for the investigation of problems in engineering mechanics; a completely equipped materials science laboratory, including advanced scanning electron microscopes, an Auger microprobe, a transmission electron microscope and X-ray diffractometers; an oscillating water tunnel, a unique underwater towing tank and a low turbulence water channel; a vibration analysis laboratory; a fluid power controls laboratory; a robotics and real-time control laboratory; facilities for experimentation with low velocity air flows; equipment for instruction in thermal transport phenomena; a laser doppler velocimeter; nuclear radiation detection equipment and an interactive CAD/CAE computer graphics laboratory. Experimentation is further enhanced by a broad selection of analog and digital data acquisition and processing equipment and instrumentation.

RESEARCH PROGRAM (Research and Academic)-FY2001:

The Naval Postgraduate School’s sponsored program exceeded $49 million in FY2001. Sponsored programs include both research and educational activities funded from an external source. A profile of the sponsored program for the Department of Mechanical Engineering is provided below.

Size of Program: $1158K
FACULTY LISTING

McNelley, Terry R.
Professor and
Chair
ME/Mc
656-2589/2586
tmcnelley@nps.navy.mil

Kwon, Young
Professor and
Associate Chair for Research
ME/Kw
656-3385
ykwon@nps.navy.mil

Calvano, Charles N.
Professor
ME/Ca
656-2364
ccalvano@nps.navy.mil

Gopinath, Ashok
Associate Professor
ME/Gk
656-3400
gopinath@nps.navy.mil

Millsaps, Knox T.
Associate Professor
ME/Mi
656-3382
millsaps@nps.navy.mil

Driels, Morris R.
Professor
ME/Dr
656-3383
mrdrriels@nps.navy.mil

Gordis, Joshua H.
Associate Professor
ME/Go
656-2866
jgordis@nps.navy.mil

Papoulias, Fotis A.
Associate Professor
ME/Pa
656-3381
fapapoulias@nps.navy.mil

Dutta, Indranath
Associate Professor
ME/Du
656-2851
dutta@nps.navy.mil

Healey, Anthony J.
Professor
ME/Hy
656-3462
ajhealey@nps.navy.mil

Sarpkaya, Turgut
Distinguished Professor
ME/Si
656-3425
sarp@nps.navy.mil

Fox, Alan G.
Professor
ME/Fx
656-2142
fox@nps.navy.mil

Kelleher, Matthew D.
Professor
ME/Kk
656-2530
mkelleher@nps.navy.mil

Shin, Young S.
Professor and
Academic Associate
ME/Sg
656-2568
yshinr@nps.navy.mil
PROJECT SUMMARIES

JMEM AIR TO SURFACE TASKS 3,8,16
Morris Driels, Professor
Department of Mechanical Engineering
Sponsors: U.S. Army Material System Analysis Activity and Naval Postgraduate School

OBJECTIVE: To improve delivery accuracy methodology and to develop a real time DA capability.

SUMMARY: The first part of the project was to develop a spreadsheet that would compute delivery accuracy of unguided weapons. This was accomplished with the assistance of LT T. Smith. The second part was to begin translating this methodology into a c++ environment capable of being integrated directly into JAWS. The third task related to the analysis of accuracy for the AGM-65 Maverick missile, and the calculation of accuracy parameters for the JAWS program.

THESES DIRECTED:


DoD KEY TECHNOLOGY AREA: Computing and Software

KEYWORDS: Bombing Accuracy, Weaponeering

REVIEW AND IMPLEMENTATION OF MOUT DOCUMENTATION AND METHODOLOGY
Morris Driels, Professor
Department of Mechanical Engineering
Sponsors: U.S. Army Training Analysis Command-Monterey

OBJECTIVE: Review Army and SOF documents dealing with methodologies applying to MOUT.

SUMMARY: This was a small start up project to review available documentation for a proposal into the application of the Acquire target acquisition model to the MOUT environment. An FY02 proposal was submitted and subsequently approved.

THESES DIRECTED:


DoD KEY TECHNOLOGY AREA: Computing and Software

KEYWORDS: Target Acquisition, MOUT, Combat Modeling

WHITE PAPER ON THE JTCG/ME TRAINING AND EDUCATION REQUIREMENTS
Morris Driels, Professor
Department of Mechanical Engineering
Sponsors: U.S. Army Material System Analysis Activity

OBJECTIVE: To review the education and training requirements stemming from JTCG products and recommend a strategy for improvement.

SUMMARY: The JTCG/ME produces many operational products for all military services. At present training and education relating to these products is uncoordinated and sparse. The white paper will review existing training and educational programs relating to these products, identify potential shortcomings and recommend a strategy for improvement.
PROJECT SUMMARIES

DoD KEY TECHNOLOGY AREA: Computing and Software

KEYWORDS: Software, Education and Training, Weaponeering

INTERFACIAL SLIDING IN MULTI-COMPONENT SYSTEMS
Indranath Dutta, Associate Professor
Department of Mechanical Engineering
Sponsor: National Science Foundation

OBJECTIVE: To investigate the mechanisms of creep at interfaces of dissimilar materials.

SUMMARY: The goal of this project is to develop a phenomenological understanding of the mechanisms operative during sliding of interfaces at high temperatures. A combination of experimental and analytical means are being utilized to investigate the kinetics of interfacial sliding and its effect on thin film systems.

PUBLICATIONS:


PRESENTATIONS:

THESES DIRECTED:

DoD KEY TECHNOLOGY AREA: Materials, Processes and Structures

KEYWORDS: Composite, Multi-layers, Thin Films, Creep, Interfacial Sliding

THERMO-MECHANICAL BEHAVIOR OF SOLDER JOINTS FOR ELECTRONIC PACKAGING
Indranath Dutta, Associate Professor
Department of Mechanical Engineering
Sponsor: Unfunded

OBJECTIVE: To obtain a mechanistic understanding of the relationship between microstructural coarsening and applied constraints during thermo-mechanical cycling of solder joints.
PROJECT SUMMARIES

SUMMARY: Flip Chip and Ball Grid Array solder joints in electronic packaging applications are subjected to large imposed strains and temperature variations during service conditions. During cycling, the microstructure coarsens, plastic strains localize, and the solder joint eventually fails by low-cycle fatigue induced by permanent creep deformation. The purpose of this project is to understand the dependence of microstructural coarsening on the plastic strain state in a solder joint during thermo-mechanical cycling.

PUBLICATIONS:


THESES DIRECTED:


DoD KEY TECHNOLOGY AREA: Materials, Processes and Structures

KEYWORDS: Electronic Packaging, Solder, Thermal Cycling, Deformation

COMPOSITIONAL AND MICROSTRUCTURAL ANALYSIS OF ADVANCED ULTRA-LOW CARBON WELDMENTS

Alan G. Fox, Professor
Department of Mechanical Engineering
Sponsor: Naval Research Laboratory

OBJECTIVE: The objective of this work (which commenced in FY99) is to quantitatively advance the ability to understand, predict and control microstructural evolution and mechanical behavior in advanced, low carbon steel weldments produced with new ultra-low carbon (ULC) filler metals. In particular, the goal is to elucidate the effects of weld chemistry and weld thermal processing history on compositional, microstructural and mechanical properties variations across weldments and amongst different weldments and to use the experimental results both as input to, and as a direct quantitative test of detailed weld simulation models developed at NRL.

SUMMARY: The work at NPS will involve the use of high resolution analytical transmission electron microscopy to determine the microstructure and microchemistry as a function of position within different ULC weldments particularly with respect to carbon in the weld metal and oxygen in the non-metallic inclusions generated as a result of the welding process.

DoD KEY TECHNOLOGY AREAS: Materials, Processes and Structures

KEYWORDS: HSLA Steels, Welding, Ultra-Low Carbon Steel Weld, Electron Microscopy

THERMOFLUID AND THERMOMECHANICAL ISSUES IN ELECTRONIC PACKAGING

Ashok Gopinath, Associate Professor
Department of Mechanical Engineering
Sponsor: Unfunded

OBJECTIVE: To investigate the thermo-fluid and thermomechanical aspects of the electronic packaging of flip chips from a reliability viewpoint.
SUMMARY: This project was a continuation of the collaboration initiated in CY-2000 with Professor I. Dutta (also of the Department of Mechanical Engineering). Different topical areas were covered as follows:

(a) The flow characteristics of a liquid epoxy encapsulant designed as an underfill for flip chip devices was experimentally studied in a controlled manner. The area coverage by the underfill in capillary flow was measured as a function of chip bump pattern, point of application of underfill, and environment temperature. Observations of flow front uniformity and void formation were recorded which provide useful fundamental insight into the fluid filling challenges posed by continually reducing chip size.

(b) The effect of cycling of a localized heat source on the underside of a flip chip package die was studied in order to explore the possible formation of hot spots in the package resulting from heat flow inhibiting interfacial defects due to imperfect thermal contacts at key locations. An energy partitioning model was used to evaluate the reliability of the solder joints under such accelerated thermal fatigue cycling loads. The effects of different peak heat flux values, and thermal boundary conditions were investigated. The thermal results clearly show pronounced temperature gradients that can be induced within the package. The associated structural results applied to the damage model show that creep continues to be the primary mechanism of failure in the package.

(c) The role of underfill constraint in thermomechanical cycling was investigated in a controlled single joint shear experimental study to determine the extent of load transfer from the solder to the encapsulant. A finite element model was used to corroborate the essential deformation characteristics of the joint, and to provide insight into the experiments. The strain response of the solder joint was found to be significantly influenced by microstructural coarsening, which is countered by the hydrostatic stresses imposed by the underfill on the joint.

PUBLICATIONS:


Dunne, J.E., Smith, V.E., Gopinath, A. and Dutta, I., “Modeling the Effects of Cycling of a Localized Heat Source on a FCOC with Defects,” to be presented at the 52nd ECTC.

THESES DIRECTED:


DoD KEY TECHNOLOGY AREA: Other (Electronic Packaging)

KEYWORDS: Flip Chip, Electronic Packaging, Thermomechanical Fatigue, Underfill, Capillary Flow

TURBINE CONVECTIVE COOLING CONCEPTS EVALUATION

Ashok Gopinath, Associate Professor
Department of Mechanical Engineering
Sponsor: Naval Air Warfare Center – Aircraft Division and Defense Advanced Research Projects Agency

OBJECTIVE: To provide support and validatory analyses of ongoing work in a new MEMs-based micro-heat exchanger turbine cooling concept.
PROJECT SUMMARIES

SUMMARY: This project is a new start in FY-2001. The primary thrust of the project was to develop a multi-physics computational analysis of the proposed heat exchanger design. The micro-heat exchanger is based on the concept of the use of pin fins in the narrow gap of a shroud enclosed turbine blade. A finite element numerical analysis based on the package ANSYS has been initiated to predict the flow and heat transfer characteristics of such a micro pin fin heat exchanger. In such a short pin fin enclosed array configuration, both the pins and the end wall make substantial contributions to the heat transfer which need to be identified. For the small pin fin size relative to the blade radius of curvature, a planar model was assumed and a fully three dimensional numerical analysis was carried out. Various streamwise and spanwise pin fin spacings were used to determine both row-averaged and array-averaged heat transfer coefficients for the heat exchanger. A range of flow Reynolds numbers was covered and the results corroborated with available data in the literature. The heat transfer performance was compared with overall pressure drop characteristics to predict an optimal configuration.

PUBLICATIONS:


THESES DIRECTED:


DoD KEY TECHNOLOGY AREA: Aerospace Propulsion and Power

KEYWORDS: Pin-Fin Array, Compact Heat Exchanger, Micro Heat Exchanger, Turbine Blade Cooling

EVALUATION OF COOLING TECHNOLOGIES FOR MAGNETORESTRICTIVE ACTUATORS

Ashok Gopinath, Associate Professor
Department of Mechanical Engineering
Sponsor: Naval Surface Warfare Center – Carderock Division

OBJECTIVE: To evaluate available cooling technologies that would work within the design constraints of magnetorestrictive actuators and maintain operating temperatures below a safe threshold.

SUMMARY: This project was a short term piece of work for NSWC carried out in CY-2001. The goal of the project was to investigate and recommend possible cooling technologies that would maintain the temperature of magnetorestrictive actuators under safe operating limits. After exploring various options, and keeping the design constraints in mind, it was recommended that for baseline use simple low maintenance off the shelf heat exchanger components with no moving parts be used for robust and reliable performance of the actuator in the harsh environments envisioned. It was found that the basic cooling needs could be met with an extended surface natural convection cooling design such as a press fitted pin fin assembly. The working constraints were that the ambient temperature could be a high as 35°C while the actuator temperature was not to exceed 95°C, and that the final package was to fit within a cylindrical package of dimensions no more than one foot in length and diameter. Sample baseline calculations were provided for a typical case of an assembly of 35 circular/annular aluminum fins that could provide a heat transfer rate of as much as 650W. In addition, active cooling enhancement strategies were recommended through the use of vortex tubes that work off standard high pressure air lines to provide a jet/stream/curtain of cold air. It was suggested that strategically located vortex tubes could be used to provide an empirically calibrated blast(s) of cold air on the actuator along the length of its travel to maintain its temperature within safe operating limits.
EFFICIENT NONLINEAR TRANSIENT DYNAMIC ANALYSIS FOR STRUCTURAL OPTIMIZATION USING AN EXACT INTEGRAL EQUATION FORMULATION

Joshua H. Gordis, Associate Professor
Department of Mechanical Engineering
Beny Neta, Professor
Department of Applied Mathematics
Sponsor: National Science Foundation

OBJECTIVE: This project is concerned with the theoretical development and computational implementation of a time domain theory for locally nonlinear transient structural synthesis. Application principally will be made to seismic isolation.

SUMMARY: This research concerns the continued development of a time domain theory for structural synthesis. This theory provides the previously unavailable capability of performing exact damped transient structural synthesis for systems with localized nonlinear components with the order of the synthesis being independent of model size. The method is based on Volterra integral equations derived from the convolution integral which describe substructure coupling and structural modification. Current results demonstrate an order of magnitude reduction in compute times as compared with widely-used commercial finite element analysis packages. The use of the formulation for the optimal design of seismic isolation is under development. The algorithm has been extended to treat nonlinear memory-type elements (e.g. elastoplastic hysteretic).

PUBLICATIONS:


THESIS DIRECTED:


DoD KEY TECHNOLOGY AREA: Modeling and Simulation

KEYWORDS: Structural Dynamics, Transient Response, Nonlinear Dynamics, Seismic Isolation
PROJECT SUMMARIES

DESIGN OF LAB-SCALE MODEL TEST OF ISOLATION FOR ROLL-ON ROLL-OFF (RORO) RAMP
Joshua H. Gordis, Associate Professor
Fotis A. Papoulis, Associate Professor
Department of Mechanical Engineering
Sponsor: Naval Surface Warfare Center - Carderock Division

OBJECTIVE: The objective of this project was to perform frequency response analysis of the DTMB runs 1-503 and NRL runs 1-217 of the T-ACS seakeeping experiments.

SUMMARY: In Sea State 3 and above, the stern ramp of the Cape T ship is vulnerable to an over-stress condition when off-loading vehicles. Therefore, there exists a need to design motion-compensation devices ("isolation") which when placed between the end of the ramp and the barge, precludes the possibility of a ramp over-stress condition. Parallel to analytical studies conducted under separate funding, there is a need to establish an accurate and cost-efficient experimental set-up in order to validate the theoretical models. This need is addressed in this work. A basic experimental configuration has been designed and built. Actual testing and data analysis is set to begin during the month of February. Further data analysis and conclusions along with recommendations of the most promising designs will be reported during this year.

THESIS DIRECTED:


DoD KEY TECHNOLOGY AREA: Surface/Under Surface Vehicles - Ships and Watercraft

KEYWORDS: Frequency Response, Seakeeping, Vibration Isolation, Testing and Evaluation

MOTION MINIMIZATION IN HIGH SPEED TOWING OPERATIONS
Joshua H. Gordis, Associate Professor
Fotis A. Papoulis, Associate Professor
Department of Mechanical Engineering
Funding: Office of Naval Research

OBJECTIVE: The objective of this project was to support the Office of Naval Research in further development of the novel SLICE hull form with a trailer hull.

SUMMARY: The focus of this project was on a hinge connection between the “tractor” and “trailer” SLICE vessels. This provides a number of technical challenges in high-speed high sea state ocean towing systems that have not been studied in the past. A model describing the dynamics of the two bodies under tow was developed. A series of runs was conducted in order to gain some insight into the seakeeping behaviors of the two ships. A generic spring/damper connection was assumed to exist at the interface. Current studies aim at more realistic configurations, along with the establishment of a design and analysis procedure in order to quantify the performance degradation in a seaway. A simulation model for low frequency motions was also developed, and a comprehensive stability analysis is underway.

THESIS DIRECTED:


PROJECT SUMMARIES

DoD KEY TECHNOLOGY AREAS: Surface/Under Surface Vehicles - Ships and Watercraft

KEYWORDS: Towing, Seakeeping

REDUCING RAMP STRESS LEVELS VIA SEMI-ACTIVE DAMPING
Joshua H. Gordis, Associate Professor
Fotis A. Papoulias, Associate Professor
Department of Mechanical Engineering
Sponsor: Naval Surface Warfare Center - Carderock Division

OBJECTIVE: The current ramp design used in roll-on roll-off (RORO) operations has been determined to be structurally inadequate in sea state 3. The overall objective of this continuing project is to determine the isolation properties that are required in order to reduce ramp stress levels below the allowable for worst-case loading.

SUMMARY: A mathematical model describing the fundamental physics of a ship/ramp/barge system, including a passive isolator, was developed. The model properly accounts for hydrodynamic proximity effects and structural coupling between the bodies. Preliminary parametric studies, utilizing a standard second order model for the frequency response properties of the connecting body, of the response amplitude operator of the ramp motion were performed for varying wave directions and isolator stiffness and damping. These were utilized for random wave analysis in standard fully developed seas. The results indicated that rational selection of isolator properties could result in significant reduction of motions and stress levels in the connecting ramp. Current efforts include incorporation of actual FEM results coupled with the existing hydrodynamic prediction models.

THESES DIRECTED:

DoD KEY TECHNOLOGY AREAS: Surface/Under Surface Vehicles - Ships and Watercraft

KEYWORDS: Frequency Response, Seakeeping, RORO Operations, Vibration Isolation

STUDIES IN INTELLIGENT CONTROL OF AUTONOMOUS VEHICLES
Anthony J. Healey, Professor
Department of Mechanical Engineering
Sponsor: Ford Motor Company

OBJECTIVE: This grant is in the support of research in the subject matter and serves to aid the ongoing programs in the Center for Autonomous Underwater Vehicle Research.

SUMMARY: This project has supported the purchase of radio ethernet communications devices and radio modem connections between the ARIES robot and a shore based operator station. Also, it has supported the purchase of mobile laboratory equipment necessary to the deployment of ARIES in Monterey Bay.

DoD KEY TECHNOLOGY AREA: Surface/Under Surface Vehicles, Ships and Watercraft

KEYWORDS: Autonomous Systems, Robotics, Vehicles, Navigation
PROJECT SUMMARIES

HYDRO-THERMAL VENT MAPPING WITH MULTIPLE AUTONOMOUS UNDERWATER VEHICLES (AUV)
Anthony J. Healey, Professor
Department of Mechanical Engineering
D. B. Marco
Center for Autonomous Underwater Vehicle Research
A. Pascoal
University of Lisbon, Lisbon, Portugal
Sponsor: Office of Naval Research

OBJECTIVE: The IST has been conducting missions in the Azores using a surface catamaran vehicle (DELFIM) with plans to add an underwater vehicle (MARIUS). NPS will provide the cooperating underwater vehicle ARIES which has a video capability and an acoustic modem for underwater communications.

The approach for mapping these shallow water vent areas will be to employ an echo sounder on the DELFIM to provide bathymetry and detect the presence and general location of clusters of vents. DELFIM will communicate the cluster location data information by acoustic and radio modems to the NPS ARIES AUV. The ARIES will have the capability to reacquire the vent area using its DGPS / Doppler / IMU navigational suite, and to conduct a survey of the local area with a video camera. ARIES will provide geolocated video images of the vents, taken from a slow speed local search at constant altitude.

A joint exercise was conducted with IST, NPS, and the University of the Azores during the month of August near the Island of Faial, Azores. The detail objectives were:

- Demonstrate two vehicle underwater communications.
- Obtain video confirmation of shallow water hydro-thermal vent activity using video with location obtained from an independent source.

SUMMARY:

- Navigational accuracy mostly errors < 5m obtained with GPS popup.
- Video acquisition obtained of vent area given position from an independent source. Vent bubbles were found.
- Acoustic communications between DELFIM and ARIES with FAU modem where each vehicle was operated under autonomous control.
- All commands were received successfully and acted upon with no retransmits. The commands were sent from the support ship to the DELFIM and then to ARIES. Ranges up to 700m with 2 vehicles underway.

For this mission, a pair of acoustic modems were installed on the ARIES and on the IST DEFIM autonomous surface craft. Two laptop computers were used on the research vessel ARQUIPELAGO and are referred to as the base station systems. One laptop is used for command and control directly to the ARIES controlling computer through a radio link while the vehicle is surfaced. The second laptop is a two part link using both radio and acoustic modem communications. Radio communications are used from the ARQUIPELAGO surface ship to the DELFIM, at which point the data is sent to an acoustic modem mounted below the craft and allows communications with the ARIES while it is submerged.

The current configuration of the acoustic modem allows sending character strings up to 256 characters in length per transmit. For reasons of future compatibility across different systems, NMEA style ASCII strings are used as a standard format for the messages defined. The general form of all messages sent or received from the modem are of the form:

PUBLICATION:


DoD KEY TECHNOLOGY AREAS: Surface/Under Surface Vehicles, Ships and Watercraft

KEYWORDS: Autonomous Underwater Vehicles, AUV, Hydro-thermal Vent Mapping
PROJECT SUMMARIES

TACTICAL DECISION AIDS USING MODELING AND SIMULATION
Anthony J. Healey, Professor
Department of Mechanical Engineering
Jane Wu, Contractor
Don P. Brutzman, Associate Professor
Department of Information Science
Sponsor: Office of Naval Research

OBJECTIVE: The goals are to develop Tactical Decision Aids for using small autonomous underwater vehicles (AUVs) in very shallow water (VSW) environments. TDAs enable operators to view data gathered by these vehicles and make informed decisions as to the conduct of mine countermeasures operations. The current tactical decision aids system used by the U.S. Navy for mine countermeasures is a system named MEDAL (Mine Warfare Environmental Decision Aids Library). MEDAL is a software package running inside the GCCS-M global command and control system used by Navy ships. It is used to evaluate asset positions, minelike contacts, snippet images of contacts, snippet images of those contacts later identified as mines, and bathymetry maps. Other data such as bottom typing may be displayed if available. The objectives include the timely gathering of AUV data, converting, archiving, and translating it into the form familiar in MEDAL to Naval operational personnel. The goal is to improve the timeliness of data gathering including the post processing of sonar and video images for import into MEDAL. Long term goals are to integrate 3D visualization of data to enhance decision making, particularly in regard to deciding whether a contact is in fact a mine.

One issue in this project is how to deal with data from unclassified assets that are in development from university institutions, translate into the form used by MEDAL, and import the results into the classified Navy systems used in the fleet. To this end we have defined an automated data server system (ADS) that is linked through a local area network (LAN) to a stand alone MEDAL system. The MEDAL system runs on a TAC4 or better HP workstation. At the present time, it only runs on the HP systems with the 10.20 OS and the GCCS-M operating system. The ADS has been refined and is now interactive through screen entry from an operator. Future versions will be automated without operator intervention so that the software could run control of the system of the AUVs. The ADS allows the operator to view data through a VRML 3D viewer in which models of vehicles and contacts can be seen thereby extending MEDAL into 3D views.

SUMMARY: The initial version of the ADS has been developed and demonstrated during both Fleet Battle Exercise Hotel and its rehearsal. This initial version uses operator intervention to gather and translate AUV data into MEDAL format. During the demonstrations, data gathered from the REMUS (SHARV), Morpheous, and Drake vehicles included track positions, bathymetry (water column depth) at each track point, and, after sonar and video data processing, the image files (jpeg / gif) for contacts and their locations. The data were converted into MTF message formats and imported into MEDAL. MEDAL data was available for the fleet operators to view and plan tasking for the vehicles.

Work conducted in FY 2001 included:
- purchase of a fast HP workstation to better allow display of bathymetry data files
- preparation and on site data gathering and display support for the Kernal Blitz 01 exercise in March at Camp Pendleton
- conducting a test with the NPS ARIES AUV with an aerial relay link to transmit data files from the surfaced vehicle to the command center.

An HP C3600 workstation was purchased and a version of MEDAL Build 7 was set-up running in an external drive. The data bases have been transferred in part from last years exercise - FBE-Hotel. In the new configuration, the data flow from the NPS ADS software is through a LAN connection, but there is still no direct connectivity between the post-processing workstations for the AUVs and the ADS. We developed a LAN connection with the REMUS console, but other vehicles such as the BPAUV were operated off shore and had no ability to transmit data back to the command and control center.

In addition to data gathering, and during the KB01 exercise held at Camp Pendleton March 2001, a series of experiments was run with the ARIES underwater vehicle (http://www.es.nps.navy.mil/research/auv/auvframes.html), its support boat, (a Boston whaler), the PELICAN aircraft, and the control station at the ONR base. The objective was to transfer an image file pre-stored on the ARIES AUV, through
the aircraft to the ONR base while the aircraft was flying an AROSS sensor mission and investigate transmit rate for distances over several kilometers.

The ARIES was towed to site on "White Beach" and from 1:00pm March 17, til 3:00 March 17, 2001, Regular communication links were obtained between the ARIES on board computers and the ONR base station set up on the Camp Pendleton BOQ.

PUBLICATION:


DoD KEY TECHNOLOGY AREAS: Surface/Undersurface Vehicles - Ships and Watercraft

KEYWORDS: Underwater Robotics, Mine Countermeasures, Modeling and Simulation, Graphics, Physics Based Models

MODELING OF FIRE AND SMOKE PROPAGATION IN SHIPBOARD SPACES

Matthew D. Kelleher, Professor
Department of Mechanical Engineering
Sponsor: Naval Sea Systems Command

OBJECTIVE: The overall objective of this work is to investigate the effects of survivability considerations on the design of ships. Specifically work has been continuing to investigate the modeling of smoke propagation in shipboard compartments and passageways. It is very important that an understanding of the propagation of fire and smoke in the various shipboard spaces be developed and that some means be developed to apply that understanding to incorporate survivability considerations in the design of future combatants and to the development of fire fighting procedures.

SUMMARY: The propagation of fire-generated smoke with a counter-flow air supply in a horizontal arrangement of shipboard compartments and passageways was modeled using a computational fluid dynamics program generated by Computational Fluid Dynamics Research Corporation. This study was based on a large-scale live fire experiment performed by Naval Research Laboratory on the ex-USS SHADWELL. All simulations were evaluated at steady state conditions. A constant velocity counter-flow air supply was introduced into the model structure. The counter-flow air velocities used were 0.5, 1, and 2 m/s. This study used a Computational Fluid Dynamics combustion module to simulate a 620 kW fire generated by the complete combustion of propene gas from a burn pan in the space. Carbon dioxide from the fire was tracked throughout the structure to model smoke propagation. Seven simulations were performed with adiabatic and isothermal bulkhead, deck and overhead boundary conditions. Simulation smoke propagation results were consistent with experimental observations. Figures depicting temperature distribution, carbon dioxide distribution and mixture flow patterns at specified locations are provided in the report. The goal of this study is to evaluate the effectiveness of computational fluid dynamics modeling of smoke propagation in a shipboard space with a counter-flow air supply.

THESES DIRECTED:


DoD KEY TECHNOLOGY AREA: Modeling and Simulation

KEYWORDS: Fire Propagation, Smoke Spread, Ship Survivability, Damage Control
PROJECT SUMMARIES

INVESTIGATION OF THE USE OF ARTIFICIAL NEURAL NETWORKS IN HEAT TRANSFER
Matthew D. Kelleher, Professor
Department of Mechanical Engineering
Sponsor: Unfunded

OBJECTIVE: The objective of this study is to investigate the feasibility of employing the neural network technique as a method of using experimental data to predict heat transfer behavior. Currently, data is acquired by experimentation, collected, and then correlated to one or more of the controllable inputs using some physical and mathematical insight. Experimental uncertainties in the data accumulation are coupled with the inherent uncertainties in the mathematical correlation.

It is the goal to use neural networks, to make the predictions of thermal fluid behavior more reliable, less reliant on assumptions, and provide easier methods of evaluating these predictions. With neural networks all of the above goals are possible.

SUMMARY: Artificial neural networks have been employed to develop a predictive algorithm using experimental heat transfer data for a complex situation. The from a series of experiments investigating the boiling heat transfer from a vertical bank of tubes in refrigerant 114 with variable amounts of oil present has been used to illustrate the process. Both finned and unfinned tubes were investigated. The network was trained with a partial set of the available data. The prediction obtained using the trained network was then compared to the remaining experimental data. The artificial neural network provided an excellent predictive method.

PUBLICATIONS:

DoD KEY TECHNOLOGY AREA: Modeling and Simulation

KEYWORDS: Artificial Neural Networks

MODELING AND SIMULATION OF DAMAGE AND CRACKS IN PARTICULATE COMPOSITE MATERIALS: EFFECTS OF PRESSURE LOADING
Young W. Kwon, Professor
Department of Mechanical Engineering
Sponsors: Air Force Research Laboratory and Naval Postgraduate School

OBJECTIVE: This was a continuing research project from past several years during which a numerical modeling and simulation technique, called a multi-level (micro-macro) technique, had been developed and evaluated against experimental results. This year's effort was to study the effect of pressure loading on damage initiation and growth and to model the effect in the damage mechanics.

SUMMARY: The stress-strain behavior of a particulate composite specimen under hydrostatic pressure was modeled using the multi-scale approach. The approach was developed in the past by the investigator. The damage was described at the micro-level analysis in terms of the respective damage of each constituent material. In the present study, a damage theory was developed based on the two components of strain energy density: dilatational and deviatoric energy densities. The dilatational energy associated with the hydrostatic pressure was assumed to hold back the damage initiation. As a result, a damage theory including the hydrostatic pressure effect was developed and tested against experimental data of a specimen with the star-shaped opening. The stress-strain curves predicted from the theory agreed well with the experimental curves.

The initial crack sizes at notch tips were predicted and compared to the experimental results with or without initial hydrostatic pressure. The predicted values compared very well to the test data. The crack
PROJECT SUMMARIES

formation occurred either at the root of the large semi-circular notch or at the root of the smaller radius section which connected the large semi-circular section and the straight section. The two locations competed each other. The sizes and locations of initial cracks were in good agreement between the experimental and numerical results.

PUBLICATIONS:


THESIS DIRECTED:


DoD KEY TECHNOLOGY AREA: Aerospace Propulsion and Power, Materials, Processes, and Structures, Modeling and Simulation

KEYWORDS: Particle Reinforced Composite, Solid Rocket Propellant, Damage and Crack, Modeling and Simulation, Initial Crack Size, Hydrostatic Pressure
PROJECT SUMMARIES

MODELING AND SIMULATION OF THE HUMAN THORAX UNDER BULLET IMPACT
Young W. Kwon, Professor
Department of Mechanical Engineering
Sponsor: Armed Forces Institute of Pathology

OBJECTIVE: This was a continuing research project from the previous years. This year's effort was to model the human thorax especially including major internal organs with protective body armors hit by high-speed bullets in order to evaluate potential injury.

SUMMARY: The finite element analysis model was developed for the human thorax of skeleton with internal organs. The skeleton includes ribs, sternum, vertebrae, vertebral discs, facet joints, costal cartilages, muscle, etc. while internal organs include the lung, heart, trachea, etc. Two different body armors, one with a Kevlar vest and the other with a vest and armor plate, were also modeled. The results of the computer model were compared to the experimental data obtained with human cadavers with body armors hit by bullets. In the model, the measured speed of the bullet was used. The comparison of accelerations in the sternums, spines, lung, and heart were very good. The pressure inside the heart compared well between the experimental and numerical results. Those results provided reliability of the developed computer model. The program was extended to include the head and neck injury including brain damage.

PUBLICATION:


THESIS DIRECTED:


DoD KEY TECHNOLOGY AREAS: Modeling and Simulation

KEYWORDS: Finite Element Method, Human Thorax Model, Body Armors, Dynamic Response

UNIT-CELL MODEL OF OPEN METALLIC FOAM
Young W. Kwon, Professor
Department of Mechanical Engineering
Sponsor: Unfunded

OBJECTIVE: This project was to develop a unit-cell model to compute the effective strength and stiffness of an open-cell metallic foam structure.

SUMMARY: Representative unit-cell models were developed for open cell metallic foams in order to predict their effective elastic moduli and the plastic collapse strengths. Two different open-cell metallic foams were considered. One was just open cell foam and the other was open cell foam filled with an elastic material. The models were based on the metallic frames consisting of edges of tetrakaidecahedron. The filling material was modeled as elastic foundation to the ligament frames. The frame structure of the unit-
cell was analyzed using the finite element method. The plastic collapse strength was determined when the joints of ligaments became plastic hinges under the assumption of elastic-perfectly plastic material behavior of the metallic material. Both elastic modulus and plastic collapse strength were computed using a single step of finite element analysis without any iterative or incremental procedure. In addition, a very small number of finite elements was used. As a result, the unit-cell is computationally very efficient. In order to assess the representative unit-cell models, experiments were also conducted. The experimental data agreed very well with the predicted values of both stiffness and strength.

PUBLICATION:


THESES DIRECTED:


DoD KEY TECHNOLOGY AREAS: Materials, Processes, and Structures

KEYWORDS: Metal Foam, Open-Cell, Unit-Cell Model, Effective Stiffness and Strength

MECHANICAL AND MICROSTRUCTURAL CHARACTERIZATION OF COMMERCIAL AA5083 MATERIALS

Terry R. Mc Nelley, Professor
Department of Mechanical Engineering
Sponsor: University of Texas - Austin and GM Research and Development Center

OBJECTIVE: The goals of this program are: to characterize the fundamental deformation mechanisms in grain-refined AA5083 aluminum alloy material during elevated temperature deformation; and to characterize the failure mechanisms in materials from various sources.

SUMMARY: Our current understanding of microstructural refinement by deformation and recrystallization is largely empirical and so the ability to predict and then produce refined microstructures for various purposes, such as superplasticity, is limited. Recently developed computer-aided electron backscatter diffraction analysis and orientation imaging microscopy (OIM) methods have been applied to the investigation of the mechanisms of grain refinement and grain boundary development during processing of AA5083. Materials have been examined following various thermomechanical treatments and deformation histories. Grain refinement occurs via particle stimulated nucleation of primary (discontinuous) recrystallization resulting equiaxed grains, a nearly random texture, and random disorientation distribution. During elevated temperature deformation dislocation creep is indicated by the formation of a <111> fiber texture while grain boundary sliding is marked randomizing of the initial texture. Thus, local deformation conditions can be monitored by texture analysis. Cavity formation can also be evaluated by OIM.

PUBLICATIONS:


PROJECT SUMMARIES


PRESENTATIONS:


THESIS DIRECTED:


DoD KEY TECHNOLOGY AREAS: Materials, Processes and Structures

KEYWORDS: Aluminum, Superplasticity, Recrystallization, Grain Boundaries, Thermomechanical Processing

ULTRA-FINE AND NANO-GRANU MICROSTRUCTURES BY SEVERE PLASTIC DEFORMATION

Terry R. Mc Nelley, Professor
Department of Mechanical Engineering
Sponsor: Unfunded

OBJECTIVE: The goal of this program is to determine mechanisms by which ultra-fine grain structures form in severely deformed materials, such as those processed by equi-channel angular (ECA) pressing.

SUMMARY: Ultra-fine grain sizes in the sub-micrometer or even nanometer range can be achieved in metallic materials by imposing extremely large plastic strains during deformation processing. Such grain refinement will result in drastic improvements in strength/toughness combinations for structural applications as well as in improved ductility during elevated temperature forming. Methods such as ECA pressing are required in order to impart stains large enough to produce such refinement. ECA pressing is accomplished by pressing a billet of material through a die having two channels, of equal cross section, that intersect at an angle. Such a billet experiences simple shear without change in cross-sectional area and so the process is amenable to repetition. Billet rotation between successive pressing operations allows the shear plane orientation to be changed in order to achieve further control of microstructural refinement. The characteristics of the grain structures and, especially, the nature of the grain boundaries produced by such processing have remained in question. However, grain-to-grain misorientations may be readily determined by newly developed computer-aided electron backscatter pattern (EBSP) analysis methods.
PROJECT SUMMARIES

PUBLICATIONS:


PRESENTATIONS:


DoD KEY TECHNOLOGY AREA: Materials, Processes and Structures

KEYWORDS: Aluminum, Grain Refinement, Nano-Grain Materials, Recrystallization, Grain Boundaries, Materials Processing

LOW OBSERVABLE MULTI-FUNCTION STACK (LMS) EXHAUST GAS SUPPRESSION AND SUPPORT OF AT-SEA TRIALS

Knox T. Millsaps, Associate Professor
Department of Mechanical Engineering
Sponsor: Naval Surface Weapon Center – Carderock Division

OBJECTIVE: To develop and demonstrate a gas turbine exhaust signature suppression system, which is capable of meeting specified infrared (IR) and radar cross-section (RCS) goals, under specific engine-imposed constraints and overall systems constraints that the system be integrated into a low observable topside.

SUMMARY: This was the final year of a 4-year advanced technology demonstrator (ATD) project to develop a low observable multi-function stack (LMS) as part of the series of ATDs to create integrated topside technology for the next generation of surface combatants. In previous years, the NPS part of this project was to create design concepts and develop supporting analytical codes for the preliminary design of enhanced mixing eductors, and to test and optimize cold-flow geometry for reducing plume radiation. These designs were next tested at larger scale at a hot-flow facility in Memphis with NPS assistance. Finally, last year the full-scale hardware was tested in an at-sea trial. NPS supplied engineering consulting services as well as integration advice throughout the project and was a member of the integrated product team (IPT).
PROJECT SUMMARIES

PUBLICATIONS:


THESIS DIRECTED:


DoD KEY TECHNOLOGY AREA: Other (Signature Control)

KEYWORDS: Propulsion, Signature, IR, Gas Turbines, Exhaust, Enhanced Mixing

REVIEW OF ADVANCED TECHNOLOGY GAS TURBINE RESEARCH AND DEVELOPMENT PROGRAMS

Knox T. Millsaps, Associate Professor
Department of Mechanical Engineering
Sponsor: Naval Systems Engineering Station

OBJECTIVE: To review and evaluate the current research and development program for the advanced technology gas turbine program for the U.S. Navy's surface fleet gas turbine life cycle manager and to make technical recommendations for program improvement.

SUMMARY: A review of the Condition Based Maintenance (CBM) program for gas turbines for both power and propulsion, which started in November of 2001, is in progress. The major area of interest is to develop a technology road map for interfacing component level engine CBM modules into the Navy's Integrated Condition Assessment System (ICAS). More specifically, a review of methods to determine degradation in compressor performance due to dirt and salt deposition is underway as is the modeling of sensor and performance measures.

DoD KEY TECHNOLOGY AREAS: Sensors, Modeling and Simulation, Other (Reduced Manning)

KEYWORDS: Propulsion, Gas Turbines, Condition Based Maintenance (CBM), Compressor Fouling

WEB-BASED NAVAL ARCHITECTURE FOR PD-21

Fotis A. Papoulias, Associate Professor
Department of Mechanical Engineering
Funding: Center for Naval Education and Training

OBJECTIVE: The purpose of this project was to develop a web based class on Naval Architecture in support of the PD21 and the TSSE programs.

SUMMARY: The purpose of this project was to develop a web based class on Naval Architecture in support of the PD21 and the TSSE programs. The outcome of this project was the development of a comprehensive web site on Naval Architecture, with over two thousand files, incorporating text, graphs, support information material, and fully interactive examples. The site is fully integrated into the Blackboard web based delivery system adopted by NPS.
PROJECT SUMMARIES

OTHER:
A fully functional web site, in essence an electronic textbook on Naval Architecture.


KEYWORDS: Naval Architecture, Web-based Instruction, Javascript

EXTENDED STATE SPACE MODELING OF RRDF INTERFACE
Fotis A. Papoulias, Associate Professor
Department of Mechanical Engineering
Funding: Naval Surface Warfare Center - Carderock Division

OBJECTIVE: The goal of this project was to develop a model in order to bridge the gap between existing constant coefficient time domain and more accurate hydrodynamic models.

SUMMARY: A mathematical model describing the fundamental dynamics in the interface problem between a ship, a barge, and a connecting ramp was developed and solved. The hydrodynamics for the ship and the barge were described by a 12-degree of freedom fully coupled model, which was based on potential theory and incorporated proximity effects. Ramp structural dynamics were studied by a finite element model, which was calibrated based on detailed studies of commercially available codes. The models were coupled together through a spring/damper and the solution of the system was obtained in both regular waves and a representative sea state. Parametric studies with regards to different coupling conditions proved that optimization based on either relative motions or ramp maximum stress is possible.

THESES DIRECTED:


DoD KEY TECHNOLOGY AREAS: Surface/Under Surface Vehicles - Ships and Watercraft

KEYWORDS: Frequency Response, Seakeeping, RORO Operations, Vibration Isolation

MOTION MINIMIZATION IN HIGH SPEED TOWING OPERATIONS
Fotis A. Papoulias, Associate Professor
Joshua H. Gordis, Associate Professor
Department of Mechanical Engineering
Funding: Office of Naval Research

OBJECTIVE: The objective of this project was to support the Office of Naval Research in further development of the novel SLICE hull form with a trailer hull.

SUMMARY: The focus of this project was on a hinge connection between the “tractor” and “trailer” SLICE vessels. This provides a number of technical challenges in high-speed high sea state ocean towing systems that have not been studied in the past. A model describing the dynamics of the two bodies under tow was developed. A series of runs was conducted in order to gain some insight into the seakeeping behaviors of the two ships. A generic spring/damper connection was assumed to exist at the interface. Current studies aim at more realistic configurations, along with the establishment of a design and analysis
procedure in order to quantify the performance degradation in a seaway. A simulation model for low frequency motions was also developed, and a comprehensive stability analysis is underway.

THESES DIRECTED:


DoD KEY TECHNOLOGY AREAS: Surface/Under Surface Vehicles - Ships and Watercraft

KEYWORDS: Towing, Seakeeping

MECHANISM OF SPRAY GENERATION AT THE FREE SURFACE OF LIQUID JETS
Turgut Sarpkaya, Distinguished Professor
Department of Mechanical Engineering
Sponsor: Office of Naval Research and Naval Postgraduate School

OBJECTIVE: This continuing basic research is an experimental investigation of the ligament and drop formation at the free surface of liquid wall jets, flowing over smooth and sand-roughened plates towards the understanding of the physics of droplet formation, in general, and of the spray formation on bow-sheets, in particular.

SUMMARY: Measurements were made with several high-speed imagers, a pulsating laser, and a Digital Particle Image Velocimeter (DPIV) system and analyzed through the use of appropriate software. The wall-jet Reynolds number ranged from $2.4 \times 10^4$ to $4 \times 10^4$, the Froude number from 15 to 30, and the Weber number from 1,500 to 3,000. The characteristics of the ligament forest and droplets were determined from the digitized images. Principal Investigator was invited to deliver two papers at two ONR meetings: at CALTECH in April 01 and in San Diego in September 01.

PUBLICATIONS:


THESIS DIRECTED:


DoD KEY TECHNOLOGY AREA: Surface/Under Surface Vehicles - Ships and Watercraft

KEYWORDS: Hydrodynamics, Drop Formation, Spray
PROJECT SUMMARIES

OPTIMIZATION OF SUBMERGED SENSOR STABILITY
Turgut Sarpkaya, Distinguished Professor
Department of Mechanical Engineering
Sponsor: Space and Naval Warfare Systems Center - San Diego

OBJECTIVE: To provide expert advice and make recommendations to improve and/or optimize the stability of sensors immersed in earth’s magnetic field at the ocean bottom as part of deployable autonomous distributed system (as part of a deployable autonomous distributed system). Review the final report of SNWSC and offer advice for improvement.

SUMMARY: The Space and Naval Warfare Systems Center San Diego (SSC SD) is tasked by the Deployable Autonomous Distributed Systems Demonstration (DADS-D) project to mitigate sensor noise caused by hydrodynamic effects. The immediate concern is the extreme sensitivity of the fluxgate magnetometers (housed in sea-floor packages) to motion due to surface waves, currents, and the passage of non-naval bodies. This investigator has identified the nature of the relevant hydrodynamic disturbances, the hydrodynamic forces acting on a sensor package, effects of sensor proximity to the seafloor, any data in the literature relevant to the shape of the sensor package, and the frequency phenomena related to vortex shedding and surface waves.

PUBLICATIONS:


DoD KEY TECHNOLOGY AREAS: Modeling and Simulation

KEYWORDS: Sensors, Unsteady Flows, Stability, Frequency Response

REVIEW OF HYDRODYNAMIC LOADS ON SPECIFIC STRAINERS
Turgut Sarpkaya, Distinguished Professor
Department of Mechanical Engineering
Sponsor: U.S. Nuclear Regulatory Commission

OBJECTIVE: To review the appropriate topical reports and any other relevant data on hydrodynamic loads on structures submerged in the pressure suppression pools of boiling-water nuclear reactors. The ultimate purpose of these reviews and detailed analyses is to provide sound technical advice to NRC on unsteady flow about specific types of strainers and, in particular, on the prevailing Keulegan-Carpenter numbers and acceleration drag loads so that NRC can perform its regulatory duties in the light of the expert opinion and complete its review of the strainers under their consideration.

SUMMARY: A thorough study of about 3,000-page reports and papers led to the conclusion that the determination of the typical values of the Keulegan-Carpenter number, $K$, and the acceleration drag coefficient, $C_a$, for the conditions expected following a loss-of-coolant accident (LOCA) and safety/relief valve (SRV) discharge requires the load carrying capacities (LCCs) of the strainers, the positions of the largest stresses on the strainers and/or their attachments; the velocities, accelerations, (their magnitudes and directions) and their distribution throughout the suppression pool during the first few seconds of LOCA and
PROJECT SUMMARIES

SRV. In summary, the existing analyses and experiments are inadequate for the assessment of the safety of the strainers in Boiling-Water Nuclear Reactors. Proper analyses and experiments have been performed to provide sound technical guidance to NRC towards the fulfillment of its regulatory duties.

PUBLICATIONS:


THESIS DIRECTED:


DoD KEY TECHNOLOGY AREAS: Modeling and Simulation

KEYWORDS: Nuclear Reactors, Inertial Force, Perforated Bodies, Unsteady Flow

THE WAKE MODELING AND PREDICTION FOR AVOSS

Turgut Sarpkaya, Distinguished Professor
Department of Mechanical Engineering
Sponsor: National Aeronautics and Space Administration - Langley Research Center

OBJECTIVE: The purpose of the investigation was (a) to develop a new vortex decay model for the prediction of the descent of aircraft trailing vortices subjected to realistic environmental conditions (stratification, turbulence, cross wind, headwind, shear effects, and ground effect), and (b) to apply the model to field data obtained with Lidar in Memphis and Dallas-Fort Worth airports.

SUMMARY: A robust and relatively simple physics-based vortex decay model has been devised. It does not violate any hydrodynamical principles, has only one model constant, uses the turbulence eddy dissipation rate in conjunction with a theoretical model (as verified by experiments and numerical simulations), and it requires no cumbersome algorithms to account for the ground effects. Acquisition of better and more detailed field data (vortex velocities and positions; wind, shear and their gradients; better temperature, humidity, and eddy dissipation profiles), the quantification of the consequences of unstable stratification, and the optimization of the new model parameters constitute the essence of this continuing research of vital international importance. The model has been successfully tested at the Dallas-Fort Worth airport in September 2001. It is now being patented by NASA, (Sarpkaya as one of the four inventors who has devised the theoretical model and carried out the vortex-decay experiments).

PUBLICATIONS:


PROJECT SUMMARIES

OTHER:

The model has now been incorporated into NASA’s AVOSS program for the management of aircraft landings at large airports (JFK, Memphis, DFW, New Orleans). Sarpkaya is cited as one of the inventors of the model by NASA.

DoD KEY TECHNOLOGY AREA: Air Vehicles

KEYWORDS: Trailing Vortices, Aircraft Wakes, Wake Hazard

VOXRT THE BREAKDOWN IN TURBULENT SWIRLING FLOWS

Turgut Sarpekaya, Distinguished Professor
Department of Mechanical Engineering
Sponsor: National Science Foundation and Naval Postgraduate School

OBJECTIVE: Vortex breakdown is the transformation of a slender vortex into three-dimensional forms. Where, how, and under what circumstances does this transformation occur in viscous vortical flows constitute the essence of the breakdown problem. Neither a stagnation point, nor a region of reversed flow, nor the bridging of laminar-turbulent states is necessary. Trailing vortices, swirling flows in pipes, vortical flows above sweptback wings at large angles-of-attack, flows in closed containers with a rotating lid, and columnar vortices in air may experience breakdown. Where, how, and under what circumstances does the breakdown occur in viscous vortical flows constitute the essence of the investigation.

SUMMARY: The definition of the spectral characteristics of the conical region is the subject of the ongoing investigation. The mean velocities and turbulence intensities were measured in forward-scattering mode with a three-component Laser Doppler Anemometer. The results refute the conjectures that the circumstances of breakdown are insensitive to the Reynolds number and the local turbulence properties. These two factors have a strong influence on the evolution of the flow. Of all the known forms, the spiral emerges as the most fundamental breakdown form. All other forms may be regarded as transient states affected by various types of instabilities. At very high Reynolds numbers the breakdown acquires forms and characteristics never seen before: Extremely high rates of revolution, onset of core-bifurcation or core-twist, intense anisotropic turbulence, and a conical shape.

PUBLICATIONS:


DoD KEY TECHNOLOGY AREAS: Aerospace Propulsion and Power, Air Vehicles

KEYWORDS: Vortex Breakdown, Vorticity, Swirling Flow

FRAGMENTATION AND DETONATION OF ANTI-PERSONNEL MINE AND SURVIVABILITY OF SENSORS IN THE GRIZZLY

Young S. Shin, Professor
Department of Mechanical Engineering
Sponsor: U.S. Army Tank Automotive Command

OBJECTIVE: The Grizzly has various sensors including control sensors, laser systems, hydraulic lines, wires and various cameras mounted on the Grizzly armor hull which is exposed to various types of landmine detonation. The objective is to study the detonation and fragmentation process of mine such as...
OMZ-72 antipersonnel mine and to extend the study on effect of shock wave and fragmentation to the survivability of sensors, laser systems, cameras, wires and hydraulic lines exposed to the threat. Based on the results investigated, NPS will provide design guidance on protecting sensors, laser systems, wires and hydraulic lines, etc, from the threat. The pop-up anti-personnel mines such as the OZM-72 has unique and of interesting features about its horizontal dispersion of fragmentation. The project results will provide design guidance from a better understanding of the threat.

SUMMARY: Many obstacles such as minefields, barbwire entanglements, tank ditches and other fortifications are used to paralyze the forward momentum of mechanized armed forces. To combat this the Grizzly tracked vehicle was developed for the United States Army to defeat these complex obstacles and clear mine fields. Due to its intended mission various sensors, laser systems, hydraulic lines, wires and cameras are mounted on the armor hull, which are exposed to various types of landmine detonation and fragmentation.

This study is to model an OZM – 72 bounding antipersonnel mine to be used in studying the effects of shock waves and fragmentation on the survivability of the equipment mounted on the Grizzly’s armored hull. 2D and 3D finite element models of the antipersonnel mines are developed and used to simulate the detonation and fragmentation phenomena. The analysis results obtained from the models provide a basis from which design guidance can be formulated for protecting equipment or personnel from this threat.

PUBLICATIONS:


THESES DIRECTED:


DoD KEY TECHNOLOGY AREAS: Modeling and Simulation

KEYWORDS: ALE Analysis, Fragmentation and Detonation, Land Mine

IMPACT ANALYSIS AND ACTIVE VIBRATION DAMPING ON ORBITAL VEHICLES
Young S. Shin, Professor
LT Timothy Barney, USN
Department of Mechanical Engineering
Sponsor: National Aeronautics and Space Administration - Dryden

OBJECTIVE: To develop a method to determine the location, force, and orientation of an impact on a space truss using a minimal distributed sensor grid. Also achieve improved active control of vibrations induced in the truss by installed equipment operating at a constant frequency. The active control is to be achieved using piezoelectric elements installed as truss members and should be able to control the vibration at multiple nodes and sensitive to various axis without relocating the active elements. A FEM of the truss, generated using ANSYS, is to be used to assess the ability to model the implementation of the control algorithm and will be compared to the actual experimental results.

SUMMARY: As spacecraft designs become more complex, compact, and lightweight, it becomes more likely that equipment induced vibrations will adversely affect other components. The use of either passive or active damping typically requires extensive system modeling and a significant weight addition. The Adaptive Multi-Layer LMS Controller, coupled with piezoelectric active elements has been able to suppress single axis vibration of a truss by greater than 50 dB. The algorithm has also proven to be flexible with respect to actuator orientation and location with respect to the desired point of suppression. The test platform was the NPS space truss, which is a 3.7-meter long truss that simulates a space-borne appendage with sensitive equipment mounted at its extremities. One of two installed piezoelectric actuators and an
Adaptive Multi-Layer LMS control law were used to effectively eliminate an axial component of the vibrations induced by a linear proof mass actuator mounted at one end of the truss.

PUBLICATION:


THESIS DIRECTED:


DoD KEY TECHNOLOGY AREAS: Space Vehicles, Modeling and Simulation

KEYWORDS: Space Truss, Active Vibration Damping, Piezoelectric Elements, Impact Analysis, ANSYS, FEM Simulation of Active Control Method
DEPARTMENT OF
MECHANICAL ENGINEERING

2001
Faculty Publications
and Presentations
JOURNAL PAPERS


Sarpkaya, T. and Merrill, C.F., "Spray Generation from Turbulent Plane Water Wall Jets Discharging into
PUBLICATIONS/PRESENTATIONS


CONFERENCE PAPERS


CONFERENCE PRESENTATION (WITHOUT PUBLICATION)


PUBLICATIONS/PRESENTATIONS


MEETING ABSTRACTS


TECHNICAL REPORTS


CONTRIBUTION TO BOOKS


OTHER


DEPARTMENT OF
MECHANICAL ENGINEERING

Thesis Abstracts
MULTI-LEVEL TECHNIQUE FOR STIFFNESS AND STRENGTH CALCULATIONS OF WOVEN FABRIC COMPOSITE PLATE AND SHELL STRUCTURES
Ahmet Altekin-Lieutenant Junior Grade, Turkish Navy
B.S., Turkish Naval Academy, 1994
Master of Science in Mechanical Engineering-June 2001
Advisor: Young W. Kwon, Department of Mechanical Engineering

The stiffness and strength behavior of the woven fabric composite materials mainly depend on the properties of the fiber and matrix materials. A technique was developed to design and analyze woven fabric composites based on the micro-level properties of the fiber and matrix materials. The technique is based on the bilateral relationships among the fiber/matrix materials, the unidirectional composite (strand), the woven fabric layer and the laminated composite structure as in the given order. Simplified and efficient analytical models were developed for the relationship between any subsequent levels. The technique is used to predict the structural level stiffness and strength in terms of material and geometric configuration of the woven fabric and lamination. Progressive damage/failure can also be simulated at the fiber and matrix level by using this technique.

DoD KEY TECHNOLOGY AREA: Materials, Process and Structures

KEYWORDS: Multilevel Technique, Woven Fabric Composite, Fiber, Matrix, Strand, Plate, Shell, Volume Fraction, Damage Size, Undulation Angle, Failure Criteria

ADAPTIVE MULTI-LAYER LMS CONTROLLER DESIGN AND ITS APPLICATION TO ACTIVE VIBRATION SUPPRESSION ON A SPACE TRUSS
Timothy A. Barney-Lieutenant, United States Navy
B.S., Eastern Michigan University, 1993
Master of Science in Mechanical Engineering-June 2001
Advisors: Young S. Shin, Department of Mechanical Engineering
Brij N. Agrawal, Department of Aeronautics and Astronautics

This thesis develops an adaptive controller that actively suppresses a single frequency disturbance source at a remote position and tests the system on the NPS Space Truss. The experimental results are then compared to those predicted by an ANSYS finite element model. The NPS space truss is a 3.7-meter long truss that simulates a space-borne appendage with sensitive equipment mounted at its extremities. One of two installed piezoelectric actuators and an Adaptive Multi-Layer LMS control law were used to effectively eliminate an axial component of the vibrations induced by a linear proof mass actuator mounted at one end of the truss. Experimental and analytical results both demonstrate reductions to the level of system noise. Vibration reductions in excess of 50dB were obtained through experimentation and over 100dB using ANSYS, demonstrating the ability to model this system with a finite element model. This thesis also proposes a method to use distributed quartz accelerometers to evaluate the location, direction, and energy of impacts on the NPS space truss using the dSPACE data acquisition and processing system to capture the structural response and compare it to known reference signals.

DoD KEY TECHNOLOGY AREA: Space Vehicles, Modeling and Simulation

KEYWORDS: Active Vibration Suppression, Piezoceramic Actuators, Impact Analysis, Adaptive Controller, LMS
THESIS ABSTRACTS

COMPUTATIONAL MECHANICS OF THE FULL-SCALE AND MODEL-SCALE ROLL-ON, ROLL-OFF (RORO) STERN RAMP AND EXPERIMENTAL MODAL ANALYSIS OF THE MODEL-SCALE RAMP AND SUPPORT
James E. Buckley-Lieutenant, United States Navy
B.S., Oregon State University, 1994
Master of Science in Mechanical Engineering-June 2001
Advisor: Joshua H. Gordis, Department of Mechanical Engineering

It has been determined that current stern ramp designs lack adequate structural integrity during Sea State Three roll-on, roll-off (RORO) operations. Therefore, passive isolation between the stern ramp and the RORO discharge facility (RRDF) is being investigated as a means of reducing ramp stress levels. A coupled hydro-structural simulation model of the combined ship-ramp-RRDF is under development in order to evaluate candidate isolator technologies. This thesis documents a thorough study of several stern ramp finite element models in order to ascertain the suitability of these models for use in the simulation model. Additionally, an experimental facility is being developed to simulate, at model scale, RORO operations. This thesis also documents the finite element analysis and experimental modal analysis of the primary structural components of the facility, specifically the scale model stern ramp and its support.

DoD KEY TECHNOLOGY AREA: Modeling and Simulation

KEYWORDS: Roll-On, Roll-Off, RORO, Stern Ramp, Isolation

SINKING A BODY WITH BUBBLES IN CLOSED AND OPEN ENVIRONMENTS
Carl W. DeGrace-Lieutenant, United States Navy
B.S., United States Naval Academy, 1994
Master of Science in Applied Physics-December 2000
Advisor: Bruce Denardo, Department of Physics
Second Reader: Ashok Gopinath, Department of Mechanical Engineering

The presence of bubbles in a liquid decreases the average density, and thus decreases the buoyant force on a floating body. Competing with the decrease in buoyancy is an upward drag due to the bubble motion and entrained liquid. This thesis presents investigations of the critical average density required to sink a buoyant body in water with bubbles in closed and open environments. A closed environment is where bubbles fill the container, in which case there is expected to be little if any upward flow of water at the body. An open environment is where the bubbles exist over a small cross-sectional area compared to the total cross-sectional area of the container, which models the effect of a methane eruption from the ocean floor. In this case, a substantial upward flow of water is entrained in the region of the bubbles, and a downward flow consequently occurs outside this region. Experiments for both closed and open environments are reported, where the average specific gravity of the body is varied. The closed environment data significantly deviate from a quantitative theory, and the open environment data are not in accord with a qualitative theory. Possible explanations for these deviations are offered.

DoD KEY TECHNOLOGY AREA: Other (Fluid Dynamics)

KEYWORDS: Water, Density, Specific Gravity, Volume Fraction, Bubbles, Buoyancy, NonNewtonian Fluid
THESIS ABSTRACTS

MODELING THE EFFECT OF CYCLING OF A LOCALIZED HEAT SOURCE IN THE DIE OF A FLIP CHIP PACKAGE WITH DEFECTS
James E. Dunne, Jr.-Lieutenant, United States Coast Guard
B.S., University of California, Los Angeles, 1992
Master of Science in Mechanical Engineering-September 2001
Advisor: Ashok Gopinath, Department of Mechanical Engineering

In this study, the finite element based numerical tool ANSYS was used to perform a nonlinear transient coupled-field thermal and structural analysis on a flip chip package. The effect of cycling of a localized source of heat, the die was studied in order to determine the possible formation of hot spots in a flip chip package with conduction inhibiting defects such as imperfect contact between the bump and pad. Different heat source levels and defect severities (characterized by reduced bump pad conductivities) were analyzed by subjecting the package to two step-change thermal cycles for each case studied. The thermal results indicate significant temperature differences within the package in all cases thus pointing to the need for a non-isothermal analysis. The structural results indicate a seemingly anomalous behavior of increased cycles to failure with increasing power and severity of defect which can be explained by the rapidly varying nature of the stresses thus resulting in minimal creep damage.

DoD KEY TECHNOLOGY AREAS: Other (Electronic Packaging)

KEYWORDS: Flip Chip, Electronic Packaging, Thermomechanical Fatigue

MODELING OF SHIPBOARD SMOKE PROPAGATION WITH A FORCED COUNTER-FLOW AIR-SUPPLY
Garrett J. Farman-Lieutenant Commander, United States Navy
B.S., University of Rochester/Engineering, 1990
Master of Science in Mechanical Engineering-June 2001
Advisor: Matthew D. Kelleher, Department of Mechanical Engineering

The propagation of fire-generated smoke with a counter-flow air supply in a horizontal arrangement of shipboard compartments and passageways was modeled using a computational fluid dynamics program generated by Computational Fluid Dynamics Research Corporation. This study was based on a large-scale live fire experiment performed by Naval Research Laboratory on the ex-USS SHADWELL. All simulations were evaluated at steady state conditions. A constant velocity counter-flow air supply was introduced into the model structure. The counter-flow air velocities used were 0.5, 1, and 2 m/s. This study used a Computational Fluid Dynamics combustion module to simulate a 620 kW fire generated by the complete combustion of propene gas from a burn pan in the space. Carbon dioxide from the fire was tracked throughout the structure to model smoke propagation. Seven simulations were performed with adiabatic and isothermal bulkhead, deck and overhead boundary conditions. Simulation smoke propagation results were consistent with experimental observations. Figures depicting temperature distribution, carbon dioxide distribution and mixture flow patterns at specified locations are provided in the report. The goal of this study is to evaluate the effectiveness of computational fluid dynamics modeling of smoke propagation in a shipboard space with a counter-flow air supply.

DoD KEY TECHNOLOGY AREA: Modeling and Simulation

KEYWORDS: Smoke, Smoke Modeling, Smoke Propagation, Smoke Spread, Smoke Movement, Computational Fluid Dynamics, Control Shipboard Smoke, Fire Induced Flow, Fire Spread, Field Modeling, Damage Control, Convection, Forced Air Supply
THESIS ABSTRACTS

MODELING THE BIODYNAMICAL RESPONSE OF THE HUMAN HEAD FOR INJURY ANALYSIS
Danielle N. George-Lieutenant, United States Navy
B.S.M.E., San Jose State University, 1994
Master of Science in Mechanical Engineering-September 2001
Advisor: Young W. Kwon, Department of Mechanical Engineering

The objective of this study is to develop a finite element model of the human head and neck to investigate the biomechanics of head injury. The finite element model is a two-dimensional, plane strain representation of the cervical spine, skull, and major components of the brain including the cerebrum, cerebellum, brain stem, tentorium and the surrounding cerebral spinal fluid. The dynamic response of the model is validated by comparison with the results of human volunteer sled acceleration experiments conducted by Ewing et al. To validate the head model, one of the head impact experiments performed on cadavers by Nahum et al. is simulated. The model responses are compared with the measured cadaveric test data in terms of head acceleration, and intracranial pressures measured at four locations including the coup and contrecoup sites. The validated model is used to demonstrate that the Head Injury Criterion (HIC), which is based on resultant translational acceleration of the center of gravity of the head, does not relate to the various mechanisms of brain injury and is therefore insufficient in predicting brain injury.

DoD KEY TECHNOLOGY AREAS: Modeling and Simulation

KEYWORDS: Finite Element Method, Human Thorax Model, Biodynamical Response

DETERMINATION OF INCLUSION CHEMISTRY AND SIZE DISTRIBUTION IN STEEL WELDMENTS BY ANALYTICAL ELECTRON MICROSCOPY
Craig A. Hackstaff-Lieutenant, United States Navy
B.S., United States Naval Academy, 1994
Master of Science in Mechanical Engineering-June 2001
Advisor: Alan G. Fox, Department of Mechanical Engineering

The U.S. Navy has been concerned about reducing the number of inclusions in steel weldments to increase the toughness of the weld metal. Research has shown that particular inclusions can nucleate the acicular ferrite microstructure in the weld metal, which can increase toughness without compromising strength. The present study investigated the inclusion chemistry and size distribution in aluminum-deoxidized C-Mn steel weldments. The results showed that the addition of aluminum to the C-Mn weld metal will produce inclusions, that can nucleate acicular ferrite by epitaxy, and that the number and volume fraction of inclusions is reduced. This indicates that aluminum deoxidation of steel weld metal can have positive benefits for C-Mn weld metal strength and toughness.

DoD KEY TECHNOLOGY AREA: Materials, Processes, and Structures

KEYWORDS: Acicular Ferrite, Shielded Metal Arc Welding, C-Mn Steel Weldments, Non-metallic Inclusions

RECURSIVE BLOCK-BY-BLOCK INTEGRAL EQUATION SOLUTION FOR TRANSIENT DYNAMIC ANALYSIS WITH MEMORY-TYPE ELEMENTS
Al V. Jarque-Lieutenant, United States Navy
B.S., University of California, San Diego, 1994
Master of Science in Mechanical Engineering-March 2001
Advisor: Joshua H. Gordis, Department of Mechanical Engineering

An efficient method of computing structural response of multi-story nonlinear base isolated buildings for a given seismic event is presented. Using a recursive block-by-block integral equation formulation (RBBIEF) solution to the governing nonlinear Volterra integral equation, structural base motion coupled to an
arbitrary number of nonlinear base isolators can be computed for discrete seismic time histories in an expeditious and exacting manner. The general solution to the governing nonlinear Volterra integral is formulated and subsequently converted into code using MATLAB. The succeeding analysis incorporates modal properties, computed from conventional finite element (FE) techniques, and the generated MATLAB programs to solve a varying set of multi-degree of freedom structures coupled to both linear and nonlinear isolators. Ultimately, an analysis is conducted on a 30-story building that was overly designed using the 1994 Load Resistance Factor Design and the 1994 Uniform Building Codes for earthquake loading. The method demonstrates that the Volterra integration scheme in the time domain is very effective and efficient.

DoD KEY TECHNOLOGY AREAS: Computing and Software, Materials, Processes, and Structures, Modeling and Simulation, Other (Civil Engineering)

KEYWORDS: Finite Element, Nonlinear Dynamic Transient Response, Seismic Response, Volterra integral, Convolution Integral, Nonlinear Structural Base Isolation, Hysteretic isolators

AUV STEERING PARAMETER IDENTIFICATION FOR IMPROVED CONTROL DESIGN
Jay H. Johnson-Lieutenant, United States Navy
B.S., University of Kansas, 1993
Master of Science in Mechanical Engineering-June 2001
Advisor: Anthony J. Healey, Department of Mechanical Engineering

Any effort to provide precision control for an Autonomous Underwater Vehicle requires an accurate estimation of both the vehicle's physical and hydrodynamic parameters. Here a vehicle model for controlled steering behaviors was developed and the hydrodynamic parameters were calculated from actual data obtained from operation. The steering equation parameters are based on a least squares fit to sideslip and turn rate data using maximum likelihood of batch processing. In this way, a more accurate simulation has been found for the development of a track controller that stably drives the vehicle between mission waypoints. Prediction accuracy of the model was better than ninety-five percent over the data set used.

DoD KEY TECHNOLOGY AREAS: Surface/Under Surface Vehicles-Ships and Aircraft

KEYWORDS: Underwater Vehicle, AUV, Control, System Identification, Autonomous Systems, Robotics

SEMI-RIGID TOWING MODEL FOR ANALYSIS OF MANEUVERING
IN THE HORIZONTAL PLANE
Garrett D. Jones-Lieutenant, United States Navy
B.A., United States Naval Academy, 1994
Master of Science in Mechanical Engineering-September 2001
Advisor: Fotis A. Papoulias, Department of Mechanical Engineering

A SIMULINK towing model is developed from the surge, sway, and yaw equations of motion in order to study the horizontal maneuverability of vessels in a semi-rigid towing operation. This analysis is conducted in order to validate rigid-connection towing and to give insight into the design of the tow connector. The connection is modeled as a linear spring and the maneuverability of the vessels is studied as the stiffness is varied from conditions of semi to completely rigid. This study is based on two Swath hull vessels, the SLICE and KAIMALINO, towing in close proximity under calm water conditions.

DoD KEY TECHNOLOGY AREAS: Modeling and Simulation, Surface/Under Surface Vehicles-Ships and Watercraft

KEYWORDS: Towing, SeaKeeping
THESIS ABSTRACTS

COUPLED LAGRANGIAN AND EULERIAN APPROACH TO DETONATION AND
FRAGMENTATION PROBLEMS
Mark S. Kloster-Lieutenant, United States Navy
B.S., Norwich University, 1995
Master of Science in Mechanical Engineering-September 2001
Advisor: Young S. Shin, Department of Mechanical Engineering

Many obstacles such as minefields, barbwire entanglements, tank ditches and other fortifications are used
to paralyze the forward momentum of mechanized armed forces. To combat this the Grizzly tracked
vehicle was developed for the United States Army. Due to the Grizzly's mission various sensors; laser
systems, hydraulic lines, wires and cameras are mounted on the armor hull, which are exposed to various
types of landmine detonation and fragmentation. This thesis studies the effects of shock waves and
fragmentation on the survivability of the equipment mounted on the Grizzly's armored hull. Models of an
OZM-72 antipersonnel mine are developed and used to simulate the detonation and fragmentation
phenomena. The analysis results obtained from the models provide a basis from which design guidance can
be formulated for protecting equipment or personnel from this threat.

DoD KEY TECHNOLOGY AREAS: Modeling and Simulation

KEYWORDS: Fragmentation, Detonation, Land Mine

STRUCTURAL HEALTH MONITORING: NUMERICAL DAMAGE PREDICTOR FOR
COMPOSITE STRUCTURES
Daniel L. Lannamann-Lieutenant, United States Navy
B.S.M.E., University of Maine, 1994
Master of Science in Mechanical Engineering-March 2001
Advisor: Young W. Kwon, Department of Mechanical Engineering

The use of composite materials in both civil and military applications is increasing as composites
potentially offer many advantages over traditional structural materials. Composites typically provide
superior strength to weight ratio, better resistance to corrosion, and especially for military applications,
greater ballistic protection. Wide use of composites is found in aircraft, armored vehicles, ships and civil
structures.

This present research demonstrates the ability to numerically detect damage in a composite sandwich
structure using a robust non-linear finite element model (FEM). FEM techniques are used to directly
represent damage and the model's response is investigated. Changes in elemental strain and strain
frequency, through a Fast Fourier Transform (FFT), is evaluated. Both a cantilevered beam and a simply
supported plate are studied.

DoD KEY TECHNOLOGY AREAS: Materials, Processes, and Structures, Manufacturing Science and
Technology (MS&T), Modeling and Simulation, Other (Civil Engineering)

KEYWORDS: Structural Health Monitoring, Finite Element Method, Composites, DYNA3D, and Non-
Destructive Damage Detection

MODELING THE BIODYNAMICAL RESPONSE OF THE HUMAN THORAX WITH BODY
ARMOR FROM A BULLET IMPACT
John A. Lobuono-Lieutenant, United States Navy
B.S.M.E., Rochester Institute of Technology, 1991
Master of Science in Mechanical Engineering-March 2001
Advisor: Young W. Kwon, Department of Mechanical Engineering

The objective of this study is to develop a finite element model of the human thorax with a protective body
armor system so that the model can adequately determine the thorax's biodynamical response from a
projectile impact. The finite element model of the human thorax consists of the thoracic skeleton, heart, lungs, major arteries, major veins, trachea, and bronchi. The finite element model of the human thorax is validated by comparing the model’s results to experimental data obtained from cadavers wearing a protective body armor system undergoing a projectile impact. When the model is deemed valid, a parametric study is performed to determine the components of the model that have the greatest effect on its biodynamical response to a projectile impact.

DoD KEY TECHNOLOGY AREA: Modeling and Simulation, Conventional Weapons

KEYWORDS: Finite Element Analysis, Human Thorax Model, Impact Analysis, Body Armor

EVALUATION OF THE USE OF GPS-AIDED WEAPONS TO ATTACK MOVING TARGETS
Randolph L. Mahr-Commander, United States Navy
B.S., United States Naval Academy, 1983
Master of Science in Aeronautical Engineering-March 2001
Advisor: Russell W. Duren, Department of Aeronautics and Astronautics
Second Reader: Morris R. Driels, Department of Mechanical Engineering

The current intelligence gathering and strike decision infrastructure is optimized to handle geographically and temporally fixed targets. When tasked to respond to targets that require near immediate engagement, however, the system is stressed to the limit of its capability. When these time sensitive targets are capable of relocating, the process of rapidly applying lethal force becomes even more complicated. This thesis examines the problems associated with attacking a moving target using low cost GPS-aided standoff weapons, without an integrated weapon seeker. It begins with a discussion of the history and evolution of the Navy’s ability to attack time sensitive moving targets, and provides the description of a system that could address shortcomings noted. MATLAB Simulink was used to develop a model to simulate the proposed system, and determine the responses to various combinations of identified error sources. The results of the research showed that the type of system proposed is technically feasible.

DoD KEY TECHNOLOGY AREAS: Air Vehicles, Command, Control, and Communications, Conventional Weapons, Sensors, Modeling and Simulation, Other (Time Critical Strike)


SURFACE SHIP SHOCK MODELING AND SIMULATION: EXTENDED INVESTIGATION
Philip E. Malone-Lieutenant, United States Navy
B.S., U.S. Merchant Marine Academy, 1993
Mechanical Engineer-December 2000
Advisor: Young S. Shin, Department of Mechanical Engineering

Surface Ship Shock trials play an essential role in ship test and evaluation (T&E), and Live Fire Test and Evaluation (LFT&E) requirements for the lead ship of each new construction shock hardened ship class. These tests provide insight into platform vulnerabilities with respect to close proximity underwater explosion (UNDEX) events, and produce significant decision-making data for corrective action. The high cost of conducting ship shock trials has lead to a significant effort to develop modeling and simulation capabilities that can provide decision-making data comparable to that gained from the actual tests. Unfortunately, efforts to capture the response of a ship’s structure to an UNDEX event require extremely large and complex finite element models of not only the ship’s structure but the surrounding fluid. This fluid volume is required to capture the effects of the cavitation caused by the UNDEX shock waves. The computational expense of running these finite element models is tremendous. This thesis reviews the work on this subject completed at the Naval Postgraduate School. Additionally, it provides further investigation
into the amount of the fluid that must be modeled to accurately capture the structural response of a 3D finite element model and presents a second generation finite element model of the USS JOHN PAUL JONES (DDG 53) for use in 3D analysis.


KEYWORDS: Underwater Explosion, Shock and Vibration

AN EXPERIMENTAL INVESTIGATION OF THE BOW WAVE ON USS COLE (DDG-67)
Howard B. Markle, II-Lieutenant, United States Navy
B.S., Pennsylvania State University, 1992
Mechanical Engineer-September 2001
Master of Science in Mechanical Engineering-September 2001
Advisor: Turgut Sarpkaya, Department of Mechanical Engineering

This is an experimental investigation into the formation of the bow wave on USS COLE (DDG-67) and her 1/250 scale model. The experiment examines the bow wave from a hydrodynamic signature point of view. Previous experiments have looked at the phenomenon from an icing, deck wetness or hull resistance standpoint. Very little research has emphasized the importance to the Navy of the effects of the bow wave and subsequent spray on the overall radar cross-section and stealth of the vessel. Measurements were conducted on a 1/250-scale model and compared to video of the USS COLE (DDG-67) wherever possible. The effects of steady, heave, pitch and combinations of heave and pitch motions were studied to quantify the base flow in comparison to the USS COLE. The Froude Number for the majority of the work was 0.25. Model scale frequencies ranged from 1 to 5 Hz, pitch angles from 0.85 degrees to 3.75 degrees and heave amplitudes from 1/8 to 1/2 of an inch. This research, coupled with subsequent studies of sheet separation and a physics based understanding of all the mechanisms, is essential to developing a numerical model that could begin to predict the basics of the highly complex bow wave and spray region.

DoD KEY TECHNOLOGY AREAS: Surface/Under Surface Vehicles-Ships and Watercraft

KEYWORDS: Hydrodynamics, Bow Wave, USS Cole

VALIDATION OF LOW OBSERVABLE STACK EDUCTOR DESIGN FOR GAS TURBINE EXHAUST SYSTEMS
John C. Markowicz-Lieutenant, United States Navy
B.S.M.E., Tufts University, 1992
Mechanical Engineer-September 2001
Master of Science in Mechanical Engineering-September 2001
Advisor: Knox Millsaps, Department of Mechanical Engineering

An experimental and analytical program was conducted to improve the entrainment performance of a low aspect ratio mixing tube (about unity) eductor. A new primary flow pattern, consisting of eight high aspect ratio, pie-shaped nozzles, was designed to improve mixing and product better outlet flow uniformity. The aerodynamic performance of the new design was measured in a 1/5 scale, cold-flow facility, and the results compared to a nozzle plate with 16 constant-width, radial nozzles. Experimental results are presented for a range of conditions and include the effects of mixing tube misalignment and inlet blockage. The new nozzle is shown to increase the secondary pumping ratio by 7%. In addition, a one-dimensional, steady, analytical model of an eductor, which includes frictional losses and outlet momentum non-uniformity is presented. The model predicts the performance of real eductors to within 3% and shows that the momentum non-uniformity is the primary factor limiting performance.
DEVELOPMENT OF A MODEL TO PREDICT AND ASSESS SURFACE SHIP RECOVERABILITY
Brian A. Metcalf-Lieutenant, United States Navy
B.S., U. S. Naval Academy, 1994
Master of Science in Mechanical Engineering-December 2000
Advisors: Charles N. Calvano, Department of Mechanical Engineering
David W. Byers, Naval Surface Warfare Center-Carderock Division

Survivability has become an increasingly important issue in the design of future naval warships. Quantifiable requirements for susceptibility and vulnerability have long been employed, but no model or computational methods exist to calculate the ability of a surface ship to "control the spread of damage and restore lost capabilities." Recoverability is defined as the probability of recovering from damage caused by a specific weapon. This thesis analyzes the complex issues involved in determining recoverability and setting parameters for recoverability measurement criteria. Two methods to calculate the probability of recovery, PR, are proposed along with sample data, analysis and applications. The variables and information required to implement the methodologies are outlined in significant detail to provide a basis for future model development.

VERTICAL PLANE RESPONSE OF SURFACE SHIPS IN CLOSE PROXIMITY TOWING
Christopher A. Nash-Lieutenant, United States Navy
B.S., United States Naval Academy, 1994
Master of Science in Mechanical Engineering-June 2001
Advisor: Fotis A. Papoulis, Department of Mechanical Engineering

The purpose of this thesis is to analyze the vertical plane response of surface ships in close proximity towing. The problem is formulated by using the heave and pitch equations of motion in regular waves. The vertical motion of the leading and trailing ship attachment points is calculated. The relative motion between these points is then matched through a notional spring/damper model of the connection. This allows calculation of the complete response amplitude operators for the two ships in terms of their relative motion and connection force. Parametric studies are conducted in terms of connection spring and damper characteristics, speed, and sea direction. Regular wave results are extended in standard fully developed random seas. A notional example provides insight into future studies necessary to validate the close-proximity towing concept.

DoD KEY TECHNOLOGY AREAS: Modeling and Simulation

KEYWORDS: Signature Control, Gas Turbines, Propulsion,

DoD KEY TECHNOLOGY AREAS: Computing and Software, Surface/Under Surface Vehicles-Ships and Watercraft, Modeling and Simulation

KEYWORDS: Ship Survivability, Survivability, Damage Control, Recoverability, Ship Design

DoD KEY TECHNOLOGY AREA: Surface/Under Surface Vehicles-Ships and Watercraft, Modeling and Simulation

KEYWORDS: Slice, Kaimalino, Seakeeping, Swath, RAO
THESIS ABSTRACTS

A HOT-STAGE ATOMIC FORCE MICROSCOPE FOR THE MEASUREMENT OF PLASTIC DEFORMATION IN METALLIC THIN FILMS DURING THERMAL CYCLING

Thomas E. Shultz-Lieutenant, United States Navy
B.A., Occidental College, 1994
Master of Science in Mechanical Engineering-June 2001
Advisor: Indranath Dutta, Department of Mechanical Engineering

An Atomic Force Microscope is equipped with a hot-stage and a vacuum system in order to enable in-situ studies of plastic deformation and interfacial sliding of thin metallic films on Si substrates during thermal cycling. The apparatus can reach sample temperatures of 100°C while maintaining optimum resolution. The system will allow future in-situ thermal cycling experiments on microelectronic devices in a protected environment to provide insight into the role of plastic deformation in metallic thin films on the stability of future generations of device structures. The details of the design, along with the performance limitations of the system are discussed. Preliminary results demonstrating the performance of the system at an elevated temperature are presented. Limited post-situ results from direct measurement of the plastic deformation of thin Cu films on Si substrates induced by thermal cycling are also presented, primarily with the objective of establishing the need for detailed in-situ studies. While artifacts such as permanent dimensional changes of the film are observed post-situ, a detailed mechanistic understanding of the interaction between the temperature-dependent stress state of the film and the resultant inelastic deformation within the film and at the interface can only be obtained through in-situ experiments.

DoD KEY TECHNOLOGY AREA: Electronics, Materials, Processes, and Structures


A FINITE ELEMENT ANALYSIS OF THERMAL FATIGUE STRESSES IN THE SOLDER JOINTS OF A FLIP CHIP PACKAGE

Victor E. Smith-Lieutenant, United States Navy
B.S., University of South Carolina, 1994
Master of Science in Mechanical Engineering-September 2001
Advisor: Ashok Gopinath, Department of Mechanical Engineering

A nonlinear finite element model was created using ANSYS to analyze the deformation and stresses in the solder bumps of a flip chip package subjected to thermal cycling. A parametric study of the effects of different dwell times, temperature ranges, and ramp rates in a thermal fatigue cycle was conducted for two different package geometries. The goal of this study was to use an energy density damage analysis to investigate the reliability (in cycles to failure) of a typical flip chip package by examining critical solder bump stress-strain behavior due to thermal cycling. The creep damage mechanism was found to be the primary mode of failure, which severely limited package life. A concurrent study of the behavior of the package with and without underfill showed that the bumps surrounded by underfill experienced considerably lower creep damage due to increased hydrostatic stresses, which in turn significantly extended the life of the package.

DoD KEY TECHNOLOGY AREAS: Other (Electronic Packaging)

KEYWORDS: Flip Chip, Electronic Packaging, Thermomechanical Fatigue

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THESIS ABSTRACTS

PRODUCTION OF ULTRA-FINE GRAINS AND EVOLUTION OF GRAIN BOUNDARIES DURING SEVERE PLASTIC DEFORMATION OF ALUMINUM AND ITS ALLOYS
Douglas L. Swisher-Lieutenant, United States Navy
B.S., United States Naval Academy, 1993
Mechanical Engineer-December 2000
Master of Science in Materials Science and Engineering-December 2000
Advisor: Terry R. McNelley, Department of Mechanical Engineering

Equal channel-angular pressing (ECAP) is a recently developed method for deformation processing of material that can produce an ultra-fine grain structure in bulk material through severe plastic deformation. This study will present results on microstructural evolution during repetitive ECAP of pure aluminum. The principal method of data collection was Orientation Imaging Microscopy (OIM). The results of the study indicate that, after one ECAP pass, the structure is inhomogeneous and anisotropic, and consists mostly of deformation-induced features. After repetitive ECAP, the aluminum material exhibited a homogeneous grain size but retained an anisotropic character to the microstructure. After twelve ECAP passes the microstructure consisted mainly of fine grains surrounded by high-angle boundaries but an appreciable fraction of low-angle boundaries remained. This microstructure thus comprises a mixture of deformation-induced and recrystallization features. Further results were also obtained documenting the existence of deformation banding in this material as well as in a rolled aluminum alloy. This phenomenon may be general in nature and associated with severe plastic deformation in aluminum and its alloys.

DoD KEY TECHNOLOGY AREAS: Materials, Processes, and Structures, Manufacturing Science and Technology (MS&T)


DEVELOPMENT OF EXPERIMENTAL FACILITY FOR ROLL-ON ROLL-OFF RAMP ISOLATION DYNAMICS
Richard A. Trevisan-Lieutenant, United States Navy
B.S., Marquette University, 1993
Master of Science in Mechanical Engineering-June 2001
Advisors: Joshua H. Gordis, Department of Mechanical Engineering
Fotis A. Papoulias, Department of Mechanical Engineering

It has been determined that a high stress state occurs in the Roll-on Roll-off (RORO) ship offload stern ramp during vehicle transfers in Sea State 3 conditions. Motion compensation systems (i.e. isolators) between the ramp and the barge (RRDF) are needed to minimize the high stress levels in the ramp. This thesis documents the design, analysis, and construction of a facility to evaluate the performance of candidate isolation systems to be used to minimize ramp stresses. The facility consists of a fabricated aluminum scale ramp model designed to mimic the structural dynamics of a full-scale ramp, a fabricated supporting structure and an actuator that simulates wave motion inputs to the barge-end of the isolator.

DoD KEY TECHNOLOGY AREA: Modeling and Simulation

KEYWORDS: Isolation, Roll-on, Roll-off, RORO, Stern Ramp

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FLOW CHARACTERISTICS OF LIQUID EPOXY UNDERFILL IN A NARROW GAP FOR FLIP CHIP DEVICES 
Stewart M. Wennersten-Lieutenant, United States Navy 
B.A., George Washington University, 1993 
Master of Science in Mechanical Engineering-March 2001 
Advisor: Ashok Gopinath, Department of Mechanical Engineering

The flow characteristics of a liquid epoxy encapsulant designed as an underfill for flip chip computer devices was studied in a controlled manner. Different temperatures, patterns, underfills, and points of application were used to investigate the characteristics of capillary flow through a narrow gap to determine optimal conditions of importance in computer flip chip manufacturing. Observations on flow front uniformity, void formations, distance/time covered, were recorded for all experimental runs. Qualitative visual data was recorded to corroborate the trends found for liquid underfill flow in a flip chip device. This data has been used to generate time-distance plots for determining optimal conditions for flow. The results of this work provide useful fundamental insight into fluid mechanics issues of flip chip computer device manufacturing posed by the challenges of continually decreasing computer chip size.

DoD KEY TECHNOLOGY AREA: Manufacturing Science and Technology (MS&T)

KEYWORDS: Flip Chip, Capillary Flow, Liquid Epoxy Underfill
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