

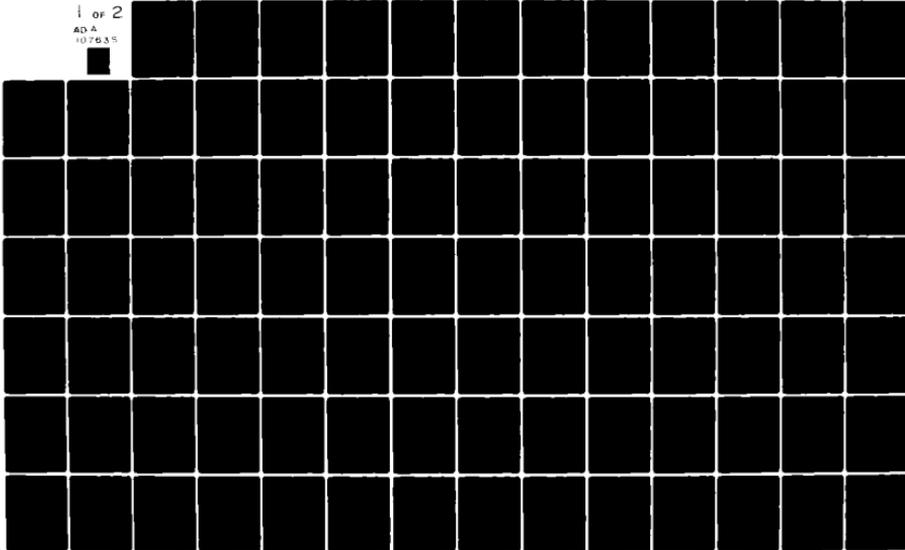
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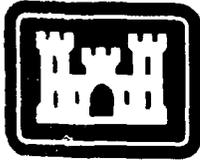
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TECHNICAL REPORT K-81-2

THEORETICAL BASIS FOR CTABS80: A COMPUTER PROGRAM FOR THREE-DIMENSIONAL ANALYSIS OF BUILDING SYSTEMS

by

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September 1981

Final Report

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THEORETICAL BASIS FOR CTABS80



Prepared for Office, Chief of Engineers, U. S. Army
Washington, D. C. 20314

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U. S. Army Engineer Waterways Experiment Station
P. O. Box 631, Vicksburg, Miss. 39180

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20. ABSTRACT (Continued)

vertical columns (or piers) and horizontal beams (or spandrels). However, with special modeling techniques, very complex situations may be considered. A special shear panel element is developed to enable modeling of discontinuous shear walls and shear walls with arbitrary openings. A diagonal bracing system to model braced frames (X-braced, K-braced, or eccentrically braced systems) is also presented.

The column, shear panel, and diagonal formulations include the effects of bending, axial, and shear deformations. Bending and shear deformations are also included in the beam formulation; however, the effects of axial deformations are neglected.

The effects of the finite dimensions of the beams and columns on the stiffness of a frame or shear wall system are automatically included.

The buildings may be unsymmetrical and nonrectangular in plan. Torsional behavior and interstory compatibility are accurately reflected in the results.

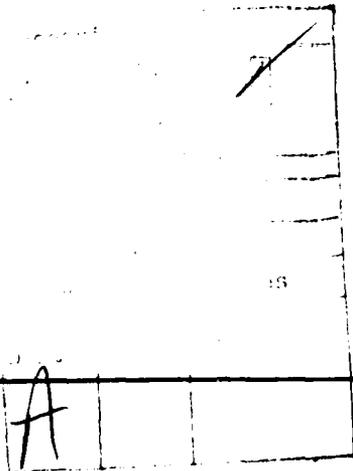
Four independent vertical and two independent lateral static load conditions are possible in any one run. These six static load conditions may be combined in any ratio to each other or to a lateral dynamic earthquake input which may be specified as a time-dependent ground acceleration or as an acceleration response spectrum.

Three-dimensional mode shapes and frequencies are evaluated.

The unique solution procedure used by CTABS80 considers the frame and shear walls as substructures, reduced with a modified wave front technique. This method results in a significant reduction in the program data preparation, computational effort, and storage requirements.

The consecutive levels of each of the individual frames can be arbitrarily connected to any (sequential by not necessarily consecutive) level of the structure, thereby making it possible for frames to bypass certain story levels. This option gives the program the capability to model partial diaphragms and multidiaphragms at any level.

A user's guide for the program is presented in Waterways Experiment Station Instruction Report K-81-9.



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PREFACE

This report presents the theoretical basis for a computer program called CTABS80 that can be used for static and dynamic analysis of multi-story frame and shear wall buildings. Dr. E. H. Wilson, University of California, Berkeley, was responsible for developing the original version of the program (TABS), sponsored mainly by a National Science Foundation Grant.

Modifications to the program to make it a more useful tool for Corps of Engineers' personnel were made by Mr. Ashraf Habibullah, Computers/Structures International, Oakland, Calif. His work was sponsored with funds provided to the Automatic Data Processing (ADP) Center, U. S. Army Engineer Waterways Experiment Station (WES), Vicksburg, Miss., by the Military Programs Directorate of the Office, Chief of Engineers, U. S. Army (OCE), under the Computer-Aided Structural Engineering (CASE) Project. This report and a companion user's guide for CTABS80 are the work of Dr. Wilson and Messrs. H. H. Dovey and Habibullah.

Specifications for the modifications to TABS were provided by the members of the CASE Task Group on Building Systems. The following were members of the Task Group (though all may not have served for the entire period) during the period of modifications to the program:

- Mr. Dan Reynolds, Sacramento District (Chairman)
- Mr. Jerry Foster, Baltimore District
- Mr. Joseph Hartman, St. Louis District
- Mr. David Illias, Portland District
- Mr. Sefton Lucas, Memphis District
- Mr. Jun Ouchi, Pacific Ocean Division
- Mr. David Raisanen, North Pacific Division
- Mr. Pete Rossbach, Baltimore District
- Mr. James Simmons, Baltimore District
- Mr. Ollie Werner, Middle East Division
- Mr. Gene Wyatt, Mobile District

Dr. N. Radhakrishnan, Special Technical Assistant, ADP Center, WES, and CASE Project Manager, and Mr. Paul K. Senter, Computer-Aided Design Group (CADG), ADP Center, coordinated and monitored the work. Ms. Deborah K. Martin, CADG, supported the Task Group in changing the program to accept free-field input. Mr. Seymour Schneider, Military Programs Directorate, was the OCE point of contact. Mr. Donald L. Neumann was Chief, ADP Center.

Directors of WES during this period were COL J. L. Cannon, CE, COL N. P. Conover, CE, and COL T. C. Creel, CE. Technical Director was Mr. F. R. Brown.

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CONVERSION FACTORS, INCH-POUND TO METRIC (SI)
UNITS OF MEASUREMENT

Inch-pound units of measurement used in this report can be converted to metric (SI) units as follows:

<u>Multiply</u>	<u>By</u>	<u>To Obtain</u>
feet	0.3048	metres
inches	2.54	centimetres
kips (1000 lb force)	4.448222	kilonewtons
kips (force) per foot	14.593904	kilonewtons per metre
pounds (force) per square foot	47.880263	pascals
pounds (mass) per cubic foot	16.01846	kilograms per cubic metre

THEORETICAL BASIS FOR CTABS80: A COMPUTER
PROGRAM FOR THREE-DIMENSIONAL ANALYSIS
OF BUILDING SYSTEMS

CHAPTER I: INTRODUCTION

A. Purpose

This report presents the theoretical basis for CTABS80, a computer program for the linear three-dimensional structural analysis of multistory frame and shear wall buildings subjected to static and dynamic loadings. A user's guide for the program is presented in Waterways Experiment Station (WES) Instruction Report K-81-9⁽¹⁸⁾.

B. General-Purpose Programs for Structural Analysis

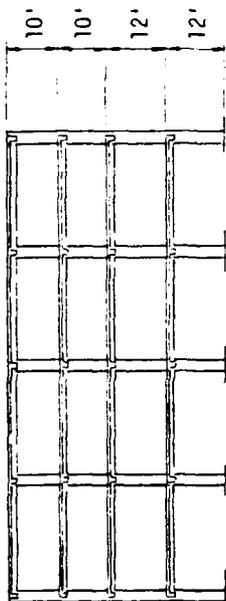
There are many two- and three-dimensional computer programs for the linear analysis of complex structures ^(1,2). Most of these programs can be used for the static and dynamic analysis of multistory frame and shear wall buildings. However, most of these programs do not give special recognition to the fact that building systems in themselves are a very special class of structures from an analytical point of view. The following are some of the characteristics that are inherent in the nature of a building analysis that a general-purpose analysis program may not recognize, thereby resulting in significant losses in man-hours, computer time, and possibly accuracy:

1. Most buildings are of simple geometry with horizontal beams and vertical columns. A simple rectangular grid can define such a geometry

vertical columns. A simple rectangular grid can define such a geometry with minimal input. See Figure 1.

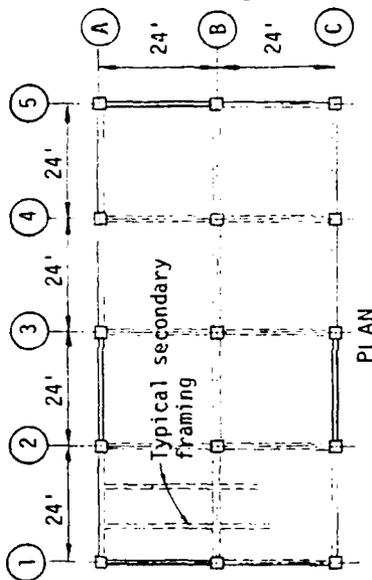
2. Many of the frames and shear walls are typical. Most general-purpose programs do not recognize this fact; therefore, the input may be large, and some internal calculations may be unnecessarily duplicated.
3. The in-plane stiffnesses of the floor systems of most buildings are very high. General-purpose programs do not necessarily recognize this, resulting in a set of equilibrium equations which may be very large, and thereby causing an increase in computation effort by a factor of 10 to 100. Also, numerical errors may be introduced since the in-plane floor stiffnesses are several orders of magnitude greater than the story-to-story stiffnesses of the structure. Since these two stiffnesses are added in a direct stiffness approach, double precision may be required in the solution.
4. The loading in building systems is of a restricted form. Loads, in general, are either vertically down (dead or live) or lateral (wind or seismic). The vertical loads are usually applied on the beams, and the lateral loads are generated at the floor levels.
5. In many buildings, the dimensions of the members are large and have a significant effect on the stiffness of the frame. Therefore, corrections need to be applied to the member stiffnesses. Most general-purpose programs work on center-line dimensions, and stiffness corrections are usually very tedious to implement.
6. In the dynamic analysis of buildings, the mass of the structure can be accurately lumped at the floor levels. Recognizing this fact

Horizontal rigid diaphragms connecting the frames at each level



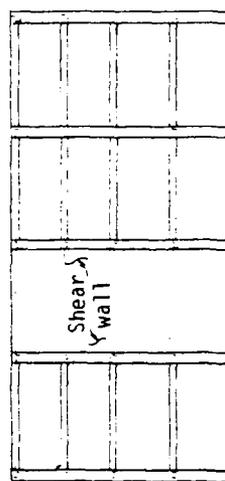
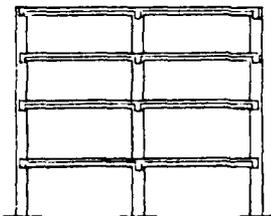
ELEVATION - FRAME ALONG LINE (B)

ELEVATION - TYPICAL FRAME ALONG LINES (1) AND (5)



PLAN

ELEVATION - TYPICAL FRAME ALONG LINES (2) (3) AND (4)



ELEVATION - TYPICAL FRAME ALONG LINES (A) AND (C)

NOTE/

Structure has 4 typical frames and 8 total frames

Figure 1. Typical frame and shear wall building

significantly reduces the size of the eigenvalue problem to be solved.

7. Various code loading requirements necessitate special options that allow convenient combinations of the vertical and lateral static and dynamic loadings. Also, the member forces need to be printed out at the support faces of the members. Such transformations are not automatic in general-purpose programs.
8. It is desirable to have a building analysis computer output printed in a special format; i.e., in terms of a particular frame, story, column, and beam. Also, special output such as story shears may be desirable.

In light of the above-mentioned and other reasons, the need for special-purpose programs for building analysis is apparent.

C. Special-Purpose Programs for Building Analysis

Various programs have been developed at the University of California at Berkeley for the linear analysis of multistory buildings in the past two decades (4,5,6). These programs have been used in the profession on many major structures in many different countries. One of the major reasons for the development of computer program TABS (1,2,3) was the direct "feedback" from the profession in the use of these programs.

The first of these programs, FRMSTC, is a static load analysis program for symmetrical buildings with parallel frames and shear walls. Lateral mode shapes and frequencies are also evaluated.

Program FRMDYN is the same as FRMSTC except that the load input is ground accelerations due to a specified earthquake. Time-dependent displacements and member forces are produced but are not combined with static loads.

Program LATERAL is an extension of FRMSTC to the static analysis of a system of frames and shear walls which are not parallel. Three degrees of freedom exist at each story level. This program does not have dynamic options.

The first version of TABS was released in 1972, with the intent of replacing the computer programs described above. CTABS80 is an enhanced version of the original version of TABS and is intended to supercede other enhanced versions such as XTABS and TABS77.

The computer program ETABS ⁽¹⁵⁾ was released in 1975. The program allows three-dimensional frame input in which common column compatibility is enforced. The input data are more complex than those of TABS, and use of this program is only recommended if common column compatibility is important.

For buildings with other complexities, such as discontinuous or flexible diaphragms, sloped diaphragm, nonrectangular framing systems, etc., a general-purpose program such as SAPIV ⁽¹²⁾ or EASE2 ⁽¹¹⁾ is still the most appropriate solution tool.

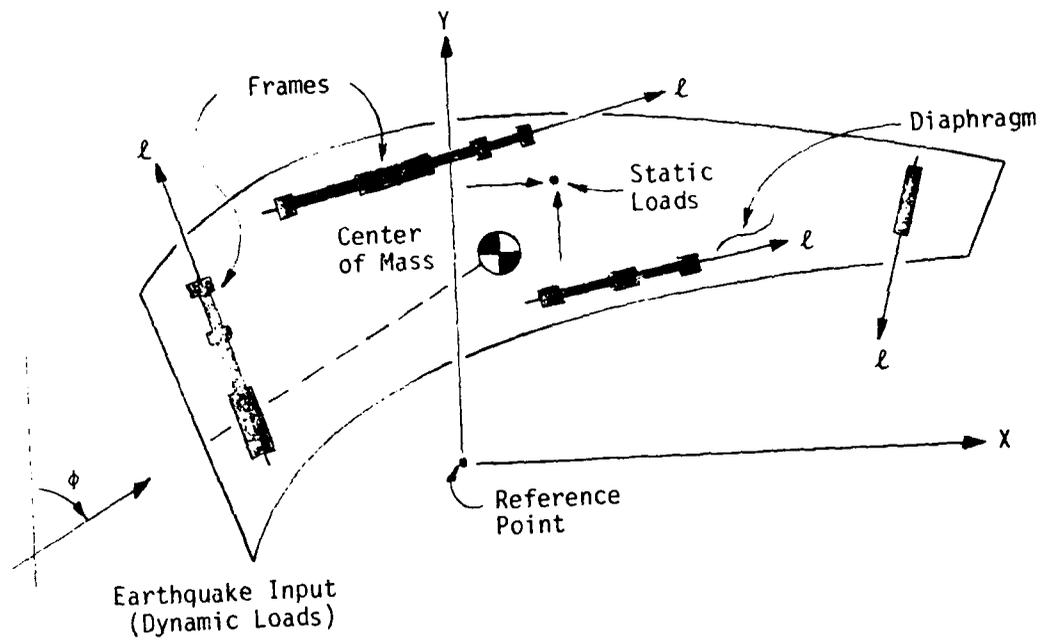
D. Disclaimer

Considerable time, effort, and expense have gone into the development and documentation of CTABS80, and the program has been thoroughly tested and used. In using the program, however, the user accepts and understands that no warranty is expressed or implied, either by the sponsors, the developers, or the distributors, as to the accuracy or the reliability of the program. The user must clearly understand the basic assumptions of the program and must verify his own results.

CHAPTER II: STRUCTURAL IDEALIZATION

An exact three-dimensional structural analysis is required for only a limited number of buildings. For the majority of buildings the following approximations can be made. These approximations greatly simplify the preparation of input data and significantly reduce the computational efforts associated with the analysis of the structure.

1. The structure is idealized as an assemblage of vertical planar "frames". A frame consists of m columns and $(m-1)$ beams. As long as shear and bending deformations are included in all members there is no need to distinguish between a shear wall/spandrel versus a beam/column system. See Figure 2.
2. The out-of-plane stiffnesses of all frames are assumed to be zero. Therefore each column at every floor has two degrees of freedom, a vertical displacement and a rotation. In addition, there is one lateral degree of freedom at every floor level of the frame.
3. Each floor is modeled as a horizontal diaphragm. This diaphragm is assumed to be infinitely stiff in-plane. The out-of-plane stiffness of this diaphragm is neglected. Bending stiffness of the floors may be included approximately in the modeling of the individual frames. It is apparent that axial deformation is not permitted in the beams. Floor levels must be the same for all frames. See Figure 2.
4. The floor diaphragm connects all the frames together at the corresponding level. The connection is only in a lateral sense. The frames otherwise are completely independent of each other. This also means that compatibility is not enforced with regard to



PLAN

Figure 2. Typical story level

displacements at columns which are common to more than one frame. Thus axial deformations in common columns will not be the same. As for joint rotations, if the frames with common members are perpendicular in plan view, then the rotations are uncoupled. This assumption invalidates the program for use in the analysis of structures in which the tubular effect or common column compatibility is important.

5. Vertical loads are applied to each frame on a tributary area basis. The diaphragm will not transfer any vertical load from one frame to another. However, no frame can sidesway independently without engaging the other frames.
6. Lateral loads are applied as loads for the complete floor at each level. The loads are applied at specified locations on the floor diaphragms and get distributed to the various frames in accordance with their corresponding stiffnesses and locations.

A. The Frame Substructure

The elevation of a typical frame is shown in Figure 3. The frame is basically of rectangular geometry with vertical column center lines and horizontal floor levels as the basic reference lines for the description of the frame.

The frame is an assemblage of column, beam, panel, and bracing elements. Vertical loading is applied to the individual frames by means of loading patterns associated with each beam.

The column and beam elements have options for rigid offsets at each end to compensate for the effects of the finite dimensions of the members on

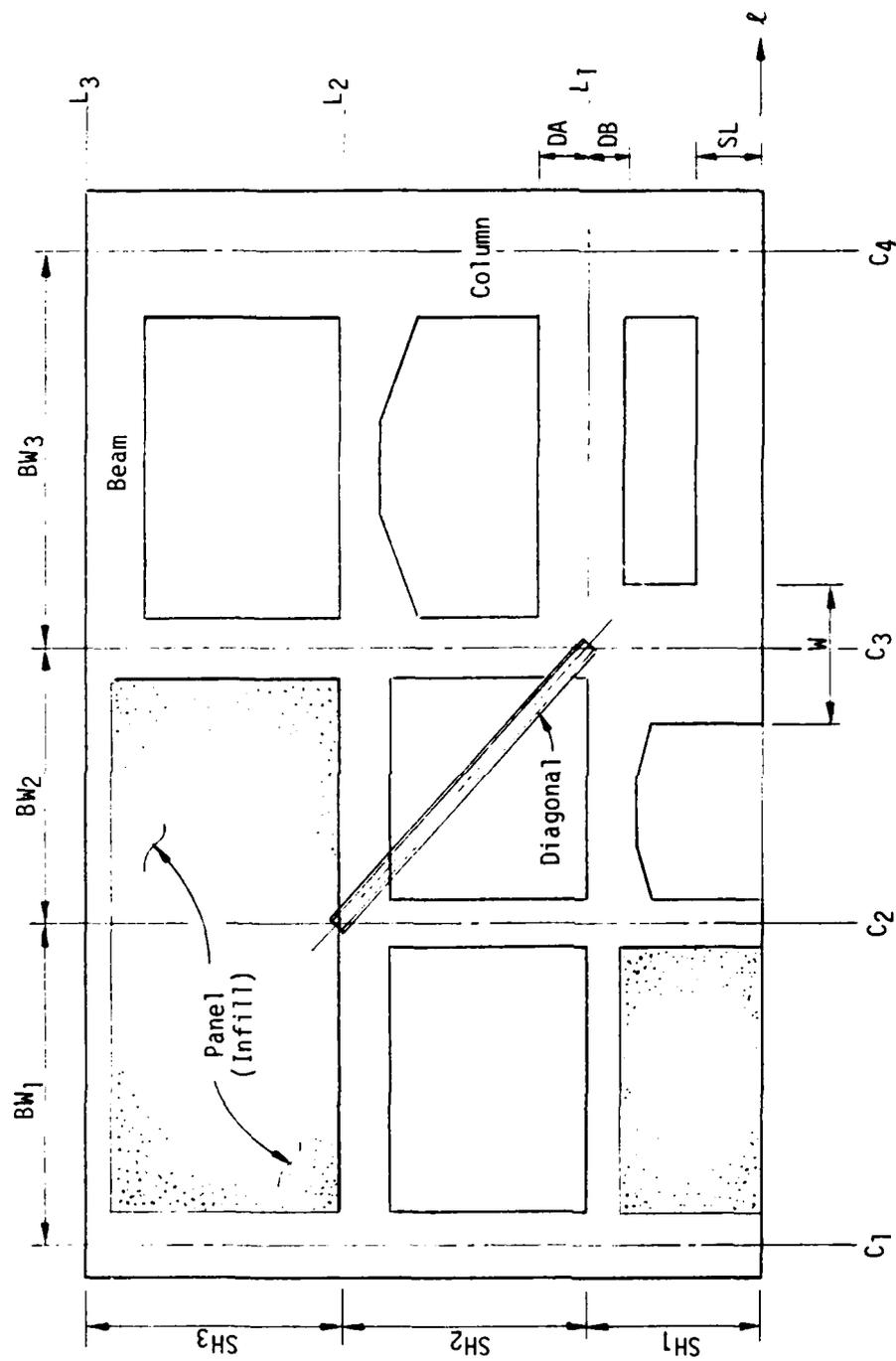


Figure 3. Elevation of typical frame

the stiffness of the system. The procedure used to set the lengths of these rigid offsets is presented later in this report.

(i). Individual Member Stiffnesses

The complete stiffness matrix of each frame is assembled by the direct stiffness technique. This involves calculating the local stiffness matrix, \underline{k} , for each member along with a transformation matrix, \underline{a} , which transforms the local displacements and forces, $\underline{\phi}$, \underline{S} , to global displacements and forces, \underline{r} , \underline{R}

$$\begin{array}{ll} \text{or: } \underline{\phi} = \underline{a} \underline{r} & \text{also: } \underline{S} = \underline{k} \underline{\phi} \\ \underline{S} = \underline{a} \underline{R} & \text{and: } \underline{R} = \underline{K} \underline{r} \end{array}$$

where \underline{K} is the stiffness matrix in global coordinates.

Substituting $\underline{\phi} = \underline{a} \underline{r}$ and $\underline{S} = \underline{a} \underline{R}$ into $\underline{S} = \underline{k} \underline{\phi}$ we get:

$$\underline{a} \underline{R} = \underline{k} \underline{a} \underline{r}$$

Premultiply both sides by \underline{a}^T and recognizing $\underline{a}^T \underline{a} = \underline{I}$ we get:

$$\underline{a}^T \underline{a} \underline{R} = \underline{a}^T \underline{k} \underline{a} \underline{r}$$

$$\underline{R} = \underline{a}^T \underline{k} \underline{a} \underline{r}$$

$$\text{As } \underline{R} = \underline{k} \underline{r} \text{ we get } \underline{K} = \underline{a}^T \underline{k} \underline{a}$$

Thus knowing the local stiffness matrix \underline{k} and the coordinate transformation matrix \underline{a} the global stiffness matrix may be evaluated.

The \underline{a} and \underline{k} matrices for the column, beam, panel, and brace elements are presented in Figures 4, 5, 6, and 7, respectively.

$$\begin{Bmatrix} M_i \\ M_j \\ S \end{Bmatrix} = \begin{bmatrix} S_a & S_b & 0 \\ S_b & S_a & 0 \\ 0 & 0 & S_c \end{bmatrix} \begin{Bmatrix} \phi_i \\ \phi_j \\ \delta \end{Bmatrix}$$

$$S_c = k_c \phi_c$$

FORCE/DEFORMATION TRANSFORMATION

$$\begin{Bmatrix} \phi_i \\ \phi_j \\ \delta \end{Bmatrix} = \begin{bmatrix} 1 + \frac{b}{h} & \frac{1}{h} & \frac{a}{h} & -\frac{1}{h} & 0 & 0 \\ \frac{b}{h} & \frac{1}{h} & 1 + \frac{a}{h} & -\frac{1}{h} & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{Bmatrix} \theta_B \\ u_B \\ \theta_T \\ u_T \\ v_B \\ v_T \end{Bmatrix}$$

$$\phi_c = \begin{bmatrix} a_c \\ r_c \end{bmatrix}$$

DEFORMATION/DISPLACEMENT TRANSFORMATION

$$k_c = \begin{bmatrix} a_c^T & k_c & a_c \end{bmatrix}$$

COLUMN STIFFNESS MATRIX
(6x6)

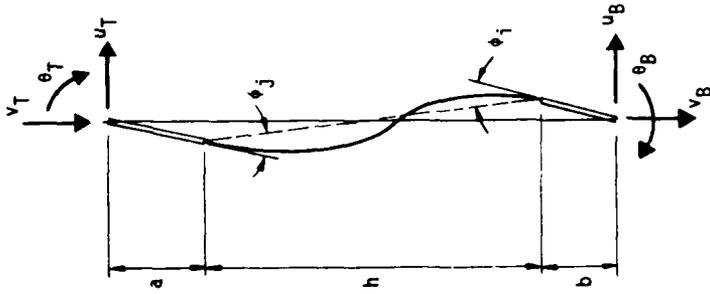


Figure 4

$$\begin{Bmatrix} M_i \\ M_j \end{Bmatrix} = \begin{bmatrix} s_a & s_b \\ s_b & s_a \end{bmatrix} \begin{Bmatrix} \phi_i \\ \phi_j \end{Bmatrix}$$

$$s_b = k_b \phi_b$$

FORCE/DEFORMATION TRANSFORMATION

$$\begin{Bmatrix} \phi_i \\ \phi_j \end{Bmatrix} = \begin{bmatrix} 1 + \frac{b}{L} & \frac{1}{L} & \frac{a}{L} & -\frac{1}{L} \\ \frac{b}{L} & \frac{1}{L} & 1 + \frac{a}{L} & -\frac{1}{L} \end{bmatrix} \begin{Bmatrix} \theta_L \\ v_L \\ \theta_R \\ v_R \end{Bmatrix}$$

$$\phi_b = \begin{bmatrix} a_b & r_b \end{bmatrix}$$

DEFORMATION/DISPLACEMENT TRANSFORMATION

$$k_{-b} = \begin{bmatrix} a_b^T & k_b & a_b \end{bmatrix}$$

BEAM STIFFNESS MATRIX

(4x4)

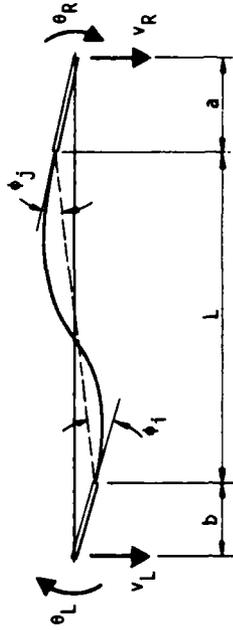


Figure 5

$$\begin{Bmatrix} M_i \\ M_j \\ S \end{Bmatrix} = \begin{bmatrix} S_a & S_b & 0 \\ S_b & S_a & 0 \\ 0 & 0 & S_c \end{bmatrix} \begin{Bmatrix} \phi_i \\ \phi_j \\ \delta \end{Bmatrix}$$

$$S_c = k_c \phi_c$$

FORCE/DEFORMATION TRANSFORMATION

$$\begin{Bmatrix} \phi_i \\ \phi_j \\ \delta \end{Bmatrix} = \begin{bmatrix} \frac{1}{h} & -\frac{1}{h} & -\frac{1}{L} & \frac{1}{L} & 0 & 0 \\ \frac{1}{h} & \frac{1}{h} & -\frac{1}{h} & 0 & -\frac{1}{L} & \frac{1}{L} \\ 0 & 0 & \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} \end{bmatrix} \begin{Bmatrix} u_B \\ u_T \\ v_{LB} \\ v_{RB} \\ v_{LT} \\ v_{RT} \end{Bmatrix}$$

$$\phi_p = a_p^T r_p$$

DEFORMATION/DISPLACEMENT TRANSFORMATION

$$k_p = a_p^T k_p a_p$$

PANEL STIFFNESS MATRIX
(6x6)

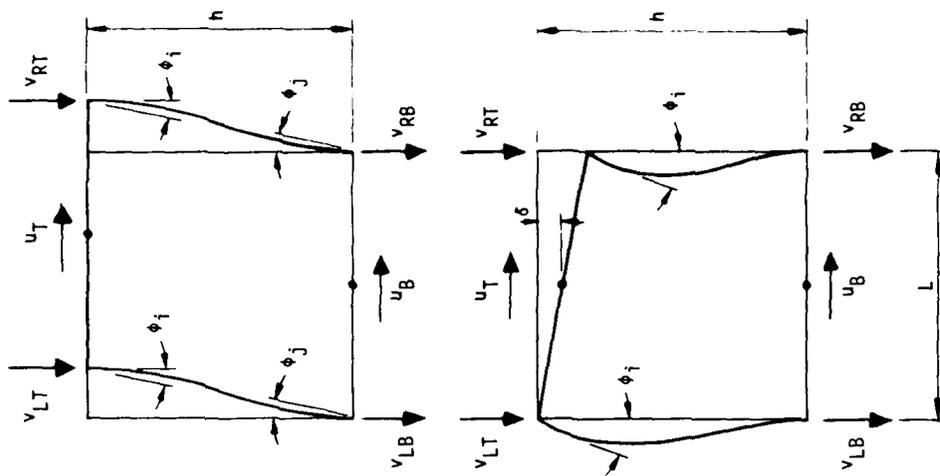


Figure 6

$$\begin{Bmatrix} M_i \\ M_j \\ S \end{Bmatrix} = \begin{bmatrix} s_a & s_b & 0 \\ s_b & s_a & 0 \\ 0 & 0 & s_c \end{bmatrix} \begin{Bmatrix} \phi_i \\ \phi_j \\ \delta \end{Bmatrix}$$

$$s_D = k_D \phi_D$$

FORCE/DEFORMATION TRANSFORMATION

$$\begin{Bmatrix} \phi_i \\ \phi_j \\ \delta \end{Bmatrix} = \begin{bmatrix} 1 & \frac{h}{DD} & 0 & -\frac{h}{DD} \\ 0 & \frac{h}{DD} & 1 & -\frac{h}{DD} \\ 0 & -\frac{L}{D} & 0 & \frac{L}{D} \end{bmatrix} \begin{Bmatrix} \theta_B \\ u_B \\ \theta_T \\ u_T \\ v_B \\ v_T \end{Bmatrix}$$

$$\phi_D = \begin{bmatrix} \theta_D \\ r_D \end{bmatrix}$$

DEFORMATION/DISPLACEMENT MATRIX

$$k_D = \begin{bmatrix} k_D^T & k_D \\ k_D & k_D \end{bmatrix}$$

DIAGONAL (BRACE) STIFFNESS MATRIX

(6x6)

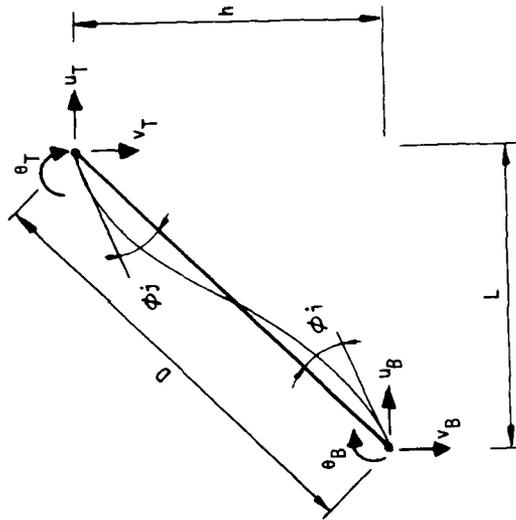


Figure 7

The column element formulation accounts for bending, axial and shear deformations. The basic stiffness matrix for such an element is shown in Figure 8. The column ends have options for rigid offsets. Figure 4 shows the six degrees of freedom associated with the column element and the deformation displacement transformation matrix linking the frame joint displacements to the column end deformations.

The beam element formulation is similar to that of the column except that the axial force component is dropped leaving a stiffness and transformation matrix as shown in Figure 5.

The panel element formulation is basically the same as that of the column except that each rotational degree of freedom is transformed into the two vertical displacements of the column lines bounding the panel element at each corresponding level. The axial degrees of freedom of the panel are also transformed as being an average of the vertical degrees of freedom of the two column lines bounding the panel element at each corresponding level. The degrees of freedom of the frame associated with the panel are therefore all translational. No rigid offsets are used. see Figure 6.

The diagonal element formulation is exactly the same as that of the column except that the brace is inclined and no rigid offsets are used. See Figure 7.

$$\begin{Bmatrix} M_i \\ M_j \\ S \end{Bmatrix} = \begin{bmatrix} S_a & S_b & 0 \\ S_b & S_a & 0 \\ 0 & 0 & S_c \end{bmatrix} \begin{Bmatrix} \phi_i \\ \phi_j \\ \delta \end{Bmatrix}$$

FORCE/DEFORMATION TRANSFORMATION

Where: $S_a = \frac{2EI}{L} \left(\frac{2}{1+2\beta} \right)$

$S_b = \frac{2EI}{L} \left(\frac{1-\beta}{1+2\beta} \right)$

$S_c = \frac{AE}{L}$

$\beta = \frac{6EI}{L^2 \bar{A} G}$

A = axial area

\bar{A} = effective shear area

I = moment of inertia

E = elastic modulus

G = shear modulus

L = length

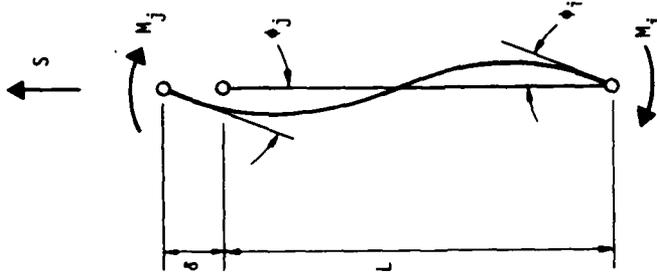


Figure 8

FLEXURAL MEMBER WITH AXIAL DEFORMATIONS

The complete stiffness matrix for each frame has two degrees of freedom for each beam-column intersection and one lateral degree of freedom per story.

(ii). Lateral Frame Stiffness

With the frame degrees of freedom appropriately ordered, the frame equilibrium equations have the form shown in Figure 9 . Where N is the number of stories in the frame, r_n is the vector of joint displacements (that is vertical displacement and rotation) at story level n and r_L is the vector of lateral story displacements. Lateral loads are applied to the complete structure and are considered when the lateral stiffness matrix for the complete building is assembled. Gaussian elimination is performed on the full system up to and including the equations:

$$R_N = C_{N-1} r_{N-1} + K_N r_N + E_N r_L$$

The last N equations (r_L is a vector of order N) may now be written as:

$$R_L = K_L r_L$$

The vector R_L is the lateral load submatrix of the frame and is modified by the elimination process due to vertical loading on the frame. These terms represent the sidesway effects under vertical loading. The matrix K_L clearly represents the frame lateral stiffness matrix; i.e., the stiffness matrix of the frame in terms of only the lateral story displacements.

Within the computer program the following approach is adopted in order to reduce storage requirements. The assembly and reduction process is

				SIZE
R_1	$K_1 \quad C_1$	E_1	r_1	2NC
R_2	$C_1^T \quad K_2 \quad C_2$	E_2	r_2	2NC
R_3	$C_2^T \quad K_3 \quad C_3$	E_3	r_3	2NC
\vdots	$\vdots \quad \vdots \quad \vdots$	\vdots	\vdots	
R_n	$\vdots \quad \vdots \quad \vdots$	E_n	r_n	2NC
R_{n+1}	$C_n^T \quad K_{n+1}$	E_{n+1}	r_{n+1}	2NC
\vdots	$\vdots \quad \vdots \quad \vdots$	\vdots	\vdots	
R_{N-1}	$\vdots \quad \vdots \quad \vdots$	$K_{N-1} \quad C_{N-1} \quad E_{N-1}$	r_{N-1}	2NC
R_N	$\vdots \quad \vdots \quad \vdots$	$C_{N-1}^T \quad K_N \quad E_N$	r_N	2NC
R_L	$E_1^T \quad E_2^T \quad \dots \quad E_n^T \quad E_{n+1}^T \quad \dots \quad E_{N-1}^T \quad E_N^T \quad K_L$	$\vdots \quad \vdots \quad \vdots$	r_L	NS+1

The equations in core at any one time are blocked out above.

NC = No. of Column Lines NS = No. of Stories

Figure 9. Complete equation system of frame substructure

carried out systematically story by story from the top of the structure such that at any level, n , we consider the system shown below:

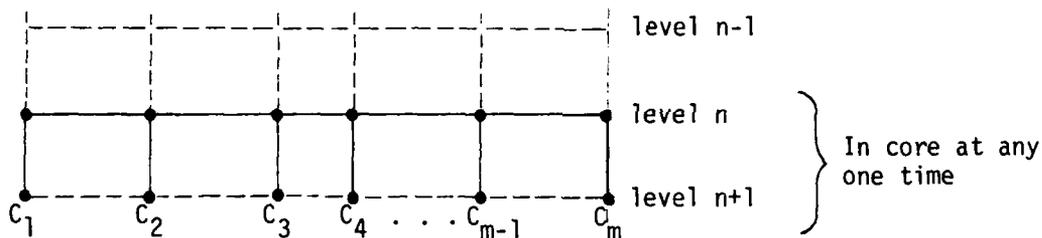
$$\begin{Bmatrix} R'_n \\ R'_{n+1} \\ R'_L \end{Bmatrix} = \begin{bmatrix} K'_n & C'_n & E'_n \\ C'^T_n & K'_{n+1} & E'_{n+1} \\ E'^T_n & E'^T_{n+1} & K'_L \end{bmatrix} \begin{Bmatrix} r_n \\ r_{n+1} \\ r_L \end{Bmatrix}$$

where the prime indicates that the submatrices may have been modified by previous elimination.

At each level the following steps are performed:

- a. Add in the individual member stiffnesses for level n .

These are shown below:



- b. Perform the elimination on the equations of the uppermost partition in the equations above
- c. Save these reduced equations for subsequent back-substitution.
- d. Rearrange the submatrices in the equation above appropriately in order to proceed to the next level. This rearrangement is as follows:

$$\begin{Bmatrix} R'_{-n+1} \\ \underline{0} \\ R'_L \end{Bmatrix} = \begin{bmatrix} K'_{n+1} & \underline{0} & E'_{n+1} \\ \underline{0} & \underline{0} & \underline{0} \\ E'^T_{-n+1} & \underline{0} & K'_L \end{bmatrix} \begin{Bmatrix} r_{n+1} \\ r_{-n+2} \\ r_L \end{Bmatrix}$$

e. Repeat the above steps for the next level. Thus after the elimination is completed for joint displacements at all story levels, we are left with the lateral stiffness matrix for the frame.

(iii). Rigid Joint Offset For Beams and Columns

The deformations within the joint, an area bounded by the finite dimensions of any beam and column intersection (shown shaded in Figure 10) are neglected. In other words, this area is assumed to be an infinitely rigid rectangular diaphragm.

This is achieved by providing rigid offsets at the ends of the beams equal in length to one half of the widths of the column below at each corresponding end. Rigid offsets are also provided at each end of the columns equal to the depth of the larger of the beams on either side of the column at the corresponding level.

It has been found that, in general, a reduction in the lengths of the rigid offsets to compensate for some deformation that may exist in the joint is justifiable and gives better results, especially in cases where the member dimensions are substantial. See Reference 9.

Reduction of the rigid link dimension has been coupled to the size of the member. In other words, the rigid link is calculated as described above and then is reduced by 25% of the dimension of the member, at each end.

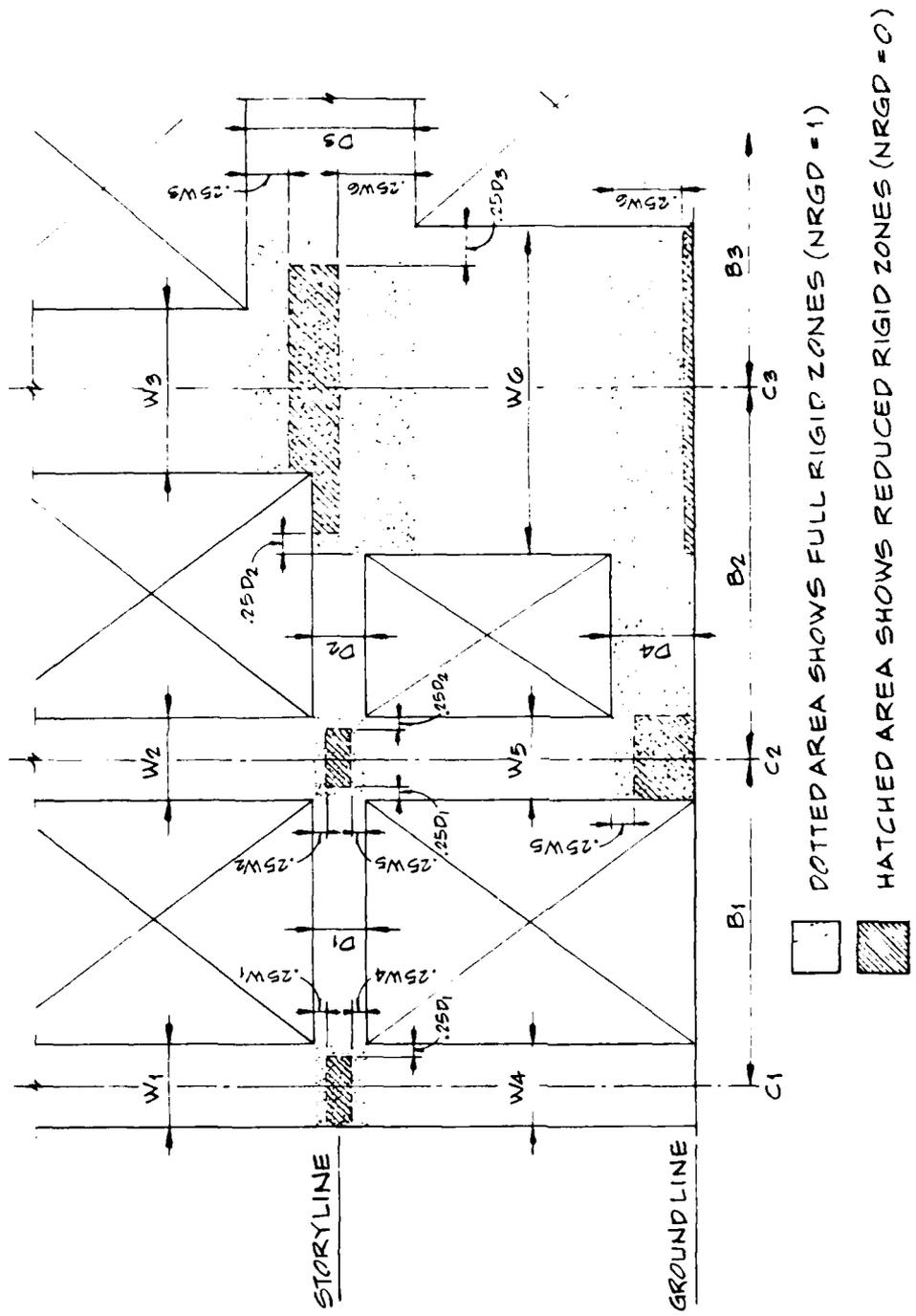


Figure 10. Illustration of rigid zone reduction methodology

Thus the beam rigid links are reduced by 25% of the beam depth and the column rigid links are reduced by 25% of the column width at each end. The reduction cannot, of course, result in a negative rigid link length. This reduction procedure is optional. If no column widths or beam lengths are input the rigid link lengths degenerate to zero and the analysis is carried out on the frame grid line basis.

B. The Complete Structure

In order to combine the frame lateral stiffness matrices into a complete structure lateral stiffness matrix, each of the frame stiffnesses must be transformed to a common displacement coordinate system (which will be referred to as the global system). The global system chosen is two translations and one rotation per story. The origin of these global displacement coordinates at each story level is taken at the center of mass of that story segment. This position may vary from story to story. Such a formulation will degenerate the mass matrix to a diagonal form, thus simplifying the eigen-value problem in the dynamics.

The first step is to develop the transformation between the frame lateral displacements and the global displacements. With reference to Figure 11, the transformation at any level, n , is as follows:

$$r_{Ln} = \langle \cos\alpha \quad \sin\alpha \quad -d_n \rangle \begin{Bmatrix} r_{xn} \\ r_{yn} \\ r_{\theta n} \end{Bmatrix}$$

or: $r_{Ln} = a_n r_n$

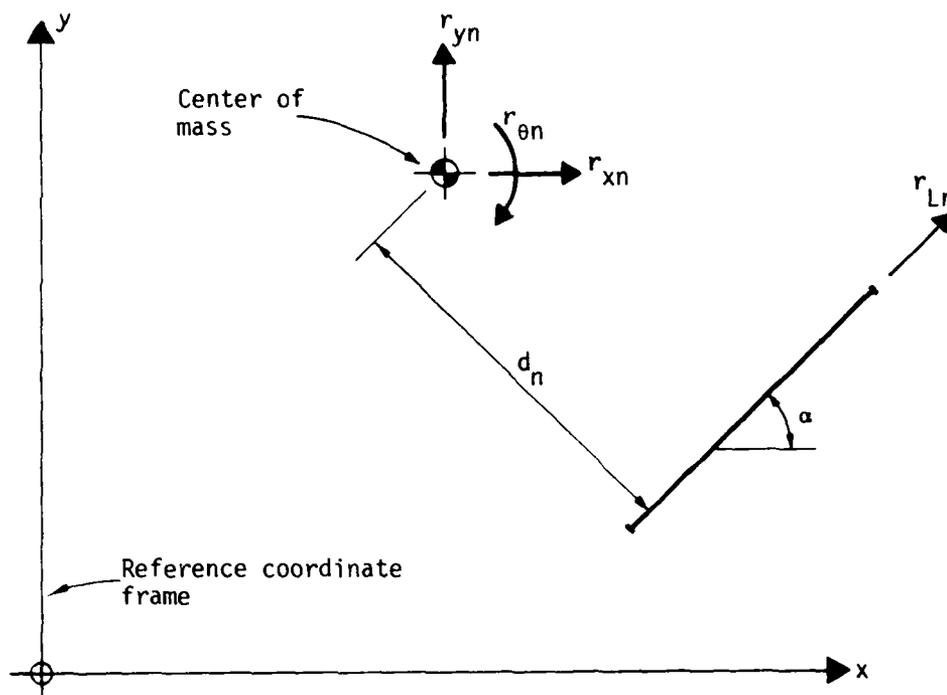


Figure 11. Structural global lateral displacements and frame local lateral displacements

Assembling the transformations for all floors, we obtain the complete transformation between frame lateral displacements and global displacement as follows:

$$\begin{Bmatrix} r_{L1} \\ r_{L2} \\ \cdot \\ \cdot \\ r_{Ln} \\ \cdot \\ \cdot \\ r_{LN} \end{Bmatrix} = \begin{bmatrix} a_1 & & & & & & & \\ & a_2 & & & & & & \\ & & \cdot & & & & & \\ & & & \cdot & & & & \\ & & & & a_n & & & \\ & & & & & \cdot & & \\ & & & & & & \cdot & \\ & & & & & & & a_N \end{bmatrix} \begin{Bmatrix} r_1 \\ r_2 \\ \cdot \\ \cdot \\ r_n \\ \cdot \\ \cdot \\ r_N \end{Bmatrix}$$

or:

$$r_{Li} = A_i r$$

r is the complete vector of global displacements. The frame lateral stiffness is transformed to the global system and becomes:

$$K_{-i} = A_i^T K_{-Li} A_i$$

where the subscript i denotes the i th frame.

The structure lateral stiffness is assembled by the addition of components from all frames: i.e.,

$$K = \sum_i K_{-i}$$

The frame lateral load vector from sidesway effects must also be transformed to the global system. This transformation is shown by:

$$R_{-i} = A_i^T R'_{-Li}$$

The global load vector is formed by the summation of frame sway effects and the addition of externally applied lateral loads \underline{F} , i.e.:

$$\underline{R} = \sum_i \underline{R}_i + \underline{F}$$

The global forces \underline{F} are specified; however, they are also given by:

$$\underline{F} = \sum A_i^T P_{Li}$$

Expanding the tri-matrix product:

$$\underline{K}_i = A_i^T \underline{K}_{Li} A_i$$

we get:

$$\begin{bmatrix} K_{11} & K_{12} & \cdot & \cdot & \cdot \\ K_{21} & K_{22} & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & K_{ij} & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & K_{NN} \end{bmatrix} = \begin{bmatrix} a_1^T \\ a_2^T \\ \cdot \\ a_i^T \\ \cdot \\ a_N^T \end{bmatrix} \begin{bmatrix} k_{11} & k_{12} & \cdot & \cdot \\ \cdot & \cdot & \cdot & k_{NN} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ \cdot \\ a_j \\ \cdot \\ a_N \end{bmatrix}$$

It is worth noting that a typical 3 x 3 submatrix \underline{K}_{ij} within \underline{K}_i has the form $a_i^T k_{ij} a_j$. Obviously this product may be formed independently for each term in and added directly into \underline{K} . Hence the global equilibrium equations are formed.

$$\underline{R} = \underline{K} \underline{r}$$

It may be noted that the global stiffness \underline{K} is a full matrix, but it is of course relatively small compared to the total number of degrees of freedom associated with all the frames in the structure.

CHAPTER III: STATIC ANALYSIS

The static analysis equations:

$$R = k r$$

are solved directly by Gaussian elimination giving a vector of global lateral displacements, r . Next, for each frame, the lateral displacements, r_{Li} are computed using:

$$r_{Li} = A_i r$$

To complete the solution for each frame, the following system is considered.

$$\underline{R}'_n = \begin{bmatrix} K'_n & C'_n & E'_n \end{bmatrix} \begin{bmatrix} r_n \\ r_{n+1} \\ r_L \end{bmatrix}$$

Note that these are the equations which were reduced, then saved at each level, n , of the frame. That is, K'_n was triangularized. At any stage, n , r_{n+1} and r_L are known and so r_n is computed by back substitution. To start this sequence, we simply note that for $n = N$ (the number of stories in the structure) r_{N+1} represents the displacements at the foundation which are zero since columns are assumed rigidly connected to the foundation. Thus the frame joint displacements are computed successively story by story and individual member forces may be computed at the same time from the force/deformation transformations previously presented.

A. Vertical Loads Analysis

The vertical loads are applied on each individual frame as beam span loads. Four independent vertical loading conditions are possible. The self weight of the frames can be automatically calculated by the program and added to the load vector of the first load condition. Typically the first load condition is used for the dead load analysis of the structure; the second load condition is used for the live load analysis of the structure. The third and fourth load conditions may be used for skip live loading or left unused.

B. Lateral Load Analysis

The lateral static loads are applied as forces acting at a particular point on each floor level. Two independent lateral loading conditions are possible. The lateral loads may be due to wind or earthquake. The wind loads have to be calculated and input by the user, based upon the wind pressure and the exposed tributary area of the building at each level of the structure. The seismic static equivalent loads may be automatically calculated by the program, based upon the requirement of Reference 14. The modal participation factors calculated by the program are used to determine the predominant directions of the modes and the time periods of the predominant modes are used in calculating the seismic loads in the corresponding directions.

The program has options to calculate the dynamic properties, such as the mass and mass moment of inertia of each floor level based upon simplified user input.

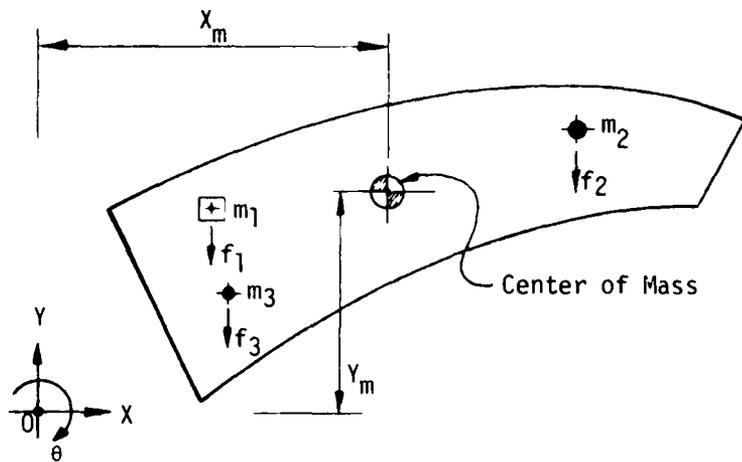
CHAPTER IV: DYNAMIC ANALYSIS

The exact formulation of the dynamic response of a structure involves an infinite number of degrees of freedom. For most structures, however, the response may be adequately captured by a limited number of discrete points (or joints) within the system. In the buildings considered here, the response may be described by the lateral motions of each floor level, as previously described for the formation of the lateral structure stiffness matrix. The center of mass is used as the master constraint location at each level in the generation of the lateral stiffness matrix. The tributary mass of each story level is lumped at the center of mass of the level along with the mass moment of inertia of the floor about a vertical axis through the center of mass to compensate for the rotational aspects of the lumping process. The resulting mass matrix is of diagonal form. With this lumped parameter idealization, equilibrium of the structure is described by a set of ordinary second order differential equations.

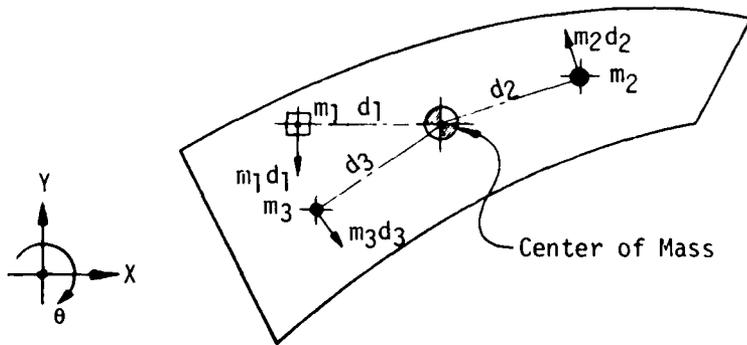
A. Mass Approximation, Mass and Mass Moment of Inertia

In the diaphragm shown in Figure 12, there are various lumped masses ($m_1, m_2, m_3 \dots$ etc.) and other distributed masses associated with the diaphragm level.

When the diaphragm is subjected to a unit translational acceleration in the Y-direction, inertia forces opposing the direction of the acceleration will be generated, i.e. $f_1 = m_1 \times 1, f_2 = m_2 \times 1, f_3 = m_3 \times 1 \dots$. The resultant of all these forces and line of action of the resultant can be determined. The magnitude of the resultant is found to be $= f_1 +$



(a) DEFINITION OF MASS AND CENTER OF MASS



(b) DEFINITION OF MASS MOMENT OF INERTIA

Figure 12

$f_2 + f_3 \dots = m_1 + m_2 + m_3 \dots =$ total mass associated with the diaphragm. The resultant is parallel to the Y-direction and passes through a point at a distance X_m from 0.

Similarly, a unit translation in the X-direction will give a resultant of the same magnitude but parallel to the X-direction and passing through a point a distance Y_m from 0.

The coordinates X_m, Y_m define the location of a point known as the center of mass.

Redefining the term, Mass: "The mass of a diaphragm may be defined as the force generated when the center of mass of the diaphragm undergoes a unit translational acceleration. This force acts at the center of mass, resulting in no associated moment."

$$\text{Mass} = \sum_{i=1}^n m_i$$

Similarly, defining the term, Mass Moment of Inertia (or Rotational Mass): "The mass moment of inertia of a diaphragm may be defined as the moment generated when the center of mass of the diaphragm undergoes a unit rotational acceleration about a vertical axis. No resultant translational force is associated with the couple."

The radial distances from the center of mass of the lumped masses $m_1, m_2, m_3 \dots$ are $d_1, d_2, d_3 \dots$ respectively, as shown in Figure 12.

Due to a unit rotational acceleration of the center of mass about a vertical axis, $m_1, m_2, m_3 \dots$ will have translational accelerations of $d_1 \times 1, d_2 \times 1, d_3 \times 1 \dots$. Thereby giving corresponding inertia forces of

$m_1 d_1, m_2 d_2, m_3 d_3 \dots$. The moments of these forces about a vertical axis through the center of mass are $m_1 d_1^2, m_2 d_2^2, m_3 d_3^2 \dots$.

$$\therefore MMI = m_1 d_1^2 + m_2 d_2^2 + m_3 d_3^2 \dots$$

$$= \sum_{i=1}^n m_i d_i^2$$

= Polar Moment of Inertia of all Masses, about a vertical axis through the center of mass

B. Dynamic Equilibrium Equations

The equilibrium equations for a structure, including dynamic effects, may be written in the following form:

$$\underline{M} \ddot{\underline{r}}_a + \underline{C} \dot{\underline{r}} + \underline{K} \underline{r} = \underline{P}(t) \dots \dots \dots (a)$$

where: \underline{M} = mass matrix

\underline{C} = damping matrix

\underline{K} = stiffness matrix

$\underline{P}(t)$ = applied load vector, which may be time dependent

\underline{r} = displacement vector of deformation relative to support motion

$\ddot{\underline{r}}_a$ = absolute acceleration vector

\underline{r} and \underline{r}_a are related in the following fashion:

$$\underline{r}_a = \underline{v}_g + \underline{r}$$

where \underline{v}_g is the vector of pseudo-static displacements due to support movement. Also:

$$\ddot{\underline{r}}_a = \ddot{\underline{v}}_g + \ddot{\underline{r}}$$

These vectors have the following form for a typical floor, of a building shown in Figure 13.

$$\begin{Bmatrix} r_{xa} \\ r_{ya} \\ r_{\theta a} \end{Bmatrix}_n = \begin{Bmatrix} v_{gx} \\ v_{gy} \\ v_{g\theta} \end{Bmatrix} + \begin{Bmatrix} r_{xn} \\ r_{yn} \\ r_{\theta n} \end{Bmatrix} = \begin{Bmatrix} \sin \beta \\ \cos \beta \\ 0 \end{Bmatrix} v_g + \begin{Bmatrix} r_{xn} \\ r_{yn} \\ r_{\theta n} \end{Bmatrix}$$

and:

$$\begin{Bmatrix} \ddot{r}_{xa} \\ \ddot{r}_{ya} \\ \ddot{r}_{\theta a} \end{Bmatrix}_n = \begin{Bmatrix} \sin \beta \\ \cos \beta \\ 0 \end{Bmatrix} \ddot{v}_g + \begin{Bmatrix} \ddot{r}_{xn} \\ \ddot{r}_{yn} \\ \ddot{r}_{\theta n} \end{Bmatrix}$$

i.e.:

$$\underline{r}_{na} = \underline{b} \underline{v}_g + \underline{r}_n$$

Or, for all floors:

$$\underline{r}_a = \underline{B} \underline{v}_g + \underline{r}$$

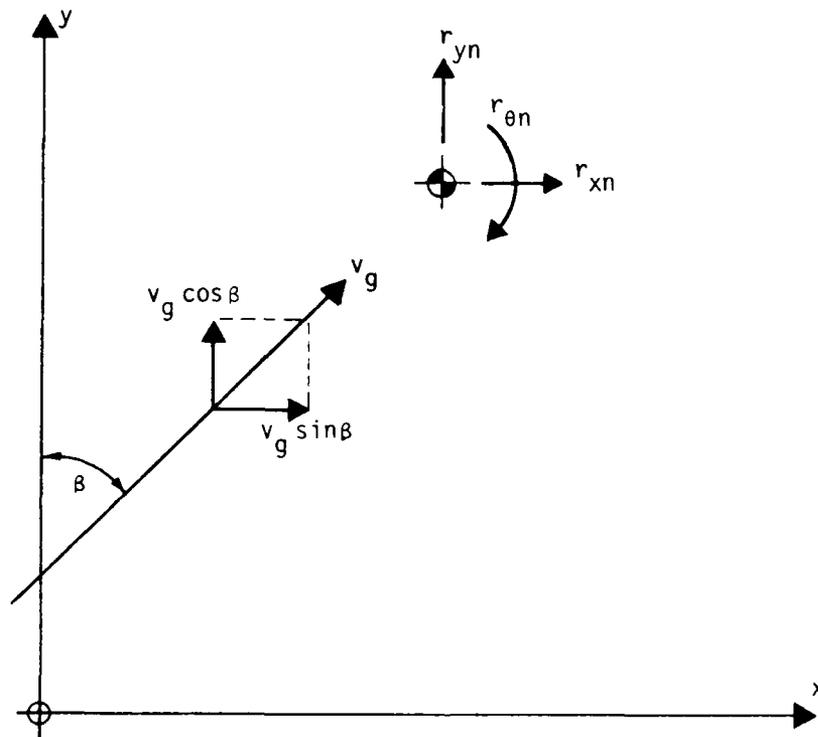


Figure 13. Ground and structural displacements

where:

$$\underline{B} = \begin{Bmatrix} b_1 \\ b_2 \\ b_3 \\ \cdot \\ \cdot \\ b_N \end{Bmatrix} ; \quad b_1 = b_2 \text{ etc.}$$

In the case of seismic analysis, there are no externally applied loads; i.e., $P(t) = 0$. Then equation (a) may be written as:

$$\underline{M} (\ddot{\underline{r}} + \underline{B} \ddot{v}_g) + \underline{C} \dot{\underline{r}} + \underline{K} \underline{r} = \underline{0}$$

or:

$$\underline{M} \ddot{\underline{r}} + \underline{C} \dot{\underline{r}} + \underline{K} \underline{r} = - \underline{M} \underline{B} \ddot{v}_g \quad \dots \dots (b)$$

This coupled set of equations may be solved simultaneously with an appropriate numerical technique. Another approach, which will be used here, is to find a transformation which uncouples the equations so that they may be solved independently. This transformation, of course is via the eigen-vectors or mode shapes of the system.

C. Mode Shapes and Frequencies

The vibration mode shapes represent the solution of the undamped free vibration problem given by:

$$\underline{M} \ddot{\underline{r}} + \underline{K} \underline{r} = \underline{0}$$

The eigen-value problem to be solved is written as:

$$\underline{K} \underline{\phi} = \underline{\omega}^2 \underline{M} \underline{\phi}$$

where: $\underline{\phi}$ = mode shapes

$\underline{\omega}$ = frequencies

The mode shapes are normalized such that:

$$\underline{\phi}^T \underline{M} \underline{\phi} = \underline{I}$$

then also:

$$\underline{\phi}^T \underline{K} \underline{\phi} = \underline{\omega}^2$$

Also, it is assumed that the damping matrix \underline{C} is of a form that is uncoupled by the mode shapes; specifically it is assumed that:

$$\underline{\phi}^T \underline{C} \underline{\phi} = [2\lambda_m \quad \omega_m]$$

so that λ_m represents the damping of the m th mode.

The actual displacements, \underline{r} , are now expressed as a linear combination of the mode shapes.

$$\underline{r} = [\underline{\phi}_1 \quad \underline{\phi}_2 \quad \underline{\phi}_3 \quad \dots \quad \underline{\phi}_N] \begin{bmatrix} z_1(t) \\ z_2(t) \\ \cdot \\ \cdot \\ z_N(t) \end{bmatrix} \dots (c)$$

i.e.: $\underline{r} = \underline{\phi} \underline{z}$

also $\dot{\underline{r}} = \underline{\phi} \dot{\underline{z}}$

where: m_1 = mass of story 1

J_1 = rotational mass moment of inertia of story 1

i.e.:

$$\underline{M} \underline{B} = \begin{bmatrix} m_1 \sin\beta \\ m_1 \cos\beta \\ 0 \\ m_2 \sin\beta \\ m_2 \cos\beta \\ 0 \\ \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

So, a typical term of \underline{p}^* has the form:

$$\begin{aligned} p_m^* &= \underline{\phi}_m^T \underline{M} \underline{B} \\ &= \langle \phi_{1x} \ \phi_{1y} \ \phi_{1\theta} \ \phi_{2x} \ \phi_{2y} \ \phi_{2\theta} \ \dots \rangle \begin{Bmatrix} m_1 \sin\beta \\ m_1 \cos\beta \\ 0 \\ m_2 \sin\beta \\ m_2 \cos\beta \\ 0 \\ \cdot \\ \cdot \\ \cdot \end{Bmatrix} \end{aligned}$$

$$p_m^* = \sum_{n=1}^N m_n \{ \sin\beta \phi_{nx} + \cos\beta \phi_{ny} \}$$

Now a typical equation governing the response in the m th mode has the form:

$$\ddot{z}_m + 2\lambda_m \omega_m \dot{z}_m + \omega_m^2 z_m = P_m^* \ddot{v}_g \quad \dots \dots \dots (d)$$

For any earthquake, the ground acceleration, \ddot{v}_g is specified as a set of discrete values and linear interpolation is used for intermediate values. On any linear portion then:

$$\ddot{v}_g = A + Bt$$

where A and B are computed from the end values as shown in Figure 14.

On any linear segment t_1, t_2 then:

$$\ddot{z}_m + 2\lambda_m \omega_m \dot{z}_m + \omega_m^2 z_m = P_m^* (A + Bt)$$

The solution to this equation is summarized in Figure 14.

At rest initial conditions are used for the first linear portion. The values of displacement and velocity at the end of any linear portion form the initial conditions for the following linear segment and so on. Repetition gives the complete solution over the required time span. With solutions for each mode, equation (c) is used to give a set of structure displacements r at each output time step.

The backsubstitution procedure used for the time history analysis is exactly the same as that described for the static analysis in Chapter III. Backsubstitution for each time step is equivalent to one static load backsubstitution. The frame displacements and member forces are determined at each time step and the maxima of these parameters over the time span are output as dynamic load condition 3.

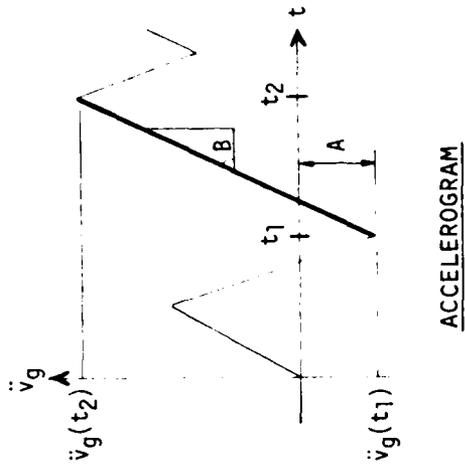
For the equation: $\ddot{z}_m + 2\lambda_m \omega_m \dot{z}_m + \omega_m^2 z_m = P_m^* (A + Bt)$
 On any linear segment such as t_1, t_2 , the solution is given by:

$$\begin{aligned} z_m(t) = & P_m^* e^{-\lambda_m \omega_m t} \left\{ \left[z_m(t_1) - \frac{A}{\omega_m} + \frac{2\lambda_m B}{3\omega_m} \right] \cos \omega_{Dm} t \right. \\ & + \left. \frac{1}{\omega_{Dm}} \left[\dot{z}_m(t_1) + \lambda_m \omega_m z_m(t_1) - \frac{\lambda_m A}{\omega_m} + \frac{B(2\lambda_m^2 - 1)}{2\omega_m} \right] \sin \omega_{Dm} t \right\} \\ & + P_m^* \left[\frac{A}{\omega_m} - \frac{2\lambda_m B}{3\omega_m} + \frac{Bt}{\omega_m} \right] \end{aligned}$$

42

and:

$$\begin{aligned} \dot{z}_m(t) = & P_m^* e^{-\lambda_m \omega_m t} \left\{ \left[\dot{z}_m(t_1) - \frac{B}{\omega_m} \right] \cos \omega_{Dm} t \right. \\ & + \left. \left[A - \frac{2\lambda_m^2 z_m(t_1)}{\omega_m} - \lambda_m \omega_m \left(z_m(t_1) + \frac{t_1}{2\omega_m} \right) \right] \frac{\sin \omega_{Dm} t}{\omega_{Dm}} \right\} \\ & + P_m^* \frac{B}{\omega_m} \end{aligned}$$



ACCELEROGRAM

where:

$$A = \ddot{v}_g(t_1)$$

$$B = \frac{\ddot{v}_g(t_2) - \ddot{v}_g(t_1)}{t_2 - t_1}$$

$$\omega_{Dm} = \omega_m (1 - \lambda_m^2)^{1/2}$$

$z_m(t_1), \dot{z}_m(t_1)$ are the initial conditions for the segment t_1, t_2

Figure 14. Closed form time integration scheme of CTABS80

E. Response Spectrum Analysis

Unless actual histories of displacements and forces are required for a specific earthquake a more realistic and economical approach for dynamic analysis is via the response spectrum method. For a particular ground motion history $\ddot{v}_g(t)$, the spectrum curve is defined as follows:

The response of a single mass system with damping λ , and circular frequency ω , subjected to a ground motion history $\ddot{v}_g(t)$ is governed by the equation:

$$\ddot{u}(t) + 2\lambda\omega \dot{u}(t) + \omega^2 u(t) = \ddot{v}_g(t)$$

Let u_{\max} be the maximum absolute value that $u(t)$ attains. A plot of this maximum displacement versus the frequency ω for each λ is by definition the displacement response spectrum (Sd) for the earthquake $\ddot{v}_g(t)$. A plot of $u_{\max}\omega$ is the pseudo-velocity spectrum (PSv) and a plot of $u_{\max}\omega^2$ is the pseudo-acceleration spectrum (PSa). These pseudo-velocity and acceleration spectra are of the same physical interest but are not an essential part of a response spectrum analysis.

Recalling equation (d), if the dynamic loading on the structure is specified in terms of the pseudo-acceleration spectrum, then the maximum response for the m th mode is given by:

$$Z_{m \max} = p_m^* \frac{\text{PSa}(\omega_m, \lambda_m)}{\omega_m^2}$$

Therefore, the maximum contribution of mode m to the total three dimensional response of the structure is:

$$r_m = Z_{m_{\max}} \phi_m$$

For all modes S_d is, by definition, positive. The maximum modal displacement r_m is proportional to the mode shape ϕ ; and the sign of the proportionality constant is given by the sign of the modal participation factor, P_m^* . Therefore, each maximum modal displacement has a unique sign. Also, the maximum internal modal forces, which are consistently evaluated from the maximum modal displacements, have unique signs.

A complete analysis is performed down to the member force level with the maximum modal displacements of the structure for each individual mode using the backsubstitution procedure described in Chapter II.

The maxima in each mode will generally occur at different times. The combination of the modal components of the displacements and member forces to give resultant values for design purposes is performed at the design parameter level by the following methods.

1. The Square-Root-of-the-Sum-of-the-Squares (SRSS)⁽¹³⁾ method
2. The Absolute Sum (ABS)⁽¹³⁾ method
3. The Complete Quadratic Combination (CQC)⁽¹⁰⁾ method

The SRSS method and the ABS method entirely neglect the signs of the modal contributions. The SRSS method in general gives good approxi-

mations of the dynamic response in structures with well separated frequencies. The ABS method is basically for interest to give an upper bound on the maximum values.

In structures with closely spaced modes or multiple frequencies, the fact that the SRSS method neglects the signs of the modal components may cause the design parameters to be dramatically overestimated in some elements while being significantly underestimated in other elements. The CQC method overcomes this difficulty and it is recommended as the best of the three methods for obtaining the most realistic results.

F. Dynamic Options

The dynamic options currently available in CTABS80 are:

1. Calculation of mode shapes and periods (frequencies)
2. Response spectrum analysis for any acceleration spectrum supplied by the user using the:
 - a. SRSS modal combination as Dynamic load condition 1
 - b. Sum of absolute value modal combinations as Dynamic load condition 2
 - c. Complete Quadratic combinations as Dynamic load condition 3
3. Time history analysis maxima for any ground motion supplied by the user as Dynamic load condition 3

Either dynamic analysis condition may be combined with any static load condition.

1. SRSS COMBINATION

$$F_{(1 \times 1)} = \sqrt{\begin{matrix} \underline{f}^T & \underline{I} & \underline{f} \\ (1 \times n) & (n \times n) & (n \times 1) \end{matrix}}$$

Where \underline{I} is an identity matrix

2. ABS COMBINATION

$$F_{(1 \times 1)} = \underline{f}^T \text{ sign } \underline{f}_{(1 \times n) \quad (n \times 1)}$$

Where sign \underline{f} is a unit matrix containing the signs of the corresponding elements of matrix \underline{f}

3. CQC COMBINATION

$$F_{(1 \times 1)} = \sqrt{\begin{matrix} \underline{f}^T & \underline{C} & \underline{f} \\ (1 \times n) & (n \times n) & (n \times 1) \end{matrix}}$$

Where \underline{C} is the matrix of modal cross-correlation coefficients given by:

$$C_{ij} = \frac{8\lambda^2(1+r)r^{3/2}}{(1-r^2)^2 + 4\lambda^2r(1+r)^2}$$

NOTES/

f = vector of modal components

F = combined resultant

n = number of modes

where $r = \omega_i/\omega_j$, the ratio of the circular frequencies of the coupling modes and λ is the damping associated with the response spectrum curve being used.

Figure 15. Summary of modal combination techniques used in CTABS80

CHAPTER V: GENERAL OBSERVATIONS

A. Program Application

The effective application of a computer program for the analysis of practical situations involves a considerable amount of experience. The most difficult phase of the analysis is in assembling an appropriate model which captures the major characteristics of the structural behavior of the building. No computer program can replace the engineering judgement of an experienced engineer. It is well said that an incapable engineer cannot do with a ton of computer output what a good engineer can do on the back of an envelope. Correct output interpretation is just as important as the preparation of a good structural model. Verification of unexpected results needs a good understanding of the basic assumptions and the mechanics of the program. Static equilibrium checks are necessary not only to check the computer output but to understand the basic structural behavior of the building.

B. Static Seismic Analysis of Buildings

At the present time, the seismic design of most buildings in California and other earthquake regions of the United States is based upon the Uniform Building Code. The UBC method allows the seismic loads to be approximated by an equivalent set of lateral static loads. The magnitude of the loads is based upon the seismic zone, the structural system, and the fundamental period of the structure. Corrections to compensate for local soil conditions and the physical importance of the structure are also defined.

An approximate formula, specified in the UBC, may be used to estimate the fundamental period. The period associated with the predominant structural mode obtained via the TABS program is more accurate and appropriate. The suggested UBC distribution of the lateral loads over the height of the building is triangular with some correction to allow for higher mode effects. Behavior of structures that have dynamically decoupled regions due to stiffness and/or mass discontinuities, causing significantly non-triangular inertia load patterns are not adequately covered by the code. By examining the structural modes produced by a TABS analysis such structural complexities can be isolated.

The determination of the minimum horizontal torsional design moments, as specified by the UBC for the design of structures having rigid diaphragms, requires the location of a center of rigidity of the structure at each level. The definition of torsional moments on such a basis for multi-story structures is technically vague. It is only meaningful in single story structures where there are no stories above or below to affect the rotation of the level under consideration.

The UBC lateral loads are only a small fraction of the loads developed during a significant earthquake, and must therefore be considered as minimum requirements. As a result of the above mentioned inadequacies the need for a more comprehensive code earthquake analysis methodology is apparent to most structural engineers⁽⁸⁾.

C. Computer Methods Versus Hand Methods

High speed digital computers and the development of computer programs such as TABS have given engineers the capability to consider aspects of

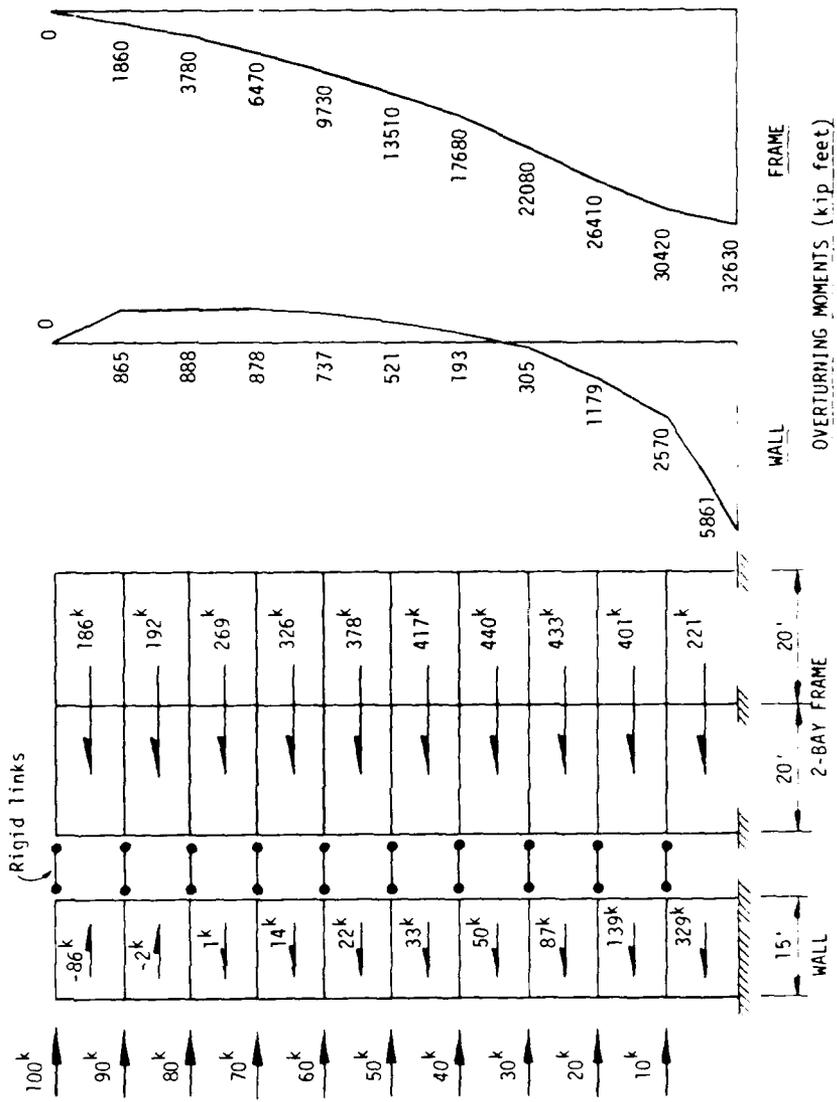
structural behavior that conventional hand analysis techniques have traditionally neglected. Hand analysis techniques used by practicing engineers for the lateral analysis of multistory structures have been shown to violate joint statics and compatibility.

The following examples demonstrate the degree of error that could be present in a conventional hand analysis, by comparison with a TABS analysis; i.e., one that completely satisfies statics, compatibility, and boundary. Examples presented are of simple symmetrical multistory buildings with symmetrical loading. The stories, therefore, translate under lateral load without rotating, thereby keeping the problems clear and demonstrative. The proportions of the structures and magnitudes of the forces have been chosen to generate problems of a nature that a conventional structural engineer is commonly faced with in practice.

(i). Example 1

This is a classic example of shear wall-frame interaction. A 10 story shear wall is connected in parallel with a ten story frame at each story level through a rigid link. The axial deformations in the beams are neglected, thus simulating a rigid diaphragm. Therefore, the lateral displacements of the respective stories of the frame and shear wall are equal. See Figure 16.

Consider the top story. Based on a conventional hand analysis, one would, in general, tend to ignore the stiffness of the frame and conclude that the shear wall takes close to 100% of the applied 100 K, and that the frame being relatively flexible gets a negligible amount of the shear.



NOTE/
 Walls are 12" thick
 Columns are 24" x 24" typ.
 Beams are 12" x 24" typ.
 Story height = 10' typ.

Figure 16

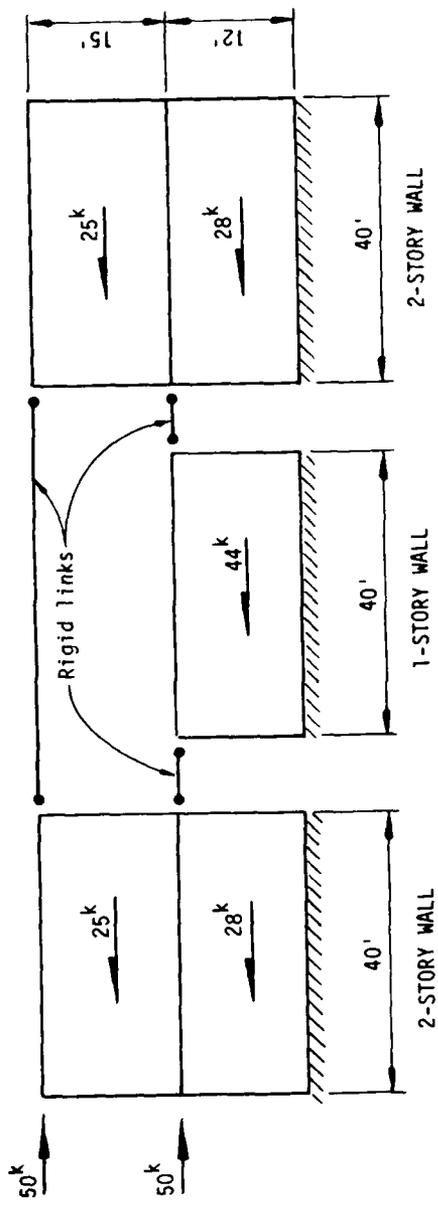
A "correct" analysis, however, reveals that the frame has a total shear of 186 K at that level. Thus, the frame, besides carrying the total 100 K applied load, is laterally supporting the shear wall which puts an additional 86 K on the frame. The shear wall is in effect acting as a propped cantilever supported by the frame at the upper story levels.

The phenomenon may be explained as follows: If the frame and shear wall are loaded independently with the load, and the lateral displacements of the respective floors compared, it will be observed that the shear wall has larger lateral displacements in the upper levels, whereas the frame has larger displacements in the lower stories and vice versa. Compatibility of joint rotations will have a significant effect on these displacement patterns. When loaded together, the constraint of equal story displacements is enforced, thus resulting in this unique shear distribution. Notice that in the lower stories the shear gradually shifts to the shear wall.

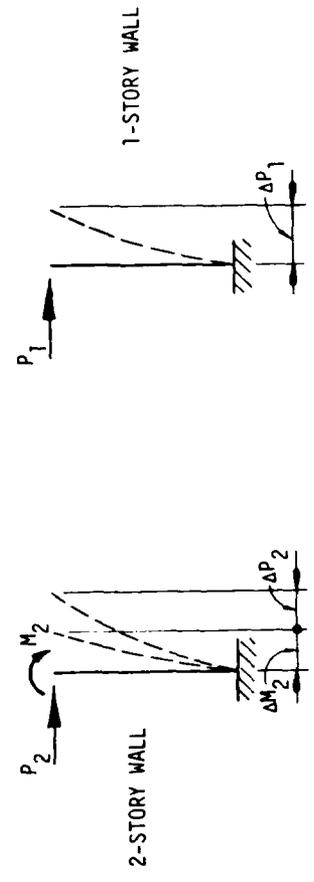
This example demonstrates the importance of the interaction of all the elements on one another and that the hand analysis method of analyzing an n-story structure as n 1-story structures stacked one over the other with no interaction of one on the other can lead to highly unreliable results.

(ii). Example 2

This problem consists of two 2-story walls and one 1-story wall. See Figure 17a. Again, as in Example 1, the walls are connected by rigid links at the floor levels to simulate a rigid diaphragm and to enforce



NOTE/
All walls 12" thick



(b) FREE BODY DIAGRAM OF LOWER LEVEL

Figure 17

equal lateral story displacements in all the walls. The walls are loaded with a total story load of 50 K at each level. As expected in a conventional hand analysis, the 2-story walls equally share the 50 K lateral load at the upper level.

Now let us consider the shear distribution in the bottom story. The base shear is 100 K. In the light of the fact that there are three resisting elements at this level, all 40' long and 1' thick, a conventional hand analysis would conclude that the base shear will be carried equally by all three elements; that is 33 K each.

A "correct" analysis, however, indicates that the 1-story wall takes over 50% more shear than each 2-story wall. In Figure 17b are presented the free body diagrams of the lower levels of the 1-story wall and the 2-story walls. Consider the lateral story displacements of the 1st level in each wall. In the 1-story wall the lateral displacement, ΔP_1 , is due to P_1 , the shear force in the wall. In the 2-story wall the lateral displacement is due to two factors. Firstly, ΔP_2 , that is due to P_2 , the shear force in the wall and, secondly, ΔM_2 , due to M_2 , the moment at the top of the wall due to the fact that the wall is 2 stories high. Now for the lateral displacements to be equal:

$$\Delta P_1 = \Delta P_2 + \Delta M_2$$

Therefore $\Delta P_1 > \Delta P_2$
so that $P_1 > P_2$

The discrepancy between the conventional hand analysis method and the "correct" method here, again, is due to the fact that the effect of the upper story on the lower story is accounted for incompletely.

(iii). Example 3

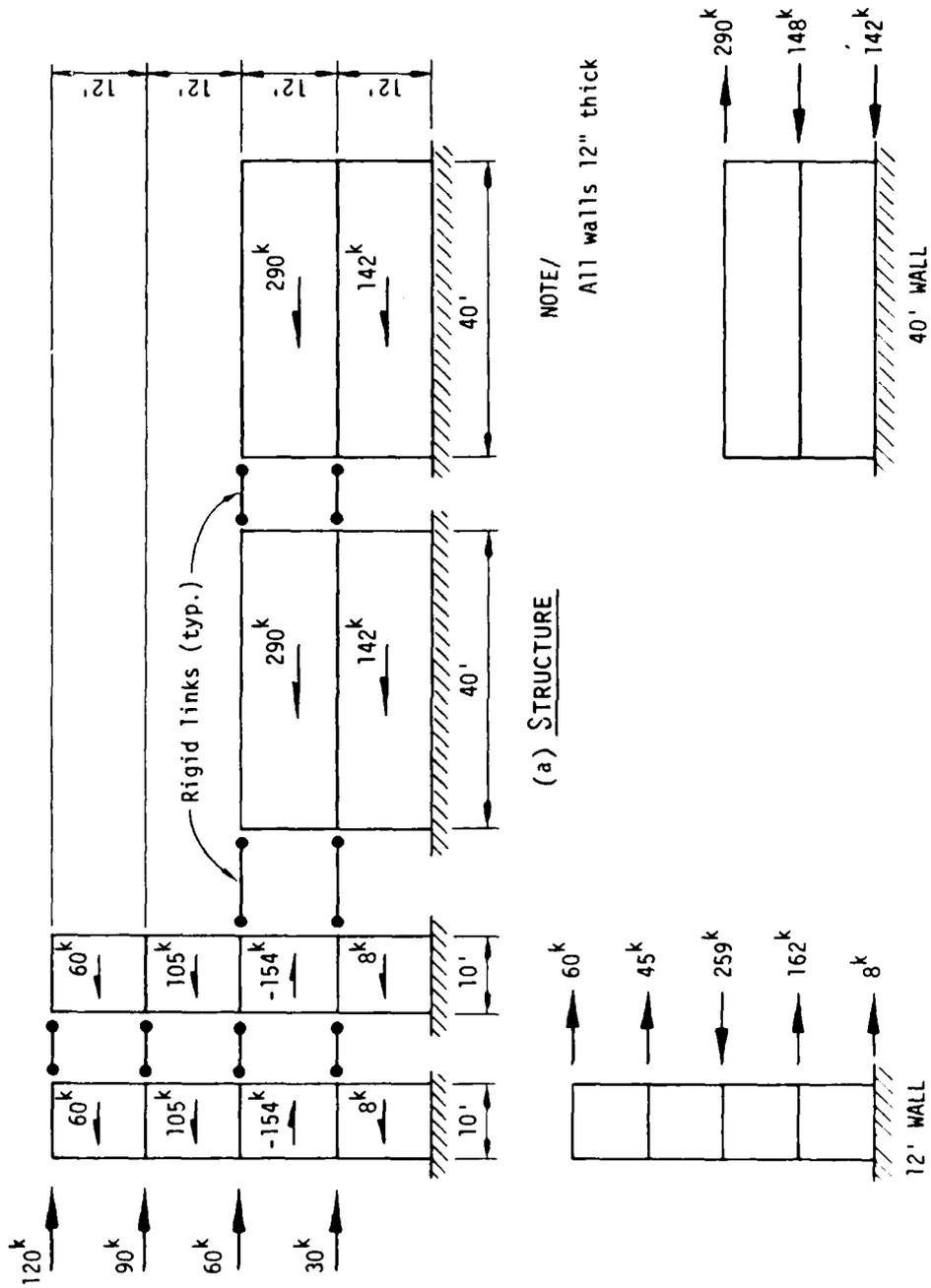
This structure consists of 4 walls. Two 4-story walls and two 2-story walls. See Figure 18a. Again, the walls are connected by rigid links at the floor levels to simulate a rigid diaphragm.

In the "correct" analysis the shear forces in the 10 foot walls in the 3rd and 4th levels are as would be expected in a conventional hand analysis. Note the shear distribution at the 2nd level. At this level there is a considerable increase in the story stiffness due to the two 40-foot walls. This restricts the lateral diaphragm movement to the extent that the 10' walls are in effect laterally supported by the diaphragm at this level, and, therefore, behave like over-hanging cantilevers as shown in Figure 18b. This explains why these walls have a negative shear of 154 K each at this level.

The conventional hand analysis method for such problems completely disregards the possibility of negative shear forces occurring in the walls, thereby always assuming that the walls support the diaphragm laterally, and not recognizing that at times the diaphragm may actually be the support for certain walls at certain levels.

(iv). Example 4

This example demonstrates the effect of axial deformations on the distribution of shear to a series of walls, Consider the structure shown in Figures 19a and 19b. The structure consists of two solid walls, and one wall terminating on two columns. In case A, the columns are 12" square, see Figure 19a. Again, the walls are connected by rigid



(b) FREE BODY DIAGRAMS (SHEAR LOADS)

Figure 18

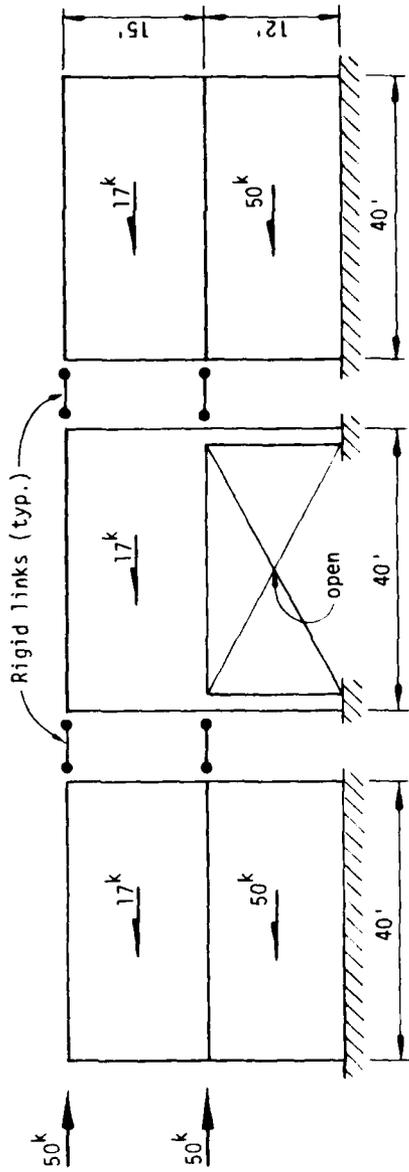


FIGURE 19a: CASE A

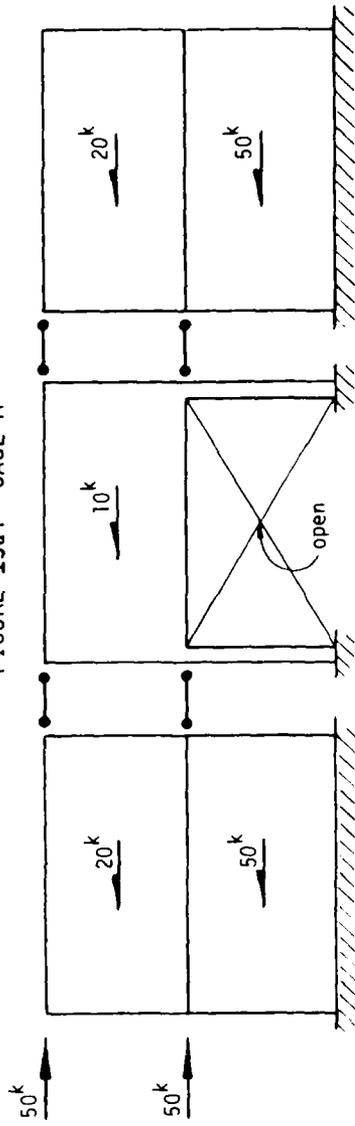


FIGURE 19b: CASE B

NOTE/
All walls 12" thick

Figure 19

links at the story levels.

Consider the shear distribution in the upper level. In case A, a "correct" analysis indicates that the 50 K story shear is distributed approximately equally among the 3 walls. A conventional hand analysis would lead us to the same conclusion. In case B, however, the shear taken by the wall terminating on columns is 50% of that taken by the solid walls. The reason being that the smaller axial area of the columns gives larger axial deformations which, in turn, reduce the lateral rigidity of the wall in the story above.

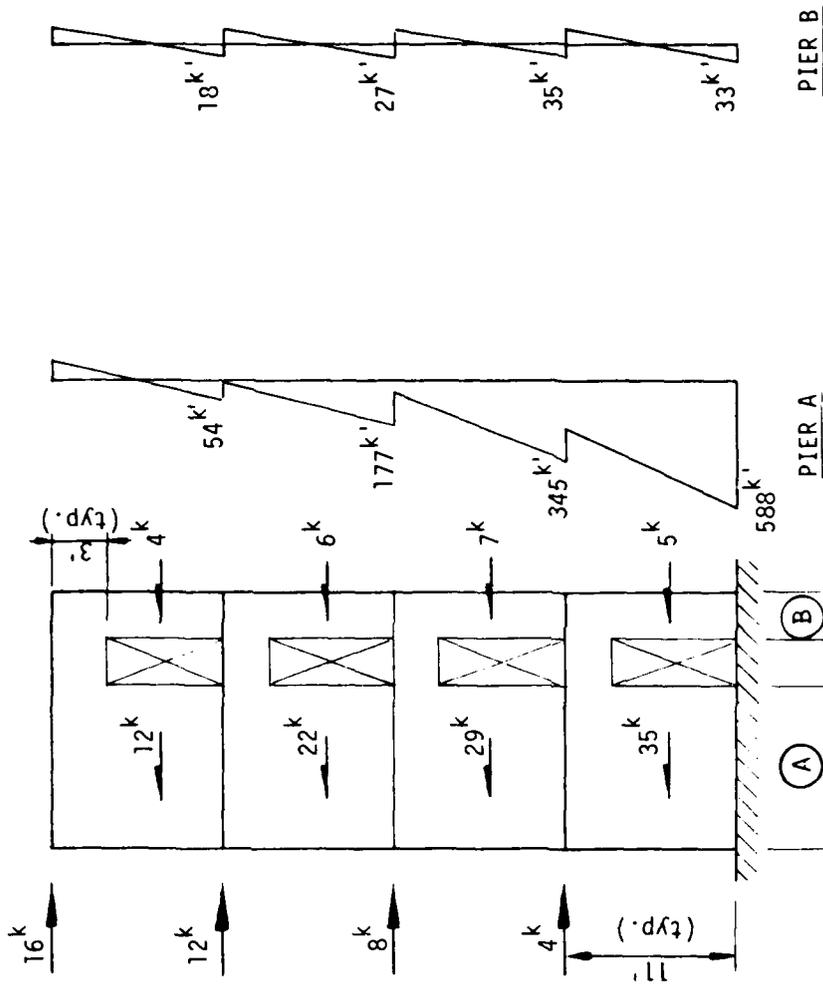
A conventional hand analysis neglects the effects of axial deformations, and, therefore, would give an equal shear distribution in all three walls regardless of the size of the columns.

(v). Example 5

This example clearly demonstrates the analytical discrepancy in analyzing an n-story structure as n 1-story structures. The structure is a shear wall with the same story height, wall dimensions and openings at every level. See Figure 20.

A conventional hand analysis (analysis of the structure as four 1-story structures) would indicate that the location of the point of contra-flexure of the piers in all the stories would be at a constant distance vertically from the corresponding diaphragm. Also, the ratio of the shear force in pier A to that in pier B in all stories will be constant.

A "correct" solution of the structure, however, shows that there is no point of contra-flexure in pier A in the first three stories. Also, the



BENDING MOMENT
DIAGRAMS

NOTE/
Wall thickness = 12"

Figure 20

percentage of the story shear carried by pier B is not constant in all stories but decreases as we move into the lower stories.

Joint rotation incompatibility from story to story is the main cause for this discrepancy between the hand analysis and the "correct" analysis.

(vi). Example 6

This is another example demonstrating the effect of axial deformations on the shear distribution. The structure consists of slender piers framing into relatively stiff spandrels and is 8 stories tall. See Figure 21. For all practical purposes, the piers may be considered fixed in rotation at both ends. Since all the piers are of the same size, a conventional hand analysis would indicate that the story shear is distributed equally among the 5 piers.

A "correct" analysis, as we can see, indicates that the piers closer to the center take a higher percentage of the story shear. In the top story for instance, the center pier takes over 65% higher shear than the end pier. This discrepancy is due to the fact that the "correct" analysis considers axial deformations in the piers, whereas the hand analysis does not.

This behavior may be explained by the following analogy. Consider the lateral displacements in a vertical cantilever with a rectangular cross section and lateral loading. If the shear deformations are negligible compared to the bending deformations in the cantilever, the distribution of the shear stress across the section is parabolic with the maximum at the center. However, if the deformation pattern is one of pure shear,

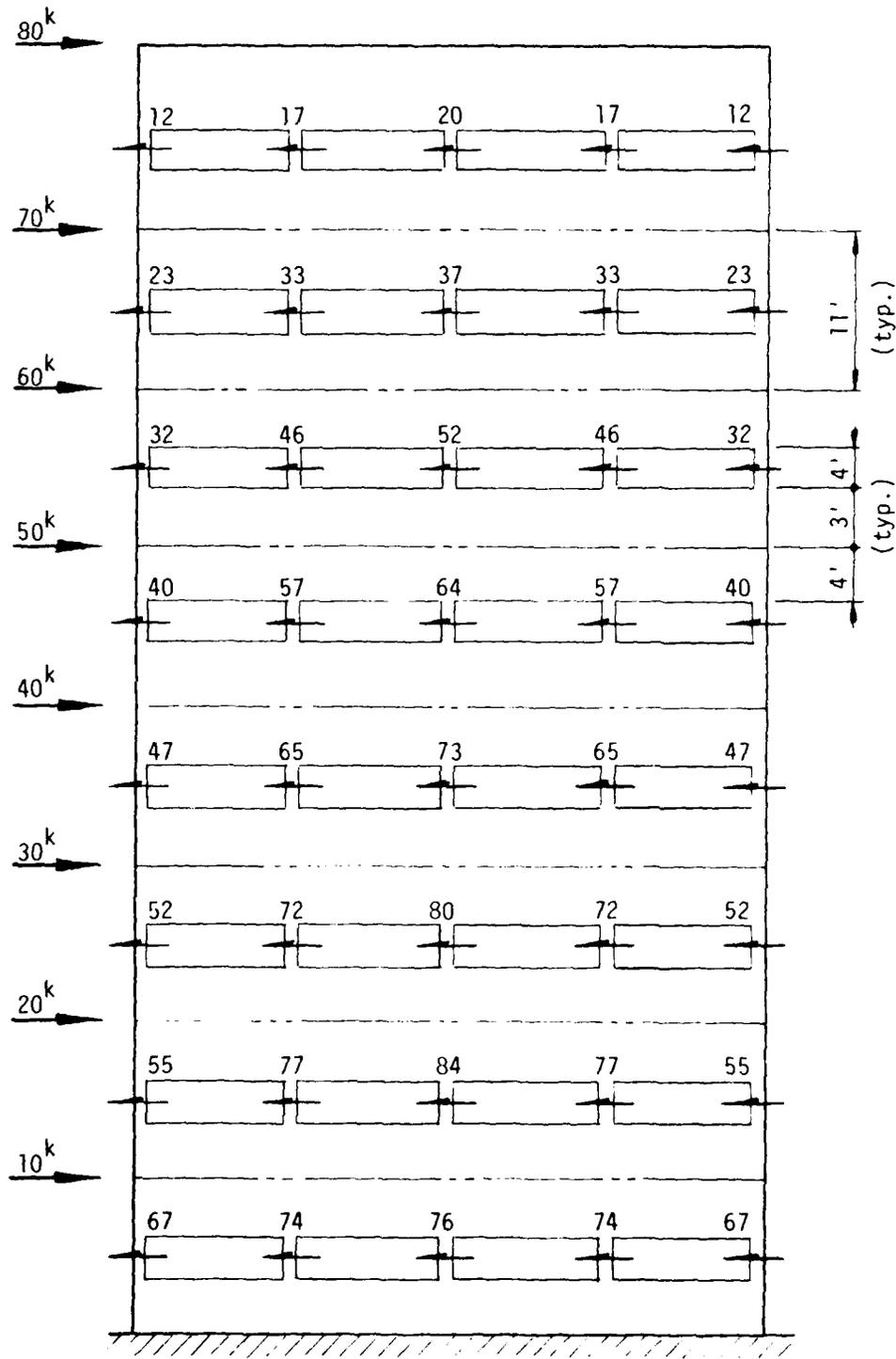


Figure 21

such that the bending deformations are negligible, the shear stress distribution is constant over the section and not parabolic.

The axial deformations of the piers in this example correspond to the bending deformations in the analogy above. If the piers were axially stiff to the extent that there were no axial deformations, the shear distributions in the piers would be equal. However, as the piers deform axially, the piers closer to the middle have heavier shear. This also explains why the shear distribution is more uniform as we move into the lower stories.

D. Dynamic Seismic Analysis of Buildings

The deficiencies of the present seismic design procedures are clearly summarized in Reference 8. It is apparent that the present code is a very approximate method based on the first mode only. The foundation factors discussed later are not considered. Another factor which is important in an elastic analysis is the damping. Spectra for damping of 2 and 10% are shown in Figure 22. It is clear that the Uniform Building Code seismic loads are very small compared to the forces produced in recorded earthquakes. It has been estimated that earthquakes of the Parkfield magnitude can be expected about once per year at some point in California, and earthquakes of the El Centro magnitude may be expected every five or six years.

The selection of a design spectrum for the response spectrum analysis of a particular building will depend on the geographical area, the local soil condition, the type of construction material and the intended use of the

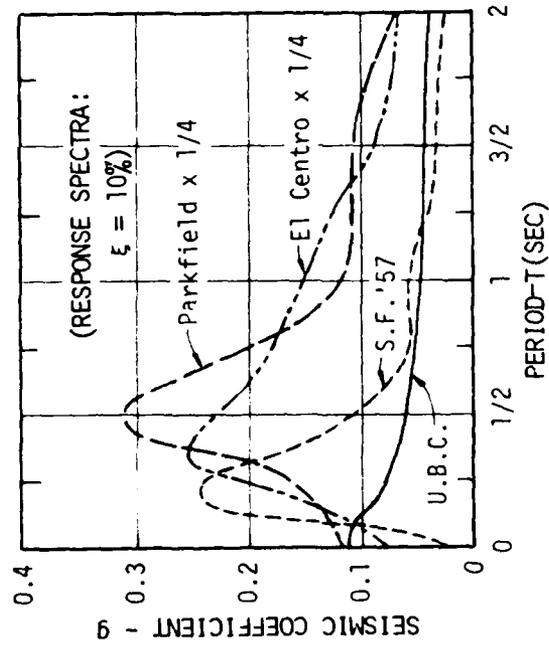
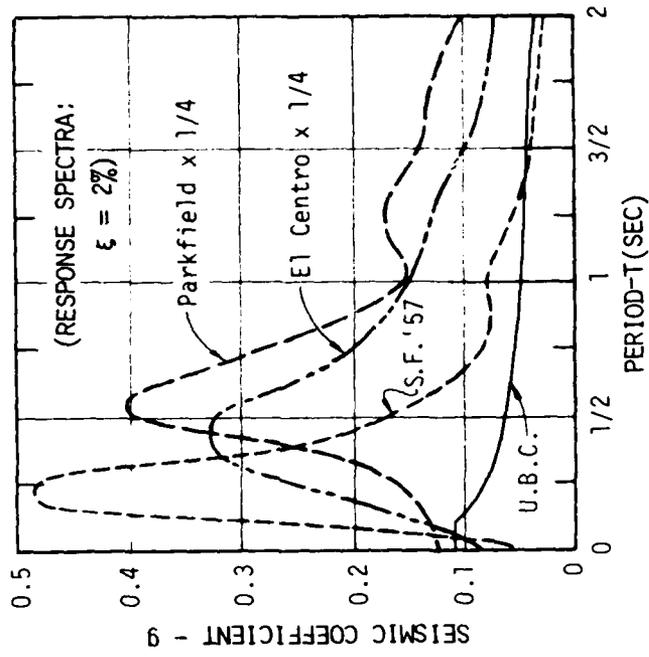


Figure 22. Response spectra

building. Many Soils Engineering firms now specialize in the dynamics of soil systems to evaluate specific sites and recommend shapes and intensities for dynamic response spectra. Most lending agencies are requiring dynamic analysis of structures as part of their financing terms for buildings in major metropolitan areas of California.

For certain types of earthquakes it has been observed that the vertical accelerations are comparable in magnitude to the lateral accelerations. However, all buildings have been designed elastically for a minimum of $1g$ in the vertical direction; therefore, these additional vertical forces very often do not cause direct damage to the structure. Of course, they should be considered in the design of members in addition to the lateral earthquake loads. For most structures the stiffness in the vertical direction is very large; hence, the vertical periods will be very small. Therefore, a dynamic analysis in the vertical direction may not be required. A direct increase in dead load stresses may be a good method to approximate the effects of vertical earthquake loads.

E. Foundation - Building Interaction

Foundation modeling has always been an area of particular concern. The vertical and rotational stiffnesses under each column can be easily input by providing an extra "dummy" story. However, the assigning of accurate stiffness values for these soil springs can be difficult.

In recent years considerable research has been conducted in the area of foundation - building interaction. However, very little of this work has been of direct value to the profession involved in the earthquake analysis

of buildings. Several of the suggested approaches have been difficult to apply in case of complex buildings, or they have had serious theoretical restrictions.

Before foundation interaction effects are included in the analysis it is necessary to define the exact location of the earthquake input. If the design criteria states that the input is at the base of the building then it is impossible to say that the building will modify the input, and it is impossible to include interaction effects.

A large amount of research in this area has been associated with machines vibrating on an infinite foundation where the term radiation damping has been used. This work has little value in earthquake engineering since the energy source is not at the base of the building. It is easy to show that the energy stored in the building is very small compared to the energy stored in the immediate foundation area in the case of earthquake input. Also, the machine vibration problem is a steady state phenomenon, whereas earthquakes produce a transient loading.

The continuous foundation contains an infinite number of degrees of freedom. Therefore, any approach which suggest representing the lateral behavior of the foundation with a simple spring, dashpot and mass system is a very gross approximation. In fact, this technique can produce a filtering effect on the earthquake input and cause serious errors. For lateral earthquake input, this type of approximation is only acceptable in the representation of the rotational stiffness at the base of columns and shear walls.

The most significant factor to consider is the modification of the basic

earthquake rock motion by the layers of soil material under the building⁽⁷⁾. For certain earthquakes and locations this may be a factor of 2 or 3 in amplification. Therefore, it is very important that the dynamic behavior of the site is studied independently of the building. The results of such a study will result in a suggested acceleration spectrum to be used in the analysis of the building. Figure 23 indicates the type of results which can be expected from such a site analysis.

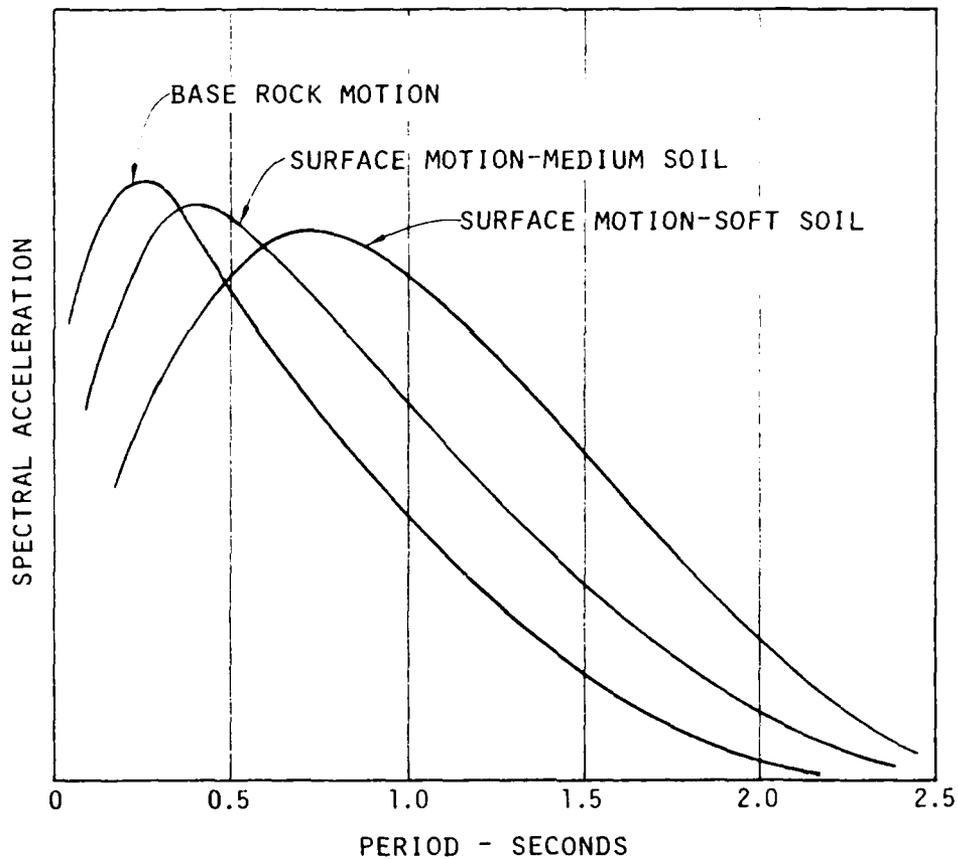


Figure 23. Spectral variation due to soil conditions

CHAPTER VI: INTERNAL ORGANIZATION

An outline of the subroutine structure of CTABS80 is presented in Figure 24. There are seven major calls from CTABS80 associated with the seven major blocks of the program.

1. The first operation is to read the basic control information. The data associated with the complete building (story data and structural lateral loads) is then rolled in via subroutine TABI.
2. The next operation involves reading in the frame data of every different frame in the structure. The frame elevations are plotted, if requested. In non-data check modes the frame stiffnesses are formulated and reduced and the frame lateral stiffness matrices and back-substitution equations are written sequentially on disc. This operation is implemented by the call to subroutine TABF.
3. The call to subroutine TABL reads the frame location data and formulates the complete lateral structural stiffness matrix of the whole building.
4. Subroutine SFRAME causes a plan view of the building to be plotted, showing the frame locations and the directions of their local axes.
5. The call to subroutine TABE gives the modeshapes and frequencies of the structure (TABM) and triggers the automatic UBC lateral seismic load calculation (TUBC). Also the dynamic analysis control information is read in by this call. Structural lateral displacements due to the static loads (TABQ) and response spectrum dynamic loads are obtained at this stage.

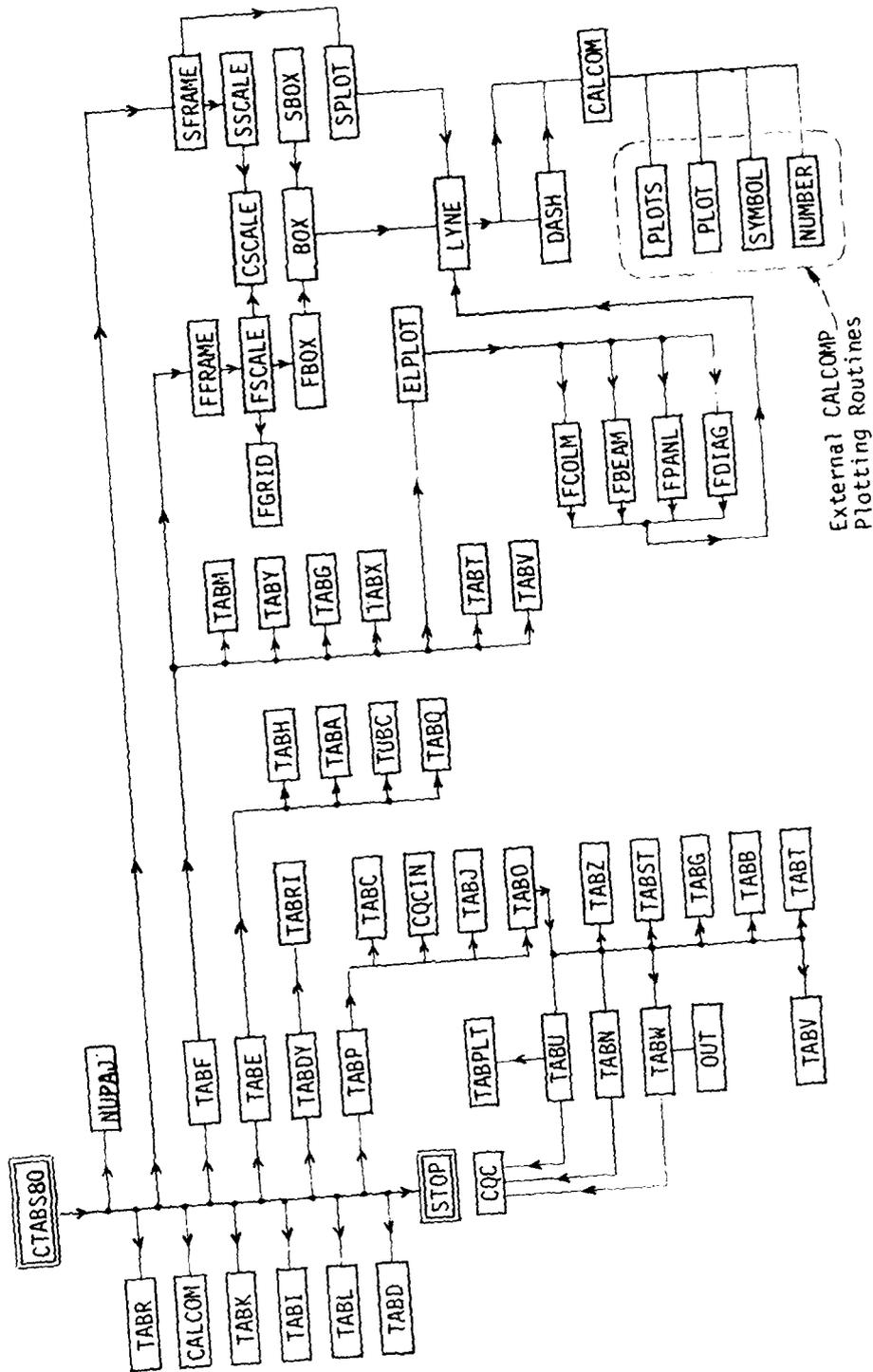


Figure 24. Internal organization of CTABS80

6. Subroutine TABDY reads in the time history earthquake ground motion data and causes the structural lateral displacements to be calculated for each time step.
7. Finally, subroutine TABP is called. This subroutine calls TABC to read the load case definition data for each frame. Then TABU is called to print the frame lateral displacements and TABO is called to calculate the frame joint displacements for each static load condition and each spectral mode or response time increment from the back substitution equations previously saved.

As the displacements are calculated the member forces are also evaluated and printed according to the load case definition data (TABW).

CHAPTER VII: CONCLUSIONS

A general computer program for the elastic three-dimensional static and dynamic analysis of frame and shear wall buildings has been presented. For buildings which can be approximated by independent frames and shear walls the program is very economical and easy to use as compared to a general purpose three-dimensional structural analysis program.

Many new options have been implemented in this release to make the program a more practical and useful engineering tool.

The program is based on linear theory. Non-linear behavior such as P- Δ effects and material plasticity are not captured by the program.

If non-linear effects are to be considered a step-by-step response analysis is required; however, this involves a significant increase in computational effort and will be justified for only a limited number of buildings. In addition, the non-linear material properties both for most structural and non-structural members have not been established accurately from experimental work.

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APPENDIX A: FORTRAN IV LISTING OF CTABS80


```

STOP 7777
150 CONTINUE
CALL SECOND (T11)
SETTING RIGID ZONE REDUCTION FACTOR
RIGID=25
IF (INP.GD.NE.O) RIGID=0.
MIMP=1
MOUT=1
IF (INOPT.EQ.3) MIMP=0
IF (INOPT.EQ.2) MIMP=0
IF (INOPT.EQ.2) MOUT=0
I3=3
I5=0
I7=50.FU.O) GO TO 50
I9=80
I5=MSD-1
50 MSS=ASTO13
IF (NEG.CT.MSS) MFO=MSS
IF (NAT.FD.O) MFO=0
CALL NUPAJ (L1,Z7,TESTE)
WRITE (KOUT,2001) NST,MDF,MTF,MD,MAT,MFO,MSD,MUPT,NBGD,MOSP,
MURC,MPP7,MPT7
IF (NAT.EQ.1) NAL=1
IF (NAT.EQ.O) NAL=1
BEHIND RIAPS
WRITE (KTAPE) (MST,INDG,MTE,MTE)
WRITE (KTAPE) (MST,INDG,MTE,MTE)
STRESS TRANSDUCER DATA
READ (KINP,1002) ANI,ANP
IF (ANI.EQ.O) ANI=1.0
IF (ANP.EQ.O) ANP=1.0
IF (INP.FD.O)
WRITE (KOUT,1001) ANI,ANP
BEHIND 1
BEHIND 2
BEHIND 3
READ AND PRINT IF STUDY INFORMATION
TABS80 101
TABS80 102
TABS80 103
TABS80 104
TABS80 105
TABS80 106
TABS80 107
TABS80 108
TABS80 109
TABS80 110
TABS80 111
TABS80 112
TABS80 113
TABS80 114
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TABS80 141
TABS80 142
TABS80 143
TABS80 144
TABS80 145
TABS80 146
TABS80 147
TABS80 148
TABS80 149
TABS80 150
M0=1
M1=M0*ASTO10F
M2=M1*150NST
M3=M2*20NST
M4=M3*20NST
M5=M4*10PAT
M6=M5*10PAT
M7=M6*10PAT
M8=M7*10PAT
M9=M8*10NST
IF (M9.GT.M702) CALL TAPP (LNO-M702)+13
CALL TABE (A1M1,A1M2,A1M3),A1M4),A1M5),A1M6),A1M7),A1M8),
N,I,MPAT)
READ AND PRINT OF FRAME PROPERTIES AND FORM LATERAL STIFFNESSES
DO 200 I=1,MDF
READ (KINP,1001) FMD,F,MC,MS,MCP,MBP,MFEF,MCOM,MFAN,MDIG,IPLT,
MSCC
IF (INPL.EQ.O) IPLT=0
IF (INPL.FO.3) IPLT=0
IF (MSCC.NE.O) MSCC=1
IF (MIMP.EQ.O) GO TO 250
CALL SECOND (T1)
LINE=99
CALL NUPAJ (L1,Z7,TESTE)
WRITE (KOUT,2001) FMD,F,MC,MS,MCP,MBP,MFEF,MCOM,MFAN,MDIG,IPLT,
MSCC
250 MB=MC-1
MCP=MC*1
MBP=MB*1
MM=MCP*MS+1
M2=M1*100NST
M3=M2*MB
M4=M3*MB*1
M5=M4*MB*1
M6=M5*20NEF
M7=M6*MB*1
M8=M7*MS*MB*1
M9=M8*MS*MC
M10=M9*20MB*1
M11=M10*20MB*1
M12=M11*20MDIG
M13=M12*MDIG
M14=M13*MB*1
M15=M14*MB*1
M16=M15*MB
TABS80 151
TABS80 152
TABS80 153
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TABS80 198
TABS80 199
TABS80 200

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200 CONTINUE
IF (INP.EQ.0) GO TO 200
CALL MUPAJ (I,5) IFESTI
CALL SECOND (TTTT)
WRITE (RUNIT,2003) I,TTTT
200 CONTINUE
*
MDC=NO*NST*(MDF+2)-1
WRITE (RTAPE) (A(I),I=MD,MLOC)
C
CALL SECOND (T122)
C
ASSEMBLE STRUCTURAL STIFFNESS AND LATERAL LOAD VECTORS
*
N1=N2+MSS*NS
N2=N3+MSS
N3=N4+(NST-1)*NST/2
N4=N5+NST
N5=N6+NST*NF
N6=N7+5*NF
N7=N8+NF
IF (NG.GT.MT) CALL TABR(NG-MT),1
CALL TABR (A1M1,A1M2,A1M3,A1M4,A1M5,A1M6,A1M7,A1M8,A1M9,A1M10,A1M11,A1M12,A1M13,A1M14,A1M15,A1M16,A1M17,A1M18,A1M19,A1M20,A1M21,A1M22,A1M23,A1M24,A1M25,A1M26,A1M27,A1M28,A1M29,A1M30,A1M31,A1M32,A1M33,A1M34,A1M35,A1M36,A1M37,A1M38,A1M39,A1M40,A1M41,A1M42,A1M43,A1M44,A1M45,A1M46,A1M47,A1M48,A1M49,A1M50,A1M51,A1M52,A1M53,A1M54,A1M55,A1M56,A1M57,A1M58,A1M59,A1M60,A1M61,A1M62,A1M63,A1M64,A1M65,A1M66,A1M67,A1M68,A1M69,A1M70,A1M71,A1M72,A1M73,A1M74,A1M75,A1M76,A1M77,A1M78,A1M79,A1M80,A1M81,A1M82,A1M83,A1M84,A1M85,A1M86,A1M87,A1M88,A1M89,A1M90,A1M91,A1M92,A1M93,A1M94,A1M95,A1M96,A1M97,A1M98,A1M99,A1M100,A1M101,A1M102,A1M103,A1M104,A1M105,A1M106,A1M107,A1M108,A1M109,A1M110,A1M111,A1M112,A1M113,A1M114,A1M115,A1M116,A1M117,A1M118,A1M119,A1M120,A1M121,A1M122,A1M123,A1M124,A1M125,A1M126,A1M127,A1M128,A1M129,A1M130,A1M131,A1M132,A1M133,A1M134,A1M135,A1M136,A1M137,A1M138,A1M139,A1M140,A1M141,A1M142,A1M143,A1M144,A1M145,A1M146,A1M147,A1M148,A1M149,A1M150,A1M151,A1M152,A1M153,A1M154,A1M155,A1M156,A1M157,A1M158,A1M159,A1M160,A1M161,A1M162,A1M163,A1M164,A1M165,A1M166,A1M167,A1M168,A1M169,A1M170,A1M171,A1M172,A1M173,A1M174,A1M175,A1M176,A1M177,A1M178,A1M179,A1M180,A1M181,A1M182,A1M183,A1M184,A1M185,A1M186,A1M187,A1M188,A1M189,A1M190,A1M191,A1M192,A1M193,A1M194,A1M195,A1M196,A1M197,A1M198,A1M199,A1M200,A1M201,A1M202,A1M203,A1M204,A1M205,A1M206,A1M207,A1M208,A1M209,A1M210,A1M211,A1M212,A1M213,A1M214,A1M215,A1M216,A1M217,A1M218,A1M219,A1M220,A1M221,A1M222,A1M223,A1M224,A1M225,A1M226,A1M227,A1M228,A1M229,A1M230,A1M231,A1M232,A1M233,A1M234,A1M235,A1M236,A1M237,A1M238,A1M239,A1M240,A1M241,A1M242,A1M243,A1M244,A1M245,A1M246,A1M247,A1M248,A1M249,A1M250)
CALL SECOND (T133)
*
PLOTTING PLAN VIEW / FRAME LOCATIONS
IF (MPL.EQ.0) GO TO 550
IF (MPL.EQ.2) GO TO 550
CALL SFRAME
550 CONTINUE
*
URC LATERAL LOAD DATA
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SUBROUTINE TABR (KIMP,KIMP1
  REMOVING 3-COMMENT CARDS FROM INPUT STREAM
  COMMON /JUNK/ IOLP,ICARD(18)
  DATA ISTOP1 /ZMS /
  DATA ISTOP2 /ZHMZ /
  DATA ITEST /ZMS /
  REMIND KIMP
  DO READ (KIMP,1000) IOLR,ICARD
  IF (IOLR.EQ.1) ITEST1 GO TO 10
  IF (IOLR.EQ.2) ISTOP1.AND.ICARD(1).EQ.ISTOP2) GO TO 20
  WRITE (KIMP,1000) IOLR,ICARD
  GO TO 10
20 IOLR=2M
  DO 10 I=1,1M
  10 ICARD(I)=M
  DO 10 I=1,3
  *C WRITE (KIMP,1000) IOLR,ICARD
  ENDFILE KIMP
  REMIND KIMP
  RETURN
1000 FORMAT (A1,17A,46)
END

SUBROUTINE TABR (N,ITAG)
  ERROR MESSAGE SUBROUTINE
  COMMON /GEN/ / NSI,NDF,NTF,NLO,NAT,MFO,MSD,MOP1
  COMMON /TABR/ / KIMP,KIMP,KOUT,KSTR,MTAPE
  COMMON /INFORM/ / INFO(7),IDATE(2),NPAGE(2),MAXLIN,LLINE
  CALL MUPAJ (1,3,ITEST)
  IF (ITAG.EQ.0) GO TO 999
  IF (LEFOR.GT.50) GO TO 999
  ERROR=IFROR+1
  MOP1=1
  TABS00 393 C WRITE (KOUT,1000)
  TABS00 394 C GO TO (1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19,20,21,22,
  TABS00 395 2,3,4,27,28,27,28,29,30,31),ITAG
  TABS00 396 C
  TABS00 397 C 3 WRITE (KOUT,1001) M
  TABS00 398 GO TO 999
  TABS00 399 C
  TABS00 400 C 2 WRITE (KOUT,1002) M
  TABS00 401 GO TO 99
  TABS00 402 C
  TABS00 403 C 3 WRITE (KOUT,1003)
  TABS00 404 GO TO 99
  TABS00 405 C
  TABS00 406 C 4 WRITE (KOUT,1004)
  TABS00 407 GO TO 99
  TABS00 408 C
  TABS00 409 C 5 WRITE (KOUT,1005)
  TABS00 410 GO TO 99
  TABS00 411 C
  TABS00 412 C 6 WRITE (KOUT,1006) M
  TABS00 413 LIME=LIME+1
  TABS00 414 GO TO 99
  TABS00 415 C
  TABS00 416 C 7 WRITE (KOUT,1007) M
  TABS00 417 GO TO 99
  TABS00 418 C
  TABS00 419 C 8 WRITE (KOUT,1008) M
  TABS00 420 GO TO 99
  TABS00 421 C
  TABS00 422 C 9 WRITE (KOUT,1009) M
  TABS00 423 LIME=LIME+1
  TABS00 424 GO TO 99
  TABS00 425 C
  TABS00 426 C 10 WRITE (KOUT,1010) M
  TABS00 427 GO TO 99
  TABS00 428 C
  TABS00 429 C 11 WRITE (KOUT,1011) M
  TABS00 430 GO TO 99
  TABS00 431 C
  TABS00 432 C 12 WRITE (KOUT,1012) M
  TABS00 433 GO TO 99
  TABS00 434 C
  TABS00 435 C 13 WRITE (KOUT,1013) M
  TABS00 436 GO TO 99
  TABS00 437 C
  TABS00 438 C 14 WRITE (KOUT,1014) M
  TABS00 439 GO TO 99
  TABS00 440 C
  TABS00 441 C 15 WRITE (KOUT,1015) M
  TABS00 442 GO TO 99
  TABS00 443 C
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  TABS00 488 C

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DATA ME /3H 3.3M ELI-MEIL-34 147
N=NUM
READ AND PRINT OF FRAM/STORY CONNECTIVITY DATA
K=NST-NS
DO 65 NURS-L=NSI
N=NUMS
65 MSCIN=IF3=0
DO 70 NURS-L=NS
70 MSCIN=NSI-IF1=N
READ (FRAM/STORY) MSCIN=NSI-IF1,NURS-L=NSI
CALL MUPAJ (ELI-MS/14-3),IFEST1
WRITE (ROUT-9000) (MSCIN=NURS-A,IF1),NURS-L=NSI
90 M=NS-I
N=NUMS
75 CONTINUE
DO 76 NURS-L=NS
IF (MSCIN=IF1,LE,NSCIN=NURS-L,IF3) CALL TABB (N,311)
76 CONTINUE
DO 80 NURS-L=NS
N=NUMS
80 MSCIN=IF3=NSI-MSCIN=NURS-IF1=2
IF (NURS-IF3) GO TO 100
IF (NURS-IF3) GO TO 90
CALL MUPAJ (ELI-MS/23-3),IFEST1
WRITE (ROUT-2000) (M=11),NURS-L=NSI
90 READ (TEMP-1000) (SLI1),NURS-L=NSI
IF (NURS-IF3) GO TO 100
CALL MUPAJ (ELI-MS/23-3),IFEST1
WRITE (ROUT-1111) (SLI1),NURS-L=NSI
READ AND PRINT OF COLUMN PROPERTIES

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TABS00 830

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9000 FORMAT (1A,1E)
9001 FORMAT (4H)
9002 END

SUBROUTINE TART (MSC,LBC,SD,MS,MR,ML,IL,MPROP,MST,IF)
C
C PRINT MEMBER LOCATIONS AS GENERATED
C
C DIMENSION LOCINS,MR,ML,SD(MST,1),MSC(MST,1)
COMMON /TARPE/ RIMP,KIMP,KOUT,MSTR,MTAPE
COMMON /TMEOR/ TMEO(20),TDATE(2),MPAGE(2),MAXLIN,LINE
COMMON /JUNK/ MLO,LOC(15)
P=MST-N
DO 300 J=1,MR+15
IF (J,1) GO TO 200
WRITE (KOUT,2000) (K,K=J,J)
WRITE (KOUT,2001)
DO 200 I=1,MS
DO 100 K=J,J
R1=K-J+1
LOC(K)=LBC(I+R1)
IF (LOC(K).EQ.NPROP) LOC(K)=0
100 CONTINUE
C
K=J+1
M=MSC(I+M)
CALL MUPAJ (1,1,1,TEST)
IF (TEST.EQ.0) GO TO 200
WRITE (KOUT,2000) (K,K=J,J)
WRITE (KOUT,2001)
LINE=LME+J
200 WRITE (KOUT,2001) SD,ML,1,1,LOC(K),R=1,K=1
300 CONTINUE
C
RETURN
C
2000 FORMAT (4H)
2001 FORMAT (1X,45,2X,151A)
2002 FORMAT (1X)

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SUBROUTINE TARB (SA,SB,SC,KL,A,B)
COMMON /JUNK/ MLO,MLO,MP,MN,LM(16),SS(6,6),P(6,4),T(2,4)
T(2,1)=R/KL
T(1,1)=1.0+T(2,1)
T(1,2)=1.0/AL
T(2,2)=T(1,2)
T(2,3)=1.0+T(1,3)
T(1,4)=T(1,2)
T(2,4)=T(1,4)
DO 100 I=1,4
DI=SB+T(2,1)+SB+T(2,1)
D2=SB+T(1,1)+SB+T(2,1)
DO 100 J=1,4
100 SS(J,1)=DI+T(1,1)+D2+T(2,1)
IF (SC) L20=L20+110
110 SS(5,5)=SC
SS(6,6)=SC
SS(6,6)=SC
DO 100 I=1,4
DI=SB+T(2,1)+SB+T(2,1)
D2=SB+T(1,1)+SB+T(2,1)
DO 100 J=1,4
100 SS(J,1)=DI+T(1,1)+D2+T(2,1)
110 SS(5,5)=SC
SS(6,6)=SC
120 RETURN
END

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SUBROUTINE TART (10,SA,SB,SC,KL,D,SS,CA)
COLUMN PANEL STIFFNESS AND FORCE MATRICES
DIMENSION SS(6,6),CALO(6),T(3,6)
DO 10 I=1,3
DO 10 J=1,6
10 T(I,J)=0.0
T(1,1)=1.0/ML
T(2,1)=T(1,1)
T(1,2)=T(1,1)
T(2,2)=T(1,2)
T(2,3)=T(1,3)
T(1,3)=T(1,2)
T(2,3)=T(1,3)
T(2,4)=T(1,4)
T(3,4)=T(1,4)
T(3,5)=T(1,5)
T(3,6)=T(1,6)
END

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SUBROUTINE TARB (10,SA,SB,SC,KL,D,SS,CA)
COLUMN PANEL STIFFNESS AND FORCE MATRICES
DIMENSION SS(6,6),CALO(6),T(3,6)
DO 10 I=1,3
DO 10 J=1,6
10 T(I,J)=0.0
T(1,1)=1.0/ML
T(2,1)=T(1,1)
T(1,2)=T(1,1)
T(2,2)=T(1,2)
T(2,3)=T(1,3)
T(1,3)=T(1,2)
T(2,3)=T(1,3)
T(2,4)=T(1,4)
T(3,4)=T(1,4)
T(3,5)=T(1,5)
T(3,6)=T(1,6)
END

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TABS0 1755
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90 DD 100 J=I,M
   A(I,J)=A(I,J)-A(I,J)*PIB(A(I,J))
100 A(I,J)=A(I,J)
   DD 110 L=I,M
   DD 110 L=I,M
110 B(I,L)=B(I,L)-A(I,J)*PIB(A(I,L))
120 CONTINUE
   GO TO 90
C
C   BACK SUBSTITUTION
C
130 M=M-1
   IF (P.EQ.0) GO TO 140
   M=M+1
   DD 140 L=I,M
   DD 140 J=M,M
   GO TO 130
140 B(I,L)=B(I,L)-A(I,J)*PIB(A(I,L))
C
150 RETURN
   END

SUBROUTINE TABL (MNC,A,SS,RR,S,R,D,AA,MSS,MST,MTF,MEDI)
C
C   ASSEMBLING LATERAL STEPFESS
C
DIMENSION DIMST,MTP,ATPF,S3,MEDI(MF,S3),MDC(MST,S3)
COMMON ZGEN1 / MST,MDF,MIF,MLD,NAT,MFO,MSD,MOPT,MGCO,MOSP,MUBC,
COMMON ZGEN2 / RLB(I),MIE,MNP,RIEIO
COMMON ZGEN3 / MTP,ATPF,S3,MEDI(MF,S3),MDC(MST,S3),MABLIM,LIME
COMMON ZOUT / MNP,MOUT
COMMON ZUNK / A(I),A(J)
C
IF (MNST.EQ.1) GO TO 105
C
REMI=7
DO 50 I=1,MSS
DO 40 J=1,AA
40 B(I,J)=0.
50 S(I,J)=0.
DO 100 I=1,MST
IF (I.EQ.1)
S(I,I)=1.

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TABS00 1957
TABS00 1958
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TABS00 1960
TABS00 1961
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TABS00 2001
TABS00 2002

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IF (MNC.MF.0) GO TO 60
S(I,I)=1.
DO 100 J=1,AA
DO 100 L=1,MS
LL=S*PIB(A(I,L))
100 B(I,I)=J*(A(I)-A(I,LL))
C
105 IF (MNP.EQ.0) GO TO 110
LIME=99
CALL MUPAJ (I,I,I,TESTI)
WRITE (ROUT,1000)
110 JFP=0
REMI=1
DO 500 K=1,MIE
REMI=REMI+1
IF (MNP.EQ.0) GO TO 170
CALL MUPAJ (I,I,I,TESTI)
IF (I,TESTI.EQ.0) GO TO 160
WRITE (ROUT,1000)
LIME=LIME+7
160 WRITE (ROUT,2000) K,IF,IFC,R1,Y1,X2,Y2,(MEDI(K,J),J=1,AA)
170 IF (I.EQ.1) GO TO 190
IF (I.EQ.1) CALL TABR (K,22)
IF (I.EQ.0) IF (GT,MDF) CALL TABR (K,22)
IF (MNST.ME.1)
*READ (Z) LRD,M1,(S(I),J=1,LRD),(IR(I),L1)=M1,MSTI,L=1,AA)
IF (J=1)
IF (I.EQ.1) GO TO 190
IF (I.EQ.1) CALL TABR (K,23)
DO 200 M=1,MST
ML=MSS(I)-I
AR=210*(Y2-A(I,M,6))+(X2+I*M,6)-Y1+AA*(M,5)
200 DIM,R3=AR/RL
A(I,I)=I*(Y2-X1)/XL
A(I,2)=I*(Y2-Y1)/XL
A(I,3)=A(I,2)
A(I,4)=A(I,1)
KR=0
DO 400 M=1,MST
A(I,1)=A(I,4)
ML=3*(M,1)
MNC=3*(M,1)

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TABS00 2004
TABS00 2005
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TABS00 2052

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* 3XMMODELIXTIME/16NUMBERPERIOD)
5001 FORMAT (//
* 4SH STATIC LOAD CONDITION DISPLACEMENTS
* 4SH DISPLACEMENTS ARE AT THE CENTERS OF MASS OF
* 4SHME RESPECTIVE LEVELS
* 15X+2XIMZ11UM-1+16HLOAD CONDITIONS+211UM-11H//
* 3X5HLEVEL3XNDIN41X1H10X2H110X2H1V91M9X1H8/1
5002 FORMAT (1M
* 3X+4S+2X+4S+2X+6F10.5)
5003 FORMAT (1M
* 10A3+10A3+10A3+21S+3F10.0+9X+41+F10.0)
9001 FORMAT (//23H RESPONSE ANALYSIS DATA ///
* 31H ACCELERATION HISTORY HEADING.. 10A3//
1 30H ACCELERATION INPUT FORMAT 10A3//
2 30H NUMBER OF POINTS ON HISTORY 110/
3 30H NUMBER OF OUTPUT TIMES 110/
4 30H ACCELERATION SCALE FACTOR F10.4/
5 30H TIME INCREMENT FOR HISTORY F10.4/
6 30H TIME INCREMENT FOR OUTPUT 9E+01/
7 30H TIME HISTORY TYPE F10.41/
8 30H TIME STEP IF E-TYPE HISTORY F10.41/
9 30H DAMPING 1
9003 FORMAT (// 16H MODE DAMPING )
9004 FORMAT (15+10.2)
9005 FORMAT (14+12.3)
9006 FORMAT (10A4)
END

SUBROUTINE TUBC (F+SD,TEMP,MSS,MST)
C
C REDEFINING LOAD CONDITIONS A AND B WITH UBC LOADS
C
C DIMENSION F(MSS+2),SD(MST+19),TEMP(MST)
C
COMMON /GEN1 / MST,MDF,MF,MLO,MAT,NEG,MSD,MPT,MRCO,MOSP,MURC,
* MEGT,MSS,13,15
COMMON /GEN2 / RLAB(3),AMI,AMP,RIGID
COMMON /THEDR / IHED(20),IOATE(2),MPAGE(2),MAXLIN,LINE
COMMON /TAPE / KIMP,KIMP,KOUT,KSTR,NTAPE
COMMON /KOPT / MINP,MOUT
COMMON /UBC / J,ATS,UBC1,GRAY,PERIOD(2),URCK(2),MTUP(2),MBOT(2)
C
LINE=90
IF (J.J.EQ.3) J=2
C DD 700 4+1+JJ
C IF (PERIOD(1)+15+LE..0) GO TO 700
IF (INDUT.NE.0) CALL MUPAJ (1,1,1,TEST)
CALCULATE STORY ELEVATION
TEMP(MST)=SD(MST+2)
IF (MST.EQ.1) GO TO 150
DD 100 M=2,MST
L=MST-N+1
100 TEMP(L)=TEMP(L+1)+SOIL+21
150 MT=MST-MDPIK+13+1
MB=MST-MBOTIK+15
CALCULATE STORY HEIGHT ABOVE BOTTOM OF DISTRIBUTION
IF (MB.GE.MST) GO TO 250
DD 100 M=2,MT
200 TEMP(M)=TEMP(M)-TEPP(MB+1)
SUMM=0.
250 SUMM=0.
SIGMA M AND SIGMA MH
DD 300 N=MT,MB
W=SDEN(3)+GRAV
TEMP(M)=TEMP(M)+W
SUMM=SUMM+W
300 SUMM=SUMM+TEMP(M)
SOIL FACTOR S FROM IS
S=1.5
IF (15+LE..1.E-8) GO TO 350
TT=15
IF (15+LE..0.5) TT=0.5
IF (15+LE..2.5) TT=2.5
TT=PERIOD(15)/TT
IF (15+LE..1.0) GO TO 360
GO TO 370
360 S=L.0+TT-0.5*TT*TT
GO TO 380
370 S=L.2+0.8*TT-0.3*TT*TT
380 IF (S.GT.1.5) S=1.5
IF (S.LT.1.0) S=1.0
SEISMIC FACTOR C
C-15.0*SQRT(PERIOD(1)+15)
350 C=15.0*SQRT(PERIOD(1)+15)

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C      G=L/C
C      SC=9C
C      IF ISC.GT..1N1 SC=.1N
C      V=ZSC*URCI*UBCKR1
C      FT=0.
C      IF IPER(DDK=15).GE..7J FT=-.07*PPER(DDK=15)
C      IF IFT.GT..2599J FT=.259V
C      *WRITE (KOUT,1000) RLABR(15),ZASUBCI,CUBCKR(15),SUMM,V
C      V=VSCUM
C      FT=FTSUM
C      IF INOUT.ME.OJ
C      *WRITE (KOUT,2000) V,FT
C      V=V-FT
C      V=V/SUMM
C      STORV FORCES
C      DO 400 M=1,NB
C      TEMPN1=TEMPIN*V
C      TEMPN2=TEMPINT*VFT
C      PACKING INTO 50
C      LL=8*EK(15)-LJ*3
C      MM=15*IR(15)-LJ*2
C      DO 900 M=1,NB
C      DO 950 L=1,3
C      *SC SDOIM,LL,LJ=0.
C      *SDIM,LL,LJ=SDIM,LL+1*(SDIM,MM+2J-SDIM+6J)
C      *SDIM,LL,LJ=SDIM,MM+1J-SDIM+5J
C      *SDIM,LL,LJ=SDIM,MM+1J-SDIM+5J
C      *ZOC CONTINUE
C      *LOADING INTO STRUCTURAL LOAD VECTOR
C      DO 800 J=1,NST
C      LL=1*J(1)-1J
C      DO 800 J=1,13
C      DO 800 L=1,2
C      LL=5*JL+J*15
C      *RDC FEEL(J,L)=SDLL+LLJ
C      * PRINTING MODIFIED LOAD CONDITIONS A AND B
C      TAB580 2641 IF INOUT.EQ.OJ GO TO 999
C      TAB580 2642 LINE=97
C      TAB580 2643 CALL NUPAJ (11,9,ITEST)
C      TAB580 2644 WRITE IFOUT,6000
C      TAB580 2645 C
C      TAB580 2646 CALL NUPAJ (11,6,ITEST)
C      TAB580 2647 LIME=LINE-1
C      TAB580 2648 WRITE IFOUT,5000
C      TAB580 2649 DO 500 M=1,NST
C      TAB580 2650 CALL NUPAJ (11,1,ITEST)
C      TAB580 2651 IF IFT.GT..2599J GO TO 500
C      TAB580 2652 WRITE IFOUT,5000
C      TAB580 2653 LIME=LIME+5
C      TAB580 2654 * 500 WRITE (KOUT,5001) SDIM(11),(SDIM(11)+9*10J),(SDIM(11)+16*17J)
C      TAB580 2655 C
C      TAB580 2656 CALL NUPAJ (11,6,ITEST)
C      TAB580 2657 LIME=LINE-1
C      TAB580 2658 WRITE (KOUT,6000)
C      TAB580 2659 DO 600 M=1,NST
C      TAB580 2660 CALL NUPAJ (11,1,ITEST)
C      TAB580 2661 IF IFTEST.EQ.OJ GO TO 600
C      TAB580 2662 WRITE IFOUT,6000
C      TAB580 2663 LIME=LIME+5
C      TAB580 2664 * 600 WRITE (KOUT,6001) SDIM(11),(SDIM(11)+1*17),(SDIM(11)+18*19)
C      TAB580 2665 C
C      TAB580 2666 * 999 RETURN
C      TAB580 2667 C
C      TAB580 2668 * 1000 FORMAT (///
C      TAB580 2669 * 50M UNIFORM BUILDING CODE SEISMIC LOADS FOR DIRECTION A//
C      TAB580 2670 * 5M V = Z SLICE W SC=0.1N MAX //
C      TAB580 2671 * 4M Z =F10.4//
C      TAB580 2672 * 4M S =F10.4//
C      TAB580 2673 * 4M I =F10.4//
C      TAB580 2674 * 4M C =F10.4//
C      TAB580 2675 * 4M K =F10.4//
C      TAB580 2676 * 4M W =F10.4//
C      TAB580 2677 * 4M V =F10.4,1MM)
C      TAB580 2678 * 2000 FORMAT (4H =F10.4, //4H FT.=F10.4)
C      TAB580 2679 * 4000 FORMAT (//
C      TAB580 2680 * 5M STRUCTURAL LATERAL LOAD CONDITIONS /
C      TAB580 2681 * 4M AS ADJUSTED BY UMC SEISMIC REQUIREMENTS /
C      TAB580 2682 * 500G FORMAT (//
C      TAB580 2683 * 5M STRUCTURAL LATERAL LOAD CONDITION A (X-DIRECTION). //
C      TAB580 2684 * 6M LEVEL,OXZMF10XZMFYIIXHIXIIMY)
C      TAB580 2685 * 600C FORMAT (//
C      TAB580 2686 * 5M STRUCTURAL LATERAL LOAD CONDITION B (Y-DIRECTION). //
C      TAB580 2687 * 6M LEVEL,OXZMF10XZMFYIIXHIXIIMY)
C      TAB580 2688 * 5001 FOPRAT (1X,45,4F12.2)
C      TAB580 2689 C
C      TAB580 2690 C

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230 IF (I1011 - JPIV) > 0.40, 350
240 R=I0111
250 MEPP=MI*E1
260 MI*E3=0.
270 IPI=I*1
280 X(11) = 0.
C
C SEARCH IN DEPLETED ROW FOR NEW MAXIMUM
C
C DD 320 *IPI*11,M
IF ( X(11) - ABS(MI*J1) ) > 300, 300, 320
300 REI1 = ABS(MI*J1)
I0111 = J
320 CONTINUE
MI*E1 = MEPP
350 CONTINUE
C
C X(11) = 0.
X(11) = 0.
C
C CHANGE THE OTHER ELEMENTS OF M
C DD 530 I=1,M
IF (I - JPIV) > 530, 420
MI*E1 = MI*JPIV
IF ( X(11) - COS(MI*E1) ) > 530, 370
370 REI1 = ABS(MI*JPIV)
I0111 = JPIV
390 MI*JPIV = -SINE*MI*E1
IF ( X(11) - ABS(MI*JPIV) ) > 400, 530, 510
400 REI1 = ABS(MI*JPIV)
I0111 = JPIV
GO TO 530
C
420 IF (I - JPIV) > 530, 510, 480
MI*E1 = MI*JPIV
IF ( X(11) - COS(MI*E1) ) > 530, 450, 450, 450
450 REI1 = ABS(MI*JPIV)
I0111 = JPIV
490 MI*JPIV = -SINE*MI*E1
IF ( X(11) - ABS(MI*JPIV) ) > 400, 530, 510
C
480 MEPP = MI*JPIV*11
MI*E1 = COS(MI*E1) + SINE*MI*JPIV*11
490 REI1 = ABS(MI*JPIV*11) + 400, 500, 500
I0111 = ABS(MI*E1*11)

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2870 M(JPIV,1) = -SINE*MEPP + COS(MI*JPIV*11)
2880 IF ( X(JPIV) - ABS(MI*JPIV,11) ) > 510, 510, 510
2890 X(JPIV) = ABS(MI*JPIV,11)
2900 I0(JPIV) = 1
2910 CONTINUE
C
C TEST FOR COMPUTATION OF EIGENVECTORS
C
C IF (I0(JPIV) > 0, 540, 40
540 DD 550 J=1,M
MI*E1 = UI(J,1)
UI(J,1) = COS(MI*E1) + SINE*UI(J,1)
550 UI(J,1) = -SINE*MI*E1 + COS(MI*E1)
GO TO 40
1000 RETURN
END
C
FUNCTION TABA (MPC, SE, I, PA)
RESPONSE SPECTRUM LINEAR INTERPOLATER
DIMENSION PA(2, MPC)
DO 100 I=2, MPC
T=PA(I,1)
T2=PA(I,2)
IF (T2 > T) CALL TABR (I, T2)
IF (T2 < T) AND (T < T2) GO TO 200
100 CONTINUE
C
IF (I < 1) PA(1,1) = MPC(1) TABA=PA(2, MPC)
IF (I < 1) PA(1,2) = MPC(2) TABA=PA(2, 1)
GO TO 999
C
200 R1=I(2,1)/I(2,1)
R2=I(2,2)/I(2,2)
TABA=SPR(PA(2, J)-I(1)R1+I(2)R2)
999 RETURN
C
END
C
FUNCTION COGIV, RU, NFO)

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C PERFORMING COC COMBINATION
1 DIMENSION V(MFG),RC(MFG,MFG)
C COC=0.
C DO 20 J=1,MFG
TEMP=0.
DO 10 I=1,MFG
10 TEMP=TEMP+RO(I,J)*V(I)
20 COC=COC+TEMP*V(I)
C COC=ABS(COC)
COC=SIGN(COC)
C RETURN
END

SURROUTINE COCIM (M,RO,DAMP,MFG)
C INITIALIZING MODAL CROSS CORRELATION MATRIX FOR COC
C DIMENSION W(MFG),RC(MFG,MFG)
C TUPT=0.001*(1.0)
DO 10 I=1,MFG
W(I)=TUPT/M(I)
10 CONTINUE
DO 20 J=1,MFG
DO 30 I=1,MFG
IF ((I-J) 40,50,40)
GO TO 20
50 RO(I,J)=L.
GO TO 20
40 IF (DAMP(I,30,30) 60)
10 RO(I,J)=0.
GO TO 20
60 R=W(I)/W(J)
TEMP=(I-R)*J*J*2+.001*DAMP*RO(I,I)*J*J*2
RO(I,J)=R*TEMP+RO(I,I)*RO(J,J)/TEMP
70 CONTINUE
70 CONTINUE

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TAB580 2929 C
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TAB580 2969 C
TAB580 2970 C
TAB580 2971 C
TAB580 2972
TAB580 2973
TAB580 2974

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RETURN
END

SUBROUTINE TARDY(F,PA,X,T,MSS)
EVALUATION OF 3D TIME-DEPENDENT LATERAL DISPLACEMENTS
DIMENSION F(MSS),PA(2,1),X(11),T(1)
COMMON /GEM1 / MST,MDF,MTE,MLO,MAT,MFG,MSD,MOP
COMMON /TAP1 / KTMP,KMP,KOUT,KSTR,KTRAP
COMMON /SYM / MTE,MDF,MPC-DAMP,MRO,IMTP,MOT
COMMON /JUNK / DUR(2),SFMT(10)
C ZERO DISPLACEMENTS AND READ GROUND ACCELERATIONS
DO 100 I=1,MSS
DO 100 K=1,NTIME
100 F(I,K)=0.0
IF (IMTP.EQ.IME) GO TO 400
READ (KIMP,SFMT) (PA(I,1),PA(2,1),I=1,MPC)
GO TO 450
400 TIME=0. (KIMP,SFMT) (PA(2,1),I=1,MPC)
DO 420 I=1,MPC
PA(I,1)=TIME
420 TIME=TIME+MOT
PA(I,1)=TIME
450 CONTINUE
IF (MIMP.EQ.O) GO TO 115
LINE=99
DO 130 I=1,MPC
CALL MUPAJ (I,1,ITE5)
IF (ITE5.EQ.O) GO TO 130
WRITE (KOUT,2000)
130 WRITE (KOUT,4000) PA(I,1),PA(2,1)
C CHECK GROUND ACCELERATION DATA
115 DO 120 I=2,MPC
IF (PA(I,1).GT.PA(1,1)) GO TO 120
CALL TABR(I,29)

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TAB580 2976
TAB580 2977

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TAB580 3020

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1003 FORMAT (MOTIME,...,10INCH,F,3)
1005 FORMAT (1)
2000 FORMAT (3M DISPLACEMENTS ALL ZERO...NOT PLOTTED )
2001 FORMAT (10HOSCALE - ONE INCH = 615.69X133HARIMUR AT T=
1 57HONOTE..PLOT IS OF DYNAMIC DISPLACEMENTS ONLY AND DOES NOT /
2 7X..HINCLUDE ANY SCALING BY LOAD CASE DEFINITION CARDS )
END

SUBROUTINE TABP (INTOT)
C
C CALCULATING MEMBER FORCES AND STRESSES
C
COMMON /GEN1 / MST,MDF,NIF,MLO,MAT,MFG,MSD,MOPT,MRCO,MOSP,MUBC,
COMMON /STRAP/ RIMP,RIIMP,ROUT,ESTR,MTAPE,KTAPE
COMMON /LOAD/ FMT,FM,FL,FLC
COMMON /DYN / MTYPE,DT,MFC,DAMP,MKD,IMTYP,MOT
COMMON /AL1)
C
C W=MEG
IF (ENAT.ME.3) P=0
M=1
LO=MO+NST*NDP
L1=EO+2*P*NT
L2=EO+2*P*NB
L3=L1+10*NO
L4=L3+10*NO
L5=L4+10*P
M1=L5+10*P
IF (INT.GT.MTOT) CALL TABR((M1-MTOT),1)
CALL TABC (AL1,3),AL1(4),MLO)
IF (MDPT.EQ.1) GO TO 999
C
IF (ENAT.ME.3) GO TO 40
REWIND 1
CALL COIN (AL1,1),1,MFO)
CALL COIN (AL1,1),1,DAMP,MFO)
AC CONTINUE
C
REWIND 2
REWIND MTAPE
EQ=0
M=0
MLO=6*MEG
IF (ENAT.EQ.4) PLO=6*MTIME

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M2=M1+NST*MLO
IF (M2.GT.MTOT) CALL TABR((M2-MTOT),1)
DO 500 I=1,MTF
CALL TABU (ATM1),AL1(1),AL1(1),AL1(2),AL1(3),AL1(4),AL1(5),
MST,MLO,MDO,MAT,MFO)
WRITE (ETAPE) IF,IFC,FHED
WRITE (MTAPE) IF,IFC,FHED
IF (IF.EQ.M1) GO TO 200
IF (IFC.EQ.O1) GO TO 100
IF (FIND.ME.1) GO TO 100
DO 50 K=1,NBR
50 BACKSPACE 3
100 BACKSPACE 3
100 BACKSPACE 3
READ (I3) M,MC,MS,MCP,MBP,MFEF,MPAN,MDC,G,PCOML
EQ=1
200 IF (IFC.ME.O1) GO TO 500
IF (FID.ME.2) GO TO 300
DO 250 R=1,MS
250 READ (I3) XX
300 MP=2*MC
CALL SECOND (TS)
C
MB=MC-1
M2=M1+MC*MS+1
M3=M2+MB
M4=M3+MB
M5=M4+MB
M6=M5+MB
M7=M6+MB
M8=M7+MB
M9=M8+MB
M10=M9+MB
M11=M10+MB
M12=M11+MB
M13=M12+MB
M14=M13+MB
M15=M14+MB
M16=M15+MB
M17=M16+MB
M18=M17+MB
IF (M18.GT.MTOT) CALL TABR((M18-MTOT),1)
WRITE (ETAPE) M,MC,MS,MCP,MBP,MFEF,MPAN,MDC,G,PCOML

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TAB580 3213
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TAB580 3258
C

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C LINE-99
C LLD=MLD+MPQ
C DD 500 LL=L,LLD,4
C IT=MLD-LL+1
C I=MLD,CT,LLD1,LM=LLD
C IM=LM+1-LL
C DD 150 L=LL,LM
C L=1-LL
C (F(L,CT,MLD) GO TO 155
C F(I)=FM(I,O,L)
C F(I)=FM(I,I,L)
C GO TO 150
C 155 I(I)=OH,MODE
C LLD=MLD
C I=MLD,CT,LLD1,LM=LLD
C IM=LM+1-LL
C 15C CONTINUE
C CALL MUPAJ (I,6,(TEST))
C LINE=LINE-1
C WRITE (ROUT,2000) FMD,(I(I),I(I),I(I),I(I),I(I))
C DD 400 M=1,NS
C 250 DD 360 L=LL,LM
C I=1-LL
C U(I)=0.
C IF (L,CT,MLD) GO TO 350
C I400=I3M(I)
C DD 300 J=1,6
C IF (F(I),L,EQ,0) GO TO 300
C UUU=U(I,M,J)
C IF (I400,CT,0) UUU=ABS(UUU)
C U(I)=U(I)+UUU*E4(I,3,L)
C 10C CONTINUE
C V(I)=M(I)-J
C IF (M(I),LT,0) GO TO 360
C SRS5=0.
C SABS=0.
C THST=0.
C 360 CONTINUE
C DD 410 J=7,MLD
C TEMP=ABS(U(M,J))
C IF (M(I) 160,160,180
C 160 SRS5=SRS5+TEMP+TEMP
C SABS=SABS+TEMP
C STOR(J)=J+U(I,M,J)
C GO TO 410
C 180 IF TEMP,GT,THST) THST=TEMP
C 410 SRS5=SRS5+TEMP
C SABS=SABS+TEMP
C IF (M(I),EQ,3) THST=COC(ISTOR,RO,MFO)
C TEMP=SRS5*PR(7,L)+SABS*PR(8,L)+THST*PR(9,L)
C U(I)=U(I)+TEMP
C GO TO 360
C 350 U(I)=U(I)+L*6-MLD)
C 360 CONTINUE
C 370 M=NS+NS
C M=MSC*NS+IF)
C CALL MUPAJ (I,1,(TEST))
C IF (I,TEST,EQ,0) GO TO 400
C LINE=LINE+5
C WRITE (ROUT,2000) FMD,(I(I),I(I),I(I),I(I),I(I))
C 400 WFEFF (6,200) 50(M(L,I),U(I),I,I,I)
C 500 CONTINUE
C PLDT DYNAMIC DISPLACEMENTS
C IF (M(I),NE,4) GO TO 800
C CALL TABPLT (U(I),6,I,NSI,MTIME,DT)
C 600 RETURN
C 1000 FORMAT (I6)
C 2000 FORMAT (///
C * 29H LATERAL RAPE DISPLACEMENTS 4M IN *45//
C * 6H LEVEL,413E,2A81)
C 2001 FORMAT (I4,A5,A15,6)
C FMD
C SUBROUTINE TABO
C (MSC,PP,LDIC,PDIG,IF,TT,COM,SL,SS,R,
C PP,LDIC,PDIG,IF,TT,COM,SL,SS,R,
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905 ME=LEN(P)
  A=BP(5,MR)
  B=SL(P)
  GO TO 420
906 M=LEN(M)
  A=BP(5,MR)
  B=SL(M)
  GO TO 420
C
C
C
900 IF (P.EQ.1) GO TO 901
  IF (P.EQ.MC) GO TO 910
  M=LEN(M)
  MLL=LEN(M)-1
  MLL=LEN(M)-1
  A=BP(5,MR)
  B=BP(6,MR)
  IF (A.LT.BP(5,MR)) A=BP(5,MR)
  IF (B.LT.BP(6,MR)) B=BP(6,MR)
  GO TO 420
901 M=LEN(M)
  MLL=LEN(M)-1
  MLL=LEN(M)-1
  A=BP(5,MR)
  B=BP(6,MR)
  GO TO 420
910 MLL=LEN(M)-1
  MLL=LEN(M)-1
  A=BP(5,MR)
  B=BP(6,MR)
  GO TO 420
C
420 D=CP(5,MC)EFGID
  MLL=ML-B
  AAAA
  TABS80 3597
  TABS80 3598
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  TABS80 3695
  TABS80 3696
  888=B
  A=A-D
  IF (B.LT.0.01) B=0.0
  XL=AL-J-B
  AAA=AAA-B
  888=888-B
  C
  88=0.0
  IF (L.CP(4,MC)) 430,430,429
  429 88=14.4*CP(3,MC)/(L*0.2*CP(4,MC))
  430 COMM=2.0*CP(1,MC)*CP(3,MC)/(L*(L+.2*.888))
  5B=COMM*(1-.88)
  SC=CP(2,MC)*CP(1,MC)/XL
  CALL TABZ(ISA,SB,SC,AL,A,B)
  DO 435 I=1,6
  CALL (I)-((CALL(I))-CALL(I+1))/PL
  CALL(I)-CALL(I)-CALL(I+1)*888
  435 CALL(I)-CALL(I)-CALL(I+1)*888
  C
  LMI(3)=ZPF
  LMI(3)=LMI(3)+M
  LMI(3)=LMI(3)-1
  LMI(3)=LMI(3)-1
  LMI(3)=LMI(3)+1
  C
  CALL TABM (R,XP,IXP,STOR,PO,FR,NN,MLD,MFO,M,1,1)
  IF (INDUT.EQ.0) GO TO 438
  438 DO 440 I=1,6
  440 SY(I)=SY(I)+I+1,1
  900 CONTINUE
  C
  DO TO J=1,10
  DO TO J=1,6
  70 CALL(J)=0.0
  C
  CALCULATE REAR FORCES
  IF (NB.EQ.0) GO TO 565
  IF (INDUT.EQ.0) GO TO 770

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MD-4
 ME-5
 LTP-1
 DO 600
 IF (MB,EC,NBP) GO TO 600
 C
 ML=LCIN,PJ
 M=LCIN,M+1
 A=CP15,M+1/2
 S=CP15,M+1/2
 D=(BP15,M+1)*BP(16,M+1)*FCID
 AAA-A
 BBB-B
 A-A-D
 B-B-C
 IF (A,LT,0.0) A=0.0
 IF (B,LT,0.0) B=0.0
 M=0
 N=0
 IF (BP(13,M+1)*ME-4.0,OR,AP(14,M+1)*ME-0.5) GO TO 431
 IF (BP(17,M+1) 426,426,427
 427 MB=16,40BP(12,M+1)/XL020AP(17,M+1)
 428 COM=2,40BP(11,M+1)*BP(12,M+1)/XL0112,08811)
 SA=COM*0.2,0881
 SB=COM*0.1,0881
 GO TO 428
 431 E(ML,MP(1),MB)*BP(2,M+1)/XL
 SB=BP(14,M+1)*SA
 428 CALL TAB(15,45B,0.0,XL,A,B)
 L(41)=ZM(1)-1
 L(42)=L(41)+2
 L(43)=L(41)+2
 XL=XL
 XL=BM(P)-AAA-BBB
 AA-A
 BB-B
 A-AAA
 B-BBB
 AAA-AAA-AA
 BBB-BBB-BB
 C
 DO 439 I=1,4
 CA(4,I)=TCAL(1,I)*CA(12,I)/XLL
 CA(5,I)=CCAL(4,I)
 CA(11,I)=CA(11,I)
 CA(12,I)=CA(12,I)
 CA(13,I)=CA(13,I)
 CA(14,I)=CA(14,I)
 439 CA(15,I)=CA(15,I)+CA(17,I)/Z.0
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 1000


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C      DN 300 K*Y,NH
      KR=2*IK-1J
      I*H=N*1
C      IF (L*GT*MLD) GO TO 340
C      DD 310 M=1,2
      DD*ML=0.
      DD LZO J=1,6
      TEMP=REK*P*J
      IF (IADD*GT*0) TEMP=ABS(TEMP)
      DDIM(J)=DD*(M,1)+TEMP*(J,1)
120 CONTINUE
110 CONTINUE
C      DYNAMIC COMPONENTS
C      IF (MATT=MAT-3)
150 MATT=MAT-1
      GO TO 300
      IF (MATT=1) GO TO 300
C      DD 170 M=1,2
      SRSSTP=0.
      SABSIP=0.
170 TMSTI=0.
C      DD 200 M=1,2
      DD 210 J=7,MLD
      TEMP=ABS(REK*P*J)
      DDIM(J)=DD*(M,1)+TEMP*(J,1)
      SRSSTP=TEMP
      SABSIP=SABSIP+TEMP
      STOR(LJ-01)=REK*P*J
      GO TO 210
190 IF (TEPP*GT*TMSTI) TMSTI=TEMP
210 CONTINUE
      IF (MAT, EQ, 3) TMSTI=COE(STOR*RO*F0)
200 CONTINUE
C      DD 220 M=1,2
      MESSIP=SORI(SRSSTP*J)
      DDIM(J)=DD*(M,1)+MESSIP*(J,1)
      SABSIP=SABSIP+MESSIP
      GO TO 100
C      MODAL BREAKDOWN
C      DD 340 M=1,2
      DD 310 DD*P*J)=P*IR*P*J,L)
C      TAB580 3494      300 CONTINUE
C      CALL NUPAJ (1,3,EFEST)
      IF (LTEST*EQ*0) GO TO 350
      LINE=LINE+6
      WRITE (RDUJ,2004) S01,P*ED
      WRITE (RDUJ,2005) TCOLUMN*J,J=M,NH)
      WRITE (RDUJ,2005)
      DD 350 DD 250 M=1,2
      DD 250 WRITE (RDUJ,2001) 11,12,IMDIR,100IM,11,1=1,1M)
      DD 250 WRITE (RDUJ,2005)
      LINE=LINE+1
C      400 CONTINUE
      DD 500 CONTINUE
      DD 500 RETURN
C      1000 FORMAT (E6)
      DD 2000 FORMAT (/Z1H *X,NHLOAD,4X,0X,3X,9HDIRECTION,813X,46,131)
      DD 2001 FORMAT (11H *P*6X,0X,44*F12,5J)
      DD 2004 FORMAT (17/43H JOINT DISPLACEMENTS AND ROTATIONS AT LEVEL,1M *A5,
      DD 2005 FORMAT (11H *
      END
C      SURROUTINE TAB(ISA+5B,5C+XL+A*0)
C      FORCE-DISPLACEMENT TRANSFORMATION MATRICES FOR BEAMS AND COLUMNS
      CMMDDN /JUNK/ PHEDAT,1F,1FC,ND,NF,LM(6),CALIO*61,F(10,9),T(2,4)
      T(2,1)=B/XL
      T(1,1)=1.0/T(2,1)
      T(1,2)=1.0/XL
      T(2,2)=T(1,2)
      T(1,3)=A/XL
      T(2,3)=1.0/T(1,3)
      T(1,4)=1.0/XL
      T(2,4)=T(1,4)
      DD 100 I=1,4
      CALL (I)-SAPT(I,1)+SBOT(I,2))
      100 CALL (I)-SBOT(I,1)+SAPT(I,2,1)
      CALL (I)-5C
      CALL (I)-5C
C      TAB580 3495
C      TAB580 3496
C      TAB580 3497
C      TAB580 3498
C      TAB580 3499
C      TAB580 4000
C      TAB580 4001
C      TAB580 4002
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C      TAB580 4199
C      TAB580 4200

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M=EEE15,JJ
IF IL.FO.MAL) M=M*OP(7,M)OP(8,M)
VL=-F(4,L)
TEMP=SIGN(1,-VL)
XAB=0.
PJS=0.
MPASS=0
MCON=IFFE1J)
IF INCON.EQ.0) GO TO 60
CALCULATING POINT OF ZERO SHEAR
DO 70 MCON=1,MCON
UNIFORM LOAD BEFORE MCON=TH CONCENTRATED LOAD
AA=CONLI+MCON,JJ--B
DEL=AA-RRRZ
MCON=RRRZ
IF ITEMP.ME=SIGN(1,-VL)) GO TO 80
MCON=TH CONCENTRATED LOAD
VL=VL-CONLI+MCON,JJ
MPASS=MCON
IF ITEMP.ME=SIGN(1,-VL)) GO TO 80
UNIFORM LOAD AFTER LAST CONCENTRATED LOAD
IF (MCON.ME=MCON) GO TO 70
VL=VL-RRRZ+RRRZ
MCON=VL
IF ITEMP.ME=SIGN(1,-VL)) GO TO 60
70 CONTINUE
GO TO 500
POINT OF ZERO SHEAR OCCURRED DUE TO -- UNIFORM LOAD
90 IF (ABS(ME)-L-E-10) GO TO 500
PJS=RRRZ+VL/M
IF (PJS.GE.4) PJS=0.
C) TO 100
POINT OF ZERO SHEAR OCCURRED DUE TO -- CONCENTRATED LOAD
90 PJS=RRRZ

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TAB580 4178 C 100 IF (PJS.FO.-.0) GO TO 500
TAB580 4179 C CALCULATING MAXIMUM POSITIVE OR MINIMUM NEGATIVE MOMENT
TAB580 4180 C
TAB580 4181 C F(3,L)=F(1,L)+F(2,L)OPZ5-M*PJS*PJS/2.
TAB580 4182 IF (MPASS.EQ.0) GO TO 500
TAB580 4183 DO 110 MCON=1,MPASS
TAB580 4184 110 F(3,L)=F(3,L)+F(25,B-CONLI+MCON,JJ)*CONLI+MCON,JJ
TAB580 4185 C 900 CONTINUE
TAB580 4186 C
TAB580 4187 C RETURN
TAB580 4188 C END
TAB580 4189
TAB580 4190
TAB580 4191
TAB580 4192
TAB580 4193
TAB580 4194
TAB580 4195
TAB580 4196
TAB580 4197
TAB580 4198 C PRINTING FORCES AND STRESSES
TAB580 4199 C
TAB580 4200 DIMENSION STOR(ME),RDI(ME),MDO(I,M),MDO(M,I),MDO(I,I),MDO(I,I))
TAB580 4201 DIMENSION RIN(M),MDO(I,M),MDO(I,I),MDO(I,I),MDO(I,I))
TAB580 4202 DIMENSION IFRT(6)
TAB580 4203 COMMON /GEN1 / MST,MDF,MIF,RLO,MAT
TAB580 4204 COMMON /MED1 / MED(2),IDATE(2),MPAGE(2),MFLIM,LIME
TAB580 4205 COMMON /TAPE / KTMP,KIMP,KDUT,KSTR,MRTAPE,KTAPE
TAB580 4206 COMMON /JTN / MITEP,OT,MPCC,COMP,MND
TAB580 4207 COMMON /JUNE / MREOT,IFRT,COM2,LM(6),CATIO(6),F(10,9),O(14,4),
TAB580 4208 / MREOT,IFRT,COM2,LM(6),CATIO(6),F(10,9),O(14,4),
TAB580 4209 / MREOT,IFRT,COM2,LM(6),CATIO(6),F(10,9),O(14,4),
TAB580 4210 / MREOT,IFRT,COM2,LM(6),CATIO(6),F(10,9),O(14,4),
TAB580 4211 C DATA LEFT /MHE16,MMX ,MM,246,MM,42,MM,410F1,4MM,31/
TAB580 4212 C IF IITAG.EQ.7) GO TO 540
TAB580 4213 C
TAB580 4214 C LLD=MDO*MDO
TAB580 4215 C
TAB580 4216 C MFORC=7*MF
TAB580 4217 DO 100 J=1,MFPC
TAB580 4218 DO 100 J=1,N
TAB580 4219 100 F(1,J)=0.0
TAB580 4220 C
TAB580 4221 C CALCULATE STATIC FORCES
TAB580 4222 C
TAB580 4223 C
TAB580 4224 C 150 DO 200 K=1,MU
TAB580 4225 K=LPERI
TAB580 4226 DO 200 I=1,MF
TAB580 4227 DO 200 J=1,6

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TAB580 4228
TAB580 4229
TAB580 4230
TAB580 4231
TAB580 4232
TAB580 4233
TAB580 4234
TAB580 4235
TAB580 4236
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TAB580 4260
TAB580 4261
TAB580 4262
TAB580 4263
TAB580 4264
TAB580 4265
TAB580 4266
TAB580 4267
TAB580 4268
TAB580 4269
TAB580 4270
TAB580 4271
TAB580 4272
TAB580 4273

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DATA TABSD0 /ANTABSD0/
DATA FRAME /AM FRAME/
DATA TYPE /AM TYPE /

CALL BOX

XX=0.
YY=-0.5/
CALL CALCOM (EX,YY,SZ,TABSD0,R,0.,0.6,3)
CALL CALCOM (EX,YY,SZ,FRAME,B,0.,0.6,3)
CALL CALCOM (EX,YY,SZ,TYPE,R,0.,0.6,3)
XX=XX+0.057
YY=YY+0.057
R=FLOAT(1)
CALL CALCOM (EX,YY,SZ,B,R,0.,0.,-1.,4)
XX=XX+0.057

DO 10 J=1,14
CALL CALCOM (EX,YY,SZ,FMDE(J),B,0.,0.5,3)
10 XX=XX+0.057

RETURN
END

SUBROUTINE FGRID (INSC,SD,R,Y,0,NST,NC,MS,IF)
PLOTTING RECTANGULAR GRID OF FRAME
DIMENSION SDINST(2),RINC(J),YMS(1)
DIMENSION DINST(3)
COMMON /PLOTS/ X0,Y0,RDM,XDM,RDIM,TDIP,SZ,B1,B7,Q,RAD
DATA SZ,05/
DATA S / /
DATA C /IMC/
DATA B /IMB/
COLUMN LINES
DO 10 M=1,MC
X1=XEMJ-5
Y1=-B2-2.05
CALL CALCOM (X1,Y1,S,C,R,0.,1.,1)

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TABS00 4554
TABS00 4555
TABS00 4556
TABS00 4557
TABS00 4558
TABS00 4559
TABS00 4560
TABS00 4561
TABS00 4562
TABS00 4563
TABS00 4564
TABS00 4565
TABS00 4566
TABS00 4567
TABS00 4568
TABS00 4569
TABS00 4570
TABS00 4571
TABS00 4572
TABS00 4573
TABS00 4574
TABS00 4575
TABS00 4576
TABS00 4577
TABS00 4578

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TABS00 4581
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TABS00 4589
TABS00 4590
TABS00 4591
TABS00 4592
TABS00 4593
TABS00 4594
TABS00 4595
TABS00 4596
TABS00 4597
TABS00 4598
TABS00 4599

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X1=Y1=5
R=FLOAT(PI)
CALL CALCOM (X1,Y1,S,C,R,0.,-1.,4)

X1=XEMJ
Y1=-B2
Y2=Y1+D(3)*B2
10 CALL LYME (X1,Y1,R2,Y2,1)

STORY LINES
DO 20 M=1,MS
X1=-B2-D(1)
X1=XEMJ+0.5
M=FLOAT(MS)-1
CALL CALCOM (X1,Y1,S,C,R,0.,-1.,4)

X1=-B2-D(1)
X2=XEMJ+D(2)+B1
Y1=YEMJ
Y2=Y1
CALL LYME (X1,Y1,R2,Y2,1)

X1=XEMJ-D(2)+25
Y1=YEMJ+0.5
M=FLOAT(MS)-5
10 CALL CALCOM (X1,Y1,S,C,R,0.,0.,5,3)

BASE LINE
X1=-B2-D(1)
Y1=0.5
R=0.
CALL CALCOM (X1,Y1,S,C,R,0.,-1.,4)

X1=-B2-D(1)
X2=XEMJ+D(2)+B1
Y1=0.
CALL LYME (X1,Y1,R2,Y2,1)

IF (NB.EQ.0) GO TO 999

NR=NC-1
Y1=-B2/2
Y2=Y1+0.5
CALL LYME (X1,Y1,RINC(J),Y1,1)

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TABS00 4600
TABS00 4601
TABS00 4602
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TABS00 4606
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TABS00 4639
TABS00 4640
TABS00 4641
TABS00 4642
TABS00 4643
TABS00 4644
TABS00 4645
TABS00 4646
TABS00 4647
TABS00 4648
TABS00 4649

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CALL CALCOM (X1,Y1,S,J,R,0,0,-1,3)
CALL CALCOM (X1,S1,Y1,S2,S,P,0,0,-1,3)
CALL CALCOM (X1,S2,Y1,S2,S,B,0,0,-1,4)
IF (IPLT.NE.2) GO TO 777
R=FLOAT(P)
R=FLOAT(P)
R=FLOAT(P)
IF (IPLT.NE.2) GO TO 777
R=FLOAT(P)
R=FLOAT(P)
R=FLOAT(P)
CALL CALCOM (X1,Y1,S1,T,0,0,-1,3)
CALL CALCOM (X1,Y1,S1,T,0,0,-1,4)
777 CALL LVM (X1,S2,Y1,R2-S,T,2)
J=6
CALL CALCOM (X2-S2,Y1,S1,J,R,-90,0,-1,3)
999 RETURN
C
END

SUBROUTINE FOIAC (X1,X2,Y1,Y2,W,JD,IPLT)
C
C PLOTTING DIAGONALS
C
COMMON /PLOTS/ X0,Y0,XDPR,XDPM,XDIM,YDIM,SZ,AB1,R2,0,RAD
DIMENSION H(4),Y(4)
DATA S /,10/
DATA D /1MD/
DATA T /1MT/
DATA TOL /1.E-10/
M=JD(4)
M=N/2.
D=X2-X1
D=Y2-Y1
Y=30P(COZYOK,0Y+DY)
Y=30P(COZYOK,0Y+DY)
Y=30P(COZYOK,0Y+DY)
COSI=DI/DL
SINI=DY/DL
XN=X1+DX/A.

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TABS00 4834
TABS00 4835
TABS00 4836
TABS00 4837
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TABS00 4840
TABS00 4841
TABS00 4842
TABS00 4843
TABS00 4844
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TABS00 4846
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TABS00 4924
TABS00 4925

YV=Y1+DY/A.
DX=ASINT
DY=WCOST
X(1)=X1+DX
X(2)=X2+DX
X(3)=X1-DX
X(4)=X2-DX
Y(1)=Y1-DY
Y(2)=Y2-DY
Y(3)=Y1+DY
Y(4)=Y2+DY
DX=XX
DY=YY
CALL LYM (X(1),Y(1),X(4),Y(4),1)
IF (M.LE.TOL) GO TO 100
CALL LYM (X(4),Y(4),X(1),Y(1),1)
CALL LYM (X(2),Y(2),X(3),Y(3),1)
CALL LYM (X(3),Y(3),X(2),Y(2),1)
C LABELING DIAGONAL
C
C 100 SIMT=SIMT(META)
COST=COST(META)
XN=XN-(M-.05)ASINT
YV=YV-(M-.05)WCOST
XN=XN+5*WCOST
YV=YV+5*ASINT
R=FLD(ATT)
CALL CALCOM (XN,YV,S,B,R,TT,-1,4)
IF (IPLT.NE.2) GO TO 999
XN=XN+(M-1.5)ASINT
YV=YV-(M-1.5)WCOST
CALL CALCOM (XN,YV,S1,T,0,TT,-1,3)
XN=XN+5*WCOST
YV=YV+5*ASINT
R=FLD(ATT)
CALL CALCOM (XN,YV,S,B,R,TT,-1,4)
999 RETURN
C
END

```



```

C C PLOTTING PLAN
C COMMON /GEN1 / NST,NDF,NIF
COMMON /PLOTS/ X0,Y0,EDNR,EDMN,EDIM,YDIM,SZ,GB1,GB2,Q,RAD
C
C DATA MN /ZINH/
DATA T1 /ZINH/
DATA T2 /ZINH/
DATA TOL /I.F.-6/
C
C REMIND 1
C
C DO 10 I=1,NDF
READ (1) IF,IFC,RI,VI,XZ,YZ
C
C RI=RI/Q-RMIN
VI=VI/Q-RMIN
XZ=XZ/Q-RMIN
YZ=YZ/Q-RMIN
I=I+1
Y=VI*Y2/ZZ
Y=VI*Y2/ZZ
C
C J=1
CALL CALCOM (X1,Y1,X2,Y2,I)
CALL LYM (X1,Y1,X2,Y2,I)
C
C DR=RZ-R1
DY=YZ-Y1
DL=SQRT(DR**2+DY**2)
CC=DR/DL
SS=DL/DL
IF (CC>1) RBD
IF (SS<1) COT I=100,-T
C
C J=N
CALL CALCOM (X1,Y1,X2,Y2,I)
IF (SS<1) COT I=100,-T
C
C IF (ABS(DI).GT.TOL) GO TO 30
F=90.-PRAD
GO TO 20
30 T=ATAN(DY/DR)
ZL=CC-COS(T)
SS=SIN(T)
T=I/PRD
C
C R=DL*ABS(T)
R=R+SSCC-SSSSS
V=V+SSSS-SSSSCC
CALL CALCOM (X1,Y1,X2,Y2,I)
R=R+SSSSCC
C
C TAB580 5014
C TAB580 5015
C TAB580 5016
C TAB580 5017
C TAB580 5018
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C
C Y=VY+SSSS
CALL CALCOM (X1,Y1,X2,Y2,I)
R=FLD*II
R=R+SSCC-SSSSS
V=V+SSSS-SSSSCC
CALL CALCOM (X1,Y1,X2,Y2,I)
R=R+SSCC
V=V+SSSS
CALL CALCOM (X1,Y1,X2,Y2,I)
TO CONTINUE
RETURN
END
C
C SURROUTINE CSCALE (CR,CY,XMIN,XMAX,YMIN,YMAX)
C CALCULATING SCALE
C COMMON /PLOTS/ X0,Y0,EDNR,EDMN,EDIM,YDIM,SZ,GB1,GB2,Q
C DATA TOL /I.F.-15/
C XDIM=XDMN
C YDIM=YDMN
C X=XDIM-CX
C Y=YDIM-CY
C X=XABS(XMIN-XMAX)/X
C Y=YABS(YMIN-YMAX)/Y
C Q=SY
C IF (SY<GT.SX) GO TO 50
C XDIM=XDMN
C YDIM=YDMN
C IF (SY<LT.TOL) GO TO 80
C XDIM=XDMN/SY+CX
C IF (XDIM<GT.XDMN) XDIM=XDMN
C RO=XR*DIJ-CX
C Q=ARSI(XMIN-XMAX)/X
C
C SO XMIN=XMIN/D
C YMIN=YMIN/D
C XMAX=XMAX/D
C YMAX=YMAX/D
C
C TAB580 5074
C TAB580 5075
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 TAB500 5174

TAB500 5110 C 10 I=-1
 TAB500 5111 JJ=I+2
 XL=XL+DL(I,J)
 IF (XL-CT,AL) GO TO 30
 GO TO 40
 30 DL(I,J)=DL(I,J)+XL*AL
 XL=AL*0.005
 DL(I,J)=DL(I,J)+DL(I,J)*DL(I,J)
 40 X5=RF
 X5=X5+DL(I,J)
 YF=YF+DY(I,J)
 IF (I1-LT,0) GO TO 50
 CALL CALCOM (X5,Y5,B1,B2,B3+2)
 CALL CALCOM (YF,YF,B1,B2,B3+2)
 50 IF (I1-AL) 10,20,20
 20 RETURN
 END

TAB500 5112
 TAB500 5113
 TAB500 5114
 TAB500 5115
 TAB500 5116
 TAB500 5117
 TAB500 5118
 TAB500 5119
 TAB500 5120
 TAB500 5121
 TAB500 5122
 TAB500 5123
 TAB500 5124
 TAB500 5125 C

RETURN
 END
 SUBROUTINE LYNE (X1,Y1,X2,Y2,ITAG)
 C PLOTTING LINE BETWEEN POINTS 1 AND 2
 C IF (ITAG.EQ.2) GO TO 20
 10 CALL CALCOM (X1,Y1,B1,B2,B3+2)
 CALL CALCOM (X2,Y2,B1,B2,B3+2)
 GO TO 999
 20 CALL DASH (X1,Y1,X2,Y2)
 999 RETURN
 END

TAB500 5175
 TAB500 5176
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 TAB500 5138 C
 TAB500 5139 C
 TAB500 5140 C
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 TAB500 5146
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 TAB500 5148
 TAB500 5149
 TAB500 5150 C
 TAB500 5151

SUBROUTINE DASH (X1,Y1,X2,Y2)
 C PLOTTING A DASHED LINE BETWEEN POINT 1 AND POINT 2
 DIMENSION DX(3),DY(3),DL(3)
 DATA DELTD /0.1/
 AT=J-Y1
 AT=J-Y2
 LE=DMT (AT*999+AT*999)
 TP=(AL-0.005) 20+2G,60
 60 COST=AT/AL
 SINT=AT/YAL
 DL(1)=DELTD+COST
 DY(1)=DELTD*SINT
 DL(2)=DELTD
 DY(2)=0.5*DX(1)
 DL(3)=0.5*DY(1)
 DY(3)=0.5*DL(1)
 1=-1
 YF=Y1
 YP=Y1
 XL=0.0

SUBROUTINE BOX
 COMMON /IHEDR/ (MEG(20)
 COMMON /PLOTS/ X0,Y0,X0K,XDRN,XDIM,YDIM,YSZ,B1,B2,0
 X0=0
 Y0=0
 PLOTTING BORDER LINE
 CX=2.*B2+2.*B1+-.05)
 XL=XDIM-CX
 Y1=0
 Y2=YDIM
 CALL LYNE (X1,Y1,X2,Y2+1)
 X1=XDIM
 Y1=YDIM
 CALL LYNE (X2,Y2,X1,Y1+1)
 X2=XDIM

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Wilson, Edward L.

Theoretical basis for CTABS80, a computer program for three-dimensional analysis of building systems / by Edward L. Wilson, H.H. Dovey, Ashraf Habibullah (Computer/Structures International, Oakland, Calif.). -- Vicksburg, Miss. : U.S. Army Engineer Waterways Experiment Station ; Springfield, Va. : available from NTIS, 1981. 72, 56 p. : ill. ; 27 cm. -- (Technical report / U.S. Army Engineer Waterways Experiment Station ; K-81-2)

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PUBLISHED UNDER THE COMPUTER-AIDED
STRUCTURAL ENGINEERING (CASE) PROJECT**

	Title	Date
Technical Report K-78-1	List of Computer Programs for Computer-Aided Structural Engineering	Feb. 1978
Instruction Report O-79-2	User's Guide: Computer Program with Interactive Graphics for Analysis of Plane Frame Structures (CFRAME)	Mar. 1979
Technical Report K-80-1	Survey of Bridge-Oriented Design Software	Jan. 1980
Technical Report K-80-2	Evaluation of Computer Programs for the Design Analysis of Highway and Railway Bridges	Jan. 1980
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Instruction Report K-80-4	A Three-Dimensional Stability Analysis Design Program (KDSAD) Report 1: General Geometry Module	Jan. 1980
Instruction Report K-80-6	Basic User's Guide: Computer Program for Design and Analysis of Inverted-T Retaining Walls and Floodwalls (TWDA)	Dec. 1980
Instruction Report K-80-7	User's Reference Manual: Computer Program for Design and Analysis of Inverted-T Retaining Walls and Floodwalls (TWDA)	Dec. 1980
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Instruction Report K-81-3	Validation Report: Computer Program for Design and Analysis of Inverted-T Retaining Walls and Floodwalls (TWDA)	Feb. 1981
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Technical Report K-81-2	Theoretical Basis for CTABS80: A Computer Program for Three-Dimensional Analysis of Building Systems	Aug. 1981