

AD-A166 791

IMPLEMENTATION OF MAP-TO-IMAGE-CORRESPONDENCE FOR
SYNTHETIC APERTURE RADAR IMAGE ANALYSIS(U) ARMY
ENGINEER TOPOGRAPHIC LABS FORT BELVOIR VA
G E LUKES ET AL. 1985 ETL-R-002

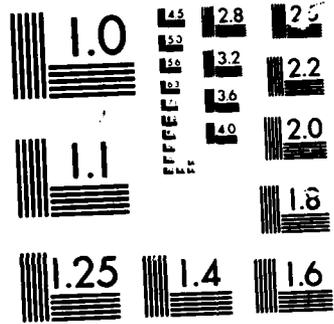
1/1

UNCLASSIFIED

F/G 17/9

NL





MICROCOPY

CHART

2

REPORT DOCUMENTATION PAGE		READ INSTRUCTIONS BEFORE COMPLETING FORM
1. REPORT NUMBER ETL-R-082	2. GOVT ACCESSION NO.	3. RECIPIENT'S CATALOG NUMBER
4. TITLE (and Subtitle) Implementation of Map-To-Image-Correspondence for Synthetic Aperture Radar Image Analysis.	5. TYPE OF REPORT & PERIOD COVERED	
	6. PERFORMING ORG. REPORT NUMBER	
7. AUTHOR(s) George E. Lukes, U. S. Army Engineer Topographic Laboratories, and J. Hannes Raggam, Technical University and Graz Research Center, Austria.	8. CONTRACT OR GRANT NUMBER(s)	
9. PERFORMING ORGANIZATION NAME AND ADDRESS U. S. Army Engineer Topographic Laboratories Fort Belvoir, VA 22060-5546	10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS	
11. CONTROLLING OFFICE NAME AND ADDRESS same	12. REPORT DATE	
	13. NUMBER OF PAGES	
14. MONITORING AGENCY NAME & ADDRESS (if different from Controlling Office)	15. SECURITY CLASS. (of this report)	
	15a. DECLASSIFICATION/DOWNGRADING SCHEDULE	
16. DISTRIBUTION STATEMENT (of this Report) Approved for public release. Distribution Unlimited.		
17. DISTRIBUTION STATEMENT (of the abstract entered in Block 20, if different from Report)		
8. SUPPLEMENTARY NOTES		
19. KEY WORDS (Continue on reverse side if necessary and identify by block number) synthetic aperture radar map-to-image correspondence digital map data planimetric augmentation		
20. ABSTRACT (Continue on reverse side if necessary and identify by block number) Radargrammetric techniques, developed to support stereo mensuration and data capture from synthetic aperture radar (SAR) imagery, have been extended to enable map-to-image correspondence for computer-assisted radar image analysis. This mechanism projects existing digital map data into the image space of a new SAR image rigorously accounting for the sensor imaging geometry and terrain configuration. Prerequisites for SAR map-to-image correspondence include (1) an analytical		

**DTIC
 ELECTED
 APR 23 1986**

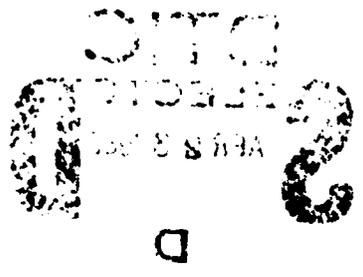
S D

DTIC FILE COPY

AD-A166 791

sensor model, (2) recovery of the image acquisition parameters and (3) three-dimensional (3d) digital map data. Analytical radar mapping techniques address the first two issues. Suitable 3d planimetric map data can be compiled directly from stereo photography using analytical plotters or indirectly using elevation data interpolated from digital elevation models to augment conventional two-dimensional map data derived from manuscripts.)

The approach is illustrated by selected examples from a case study conducted for a test area near Freiburg, West Germany. Here, 3d digital data for transportation and landcover maps were assembled from cartographic sources using planimetric augmentation. Single-image radar resections were performed for digital imagery from the SAR-80 airborne system and SIR-B satellite system using the SMART radargrammetric software system. Map-to-image correspondence was applied to each data set to produce registered map overlays. The approach has important implications for both interactive and automated analysis of SAR data and is well-suited for use in areas of high relief.



IMPLEMENTATION OF MAP-TO-IMAGE-CORRESPONDENCE
FOR SYNTHETIC APERTURE RADAR IMAGE ANALYSIS

George E. Lukes
Research Institute
U.S. Army Engineer Topographic Laboratories
Fort Belvoir, Virginia 22060-5546

J. Hannes Raggam
Technical University and Graz Research Center
Wastiangasse 6
A-8010 Graz, Austria

BIOGRAPHICAL SKETCH

George E. Lukes is a Physical Scientist at the Center for Physical Sciences, USAETL Research Institute. He is a graduate of the University of California, Berkeley and the American University, Washington, D.C. Under Department of Army sponsorship, he spent the 1984-1985 academic year at the Technical University, Graz, Austria.

J. Hannes Raggam is a Geodetic Engineer at the Institute for Image Processing and Computer Graphics, Graz Research Center. He is a graduate in geodesy of the Technical University, Graz and received a doctorate in 1985 based on development of real-time radargrammetric techniques for mapping from satellite synthetic aperture radar imagery.

ABSTRACT

Radargrammetric techniques, developed to support stereo mensuration and data capture from synthetic aperture radar (SAR) imagery, have been extended to enable map-to-image correspondence for computer-assisted radar image analysis. This mechanism projects existing digital map data into the image space of a new SAR image rigorously, accounting for the sensor imaging geometry and terrain configuration.

Prerequisites for SAR map-to-image correspondence include (1) an analytical sensor model, (2) recovery of the image acquisition parameters and (3) three-dimensional (3d) digital map data. Analytical radar mapping techniques address the first two issues. Suitable 3d planimetric map data can be compiled directly from stereo photography using analytical plotters or indirectly using elevation data interpolated from digital elevation models to augment conventional two-dimensional map data derived from manuscripts.

The approach is illustrated by selected examples from a case study conducted for a test area near Freiburg, West Germany. Here, 3d digital data for transportation and landcover maps were assembled from cartographic sources using planimetric augmentation. Single-image radar resections were performed for digital imagery from the SAR580 airborne system and SIR-B satellite system using the SMART radargrammetric software system. Map-to-image correspondence was applied to each data set to produce registered map overlays. The approach has important implications for both interactive and automated analysis of SAR data and is well-suited for use in areas of high relief.

Radar imaging geometry, described by the well-known range equations, is fundamentally different than the perspective imaging geometry of optical systems. Mathematical formulation of radar imaging conditions for specific types of systems, however, provides the basis for predicting image locations corresponding to terrestrial objects, a process analogous to the collinearity condition for optical systems.

Recovery of Image Acquisition Parameters

Recovery of image acquisition parameters, often described as triangulation, is a standard problem in the implementation of either a photogrammetric or radargrammetric system. Early efforts in radar mapping, as described by Norvelle (1972), were conducted on specialized military systems such as the AS-11 analytical plotter. More recent initiatives have been based on the extension of radargrammetric capabilities to commercial analytical plotters as described by Autometric (1982) for the APPS-IV, and Raggam and Leberl (1984) for the Kern DSR-1.

Recovery of acquisition parameters through single image resection and multi-image block adjustment has been demonstrated independently on several systems as a precursor to stereo radar map compilation. For our purposes, the availability of image acquisition parameters is necessary and sufficient to enable map-to-image correspondence for a terrestrial object described by three-dimensional ground coordinates.

Three-Dimensional Digital Map Data

Generation, management and exploitation of digital map data is the major focus of mapping research and development in the world today. In general, digital mapping activities are organized around the production and/or use of two classes of products: digital elevation data or digital elevation models (DEM) and digital planimetric data. Although digital elevation data is inherently three-dimensional, most planimetric data has been digitized from two-dimensional manuscripts. The requirement of three-dimensional digital map data necessary for map-to-image correspondence may be addressed in several ways.

Planimetric Augmentation. Two-dimensional (2d) planimetric data can be converted to three-dimensional (3d) data if a corresponding digital elevation model (DEM) is available. For every 2d coordinate pair in the data set, a corresponding elevation value is interpolated from the DEM to create a 3d coordinate triplet.

Photogrammetric Data Capture. Direct data capture of digital 3d map data from stereoscopic aerial photography using an analytical plotter as a 3d digitizer was demonstrated in the CAPIR program (Lukes, 1981). This approach maximizes metric accuracy and produces 3d planimetric data directly.

Radargrammetric Data Capture. With radargrammetric software such as SMART, it is now feasible to consider mapping directly from stereo SAR imagery using an analytical plotter. This process generates 3d ground coordinates which can be integrated into a digital mapping system.

CASE STUDY -- FREIBURG, WEST GERMANY

The concept of SAR map-to-image correspondence has been demonstrated in a case study conducted at the Institute for Image Processing and

Computer Graphics. The testsite covers an area of 5.5 by 10.0 kilometers which lies west of the city of Freiburg and east of the Rhine River in southwestern West Germany. The area is characterized by diverse land use and is used by many remote sensing research programs.

SAR Imagery

Synthetic aperture radar imagery over the Freiburg testsite has been obtained during several experiments. In 1981, the SAR580 Campaign made an extensive set of SAR acquisitions over the testsite which were digitally processed by DFVLR. In this study, a digital X-band image (3858 pixels by 2255 lines) acquired on 7 July 1981 with a nominal ground resolution of 3 meters was processed to provide an example of airborne SAR imagery. In 1984, the site was imaged from space during the Shuttle Imaging Radar Experiment (SIR-B). A digital image from this data set obtained on 10 October 1984 with a nominal resolution of 25 meters was processed as an example of spaceborne SAR imagery.

Radargrammetric Processing

In all cases, the SMART radargrammetric software was adapted to recover acquisition parameters of the digital images. Ground control was assembled from topographic maps, approximate flight profiles were inferred from incomplete collateral information and inspection of the imagery, image coordinates were measured interactively using the DIBAG digital image processing system and a single image SAR resection was performed.

Digital Map Data

Selected map overlays were compiled from standard 1:50,000 topographic maps and digitized using the DESBOD system. These were transformed to a three-dimensional representation through the process of planimetric augmentation using digital elevation model (20 meter grid spacing).

A transportation map was compiled incorporating roads (autobahn, primary roads, secondary roads), railroads, canals and powerlines. A graphic plot of the transportation map data is presented in Figure 1. A second data set is assembled for landcover classified in 14 categories as shown in Figure 2.

Annotated SAR Imagery via Map-to-Image Correspondence

For each of the four cases in this data set, the image-space overlays were generated via SAR map-to-image correspondence and displayed on the DIBAG digital image processing system. Recorded images with the map data overlays on the SAR images are presented for transportation in Figure 3 and landcover in Figure 4. In each case, use of radargrammetric procedures provides the desired correspondence between image and map data.

DISCUSSION

This example was inspired by the problem of cartographic change detection for map revision. It illustrates the significance of the planimetric augmentation concept as a means of processing existing 2d digital map data. Other earth resources tasks requiring frequent

monitoring are ideal candidates for repetitive SAR coverage. For such applications, SAR map-to-image correspondence could be exploited in the following fashion.

For the geographic area of interest, a 3d digital map data is constructed from stereo metric photography using an analytical plotter. Depending on the application, source material could include small-scale space photography from the NASA Large Format Camera and the ESA Spacelab Metric Camera, or larger scale aerial photography from conventional sources. Task-specific feature maps would be compiled; crop classification studies, for example, would require delineation of individual agricultural fields in selected test areas. A separate data base of distinctive SAR-identifiable ground control points (GCP) would be assembled to support subsequent SAR triangulation.

Routine exploitation of repetitive SAR imagery would require recovery of the image acquisition parameters based on measurement and processing of the SAR GCP. Selected digital map data would then be displayed as overlays on the new imagery using map-to-image correspondence. Based on analysis of the imagery, the data base would be updated. In applications such as crop classification, entry of attribute data interpreted for each specified map feature will be sufficient. Other problems, such as sea ice mapping, will require use of additional radar mapping procedures to enter new positional information into the data base.

This concept has been described in the context of interactive image exploitation where SAR map-to-image correspondence is used to register existing map data to a new radar image to aid the human analyst. This analytical procedure also supports map-guided scene analysis where the objective is automated interpretation of the imagery. While this image understanding research is still in its infancy, exploitation of a priori map information appears to hold significant promise to constrain autonomous search and analysis tasks. Areas of research opportunity have been outlined by McKeown and Lukes (1984) and initial research results in rule-based scene analysis of digital aerial photography in the MAPS/SPAM system have been reported by McKeown, Harvey and McDermott (1985).

Automation of the image triangulation task also holds promise. When reasonable estimates of the image acquisition parameters are available, the approximate location of GCP can be predicted to guide automated matching techniques. A sufficient number of successful matches permits automated determination of precise acquisition parameters.

CONCLUSIONS

The use of map-to-image correspondence to support the analysis of synthetic aperture radar imagery has been demonstrated for both air-borne and spaceborne SAR data. Radargrammetric techniques, developed to solve the geometric aspects of the radar mapping problem, can also play an important role in SAR image exploitation.

The three prerequisites for SAR map-to-image correspondence -- a rigorous sensor model, recovery of acquisition parameters, and three-dimensional digital map data -- can be satisfied for existing data through use of novel procedures and advanced compilation techniques.

Analytical procedures, developed for the current generation of analytical plotter instrumentation to process film-based (hardcopy) imagery,

extend naturally to systems designed to process digital (softcopy) imagery. Much further work is warranted to explore the opportunities presented by the integration of digital map and image data via map-to-image correspondence.

ACKNOWLEDGEMENTS

This research was partially supported by the U.S. Army Research, Development and Standardization Group, London. SIR-B data was provided by the Jet Propulsion Laboratory, Pasadena, California. The SAR580 data is part of the ISPRS Remote Sensing Data Set assembled by Dr. Wolfgang Goepfert. The assistance of many colleagues at the Institute for Image Processing and Computer Graphics including Rudy Huetter, Ewald Pieber, Hubert Ranzinger and Monika Ranzinger is gratefully acknowledged.

REFERENCES

- Autometric (1982) "Program Documentation for Analytical Mapping System Radar Model," USA Engineer Topographic Laboratories, Fort Belvoir, Virginia.
- Lukes, G.E. (1981) "Computer-Assisted Photo Interpretation Research at United States Army Engineer Topographic Laboratories (USAETL)," Techniques and Applications of Image Understanding III, Society of Photo-Optical Instrumentation Engineers, Washington, D.C., April 1981.
- McKeown, D.M. (1984) "Knowledge-Based Aerial Photo Interpretation," Photogrammetria Vol. 39, pp. 91-123.
- McKeown, D.M., W.A. Harvey and J. McDermott (1985) "Rule-Based Interpretation of Aerial Imagery," IEEE Pattern Analysis and Machine Intelligence, Vol. PAMI-7, No. 5, pp. 570-585.
- McKeown, D.M. and G.E. Lukes (1984) "Digital Mapping and Image Understanding," XV International Congress of Photogrammetry and Remote Sensing, Rio de Janeiro, 17-29 June 1984.
- Norvelle, F.R. (1972) "AS-11-A Radar Program," Photogrammetric Engineering, Vol. 38, pp. 77-82.
- Raggam, J. (1984) "Radar Stereo Model Set-up on the Analytical Plotter Kern DSR-1," XV International Congress of Photogrammetry and Remote Sensing, Rio de Janeiro, 17-29 June 1984.
- Raggam, J. and F. Leberl (1984) "SMART - A Program for Radar Stereo Mapping on the Kern DSR-1," Technical Papers of the 50th Annual Meeting of the American Society of Photogrammetry, Vol. 2, pp. 765-773.

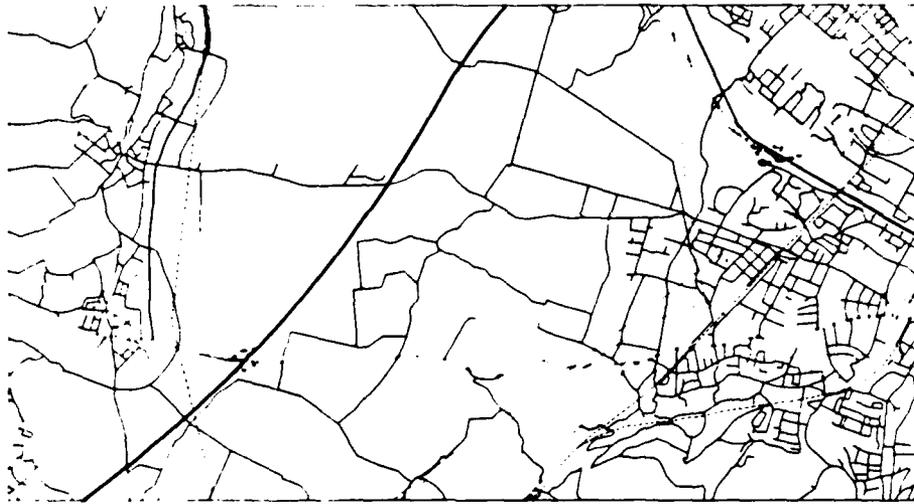


Figure 1. Testsite Transportation Data. Linear features representing the transportation network for the Freiburg test site were compiled from 1:50,000 topographic maps. Delineated features include autobahn, primary (national) roads, secondary roads, railroads, canals and powerlines.

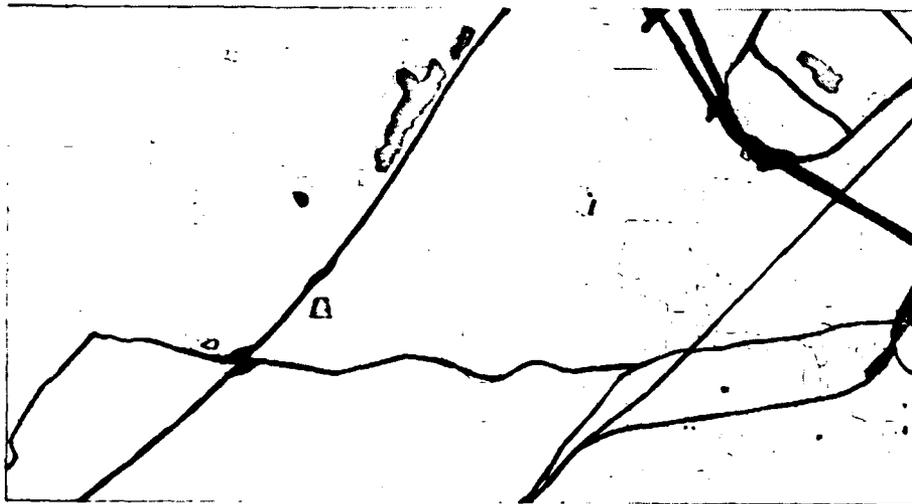


Figure 2. Testsite Landcover Data. Areal features describing Freiburg test site landcover were compiled from 1:50,000 topographic maps. Mapped features include deciduous and mixed forest, marsh, meadow/pasture, vineyard, garden, built-up areas with or without gardens, sports fields, cemetery, mine, right-of-way, open water and undefined areas (typically agricultural fields).

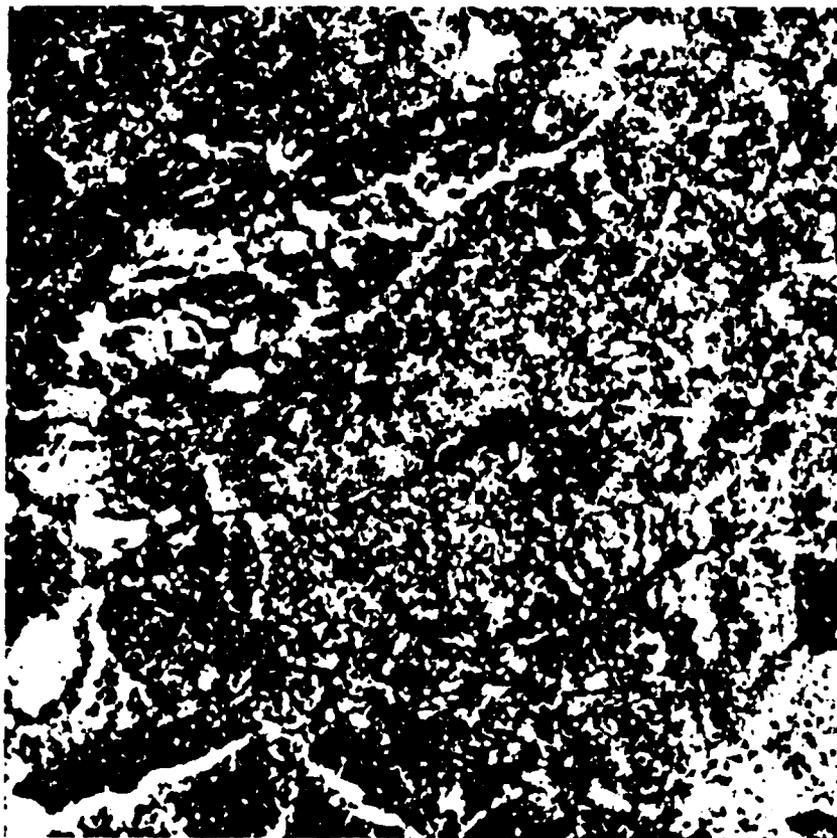


Figure 3. Testsite transportation network projected to overlay onto SAR imagery via map-to-image correspondence: above, airborne SAR580 image; below, SIR-B image acquired from the Space Shuttle.



Figure 4. Testsite landcover data projected to overlay SAR imagery via map-to-image correspondence: above, airborne SAR580 image; below SIR-B image acquired from the Space Shuttle.

END
FILMED

5-86

DTIC