

# ***Community Status Report and Proposed Revisions to the JDL Data Fusion Model***

**Alan N. Steinberg**

**Technical Director**

**TASC, Inc.**

**Arlington, VA**

**(703) 358-9090**

**[ansteinberg@tasc.com](mailto:ansteinberg@tasc.com)**

**Franklin E. White**

**Director, Program Development, Code D10T**

**SPAWAR Systems Center**

**San Diego, CA**

**Chairman, JDL Data Fusion Group**

**(619) 553-4036**

**[whitefe@spawar.navy.mil](mailto:whitefe@spawar.navy.mil)**

# REPORT DOCUMENTATION PAGE

Form Approved OMB No.  
0704-0188

Public reporting burden for this collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing this collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden to Department of Defense, Washington Headquarters Services, Directorate for Information Operations and Reports (0704-0188), 1215 Jefferson Davis Highway, Suite 1204, Arlington, VA 22202-4302. Respondents should be aware that notwithstanding any other provision of law, no person shall be subject to any penalty for failing to comply with a collection of information if it does not display a currently valid OMB control number. PLEASE DO NOT RETURN YOUR FORM TO THE ABOVE ADDRESS.

<b>1. REPORT DATE (DD-MM-YYYY)</b> 03-03-1998		<b>2. REPORT TYPE</b> Conference Proceedings		<b>3. DATES COVERED (FROM - TO)</b> xx-xx-1998 to xx-xx-1998	
<b>4. TITLE AND SUBTITLE</b> Community Status Report and Proposed Revisions to the JDL Data Fusion Model Unclassified			<b>5a. CONTRACT NUMBER</b>		
			<b>5b. GRANT NUMBER</b>		
			<b>5c. PROGRAM ELEMENT NUMBER</b>		
<b>6. AUTHOR(S)</b> Steinberg, Alan N. ; White, Franklin E. ;			<b>5d. PROJECT NUMBER</b>		
			<b>5e. TASK NUMBER</b>		
			<b>5f. WORK UNIT NUMBER</b>		
<b>7. PERFORMING ORGANIZATION NAME AND ADDRESS</b> TASC, Inc. Arlington, VAxxxxx			<b>8. PERFORMING ORGANIZATION REPORT NUMBER</b>		
<b>9. SPONSORING/MONITORING AGENCY NAME AND ADDRESS</b> Director, CECOM RDEC Night Vision and Electronic Sensors Directorate, Security Team 10221 Burbeck Road Ft. Belvoir, VA22060-5806			<b>10. SPONSOR/MONITOR'S ACRONYM(S)</b>		
			<b>11. SPONSOR/MONITOR'S REPORT NUMBER(S)</b>		
<b>12. DISTRIBUTION/AVAILABILITY STATEMENT</b> APUBLIC RELEASE					
<b>13. SUPPLEMENTARY NOTES</b> See Also ADM201041, 1998 IRIS Proceedings on CD-ROM.					
<b>14. ABSTRACT</b> Community Status - The Sensor/Data Fusion Working Group ? Origins ? Status & Problems ? Community Ideas and Feedback ? The JDL Data Fusion Model - ? Taxonomy ? Functional Model ? Proposed Revisions					
<b>15. SUBJECT TERMS</b>					
<b>16. SECURITY CLASSIFICATION OF:</b>		<b>17. LIMITATION OF ABSTRACT</b> Public Release	<b>18. NUMBER OF PAGES</b> 35	<b>19. NAME OF RESPONSIBLE PERSON</b> Fenster, Lynn lfenster@dtic.mil	
a. REPORT Unclassified	b. ABSTRACT Unclassified			c. THIS PAGE Unclassified	<b>19b. TELEPHONE NUMBER</b> International Area Code Area Code Telephone Number 703767-9007 DSN 427-9007
				Standard Form 298 (Rev. 8-98) Prescribed by ANSI Std Z39.18	

# *Outline*

- ➔ • **Community Status - The Sensor/Data Fusion Working Group**
  - Origins
  - Status & Problems
  - Community Ideas and Feedback
- **The JDL Data Fusion Model -**
  - Taxonomy
  - Functional Model
  - Proposed Revisions

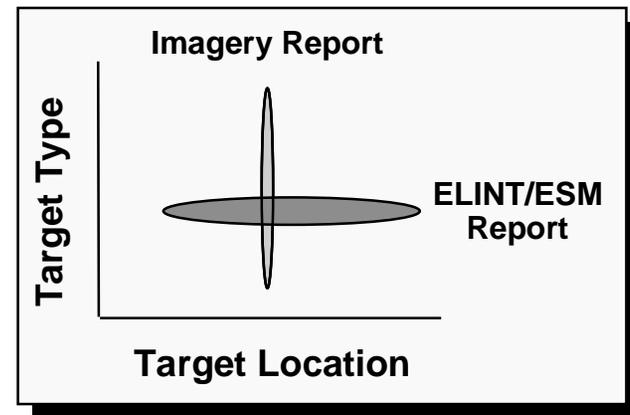
# ***Data Fusion is Essential to Interoperability and Information Utility\****

- **Expect reduced expenditures for expensive sensor platforms:**
  - Reduced coverage
  - Fewer specialized missions
  - Less redundancy / Fewer alternatives
- **Therefore, increased emphasis will be placed on *processing*, to *do more with less***
- **Flow, access and use of information**
  - Communications bandwidth and connectivity
  - Data Correlation and Fusion
  - Collection Management & Battle Management

\* *Diane Roark, Senior Staff Member, House Permanent Select Committee on Intelligence; presented at SWC Combat Info/Intel Correlation Symp., Jan 96)*

# Sensor Fusion Benefits

- **Combine Multi-Source/Multi-Discipline Information**
  - Target refinement: location/track, ID
  - Cross-domain imaging (e.g. E-O+SAR)
  - Force structure assessment
  - Own force vulnerability assessment
  - Supports Planning/Plan Execution/Re-planning
- **Maintain Track Continuity: Correlate Time-Separated Observations**
  - Intermittent sensor passes
  - Terrain masking and countermeasures
- **Cross-Sensor Cueing**
  - More efficient search
  - Enhanced detection (cued dwells; reduced threshold)
  - Reduced requirements on individual sensors (sensitivity, coverage, accuracy)
  - LO techniques (passive cueing of radar; bistatic sensing)



# ***General Deficiencies in Data Fusion Systems***

- **EFFECTIVENESS:**

- **Performance:** *Lack of timely, accurate target & situation awareness*
- **Focus:** *Information not tailored to decision-maker's needs*
- **User Confidence:** *Can't assess information quality*
- **Interoperability:** *Legacy systems can't talk to one another*
- **Data Exploitation:** *Reported data doesn't include some types of useful data*

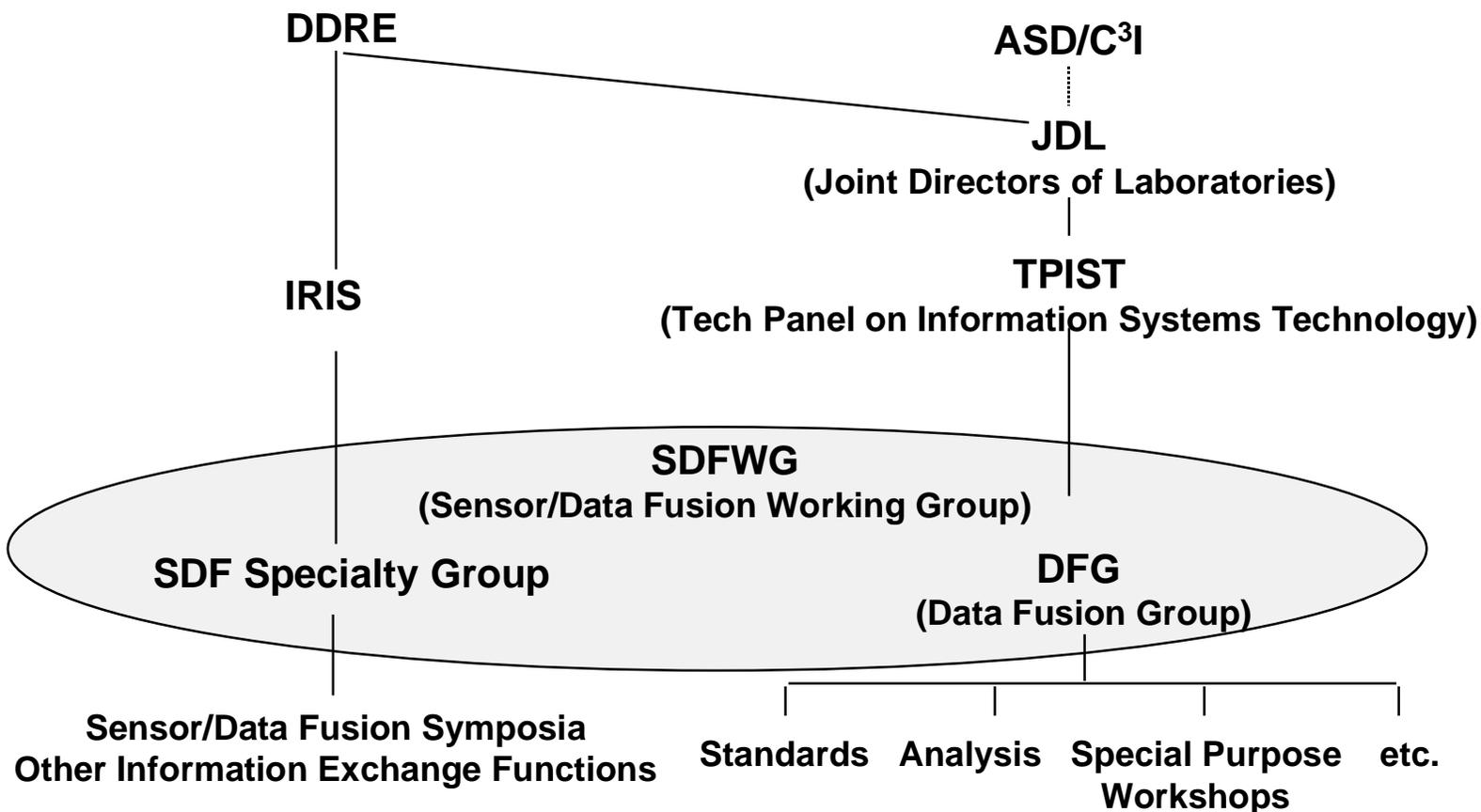
- **AFFORDABILITY:**

- *Every new system is designed from scratch*

# ***Problem Analysis***

- **Failure to use available data and designs**
- **Lack of**
  - Standard methods for specifying data fusion problems
  - Objective performance metrics
  - Generally accepted comparative analyses of alternative techniques
  - Standard multi-spectral/multi-discipline target/collection models
- **Diverse data fusion systems can be represented under a common paradigm but it requires:**
  - Requirements & MOPs
  - Target/ Collection Models
  - Architectures & Functions
  - Data Sets
- **Use of such a paradigm would facilitate**
  - System Acquisition
  - Adaptation/Re-use
  - Operation/ Interoperability
  - Evaluation

# Sensor/Data Fusion Working Group Family Tree



All-Pervasive Nature of Data Fusion  
Requires a Unified Organizational Approach

# Sensor/Data Fusion Working Group

---

To develop a successful Fusion process (automated or manual) a good understanding of the following is required:

1. Physics of the Sensor/Collector AND the Phenomena (NSSF)
  2. Data Fusion Processes (DFG)
  3. Warfare Mission Area
  4. Customer/User
- In the current Era of C4ISR and emphasis and need for integration, it is past time that we, as a community, started working on these issues.

# Key Data Fusion Problems<sup>[18,20]</sup>

- **“Easy” Problems:** Solutions Known → *Coordination, Funding, Engineering*

- |  |                                  |
|--|----------------------------------|
| – Stovepipes                             | C3 Architecture                  |
| – Interoperability & Data Latency        | C3 Arch, Interfaces & Processing |
| – Spatio-Temporal Alignment              | C3, Registration, Calibration    |
| – Integration with Collection Management | C3 Arch, Process Control         |
| – Confidence Normalization               | Source Modeling, Reporting       |
| – High Density, Dynamic Environments     | Hyp Generation, Hyp Selection    |

- **Difficult Problems:** Fundamental Research Needed → *Science*

- |   |   |
|---|---|
| – Predictable Performance                 | Modeling & Simulation                                     |
| – Highly Ambiguous, Noise-Like Indicators | Context Sensitive HG, HITL                                |
| – “Subtly-Related” Indicators             | Adaptive Fusion Trees, HITL                               |
| – Low Confidence Models                   | Hyp Generation, Hyp Selection,<br>Dynamic Databases, HITL |

HITL = Human-in-the-Loop

# *Current and Potential Future Activities*

CURRENT	FUTURE
<b>• Community Information Exchange - Government/Industry/Academia</b>	
<ul style="list-style-type: none"><li>- National Symposium (with IRIS)</li><li>- Workshops</li></ul>	<ul style="list-style-type: none"><li>- International Symposium</li><li>- Professional Journal</li><li>- Education Programs</li></ul>
<b>• Standards - Acquisition, Test and Evaluation</b>	
<ul style="list-style-type: none"><li>- Functional Model and Taxonomy</li><li>- Engineering Guidelines</li></ul>	<ul style="list-style-type: none"><li>- Algorithm/Software Library</li><li>- Test Sets</li><li>- Interfaces</li><li>- Performance Metrics</li></ul>

Evolve toward an Information Analysis Center (IAC)

# ***Develop Strategy to Coordinate Roles and Responsibilities***

- **Define Functional Needs**
  - **Standards for Acquisition, System Engineering, T&E**
    - Data exchange and commonality
  - **Technology Development**
  - **Information Exchange**
    - Symposia, Workshops, Education, Publication
  - **Data Bases and Models**
    - Algorithms, Multi-Source Test Sets and Models
- **Coordinate with**
  - **DUSD A&T**
  - **ASD/C<sup>3</sup>I**
  - **DDR&E**
  - **CMS**
  - **Joint Staff (JCS)**
  - **DISA (DII/COE)**
  - **DARPA**
  - **Labs**
  - **Intel Agencies**
  - **Services**
- **Work Toward a Prototype IAC**

# ***Burgeoning Symposia - Need Coordination?***

- **IEEE - Fusion 98 (International - Open)**
- **National Correlation Working Group (NCWG)**
- **ISCAS - Special Session**
- **Exploitation Technology Symposium (ETS)**
- **SPIE - Fusion Sessions**
- **Others?**

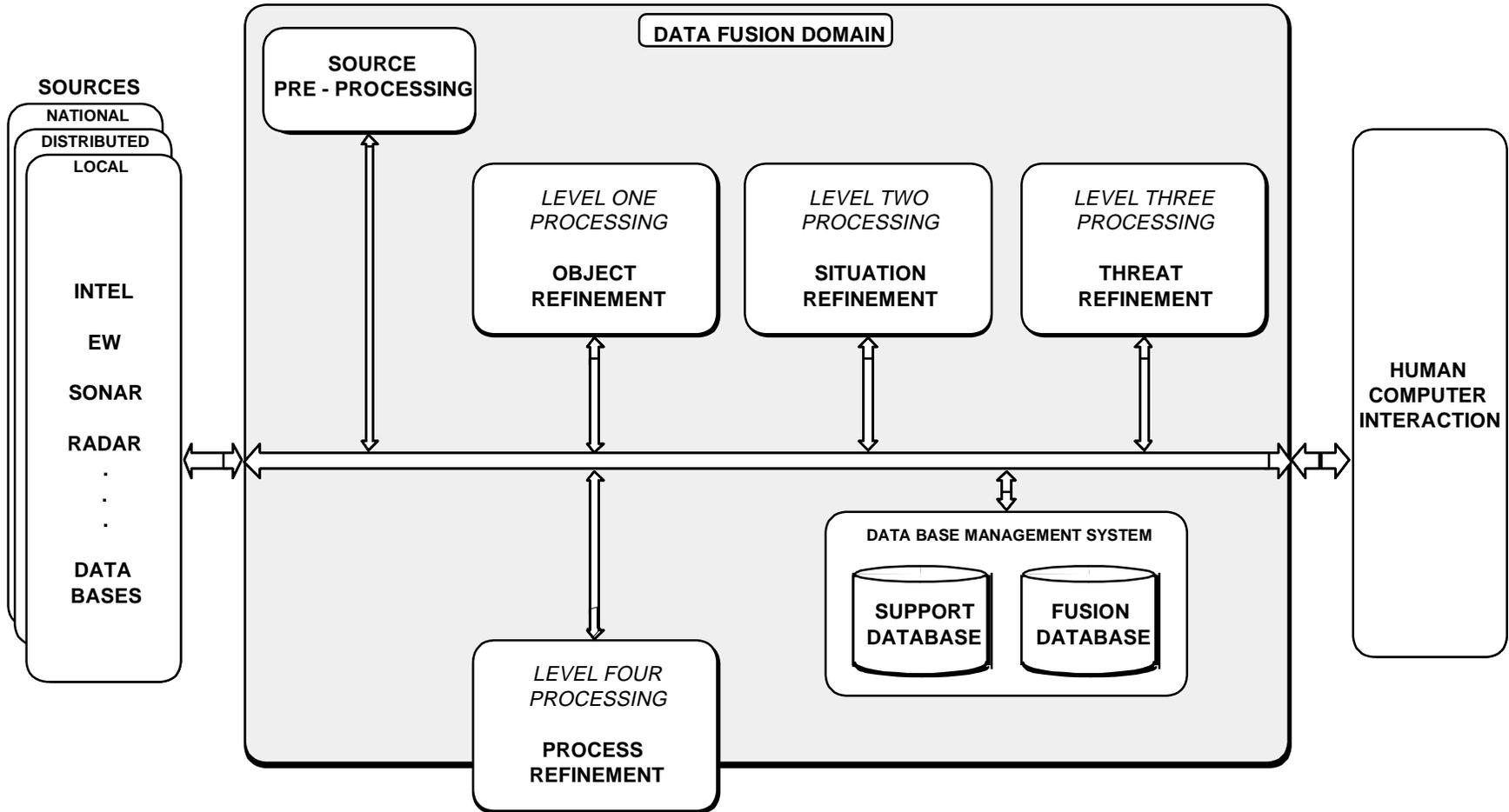
# *Outline*

- **The Sensor/Data Fusion Working Group - FE White**
  - Origins
  - Status & Problems
  - Community Ideas and Feedback
- ➔ • **The JDL Data Fusion Model - AN Steinberg**
  - Functional Model
  - Taxonomies
  - Proposed Revisions
  - Example Applications
  - Summary Assessment and Key Problems

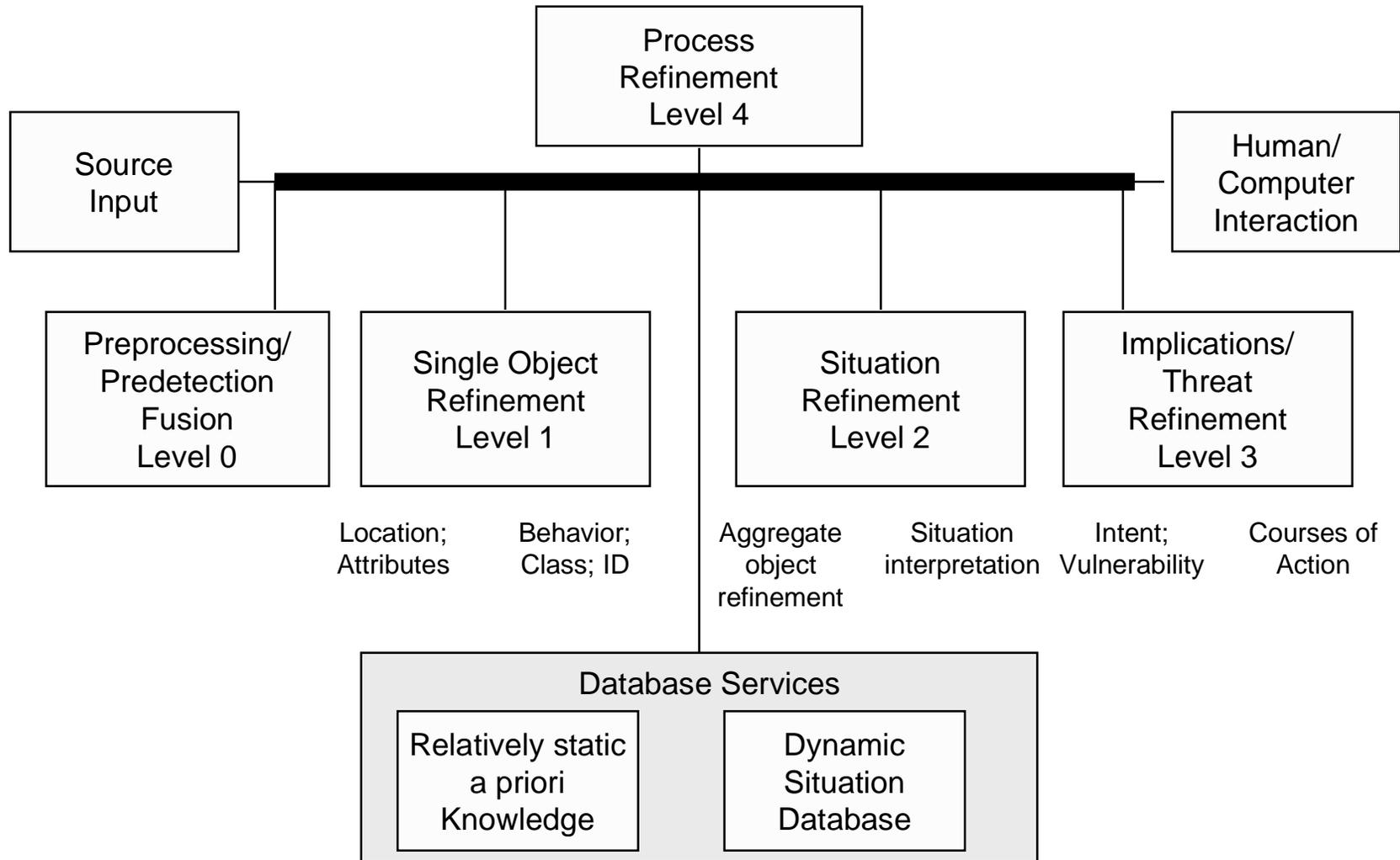


# Data Fusion Model

(Revised 1992)



# JDL Data Fusion Functional Model (Revised 1997)



# ***Definition of Component Functions***

<b><i>ALIGNMENT:</i></b>	Transforming data to common formats and frames of reference (spatio-temporal, measurement and attributive) and confidence.
<b><i>CORRELATION:</i></b>	Computing the “similarity” in data
<b><i>ASSOCIATION:</i></b>	Determining likelihood that data could have been caused by the same entity
<b><i>TRACKING:</i></b>	Creating and updating entity state estimates by associating sensor measurements over time using a predictive model of entity dynamics
<b><i>CLASSIFICATION</i></b>	Determining that a perceived entity is of a generic or specific type
<b><i>IDENTIFICATION</i></b>	Recognizing a perceived entity as particular individual
<b><i>SITUATION ASSESSMENT</i></b>	Inferring relations among entities , to include force structure and cross force relations, communications, physical context, etc.
<b><i>IMPACT ASSESSMENT:</i></b>	Estimating the significance (i.e cost/benefit) of perceived or predicted situations and impact on planned actions
<b><i>THREAT ASSESSMENT:</i></b>	Significance assessment regarding detected or predicted hostile situations, to include force susceptibilities and vulnerabilities to enemy postures, intentions and courses of action

# ***Data Fusion Functional Model***<sup>[17,19]</sup>

The JDL model (1987-91) and the draft revised model (1998)

- **Level 0 — Sub-Object Data Association and Estimation:** pixel/signal level data association and characterization
- **Level 1 — Object Refinement:** observation-to-track association, continuous state estimation (e.g. kinematics) and discrete state estimation (e.g. target type and ID) and prediction
- **Level 2 — Situation Refinement:** object clustering and relational analysis, to include force structure and cross force relations, communications, physical context, etc.
- **Level 3 — Impact Assessment ~~Threat Refinement: intent estimation, event prediction~~,** consequence prediction, susceptibility and vulnerability assessment
- **Level 4: Process Refinement:** adaptive data acquisition and processing (an element of Resource Management)

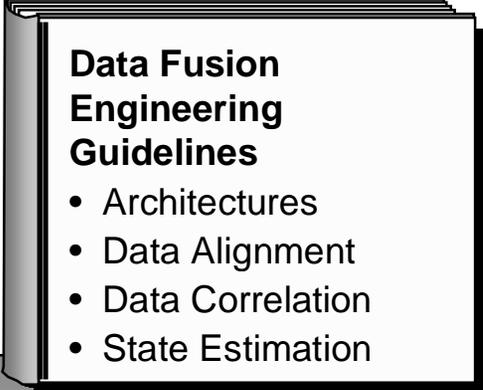
# ***Additional and Revised Taxonomies***

- **Physical Object**
  - Object, Entity, Target
- **System Representation of Physical Object**
  - Track, Perceived Entity, (Target) Hypothesis
- **Object State Dimensionality**
  - Attributive/Kinematic, Discrete/Continuous
- **Concrete Physical Object**
  - Object, Target, Platform
- **Aggregations**
  - Clusters, Aggregate Objects, Ensembles
- **Data Alignment**
  - Common Referencing, Data Pre-Processing

# ***Data Fusion Levels: Alternative Schemes***

Data Fusion "Level"	Type of Data Exploited	Type of Process		Type of Entity Characterized
		Association	Estimation	
0	<b>Measurements</b> <ul style="list-style-type: none"> <li>• Pixels</li> <li>• Predetected Signals</li> </ul>	<ul style="list-style-type: none"> <li>• Detection</li> <li>• Segmentation</li> <li>• Feature Extraction</li> <li>• Sorting</li> </ul>	<ul style="list-style-type: none"> <li>• Feature State Est.</li> <li>• Signal State Est.</li> <li>• State Prediction</li> </ul>	<ul style="list-style-type: none"> <li>• Region</li> <li>• Feature</li> <li>• (Detected) Signal</li> </ul>
1	<ul style="list-style-type: none"> <li>• Regions/ Features</li> <li>• Signals</li> <li>• Tracks</li> </ul>	<ul style="list-style-type: none"> <li>• Report/Track</li> <li>• Track/Track</li> </ul>	<ul style="list-style-type: none"> <li>• Object State Est.</li> <li>• Object State Prediction</li> </ul>	<ul style="list-style-type: none"> <li>• Physical Object (Platform, Target, Equipment)</li> </ul>
2	<b>Relationships</b> <ul style="list-style-type: none"> <li>• Subordination</li> <li>• Coordination</li> <li>• Conflict</li> </ul>	<b>Relational</b> <ul style="list-style-type: none"> <li>• Bayesian Nets</li> <li>• Clustering</li> <li>• Templating</li> </ul>	<ul style="list-style-type: none"> <li>• Aggregate State Est.</li> <li>• State Prediction</li> </ul>	<ul style="list-style-type: none"> <li>• Aggregation (Unit, Force Structure, Comm Net, etc.)</li> <li>• Situation</li> </ul>
3	<ul style="list-style-type: none"> <li>• Track State/Prediction</li> <li>• Relationship to Own Assets</li> <li>• Cost Model</li> </ul>	<ul style="list-style-type: none"> <li>• Filtering</li> <li>• Relational Analysis</li> </ul>	<ul style="list-style-type: none"> <li>• State Prediction</li> <li>• Cost/ Significance Est.</li> </ul>	<ul style="list-style-type: none"> <li>• Threat State (Event, Time, Relationship)</li> <li>• Event Prediction</li> <li>• Significance</li> </ul>
4	<ul style="list-style-type: none"> <li>• Object/Situation State</li> <li>• Event Prediction/ Significance</li> <li>• Response Plan Uncertainty State</li> </ul>	<ul style="list-style-type: none"> <li>• Operations Research</li> <li>• Optimal Control</li> </ul>	<b>Planning &amp; Control</b> <ul style="list-style-type: none"> <li>• Of Fusion Process</li> <li>• Of Information Acquisition Process</li> </ul>	<b>Plan &amp; Controls</b> <ul style="list-style-type: none"> <li>• Data Fusion</li> <li>• Collection Mgmt</li> <li>• Part of Resource Mgmt</li> </ul>

# ***SWC Project Correlation Engineering Guidelines***



## **Data Fusion Engineering Guidelines**

- Architectures
- Data Alignment
- Data Correlation
- State Estimation

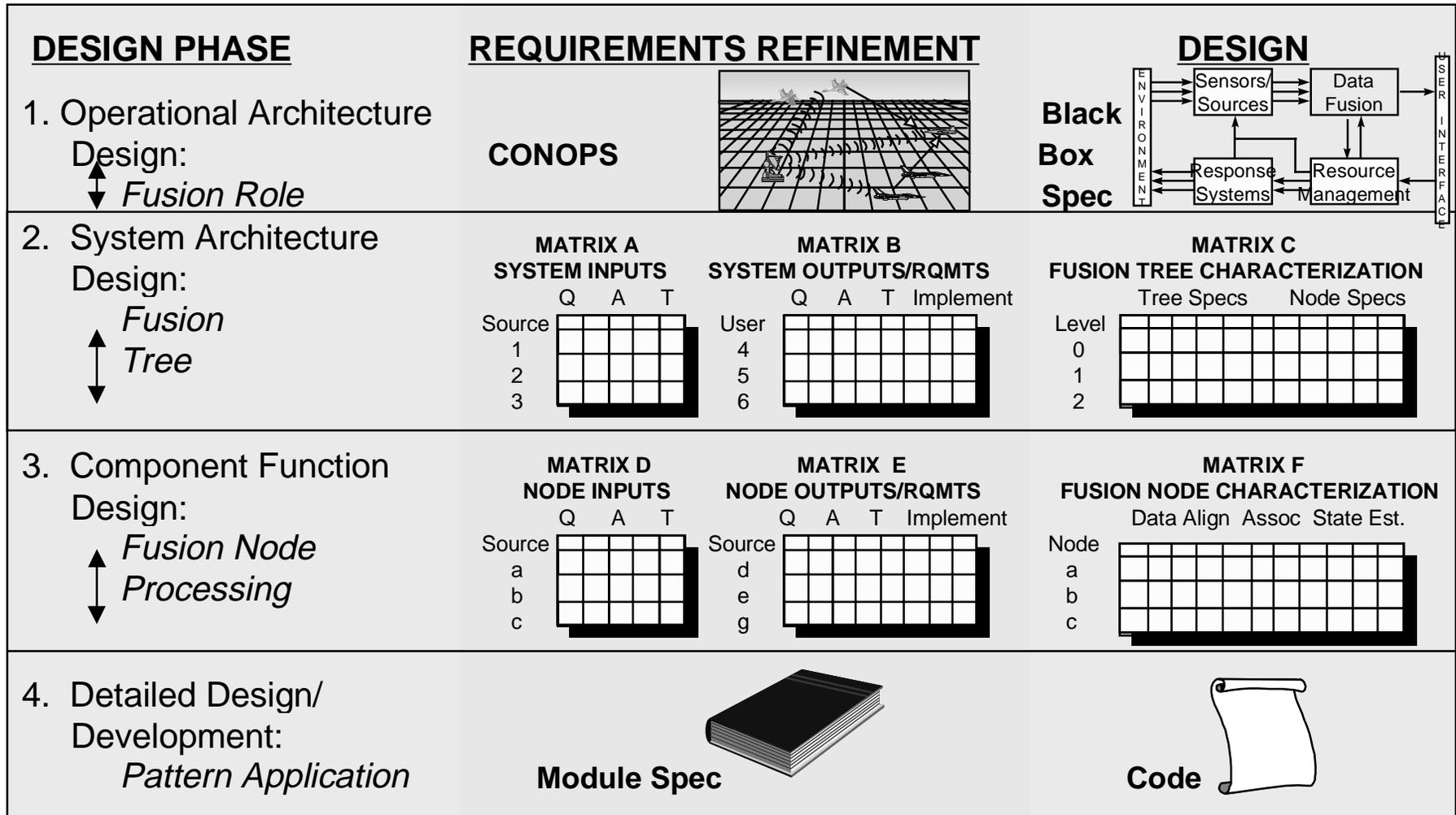
### • System Paradigm

- Taxonomy
- Evaluation Metrics:  
*MOPs, MOEs*
- Object-Oriented  
System Representation

### • Engineering Process

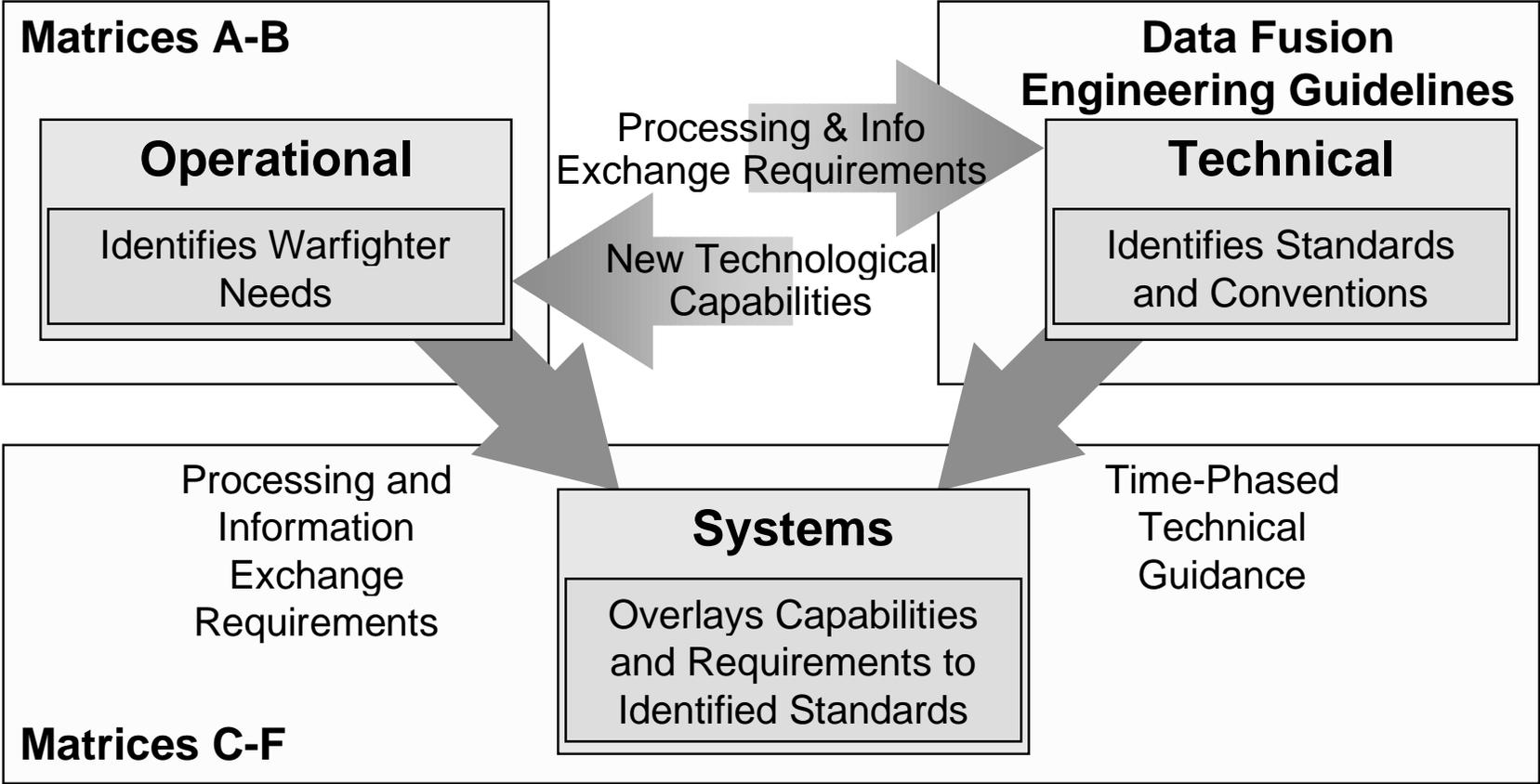
- Fusion System Role & Requirements
- Functional Partitioning:  
*Fusion Tree*
- Technique Applicability:  
*Fusion Nodes*

# Data Fusion System Engineering Phases & Products<sup>[17,18,19]</sup>

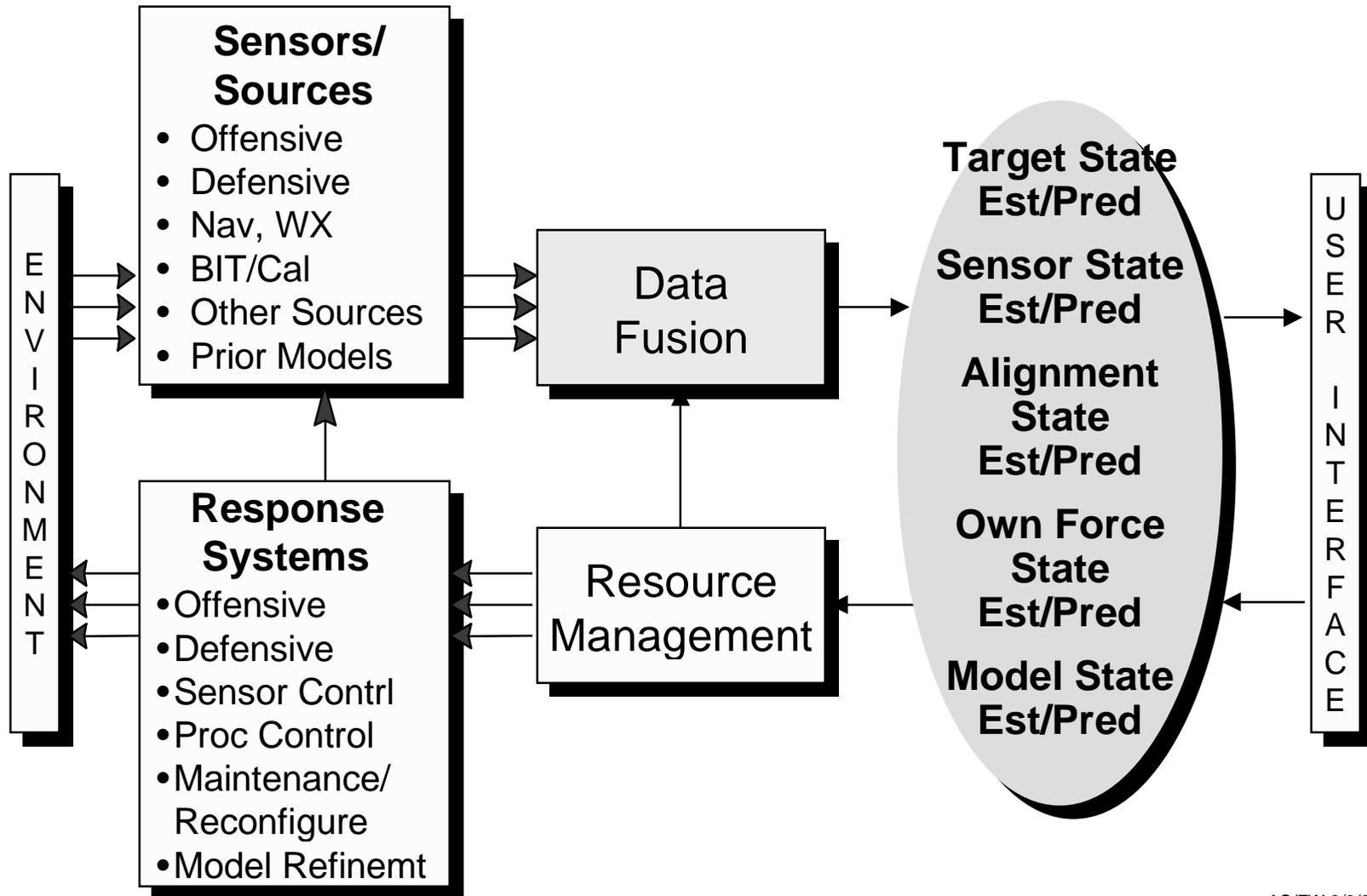


Note: Q A T = Data Quality, Availability, Timeliness

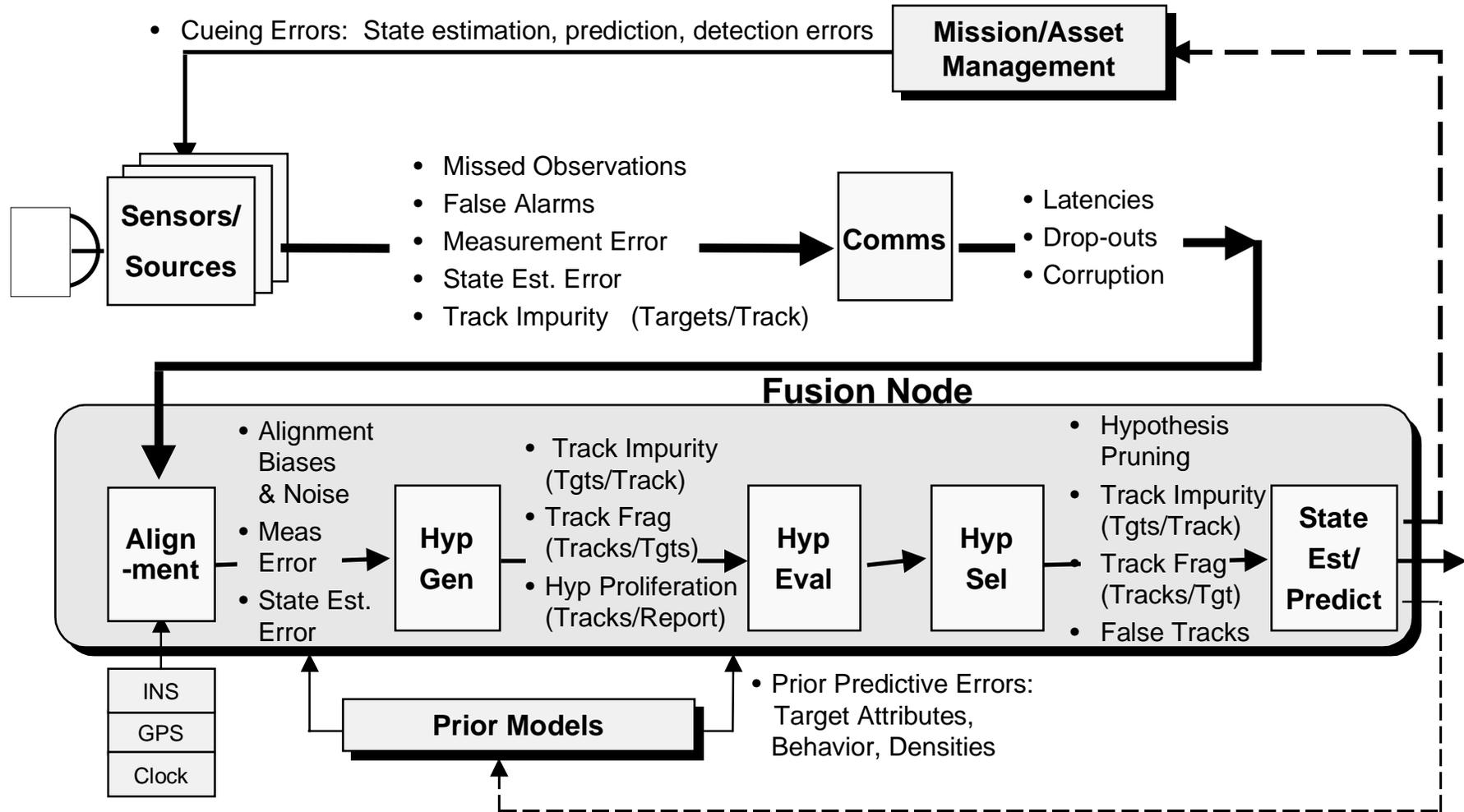
# ***Data Fusion Design in C4ISR Architecture Frameworks***



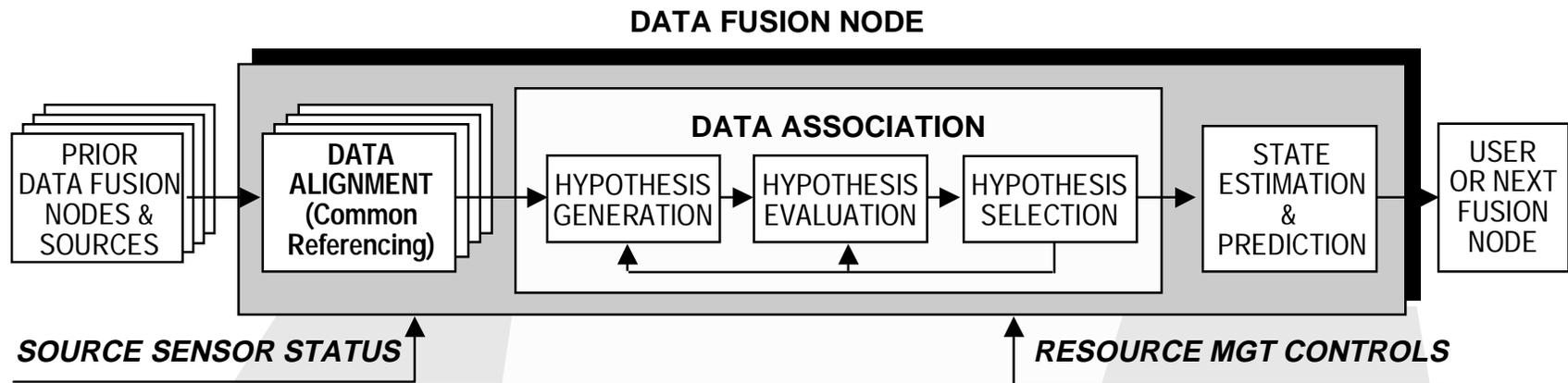
# *Role of Data Fusion in an Integrated Information Processing System*



# Sensor Fusion Performance is Affected by System Context



# Fusion Node Paradigm

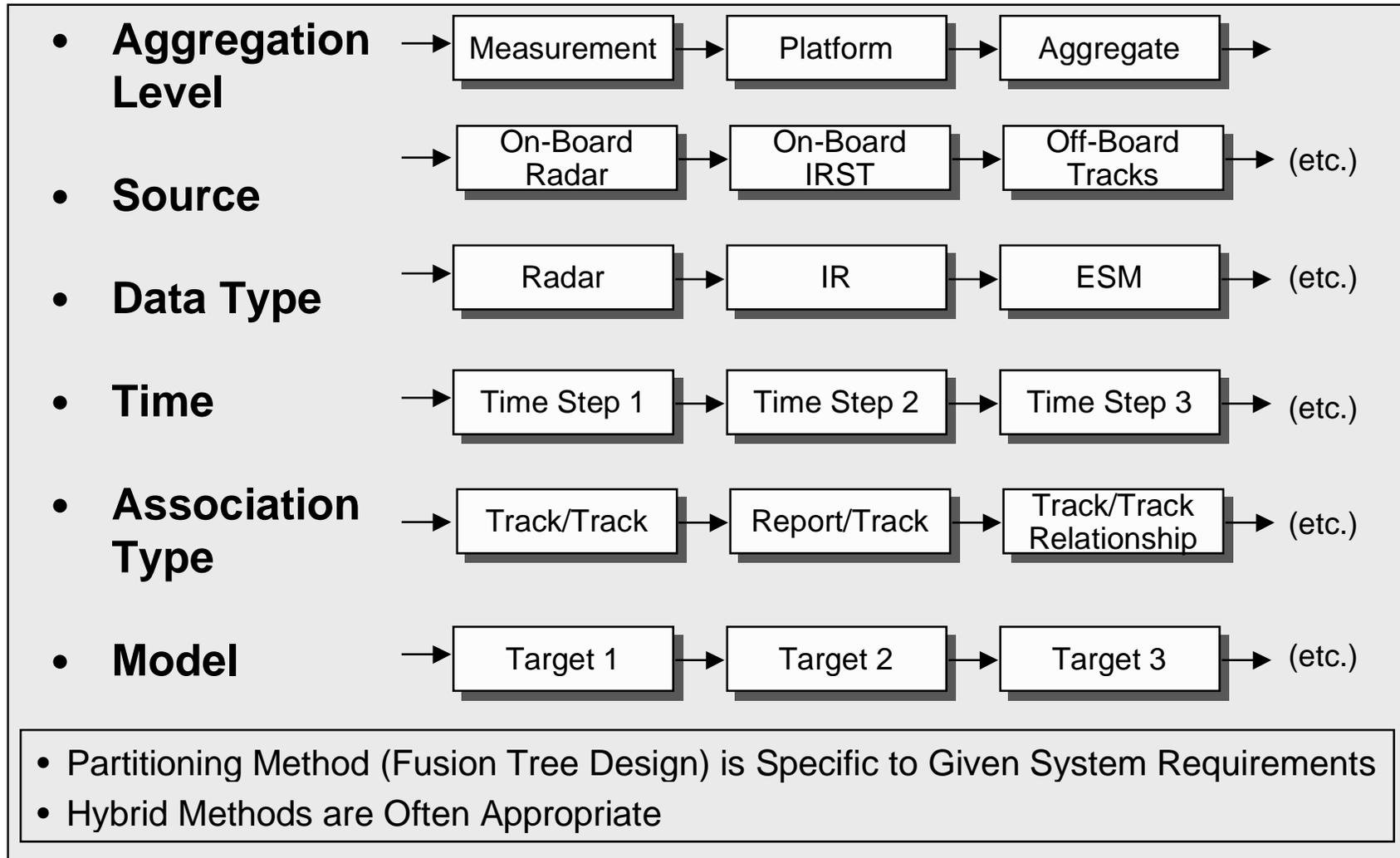


- DETECT AND RESOLVE DATA CONFLICTS
- CONVERT DATA TO COMMON TIME AND COORDINATE FRAME
- COMPENSATE FOR SOURCE MISALIGNMENT

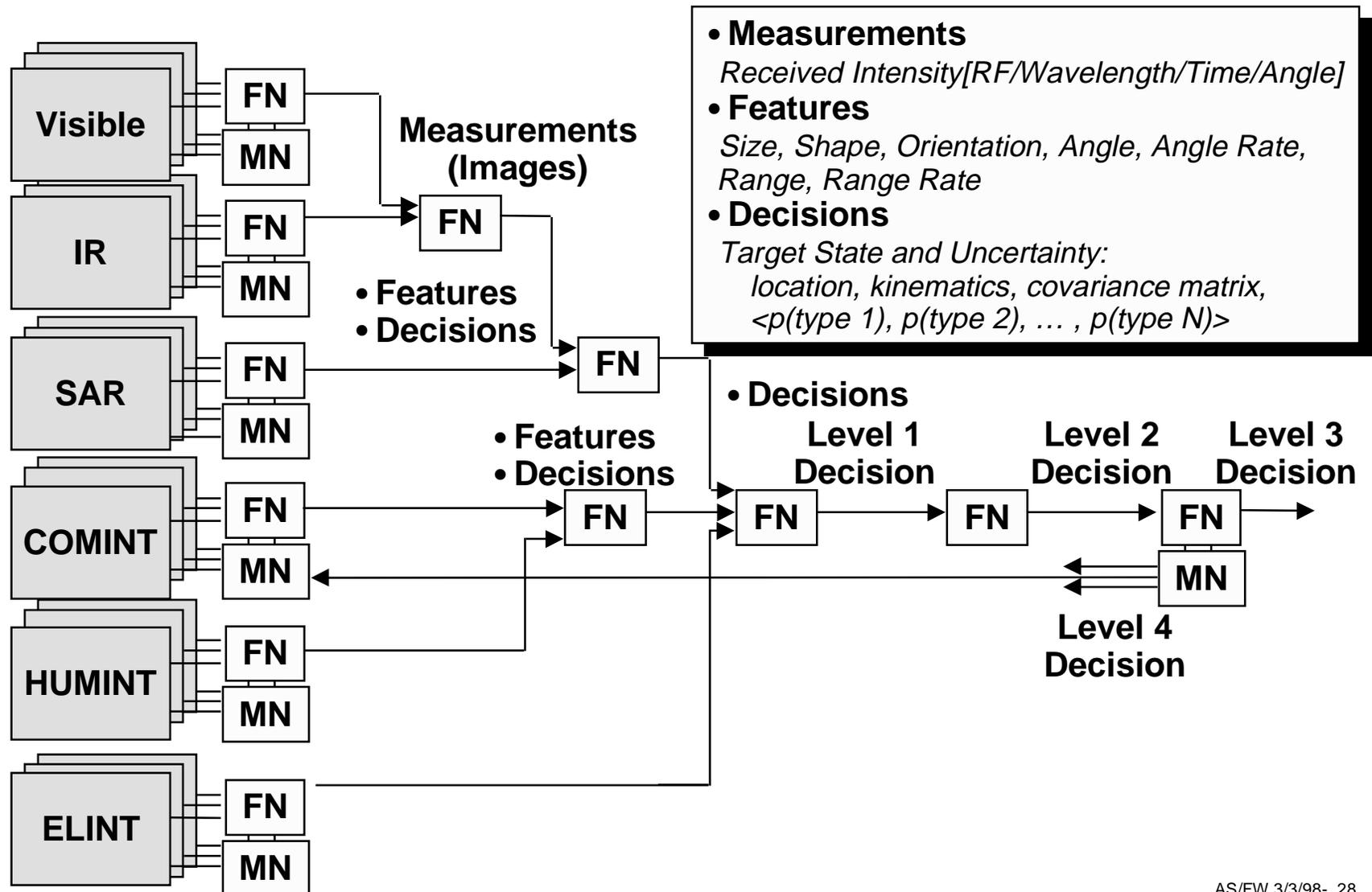
- GENERATE FEASIBLE & CONFIRMED ASSOCIATION HYPOTHESES
- SCORE HYPOTHESIZED DATA ASSOCIATIONS
- SELECT, DELETE, OR FEEDBACK DATA ASSOCIATIONS

- ESTIMATE/PREDICT ENTITY STATES
  - KINEMATICS, ATTRIBUTES, ID, RELATIONAL STATES
- ESTIMATE SENSOR/SOURCE MISALIGNMENTS
- FEED FORWARD SOURCE/ SENSOR STATUS

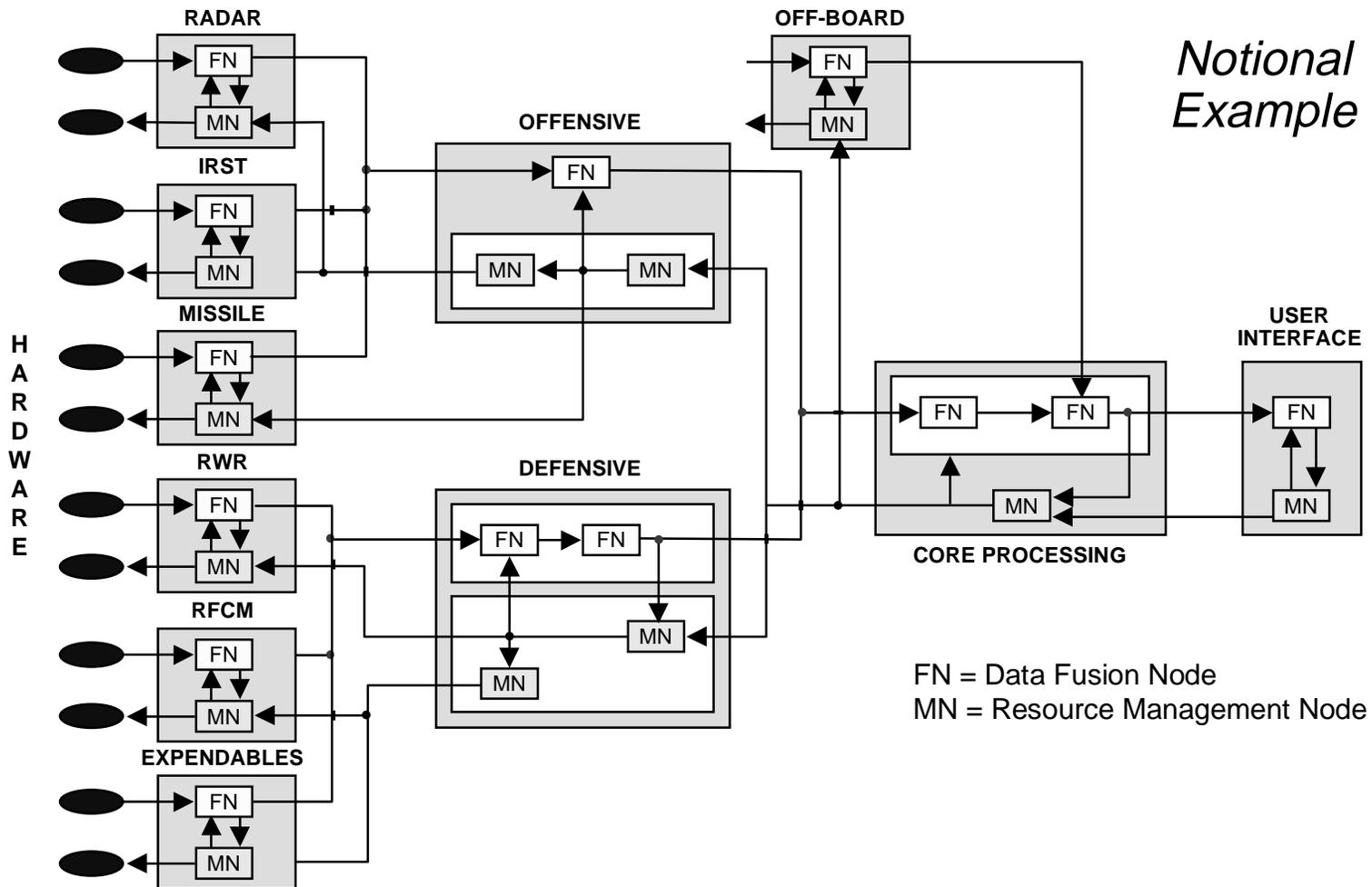
# Alternative Fusion Tree Partitioning Schemes<sup>[17,18,19]</sup>



# Battlefield Situation Awareness Example



# Hybrid Architecture Example: Data Fusion and Resource Management Trees<sup>[4]</sup>



# **Summary Data Fusion Technology Assessment (1 of 2)<sup>[4]</sup>**

<b>DATA FUSION LEVEL</b>	<b>SUMMARY OF THE STATE OF THE ART</b>	<b>CURRENT LIMITATIONS</b>	<b>DESIRED NEAR TERM CAPABILITIES</b>
Level 1: Positional, Kinematic, Attribute Estimation	<ul style="list-style-type: none"> <li>• Relatively mature               <ul style="list-style-type: none"> <li>- numerous techniques for tracking</li> <li>- current research in MHT, JPDA trackers</li> </ul> </li> <li>• Object I/D fusion dominated by feature &amp; decision methods               <ul style="list-style-type: none"> <li>- current R&amp;D in ANS and syntactic methods</li> </ul> </li> </ul>	<ul style="list-style-type: none"> <li>• Difficulty tracking targets in dense target environment, low SNR, maneuvering targets</li> <li>• Selection of attributes for classification</li> <li>• Selection/use of multiple techniques in concert</li> </ul>	<ul style="list-style-type: none"> <li>• Off-the-shelf software package for robust estimation</li> <li>• Multi-technique approach for object I/D</li> <li>• Methodology &amp; guidelines for algorithm selection</li> <li>• Standard test beds, data sets</li> </ul>
Levels 2 and 3: Situation and Significance	<ul style="list-style-type: none"> <li>• Relatively immature               <ul style="list-style-type: none"> <li>- heuristic techniques include templating, expert systems</li> <li>- numerous experimental prototypes</li> </ul> </li> </ul>	<ul style="list-style-type: none"> <li>• Doctrinal Basis not well-defined</li> <li>• Limited understanding of decision makers needs</li> <li>• Evolving threat environment</li> <li>• Limited cognitive models</li> </ul>	<ul style="list-style-type: none"> <li>• Robust techniques to solve subset of situation/threat refinement</li> <li>• Basis for cognitive models</li> </ul>
Level 4: Process Refinement	<ul style="list-style-type: none"> <li>• Mixed maturity               <ul style="list-style-type: none"> <li>- well founded technology for single sensor</li> <li>- immature for multi-sensors</li> <li>- MOPs defined</li> <li>- prototype expert systems</li> </ul> </li> </ul>	<ul style="list-style-type: none"> <li>• MOE not well-defined</li> <li>• Disconnect between mission management and fusion management</li> <li>• Hybrid architectures challenging</li> </ul>	<ul style="list-style-type: none"> <li>• MOE/MOP Consensus</li> <li>• Metrics baseline</li> <li>• Generic architecture and techniques for multi-sensor control</li> </ul>

# Summary Data Fusion Technology Assessment (2 of 2)<sup>[4]</sup>

DATA FUSION FUNCTIONAL AREA	SUMMARY OF THE STATE OF THE ART	CURRENT LIMITATIONS	DESIRED NEAR TERM CAPABILITIES
Human-Computer interface (HCI)	<ul style="list-style-type: none"> <li>Numerous tools for rapid prototyping</li> <li>Current research in display design, crew position layout, workload aspects</li> <li>Ergonomic <i>vice</i> cognitive focus</li> </ul>	<ul style="list-style-type: none"> <li>Limited HCI research specific to data fusion</li> <li>Limited cognitive models for focus of attention, stress management, alternative decision styles</li> </ul>	<ul style="list-style-type: none"> <li>Integrated exploitation of advanced technology (e.g., HDTV, virtual reality, multi-media)</li> <li>Intelligent Groupware</li> <li>Multi-person HCI</li> </ul>
Data Base Management	<ul style="list-style-type: none"> <li>Numerous commercial tools (relational models)</li> <li>Fourth-generation query languages</li> <li>Trend toward object-oriented DBMS</li> </ul>	<ul style="list-style-type: none"> <li>Simultaneous optimization of storage and retrieval</li> <li>Distributed concurrency</li> <li>Multi-level security</li> </ul>	<ul style="list-style-type: none"> <li>Natural language interfaces</li> <li>S/W based solution to multi-level security</li> <li>COTS DBMS to handle diverse data (image, text, data, KBS)</li> </ul>
Development Environment	<ul style="list-style-type: none"> <li>Robust development standards and procedures for conventional systems</li> <li>Widespread development of application specific prototypes</li> <li>Single vs. multi-sensor models</li> </ul>	<ul style="list-style-type: none"> <li>Lack of Standard MOPs and test sets</li> <li>Disjoint test beds and simulation tools</li> <li>Limited tools/MOE for Level 2,3 fusion</li> </ul>	<ul style="list-style-type: none"> <li>Robust test-bed for Test and Evaluation</li> <li>Metrics for MOP/MOE</li> <li>Fusion Software Library and Clearinghouse</li> <li>Data Fusion System Engineering methodology</li> </ul>

# ***Bibliography(1 of 3)***

- [1] Antony, Richard, *Principles of Data Fusion Automation*, Boston, Artech House, 1995.
- [2] Bar-Shalom, Yaakov and Thomas E. Fortmann, *Tracking and Data Association*, Academic Press, San Diego, CA, 1988.
- [3] Blackman, Samuel S., *Multiple-Target Tracking with Radar Applications*, Artech House, Boston, London 1986.
- [4] Bowman, Christopher L., *Data Fusion*, Course Notes, H. Silver Associates, London, September 1997.
- [5] *C4ISR Architecture Framework, Version 1.0*, C4ISR ITF Integrated Architecture Panel, CISA-0000-104-96, 7 June 1996.
- [6] Hall, David I., *Data Fusion and Multi-Sensor Correlation*, Course Notes, 1993
- [7] Hall, David L., *Mathematical Techniques in Multisensor Data Fusion*, Artech House, Boston, London 1992.
- [8] Kaspar, LTC Beth, "Advanced Tactical Targeting (AT3)," *Proceedings of DARPATech '97*, Kansas City, MO, September 1997.
- [9] Mahler, Ronald, "A Unified Foundation for Data Fusion," *Proceedings of the 1994 Data Fusion Systems Conference*, Oct. 1994.
- [10] Mahler, Ronald , "The random set approach to data fusion," *Proc. SPIE, vol 2234*, 1994.

## ***Bibliography (2 of 3)***

- [11] Pathfinder Homepage, <http://mars.primehost.com/mpf/mpftraj.html>.
- [12] Pearl, Judea, *Probabilistic Reasoning in Intelligence Systems*, Morgan Kaufmann, San Mateo, CA, 1988.
- [13] S. Przmieniecki, *Introduction to Mathematical Methods in Defense Analysis, AIAA Education Series*, AIAA, 1990.
- [14] Sea, R.G., "Optimal correlation of sensor data with tracks in surveillance systems," *Proc. 6th International Conf. on Systems Sciences*, Honolulu, HI, January, 1973, pp. 424-426.
- [15] Singer, R.A., "Estimated optimal tracking filter performance for manned maneuver targets," *IEEE Trans AES-5*, 1970, pp. 473-483.
- [16] Stein, J.J. and S.S. Blackman, "Generalized correlation of multi-target track data," *IEEE Trans. Aerospace and Electronic Systems, AES-11*, November 1975, pp. 1207-121
- [17] Steinberg, Alan N. and Christopher L. Bowman, *Data Fusion Engineering Guidelines*, SWC Talon-Command Technical Report 96-11/4, vol. 2 (1997).
- [18] Steinberg, Alan N., "Battlefield data fusion," *Proc. 2nd Annual Surveillance & Reconnaissance Conference*, Washington, D.C., 29-30 May 1997.
- [19] Steinberg, Alan N. and Bowman, Christopher L., "Development and application of data fusion engineering guidelines," *Proc. 10th National Symposium on Sensor Fusion (1997)*, in press.
- [20] Steinberg, Alan N., "Intelligence correlation, 'doing more with less'," *1st Annual Surveillance & Reconnaissance Conference*, Washington, D.C., 18-19 June 1996.

## ***Bibliography (3 of 3)***

- [21] Steinberg, Alan N. and Robert B. Washburn, "Multi-level fusion for Warbreaker intelligence correlation," *Proc. 8th National Symposium on Sensor Fusion*, 1995.
- [22] Steinberg, Alan N., "Sensor and data fusion," *The Infrared and Electro-Optical Systems Handbook*, Vol. 8 Ch. 1993, pp. 239-341.
- [23] Steinberg, Alan N., *High-Level Issues in Multisensor Data Fusion*, Course material, Center for Professional Development at the University of Maryland University College, September 1989.
- [24] Steinberg, Alan N. "Sensor/response coordination in a tactical self-protection system," *SPIE Proceedings*, Sensor Fusion I, vol. 931, 1988, pp. 115-122.
- [25] Stone, Lawrence, Michael Finn, and Carl Barlow, *Unified Data Fusion*, Report to Office of Naval Research, Contract N00014-95-C-0052, Metron, Inc., 26 January 1996.
- [26] [Waltz, Edward and James Llinas, *Multisensor Data Fusion*, Artech House, 1990.
- [27] [White, Franklin E. Jr., *Data Fusion Lexicon*, prepared for Joint Directors of Laboratories, Technical Panel for C3, Data Fusion Sub-Panel, Naval Ocean Systems Center, San Diego, 1987.
- [28] Van Keuk, G., "Software structure and sampling strategy for automatic target tracking with a phased array radar," *AGARD Conf. Proc. No. 252*, 1978].
- [29] Dannenhoffer, J., "Case-Based reasoning," AIAA Technology Committee, January 1992
- [30] DARPA DMIF Program Review, DMIFPro2, [https://www.iso.darpa.mil/WD@27000.cgi?get+iso::Office+Information\\_System+WDI\\_i\\_documents\\_frame](https://www.iso.darpa.mil/WD@27000.cgi?get+iso::Office+Information_System+WDI_i_documents_frame), 1997

# ***Community Update - Summary***

- **Pervasiveness of Data Fusion Is a Double-edged Sword:**
  - Belongs to Everybody but Nobody
- **Infrastructure is Needed to Reduce Acquisition, Development and Operational Costs**
  - Architecture Standards
  - Coordination
    - DOD, Other Government, Industry, Academia, Internationa
- **Community Needs Activism**
  - Next Generation of Leaders