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The findings in this report are not to be construed as an official Department of the Army position, unless so designated by other authorized documents.

The use of trade names or manufacturers' names in this report does not constitute endorsement of any commercial product.
A model is analyzed to study the electromagnetic acceleration of particles using a rail gun. Current is conducted between the rails by a plasma arc which accelerates down the rails driving the projectile. The analysis includes determining the electromagnetic fields within the gun and solving the fluid-mechanical equations of the plasma under the assumption that the flow parameters are steady in a frame that accelerates with the arc. Specifically, a set of coupled equations is derived which, when solved, yields the properties of the arc and the
acceleration of the projectile. A limiting-case analytic solution to the equations is found, and an iterative technique is employed to solve the equations numerically in the more general case. The results of the calculation are applied to analyze the arc in an experiment recently carried out by Rashleigh and Marshall. In addition, the properties of the arc appropriate for a larger rail gun, such as proposed in a forthcoming experiment by Westinghouse, are investigated and some approximate scaling relations derived. The results of the calculations are compared with those of others and some suggestions for future investigations are given.
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I. INTRODUCTION

Intermittently since World War I, efforts have been directed toward the research and development of a device capable of the electromagnetic acceleration of macroparticles. Such a device has the potential for a number of military applications, probably the most important of which is the so-called electric gun. The major advantage of this sort of gun over the more conventional ones is that, at least in principle, much higher muzzle velocities can be obtained. In addition, the guns should be relatively smokeless and noiseless and their projectiles should experience fairly constant acceleration.

Although the efforts mentioned above have met with varying degrees of success, it has been only since the recent experiments at the Australian National University (ANU) that military interest in the problem has been rekindled. These experiments demonstrated conclusively that the 500 MJ homopolar generator, previously developed at ANU, could provide sufficient power to accelerate a mass of about 3g to a velocity of about 6 km/s in a distance of about 3m. The renewed military interest is made evident by the current DARPA/ARRADCOM supported project underway at Westinghouse which has as its goal the acceleration of a 300g mass to a velocity of 3 km/s in a distance of about 4m. If such an objective can be met, the development of an electric gun may become a feasible military goal.

A number of devices exist for producing the electromagnetic acceleration of projectiles, the most notable being the rail gun and the mass driver. The experiments at ANU and those now underway at Westinghouse were performed using a rail gun and it is with this device that our analysis deals. A schematic of the rail gun is shown in Figure 1. Sides one and two represent the rails which carry current from the source, side three, to and from side four. The projectile is represented by the shaded part of the figure and may, if desired, be a

Figure 1. Model for rail gun.
conductor which completes the circuit. There are some advantages, however, to having the projectile an insulator and allowing the current to be conducted by a plasma arc, shown by the region between \(x = x_0\) and \(x = \ell\). The primary advantages are that better contact with the rails can be maintained by an arc than by a solid armature and that the stress imparted to the projectile is likely to be more uniform. In practice the arc can be created by, for example, an exploding wire. The earliest use of the arc-driven rail gun was apparently in experiments by Brast and Sawle who succeeded in accelerating projectiles of a few mg to velocities of a few km/s. At any rate the current distribution produces a magnetic field in the space bounded by the four sides which interacts with the current through the armature, accelerating it in the \(x\) direction.

Some theoretical analysis of the solid-armature rail gun has been carried out and, more recently, McNab has undertaken the more difficult task of obtaining some estimates of the properties of the arc in the arc-driven gun. Although these calculations provide considerable insight into the problem as well as good qualitative results, they are based upon a number of assumptions which are unlikely to be strictly valid for the problem at hand. It is assumed in McNab's analysis, for example, that the pressure, density, and temperature within the arc are uniform although it is unlikely that all three flow variables will be constant in an arc that does not move at constant velocity. In addition, it is assumed that atoms which constitute the arc are, at most, singly ionized. However, the results of the calculation indicated that the temperature of the arc was about 57,000\(^\circ\)K, and one can show that at this high temperature most of the atoms should be ionized to a higher degree.

The inadequacy of these assumptions in no way detracts from McNab's work since, as pointed out, the results do appear to be qualitatively reliable and the calculations are rather straightforward to carry out. In the present analysis, however, we wish to extend the work. In particular, we will solve the fluid-dynamical equations in the accelerating arc and, thereby, account for the position dependence of the flow variables where necessary. In addition, it will be assumed that the plasma may consist of doubly ionized as well as singly ionized atoms. The results will be applied to the Rashleigh-Marshall (RM) experiment and compared briefly to the results obtained by McNab. The question of how the arc should be scaled for a rail gun of the size proposed in the Westinghouse experiment will then be examined, and the properties of the arc under those conditions will be investigated.

8. Authors' unpublished calculations.
The report is organized as follows. In Sec. II, the model and assumptions are discussed briefly. In Sec. III, the formal analysis of the problem is presented, including the derivation of a set of coupled equations which must be solved to determine the properties of the arc and the motion of the projectile. In Sec. IV, a limiting-case analytic solution to the equations is found and their numerical solution for the more general case is discussed. The results are then applied to both the RM experiment and to the proposed Westinghouse experiment. Finally, in Sec. V, some additional discussion of the results, the assumptions, and possible future investigations is given.

II. MODEL AND ASSUMPTIONS

The model whose properties we wish to consider consists of an arc-driven rail gun such as shown in Figure 1. The rails are assumed to be perfectly conducting, infinitely thin sheets which are infinitely extended in the z direction, as is the arc. The gun itself is therefore two dimensional, although the fluid-mechanical properties of the arc are assumed to vary only in the direction of propagation. Certainly the major variation does occur in that direction because of the purely mechanical effect of accelerating the arc. However, in a real system some variations occur in directions normal to the propagation direction, and these are not accounted for in the model. The finite conductivity \( \sigma \) of the arc is accounted for, and the assumption that the rails are perfect conductors is justified on the basis that, in reality, the conductivity of the rails is several orders of magnitude higher than that of the arc. The potential difference \( V \) which is applied along side three of the model is assumed to vary with time so as to produce a constant current per unit height \( j \) on the surface of the rails. In practice, such a condition can be approximated by using as a source an inductive store of sufficiently high inductance.

We will be interested in solving the equations which govern the properties of the arc and the acceleration of the projectile in the steady-state approximation. By steady state we mean that the acceleration of the projectile and all parts of the arc is the same at any given time, and that the fluid-mechanical properties of the arc are independent of time in a frame which accelerates with the arc. It is, of course, also assumed that the mass of the arc is constant in time so that any vaporization of the rails is neglected during the time of acceleration. A number of specific criteria which must be satisfied to justify the assumption of steady state are discussed in the ensuing pages. In particular, this assumption, as well as the others, is discussed in some detail in Sec. V.
III. ANALYSIS

A. Electrodynamics.

The first problem which must be solved is to determine the electromagnetic fields associated with the arc gun in Figure 1. From the symmetry of the problem and from the results of similar calculations, we assume solutions to Maxwell's equations of the form

$$\begin{align*}
\mathbf{E} &= E(x) \hat{a}_y \\
\mathbf{B} &= B(x) \hat{a}_z
\end{align*}$$

(3.1)

where $\mathbf{E}$ and $\mathbf{B}$ are the electric and magnetic induction fields, respectively. The appropriate Maxwell equations then become*

$$\begin{align*}
\frac{\partial E}{\partial x} &= -\frac{\partial B}{\partial t} \\
\frac{\partial B}{\partial x} &= -\mu J
\end{align*}$$

(3.2a, 3.2b)

where $\mu$ is the magnetic permeability and $J$ the current density to be determined within the arc. In writing Eq. (3.2b) we have neglected the displacement current which is negligible for nonrelativistic velocities of the arc and projectile.

Equation (3.2b) implies that $\mathbf{B}$ is constant except within the arc, and since it must vanish at infinity, it vanishes everywhere to the right of $x = L$, to the left of $x = 0$, and above and below the perfectly conducting rails. Within the arc Eq. (3.2b) implies

$$B = -\mu \int_{x_0}^{x} J \, dx + c$$

(3.3)

where $c$ is an integration constant which can be determined from the continuity of $B$ and from the boundary condition

$$B(L) = -\mu \int_{x_0}^{L} J(x) \, dx + c = 0.$$  

(3.4)

We have, therefore,


* Unless otherwise noted, MKS units are used throughout this report.
\( B = \mu \int_{x}^{l} J \, dx, \quad (3.5) \)

for \( x_0 < x < l \).

In the space between \( x=0 \) and \( x=x_0 \), \( B \) is again constant and to satisfy the boundary condition at \( x=x_0 \) we must have

\( B = \mu \int_{x_0}^{l} J \, dx. \quad (3.6) \)

However, the integral on the right of Eq. (3.6) must just be equal to \( j \), the current per unit height on the rails, if current is to be conserved in the steady state. Consequently, we have

\( B = \mu j, \quad (3.7) \)

for \( 0 < x \leq x_0 \).

The electric field \( \vec{E} \) can be determined most simply by making the change of variable

\( x' = x - x_0(t) \quad (3.8) \)

in Eq. (3.2a). For steady-state conditions we find

\[ \frac{\partial E}{\partial x'} = v \frac{\partial B}{\partial x'} \quad (3.9) \]

where

\[ v = \frac{dx_0}{dt} \quad (3.10) \]

is the common velocity of the arc and projectile. Integrating Eq. (3.9), we find

\[ E = vB + F(t) \quad (3.11) \]

where \( F(t) \) is an arbitrary function to be determined.

The function \( F(t) \) can be evaluated by noting that the current density in the arc must obey the constitutive relation

\[ J = \sigma(E - vB). \quad (3.12) \]
Thus, $F(t)$ is given simply by

$$F(t) = J/\sigma.$$  \hspace{1cm} (3.13)

Furthermore, for the assumed steady conditions, the quantity $J/\sigma$ is independent of time so

$$E = E_o + vB,$$  \hspace{1cm} (3.14)

where the constant

$$E_o = J/\sigma$$  \hspace{1cm} (3.15)

represents the electric field required to drive the current through the arc. If we make use of the current-conservation relation mentioned earlier, namely,

$$\int_{x_0}^{x} J(x)dx = j,$$  \hspace{1cm} (3.16)

$E_o$ can be written in terms of known quantities as

$$E_o = \frac{j}{\int_{x_0}^{x} \sigma(x)dx}.$$  \hspace{1cm} (3.17)

In the remaining discussion we will need the values of $\hat{E}$ and $\hat{B}$ only to the right of $x=x_o$ and between the perfectly conducting rails. Writing these in terms of the dimensionless distance $\xi$ defined by

$$\xi = (x - x_o)/\ell_a,$$  \hspace{1cm} (3.18)

we have

$$\hat{B} = \mu \ell_a E_o \int_{\xi}^{1} \sigma(\xi) d\xi \hat{a}_z \hspace{1cm} 0 \leq \xi \leq 1$$  \hspace{1cm} (3.19)

$$\hat{B} = 0. \hspace{1cm} \xi > 1.$$  \hspace{1cm} (3.19)

In these equations $\ell_a$ is the length of the arc measured along the $x$ axis, viz.,

$$\ell_a = \ell - x_o.$$  \hspace{1cm} (3.20)
Similarly,
\[ \dot{E} = [E_0 + vB(\xi)]\hat{a}_y \]  
(3.21)

for \( \xi > 0 \) where \( E_0 \) is given by Eq. (3.17).

The solutions obtained in this section can be seen to satisfy all
boundary conditions appropriate to the problem and the assumption made
in Eq. (3.1) is therefore justified. A more arduous derivation\(^\text{10}\), employing
the vector potential and avoiding the assumption, produces the same
result.

B. Fluid Mechanics.

Having obtained the values of the electric and magnetic fields, we
now wish to derive a set of equations appropriate for determining the
fluid-mechanical properties of the arc. The equations which express
conservation of mass, momentum, and energy for the arc as a whole can
be written\(^\text{11}\)

\[
\frac{\partial p}{\partial t} + \frac{\partial}{\partial x} (\rho v) = 0
\]

\[
\rho \frac{\partial v}{\partial t} + \rho v \frac{\partial v}{\partial x} + \frac{\partial p}{\partial x} = f
\]  
(3.22)

\[
\rho \frac{\partial e}{\partial t} + \rho v \frac{\partial e}{\partial x} + \frac{\partial q}{\partial x} + p \frac{\partial v}{\partial x} = J^2/\sigma
\]

where \( \rho \) is the mass density in the arc, \( v \) the mean flow velocity, \( e \)
the specific internal energy, \( q \) the heat flux, \( f \) the force per unit
volume acting on the plasma, and \( p_{xx} \) the appropriate element of the
pressure tensor for one-dimensional considerations. Equations (3.22)
are identical to those generally encountered in fluid mechanics except
for the force \( f \) which is electromagnetic in origin and except for the
term \( J^2/\sigma \) which represents the Joule heating of the plasma. In compli-
ance with the assumptions previously discussed, the flow variables have
been assumed to vary only in the direction of propagation of the arc.

It is clear that the three equations in Eqs. (3.22) cannot uniquely
specify the variables \( p, \rho, v, \) and \( e \) and one needs, in addition, an
equation of state. We assume, therefore, that the plasma obeys an
ideal-gas law, namely,

\(^{10}\) Authors' unpublished calculations.
\(^{11}\) A.B. Cambel, Plasma Physics and Magnetofluidmechanics (McGraw-Hill,
New York, 1963), Chap. 8.
\[ P = (1 + \alpha) \rho \frac{k_B T}{m_0} \]  

where \( k_B \) is Boltzmann's constant, \( T \) the temperature, \( m_0 \) the atomic mass of the ion or neutral, and \( \alpha \) the ratio of electrons to heavy particles in the plasma. The method for determining \( \alpha \) will be discussed in the following section. All flow variables are assumed to vary only slowly with position so that the gas is in a state of local thermal equilibrium.

Further analysis of Eqs. (3.22) is most easily accomplished in a frame moving with the velocity \( v \) of the plasma arc. We therefore make the change of variable defined in Eq. (3.18). Noting that in the moving frame \( v \) is independent of \( \xi \) and that \( \rho, e, \) and \( P \) are independent of time, we find that the first of Eqs. (3.22) is satisfied identically, while the remaining two become

\[ \rho a + \frac{1}{\ell_a} \frac{\partial P}{\partial \xi} = f \]  

(3.24)

and

\[ \frac{\partial a}{\partial \xi} = \ell_a \frac{J^2}{\sigma}. \]  

(3.25)

In Eq. (3.24) \( a \) represents the common acceleration of the arc and projectile and \( P_{xx} \) has been replaced by the pressure, \( P \), since no velocity gradients are assumed to exist.

The force per unit volume \( f \) acting on the plasma arises from the interaction of the magnetic induction field within the arc and the current through it. The force acts in the positive \( x \) direction and its magnitude is given by

\[ f = JB. \]  

(3.26)

Consequently, Eq. (3.24) can be written in the form

\[ P(\xi) = \frac{1}{\ell_a} \int_0^{\xi} \left( J(\xi) B(\xi) - \rho(\xi) a \right) d\xi + c \]  

(3.27)

where \( c \) is an integration constant which can be determined from the condition that the pressure at the back of the projectile must be sufficient to provide it with an acceleration \( a \). Specifically, if we let

\( \rho_p \) represent the density of the projectile multiplied by its length along the x axis, we must have

\[
P(\xi=1) = \ell_a \int_0^1 (JB - \rho \alpha) \, d\xi + c = \rho_p \, \ell_a. \tag{3.28}
\]

It is clear, however, that the term \( JB \), integrated over the entire volume of the arc, yields the total force acting on the arc and projectile so

\[
(p_{\ell_a} + \rho_p) \alpha = \ell_a \int_0^1 J(\xi) B(\xi) \, d\xi.
\]

where \( \rho_{\ell_a} \) represents the average arc density multiplied by its length along the x axis. In the appendix it is proved that the acceleration \( \alpha \) is independent of how the current is distributed in the arc; in fact, the simple expression

\[
\alpha = \frac{\mu J^2}{2 (\rho_{\ell_a} + \rho_p)} \tag{3.30}
\]

is obtained. At any rate, Eqs. (3.28) and (3.29) imply \( c = 0 \), so we have at last

\[
P(\xi) = \ell_a \int_0^\xi [J(\xi) B(\xi) - \rho(\xi) \alpha] \, d\xi. \tag{3.31}
\]

The second term on the right-hand side of Eq. (3.31) is clearly negligible with respect to the first provided \( \rho_{\ell_a} < \rho_p \) as it is under most conditions.

From Eq. (3.23) the mass density of the arc is given by

\[
\rho = \frac{m_o}{k_B T (1 + \alpha)} \tag{3.32}
\]

and the length of the arc can be determined from the condition

\[
\ell_a \int_0^1 \rho(\xi) \, d\xi = \rho_{\ell_a}. \tag{3.33}
\]
Solving for \( l_a \), we obtain

\[
l_a = \rho \int_0^1 l_a \rho(\xi) \, d\xi .
\]  

(3.34)

The parameter \( \rho l_a \) is, of course, independent of \( l_a \).

Provided the temperature of the arc is sufficiently high, heat is transferred within the arc and to its surroundings primarily by radiation and conduction can be neglected. Therefore, \( q \) in Eq. (3.25) can be taken to represent the heat flux due to radiation, and we have upon integration

\[
q = \lambda_a \int_0^\xi \frac{J^2}{\sigma} \, d\xi + c .
\]

(3.35)

The constant of integration \( c \) can be determined from the fact that at the interface between the arc and the (assumed) vacuum behind it (\( \xi = 0 \)), the flux must approximately reduce to \(^{13}\)

\[
q(0) = -2\sigma_s T_o^4 ,
\]

(3.36)

where \( T_o \) is the temperature of the arc at \( \xi = 0 \) and \( \sigma_s \) is Stefan's constant, namely, \( 5.67 \times 10^{-8} \frac{J}{m^2 \text{deg}^4 \text{s}} \). Consequently, we have

\[
q = \lambda_a \int_0^\xi \frac{J^2}{\sigma} \, d\xi - 2\sigma_s T_o^4 ,
\]

(3.37)

where the unknown temperature \( T_o \) must be determined.

If the radiative mean free path within the arc is small compared to the arc length, as we shall find to be the case, the flux \( q \) can be approximated by the "radiative heat conduction" equation, \(^{13}\)

where \( \lambda \) represents the mean free path for radiation averaged over the entire frequency spectrum. Obviously to solve the equation an additional boundary condition must be specified. To obtain the condition we note that during the entire time of acceleration energy is transferred to the projectile surface, continuously heating its interior. As the projectile temperature rises, the transfer of energy from arc to projectile becomes less efficient, and this change in the transfer rate with time will clearly produce a time-dependent effect on the temperature in the arc. Thus, in a strict sense, the temperature profile of the arc is not completely steady. It is clear, however, that the projectile temperature at any time is substantially less than that of the arc and, consequently, little error should be made in assuming that the arc at the projectile surface is maintained at some constant temperature. Furthermore, since the radiative mean free path is small compared to the arc length, the properties of the arc, except very near the boundary, should be independent of this temperature. For these reasons it is convenient to assume that the projectile absorbs all the radiation which is incident upon it, just as does the vacuum behind the arc, and therefore the flux at \( \xi=1 \) reduces to

\[
q(1) = 2 \frac{\sigma_s}{\lambda} T_1^4 ,
\]

where \( T_1 \) is the arc temperature at the projectile surface. This condition supplies, then, the additional boundary condition. Further discussion of this assumption is given in Sec. V.

We have, upon integrating Eq. (3.38),

\[
T_1^4 = \frac{3\lambda a}{4\sigma_s} \int_{\xi}^{1} \frac{q}{\lambda} d\xi + T_1^4 .
\]

From Eqs. (3.37), (3.39), and (3.40), we obtain for the unknown temperatures \( T_o \) and \( T_1 \) the relationships

\[
T_o^4 = \frac{3\lambda a}{4\sigma_s} \int_{0}^{1} \frac{q}{\lambda} d\xi + T_1^4
\]

and

\[
T_1^4 = \frac{g a}{2\sigma_s} \int_{0}^{1} \frac{J^2}{\sigma} d\xi - T_o^4.
\]
Solving for $T_0$ and $T_1$ and substituting in Eqs. (3.37) and (3.40) we find

$$q = \ell_a \int_0^1 \frac{J_2}{\sigma} \, d\xi - \frac{\ell a}{2} \int_0^1 \frac{J_2}{\sigma} \, d\xi - \frac{3\ell a}{4} \int_0^1 \frac{q}{\lambda} \, d\xi$$  

(3.43)

and

$$T = \left\{ \frac{3\ell a}{4\sigma_s} \int_0^1 \frac{q}{\lambda} \, d\xi + \frac{\ell a}{4\sigma_s} \int_0^1 \frac{J_2}{\sigma} \, d\xi - \frac{3\ell a}{8\sigma_s} \int_0^1 \frac{q}{\lambda} \, d\xi \right\}^{\frac{1}{4}}$$  

(3.44)

Equations (3.43) and (3.44) provide two coupled equations for the heat flux $q$ and temperature $T$. Formally the equations can be solved by the transformation

$$q = A + F(\xi)$$  

(3.45)

After substitution into Eq. (3.43) we find

$$F(\xi) = \ell a \int_0^\xi \frac{J_2}{\sigma} \, d\xi$$  

(3.46)

and

$$A = \left[ \frac{E_0^j}{2} + \frac{3\ell a}{4} \int_0^1 \frac{F(\xi)}{\lambda} \, d\xi \right] \left[ 1 + \frac{3\ell a}{4} < \frac{1}{\lambda} > \right]$$  

(3.47)

where $< 1/\lambda >$ is the inverse of the mean free path averaged over the length of the arc, i.e.,

$$< \frac{1}{\lambda} > = \int_0^1 \frac{1}{\lambda} \, d\xi$$  

(3.48)

Equation (3.44) can now be written

$$T = \left\{ \frac{3\ell a}{4\sigma_s} \int_0^1 \frac{q}{\lambda} \, d\xi + \frac{E_0^j}{4\sigma_s} - \frac{3\ell a}{8\sigma_s} < \frac{1}{\lambda} > - \frac{3\ell a}{8\sigma_s} \int_0^1 \frac{F(\xi)}{\lambda} \, d\xi \right\}^{\frac{1}{4}}$$  

(3.49)
C. Degree of Ionization.

The parameter $\alpha$, occurring in Eq. (3.23), must be obtained before a solution to the fluid-mechanical equations considered in the last section can be found. In practice, this parameter results from the solution of a hierarchy of equations generally referred to simply as the Saha equation. In this section we outline the method by which the solution is obtained. For greater detail the reader is referred to the literature\textsuperscript{14}.

We recall that the parameter $\alpha$ represents the ratio of the number of electrons to the number of heavy particles, $N_H$. We let $x_j$ be the ratio of the number of atoms ionized $j$ times (referred to as "$j$th ions") to $N_H$. It is then evident that $\alpha$ is given by

$$\alpha = \sum_{j} x_j$$

and the electron number density in the arc by

$$n_e = \frac{\rho \alpha}{m_o}.$$  \hspace{1cm} (3.51)

The $x_j$'s are obviously normalized such that

$$\sum_{j} x_j = 1.$$ \hspace{1cm} (3.52)

In Eqs. (3.50) and (3.52), the sums over $j$ run over all values for which appreciable ionization occurs.

It has been shown that the $x_j$'s satisfy the following system of equations, usually called the Saha equation:

$$\frac{x_{j+1}}{x_j(1+\alpha)} = 2 \frac{Z_{j+1}}{Z_j} \left( \frac{m_e}{2\pi \hbar^2} \right)^{3/2} \frac{(k_B T)^{5/2} e^{-I_j}}{k_B T} = K_{j+1}(T,P).$$  \hspace{1cm} (3.53)

In Eqs. (3.53) $h$ is Planck's constant divided by $2\pi$, $m_e$ the electron mass, $I_j$ the ionization energy needed to ionize the atom $j$ times, and the $Z_j$'s are electronic partition functions for the $j$th ion. Specifically, $Z_j$ is given by

\textsuperscript{14} See Ref. 13, Chapter 3.
where \( U_{ji} \) is the energy of the \( i \)th electronic state of the \( j \)th ion and where \( g_{ji} \) is the appropriate degeneracy factor for this level. The partition functions depend upon position in the arc since the temperature is a function of position in the problem under consideration. Similarly, the \( x_j \)'s are also position dependent.

Equations (3.53) are deceptively simple looking. In practice the equation for any \( x_j \) always depends on \( x_{j+1} \) and, thus, the system of equations must be terminated at some point. If, for example, we assume that only single ionization occurs, then,

\[
\alpha = x_1, \tag{3.55}
\]

and only the term corresponding to \( j=0 \) is retained in Eqs. (3.53). The single resulting equation becomes

\[
\frac{x_1^2}{1-x_1^2} = K_1(T,P) \tag{3.56}
\]

if we use Eqs. (3.50) and (3.52). If desired, the equation can be solved for \( x_1 \) (or \( \alpha \)), and substituted into the fluid-dynamic equations of the previous section.

For the problem under study here, however, it is usually insufficient to assume only single ionization. In the event that double ionization is also allowed,

\[
\alpha = x_1 + 2x_2 \tag{3.57}
\]

and Eqs. (3.53) become

\[
\frac{x_1(x_1+2x_2)}{(1-x_1-x_2)(1+x_1+2x_2)} = K_1(T,P) \tag{3.58}
\]

\[
\frac{x_2(x_1+2x_2)}{x_1(1+x_1+2x_2)} = K_2(T,P).
\]
Again we have used Eqs. (3.50) and (3.52). These equations are most easily solved by iteration. After considerable algebra, they can be rewritten in the form

\[
x_1 = \frac{K_1 x_2}{2K_2} \left\{ \frac{1 + \frac{4K_2(1-x_2)}{K_1 x_2}}{1 + \frac{4K_2(1-x_2)}{K_1 x_2}} \right\}^{1/2} - 1 \]  

(3.59)

\[
x_2 = \frac{K_2}{K_1} \left\{ \frac{1 + \frac{4K_2(1-x_2)}{K_1 x_2}}{1 + \frac{4K_2(1-x_2)}{K_1 x_2}} \right\}^{1/2} \cdot \frac{(2+3K_1)x_2}{1+K_1} \left\{ \frac{4K_1(1+K_1)(1+x_2-2x_2^2)}{x_2^2(2+3K_1)^2} + 1 \right\}^{1/2} - 1 \]  

(3.60)

A value for \( x_2 \) is then assumed, substituted into the right-hand side of Eq. (3.60) and a new value of \( x_2 \) calculated. The process is then repeated until successive values agree to within any desired accuracy. The value for \( x_1 \) then follows directly from Eq. (3.59).

To illustrate the results we have plotted in Figure 2 values of \( x_1 \) and \( x_2 \) as a function of \( \log T \) for a pressure of \( 10^7 \) N/m\(^2\). The plasma was assumed to be a gas of partially ionized copper atoms. The partition functions in Eq. (3.54) were calculated using values\(^{15} \) for the \( g_{ji} \) and \( U_{ji} \) shown in Table I. Calculations were undertaken retaining first ten, and then fifteen, terms in the partition functions and no discernible differences were found in the results. The initial value of \( x_2 \) was chosen to be 0.01 and successive values were found to agree to within one part in \( 10^5 \) after, at most, a few tens of iterations. As can be seen from the graph no appreciable ionization exists below \( \log T \approx 9 \) (\( T=8,100^oK \)). Second ionization is negligible below \( \log T \approx 10 \) (\( T=22,000^oK \)) and then rises fairly rapidly. Once \( x_2 \) has become large (above, say, \( \log T \approx 10.5 \) or \( T = 36,000^oK \)), triple ionization is probably also important, but is not accounted for in the analysis above.

D. Summary of Governing Equations.

In the analysis of the preceding sections we have derived a system of coupled equations sufficient to determine the electromagnetic fields, the acceleration of the projectile, and the fluid-mechanical properties.

Figure 2. Ionization factors as a function of temperature.
Table I. Atomic Energy Levels and Degeneracy Factors for Copper and Its Ions. Energies are expressed in °K (from Ref. 15).

\[
\begin{array}{cccccccc}
\text{j} &=& 0 & \text{j} &=& 1 & \text{j} &=& 2 \\
I_1 &=& 89638 & I_2 &=& 235420 & I_3 &=& 427354 \\

\text{i} & & g_{0i} & & U_{0i} & & g_{1i} & & U_{1i} & & g_{2i} & & U_{2i} \\
0 & & 2 & & 0 & & 1 & & 0 & & 6 & & 0 \\
1 & & 6 & & 16114 & & 7 & & 31543 & & 4 & & 2980 \\
2 & & 4 & & 19052 & & 5 & & 32863 & & 10 & & 87463 \\
3 & & 2 & & 43923 & & 3 & & 34520 & & 8 & & 89276 \\
4 & & 4 & & 44280 & & 5 & & 37779 & & 6 & & 90827 \\
5 & & 6 & & 56125 & & 5 & & 95538 & & 4 & & 91895 \\
6 & & 4 & & 57701 & & 3 & & 96793 & & 8 & & 96398 \\
7 & & 2 & & 58894 & & 1 & & 99036 & & 6 & & 99198 \\
8 & & 9 & & 58844 & & 9 & & 98864 & & 6 & & 112150 \\
9 & & 8 & & 59196 & & 7 & & 98457 & & 4 & & 113316 \\
10 & & 6 & & 59785 & & 5 & & 100500 & & 2 & & 115682 \\
11 & & 4 & & 60849 & & 9 & & 100265 & & 4 & & 115513 \\
12 & & 2 & & 62049 & & 7 & & 102892 & & 6 & & 115867 \\
13 & & 8 & & 62591 & & 5 & & 104607 & & 4 & & 112908 \\
14 & & 6 & & 63874 & & 7 & & 101900 & & 2 & & 123895 \\
\end{array}
\]
of the arc. For easy reference the most pertinent equations are listed below [see Eqs. (3.15), (3.17), (3.19), (3.30), (3.31), (3.32), (3.34), (3.45), (3.46), (3.47), (3.49), (3.50), (3.51), (3.59), and (3.60)]:

\[ J = \sigma E_0 \]  

\[ E_0 = \frac{1}{l} \int_0^1 \sigma(\xi) d\xi \]  

\[ B = \mu \int_\xi^1 J(\xi) d\xi \]  

\[ a = \frac{\mu j^2}{2(\rho_\lambda a + \rho_p p)} \]  

\[ P = l_a \int_\xi^1 [J(\xi)B(\xi) - \rho(\xi) a] d\xi \]  

\[ \rho = \frac{m_0 P}{k_B T(1+x_1+2x_2)} \]  

\[ l_a = \frac{\rho_\lambda a}{\int_0^1 \rho(\xi) d\xi} \]  

\[ q = A + F(\xi) \]  

\[ T = \left\{ \begin{array}{l} \frac{3l_a}{4s} \int_\xi^1 \frac{q}{\lambda} d\xi + \frac{E_0 j}{4s} - \frac{3l_a A}{8s} < \lambda > - \frac{3l_a}{8s} \int_0^1 \frac{F(\xi)}{\lambda} d\xi \end{array} \right\} \]  

\[ n_e = \frac{\rho(x_1+2x_2)}{m_0} \]
\[ x_1 = \frac{K_1 x_2}{2K_2} \left\{ \left[ 1 + \frac{4K_2(1-x_2)}{K_1 x_2} \right]^{1/2} - 1 \right\} \] (3.71)

\[ x_2 = \frac{K_2}{K_1} \left\{ \left[ 1 + \frac{4K_2(1-x_2)}{K_1 x_2} \right]^{1/2} - 1 \right\} \cdot \frac{(2+3K_1)x_2}{1+K_1} \left\{ \frac{4K_1(1+K_1)(1+x_2-2x_2^2)}{x_2^2(2+3K_1)^2} + 1 \right\}^{1/2} - 1 \} \] (3.72)

In writing Eqs. (3.61) - (3.72) we have assumed that the plasma is at most doubly ionized. If we are provided with appropriate expressions for the conductivity \( \sigma \) and the mean free path \( \lambda \), the equations are sufficient to determine the twelve unknowns: \( J, B, \rho, T, q, n_e, x_1, x_2, E_0, a, \) and \( l_a \). The first nine of the unknowns are position dependent, whereas the last three are constant.

IV. SOLUTION OF EQUATIONS

A. Limiting-Case Analytic Solution

In this section we will be concerned primarily with the numerical solution of the equations summarized in Sec. IID and their application to the experimental data. Before turning to the numerical results, however, we will present a limiting-case analytic solution which is valid whenever (1) the mass of the arc is negligibly small with respect to the mass of the projectile, (2) the conductivity of the arc is constant, and (3) the radiative mean free path is inversely proportional to the pressure. The analytic solution serves as a useful check for the computer program used to evaluate the numerical results and provides some physical insight into the behavior of the equations as well. In addition, the above assumptions are not totally unreasonable for the problems which will be considered as will be seen when the more general numerical results are presented.

For constant conductivity, Eqs. (3.61) and (3.62) imply

\[ J = \frac{i}{l_a} \] (4.1)

so the current is uniformly distributed throughout the arc as expected. Equation (3.63) then becomes
\[ B = \mu j (1 - \xi) \]  \hspace{1cm} (4.2)

and the magnetic induction field varies linearly from the value \( \mu j \) at the trailing edge of the arc to zero at the leading edge. Similarly, if we neglect the second term on the right-hand side in Eq. (3.65) in compliance with the first assumption above we have

\[ P = \mu j^2 (\xi - \xi^2 / 2). \]  \hspace{1cm} (4.3)

Under assumption (3) above, we have from Eq. (4.3)

\[ \lambda = \frac{\lambda_0}{\xi - \xi^2 / 2} \]  \hspace{1cm} (4.4)

where \( \lambda_0 \) is a constant independent of position within the arc*. Equations (3.46) and (3.47) can now be evaluated and yield for the limiting-case solution

\[ F(\xi) = \frac{j^2 \xi}{\lambda_0 \lambda} \]  \hspace{1cm} (4.5)

and

\[ A = \frac{-5j^2}{8\sigma \lambda} \left[ 1 + \frac{16\lambda_0}{5\lambda} \right] \left[ 1 + \frac{4\lambda_0}{\lambda} \right] \]  \hspace{1cm} (4.6)

where \( \sigma \) denotes the constant conductivity of the arc. In obtaining Eq. (4.6) we have noted that \( <1/\lambda> \) is simply \( 1/3\lambda_0 \) when Eq. (4.4) is applicable. Provided the mean free path is small compared to the arc length, Eq. (4.6) can be expanded in powers of \( \lambda_0 / \lambda \) to obtain

\[ A \approx \frac{-5j^2}{8\sigma \lambda} \left[ 1 - \frac{4\lambda_0}{5\lambda} \right]. \]  \hspace{1cm} (4.7)

*It may be seen that \( \lambda \to \infty \) as \( \xi \to 0 \), contradicting our statement that \( \lambda \ll \lambda \) within the arc. As we shall see, however, reasonable values of \( \lambda_0 \) are of the order of \( 10^{-4} \) m while \( \lambda \) is of the order 0.1 m, so the condition is violated only very near the boundary. In fact, we found \( \lambda \ll \lambda \) over 98% of the arc in our numerical calculations. The small error incurred in the calculation resulting from the lack of validity, say, of radiative heat conduction in this small region is deemed negligible.
The expressions for $F(\xi)$ and $A$ can now be used to determine the heat flux $q$ and temperature $T$ within the arc. The flux follows directly from Eq. (3.68) and yields

$$q = \frac{j^2}{k_a \sigma o} (\xi - 5/8) + O(\lambda_o/\lambda_a) \quad (4.8)$$

where $O(\lambda_o/\lambda_a)$ denotes higher-order terms in the parameter $\lambda_o/\lambda_a$. Thus, the flux changes sign approximately five-eighths of the distance between the trailing edge of the arc, where it is negative, and the leading edge, where it is positive. The asymmetric nature of the flux results from the fact that the mean free path is a function of position.

Substituting Eqs. (4.4) and (4.5) into Eq. (3.69) and evaluating the results we find

$$T^4 = \frac{j^2 \lambda_o}{64 \sigma_s \sigma_o \lambda_o} \left[ \frac{20 \lambda_o}{k_a} + 15(1-4\lambda_o/5k_a)\xi^2 \right.$$  

$$-2(1-4\lambda_o/5k_a)\xi^3 + 6 \xi^4 \left] + O(\lambda_o^2/k_a^2) \right. \quad (4.9)$$

In the interior part of the arc where $0 < \xi < 1$, the terms of order $\lambda_o/\lambda_a$ can be neglected in Eq. (4.9) and we have

$$T = \left[ \frac{3j^2 \xi^2 (5-2\xi)(1-\xi)}{64\lambda_o \sigma_s \sigma_o} \right]^{1/4} \quad (4.10)$$

Here the temperature is independent of $k_a$ as should be expected for $\lambda_o/\lambda_a << 1$. Very near the projectile, however, as $\xi \to 1$, the lowest-order terms in Eq. (4.9) vanish and terms proportional to $\lambda_o/\lambda_a$ must be retained. We obtain then

$$T = \left[ \frac{3j^2}{16\lambda_a \sigma_s \sigma_o} \right]^{1/4} \quad (4.11)$$

Similarly, as $\xi \to 0$, or at the trailing edge of the arc, we find
Very near the boundaries of the arc, then, the temperature does depend on \( l_a \) and is lower than that at the center of the arc by a factor of the order of \( (\lambda_0 / l_a)^{3/4} \). The physical meaning of these results will be discussed in some greater detail when the numerical solutions are presented.

The solutions presented above should offer some insight into the physical meaning of the results when we attempt to interpret the numerical calculations. Further simplification of the equations in Sec. IIID is not possible without additional assumptions and, thus, numerical techniques must still be employed to obtain a complete solution even in the simplified case. However, if one can make a further assumption that the ion concentrations \( x_1 \) and \( x_2 \) are constant across the arc, a complete uncoupling of the equations is possible. Such an approximation might be reasonable, for instance, in a temperature range in which either single or double ionization was essentially complete, the other being negligible. Under this assumption we have from Eqs. (3.66) and (3.67)

\[
\lambda_a^{-1} = \frac{m_o}{\rho l_a k_B (1+x_1+2x_2)} \int_0^1 \frac{p(\xi)}{T(\xi)} \, d\xi .
\]  

(4.13)

Since Eq. (4.10) gives the temperature in the arc everywhere except for a negligible contribution near the boundaries, this expression may be used for \( T \) in Eq. (4.13) and we have, after employing Eq. (4.3) as well,

\[
\frac{1}{\lambda_a} = \frac{\mu j^{3/2} m_o}{\rho l_a k_B (1+x_1+2x_2)} \left( \frac{64 \lambda_0 \sigma \sigma_0}{3} \right)^{1/4} \int_0^1 \frac{\xi - \xi^2/2}{\xi^{1/2} (5-2\xi)^{1/4} (1-\xi)^{3/4}} \, d\xi .
\]  

(4.14)

The integral on the right-hand side of Eq. (4.14) is a constant independent of any properties of the arc and its value is about 0.46.

The value of \( \lambda_a \) for any particular set of input parameters can be calculated from Eq. (4.14) and results substituted into all equations in this section which depend on \( \lambda_a \). Consequently, under these admittedly restrictive conditions, explicit values for all unknowns discussed in Sec. IIID can be obtained.
B. Numerical Solution.

The equations in Sec. IID have been written in a form which makes them particularly amenable to solution by iterative techniques. Before proceeding, however, expressions for the conductivity $\sigma$ and radiation mean free path $\lambda$ are required. For the conductivity we have used a result obtained by Spitzer and coworkers\textsuperscript{16-18} for a completely ionized gas, namely,

$$\sigma(\xi) = \frac{2.63 \times 10^{-2} \gamma E T^{3/2}}{Z} \left[ \log \left( \frac{1.23 \times 10^{7} T^{3/2}}{Z \sqrt{n_e}} \right) \right]^{-1} \quad (4.15)$$

Here $Z$, given by

$$Z = \frac{x_1 + 4x_2}{x_1 + 2x_2}, \quad (4.16)$$

is a position-dependent number, lying between 1 and 2, which gives an indication of the degree of ionization in the gas. The multiplicative factor, $\gamma E$, actually depends weakly on $Z$. For the problem at hand, however, the gas is nearly completely doubly ionized and $\gamma E$ can be well approximated by the value 0.6833.

An expression for the radiative mean free path averaged over the frequency spectrum (Rosseland mean free path) has been derived by Raizer\textsuperscript{19} for a multiply ionized plasma. The derivation is based on the assumption that the atoms and ions which constitute the gas can be approximated by hydrogenic atoms or ions with an appropriate charge; it accounts for both bound-free and free-free (bremsstrahlung) transitions. One finds

$$\lambda(\xi) = \frac{0.91 \times 10^{11} k_B T^3 (1 + x_1 + 2x_2)}{P \left[ \begin{array}{ccc} -I_1/k_B T & -I_2/k_B T & -I_3/k_B T \\ (1-x_1-x_2)e & +4x_1e & +9x_2e \end{array} \right]} \quad (4.17)$$

for the case in which the gas is at most doubly ionized.


The numerical solution of the equations in Sec. IIID was then carried out as follows. The interval $0 < \xi < 1$ was divided into a few hundred equally spaced segments, and values for the position-dependent unknowns were estimated at every grid point from the approximate solution in Sec. IVA. Values for the constants $\ell_a$ and $E_0$ were also estimated in this manner and $a$ was calculated from Eq. (3.30). The estimated values were then used as initial values in an iterative technique by substituting them on the right-hand side of Eqs. (3.61) - (3.72) and calculating new values on the left-hand side. All integrals were evaluated simply by the trapezoidal rule. For the second iteration, a weighted average of the old and new values was used on the right-hand side. The process was then repeated and successive values were found to differ by only about one part in $10^4$ after a few hundred iterations. Calculations were performed using different step sizes and it was found that approximately 400 grid points gave sufficiently accurate results. To the extent possible the mechanics of the program was checked using the analytic solution in Sec. IVA.

C. Application to Rashleigh-Marshall Experiment.

As pointed out in Sec. I, Rashleigh and Marshall have used an arc-driven rail gun to accelerate a 3g mass to a velocity of about 6 km/s. We now wish to solve the equations in Sec. IIID using data appropriate to the RM experiment and, thereby, to analyze the arc. With two exceptions, the data which are listed in Table II are available either directly from the experiment or can be easily calculated therefrom. It has been necessary, however, to estimate the arc mass since this quantity was not measured experimentally and we have chosen to use the value of 0.1g estimated by McNab in his earlier calculations. We have in subsequent work varied $m_0$, holding the other parameters fixed, and these results will be discussed in Sec. IVD. In addition, in the experiment the outer-most edges of the rails were surrounded by insulating material which excluded the arc from this region. Consequently, the rail height, $h_0$, was somewhat larger than the arc height measured along the rails, $h_p$. In the model studied here, both these heights were assumed equal and we have therefore used for $h$ an effective height found from the geometric mean of the two values. The remaining quantities in the table are largely self-explanatory. The potential $V_0$ is the voltage measured across the muzzle of the gun; it gives rise to the electric field in Eq. (3.21) and, since $B=0$ at the muzzle, it represents physically a purely resistive drop across the plasma. The atomic mass $m_0$ was easily found to be the value indicated for the copper arc used in the experiment.
TABLE II. Experimental Data for Rashleigh-Marshall Experiment. The data, taken mostly from Ref. 1, were used in the numerical solution of the governing equations in Sec. IIID.

<table>
<thead>
<tr>
<th>Quantity</th>
<th>Description</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$w$</td>
<td>Rail separation</td>
<td>$1.27 \times 10^{-2}$ m</td>
</tr>
<tr>
<td>$h_p$</td>
<td>Plasma height on rails</td>
<td>$1.27 \times 10^{-2}$ m</td>
</tr>
<tr>
<td>$h_r$</td>
<td>Rail height</td>
<td>$1.91 \times 10^{-2}$ m</td>
</tr>
<tr>
<td>$h$</td>
<td>Effective rail height</td>
<td>$1.56 \times 10^{-2}$ m</td>
</tr>
<tr>
<td>$m_p$</td>
<td>Projectile mass</td>
<td>$3 \times 10^{-3}$ kg</td>
</tr>
<tr>
<td>$i$</td>
<td>Pulsed current</td>
<td>$3 \times 10^5$ A</td>
</tr>
<tr>
<td>$j$</td>
<td>Current per unit height</td>
<td>$1.92 \times 10^7$ A/m</td>
</tr>
<tr>
<td>$V_o$</td>
<td>Muzzle voltage</td>
<td>160 V</td>
</tr>
<tr>
<td>$m_a$</td>
<td>Arc mass</td>
<td>$10^{-4}$ kg</td>
</tr>
<tr>
<td>$m_o$</td>
<td>Ion (or atom) mass</td>
<td>$1.1 \times 10^{-25}$ kg</td>
</tr>
<tr>
<td>$\alpha$</td>
<td>Average acceleration</td>
<td>$6 \times 10^6$ m/s$^2$</td>
</tr>
<tr>
<td>$\rho_p$</td>
<td>[See Eq. (3.29)]</td>
<td>$15.1$ kg/m$^2$</td>
</tr>
<tr>
<td>$\rho_a$</td>
<td>[See Eq. (3.29)]</td>
<td>$0.51$ kg/m$^2$</td>
</tr>
</tbody>
</table>

* Estimated value.

The equations in Sec. IIID have been solved in the manner discussed in Sec. IVB and using the data in Table II. Results for the position-independent unknowns are indicated in Table III, while graphs of position-dependent quantities are shown by the solid-line curves in Figures 3-10. (The curves denoted by x's will be discussed in Sec. IVE.) These variables are plotted as a function of the dimensionless distance $\xi$. The brackets on quantities in Table III indicate that these variables were averaged over the length of the arc.

The value obtained for the acceleration is about a factor of two higher than the experimental value in Table II. Since $\alpha$ is a sensitive function of $j$, however, close agreement cannot be expected in view of the rather arbitrary manner in which $h$ was chosen. The length of the
TABLE III. Results of Numerical Calculation for RM Experiment. The arc mass, $m_a$, was 0.1g.

<table>
<thead>
<tr>
<th>Quantity</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$a$</td>
<td>$1.48 \times 10^7$ m/s$^2$</td>
</tr>
<tr>
<td>$l_a$</td>
<td>9.20 cm</td>
</tr>
<tr>
<td>$E_0$</td>
<td>$3.72 \times 10^3$ volts/m</td>
</tr>
<tr>
<td>$&lt; T &gt;$</td>
<td>$5.61 \times 10^4$ °K</td>
</tr>
<tr>
<td>$&lt; Z &gt;$</td>
<td>1.93</td>
</tr>
<tr>
<td>$V_0$</td>
<td>47 volts</td>
</tr>
<tr>
<td>$&lt; n_e &gt;$</td>
<td>$9.85 \times 10^{25}$ m$^{-3}$</td>
</tr>
</tbody>
</table>

arc $l_a$ was not explicitly measured in the experiment, but the calculated value is consistent with the estimate of around 10 cm.

The mean temperature is probably somewhat high, and it is likely that the high value results from the one-dimensional character of the model in which energy has been allowed to radiate only from the ends of the arc, not from the sides. In a two-or-three-dimensional model more surface area is available for radiation and the temperature must fall. A crude estimate of the mean temperature in a three-dimensional model may be obtained as follows. In one dimension, the surface area available for radiation is

$$A_1 = 2hw$$  \hspace{1cm} (4.18)

while in three dimensions one has

$$A_3 = 2hw + 2l_a w + 2l_a h$$  \hspace{1cm} (4.19)

Using data for the RM experiment and assuming negligible change in $l_a$, we find $A_3/A_1 \approx 14$. Since for a blackbody, the temperature varies inversely as the fourth root of the available surface area, we might expect a drop in $< T >$ of about a factor of two.
The average of the parameter $Z$, defined in Eq. (4.16), is included in the table in order to give some indication of the degree of ionization in the arc. Evidently, most of the ions are doubly ionized with very few singly ionized atoms in most of the arc. The high degree of second ionization makes it likely that some triple ionization, not accounted for, probably also exists. Again, however, $Z$ should be considerably less in a two- or three-dimensional model because of the lower temperature.

Finally, the muzzle voltage which is easily calculated from the relation

$$V_o = E_o w$$

(4.20)

was found to be 47 volts, about a factor of three smaller than that measured in the experiment. At the lower temperatures expected in three dimensions, $V_o$ should increase since, according to Eq. (4.15), the conductivity of the arc decreases with decreasing $T$.

We see therefore that the calculated quantities which can be compared to the experimental results agree to within about a factor of three. The agreement, we feel, is reasonable in view of the restrictive assumptions made in the model as well as the arbitrary way in which $m_a$ and $h$ were obtained.

Plotted in Figure 3 is the pressure as a function of position in the arc. The pressure rises from zero at the trailing edge of the arc (a possible definition of the trailing edge) to a value at the projectile sufficient to provide an acceleration $\alpha$, namely, $p_\alpha$. For the appropriate data, this value is roughly 220 MPa, or about 2200 atmospheres. If the current density in the arc were uniform, $P$ would vary as $\xi^{-\xi^2/2}$ (see Sec. IVA). The nonconstant current density, however, gives rise to deviations from this type of behavior observed in the graph. Similarly, the magnetic induction field, $B$, shown in Figure 4, varies from about 24 T at the trailing edge to zero at the projectile. The variation would be linear for constant current density as can be seen from Eq. (4.2).

The asymmetric nature of the temperature profile, shown in Figure 5, results from the position dependence of the radiation mean free path. Specifically, toward the leading edge of the arc where the density increases, the mean free path decreases. Consequently, photons created in the right-most part of the arc are radiated away with more difficulty than those in the left-most part, and there is a high concentration of energy near the projectile. Very near the projectile the temperature drops suddenly as was predicted by the analytic results in Sec. IVA.
Figure 3. Pressure, in MPa, as a function of position in the arc: —, calculation in Sec. IVC; xxx, calculation in Sec. IVE.
Figure 4. Magnetic induction field, in Tesla, as a function of position in the arc: ——-, calculation in Sec. IVC; xxx, calculation in Sec. IVE.
Figure 5. Temperature, in thousands of degrees Kelvin, as a function of position in the arc: ———, calculation in Sec. IVC; xxx, calculation in Sec. IVE.
Clearly once the photons are within a mean free path or so of the projectile surface, they are able to "see" the boundary and are radiated outward with little difficulty. Consequently, the temperature drops dramatically over this very short distance. It is also interesting to note that the temperature at $\xi = 0$, $2.53 \times 10^4 \, ^\circ$K, is larger than that at the projectile, $2.16 \times 10^4 \, ^\circ$K, by a factor of about 1.17. This factor is very close to that predicted by Eqs. (4.11) and (4.12), namely, $(5/3)^{1/4} \approx 1.14$.

The mass density, $\rho$, shown in Figure 6, varies nearly linearly from the expected value of zero at the trailing edge to about $10 \, \text{kg/m}^3$ (about eight times the density of air at STP) at the leading edge. Very near the boundary a sudden rise in the density by about a factor of five is observed. The rise results because as the temperature drops at the boundary, the degree of ionization also drops, and both these effects tend to reduce the pressure near the projectile. Thus, a steady pressure at the projectile can be maintained only if there is a proportionate increase in mass density at the surface.

In Figure 7 is plotted the electron density, $n_e$, which varies in much the same manner as the mass density as should be expected. The rise near the projectile surface, however, is not so rapid as for the mass density; even though there are more ions near the boundary, they are less highly ionized than those interior to the arc because of the lower temperature.

The curve for the current density, $J$, shown in Figure 8, is largely self-explanatory. The current falls to zero at the trailing edge of the arc where the electron density is zero, increases with increasing temperature across the arc as should be expected from Eq. (4.15), and finally drops as $T$ drops near the boundary. It should perhaps be noted from Eq. (4.15) that $\sigma$ varies nearly as $T^{3/2}$, depending only weakly on the remaining parameters. ($Z$ is nearly constant over most of the arc as can be seen in Figure 9.)

In Figure 9 is shown the mean ionic charge, $Z$, defined in Eq. (4.16). Except very close to the projectile, we found that essentially all the atoms in the arc were at least singly ionized with very few neutrals present. Therefore, within the arc a value of $Z = 2$ corresponds to $x_1 = 0$ and $x_2 = 1$, while a value of $Z = 1.8$ corresponds roughly to $x_1 = 0.33$, $x_2 = 0.67$. The unusual behavior of $Z$ near the trailing edge of the arc results from the factor $1/P$ in the Saha equation. This dependence reflects the fact that electron reattachment is a two-body interaction, whereas ionization does not necessarily require a collision. However, the results are dependent on the assumption of thermal equilibrium which
Figure 6. Mass density, in kg/m$^3$, as a function of position in the arc: ——, calculation in Sec. IVC; xxx, calculation in Sec. IVE.
Figure 7. Electron density, in m$^{-3}$ and normalized by the constant factor $10^{25}$, as a function of position in the arc: ———, calculation in Sec. IVC; xxx, calculation in Sec. IVE.
Figure 8. Current density, in MA/m², as a function of position in the arc: ---, calculation in Sec. IVC; xxx, calculation in Sec. IVE.
Figure 9. Mean ionic charge as a function of position in the arc: ——, calculation in Sec. IVC; xxx, calculation in Sec. IV E.
is not valid near \( \xi=0 \), owing to the small density there. Therefore, the detailed behavior of \( Z \) (and the other parameters) very near \( \xi=0 \) is probably open to question. In any case, the region in doubt is only a small portion of the overall profile and should have little effect on the mean properties and overall dynamics of the arc as suggested previously. Slightly to the right of \( \xi=0 \), the degree of ionization is determined predominantly by the temperature and increases with increasing temperature across the arc. Very near the projectile, the temperature drops dramatically with only a small variation in the pressure, so \( Z \) likewise drops. In fact, at the projectile surface, \( x_1 = 0.38 \) and \( x_2 \approx 0 \) so only 38\% of the heavy particles which constitute the arc are at all ionized.

Finally, we show in Figure 10 the radiation heat flux \( q \). For the limiting-case analytic solution, we found [see Eq. (4.8)], a linear behavior in \( q \) as a function of \( \xi \) with the flux changing sign at \( \xi \approx 5/8 \approx 0.63 \). For the more general calculation, the behavior is fairly well approximated by a linear variation and the sign changes around \( \xi=0.72 \).

D. Dependence of Results on Arc Mass.

Since it was necessary to estimate the value of the arc mass in the previous section, it is of some interest to ask how the results depend on \( \mu_a \). We have therefore performed the calculation for a number of different values of \( \mu_a \), holding the remaining parameters fixed at the values in the previous section.

Typical of the results are those shown in Table IV which are for an arc mass, \( \mu_a \), of 0.05 g. As can be seen from the table, the acceleration of the arc is very slightly higher than before because of the de-

<table>
<thead>
<tr>
<th>Quantity</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>( a )</td>
<td>( 1.51 \times 10^7 ) m/s(^2)</td>
</tr>
<tr>
<td>( \lambda_a )</td>
<td>4.54 cm</td>
</tr>
<tr>
<td>( E_o )</td>
<td>( 7.47 \times 10^3 ) volts/m</td>
</tr>
<tr>
<td>( &lt; T &gt; )</td>
<td>( 5.66 \times 10^4 ) °K</td>
</tr>
<tr>
<td>( Z )</td>
<td>1.94</td>
</tr>
<tr>
<td>( V_o )</td>
<td>95 volts</td>
</tr>
<tr>
<td>( &lt; n_e &gt; )</td>
<td>( 1.00 \times 10^{26} ) m(^{-3})</td>
</tr>
</tbody>
</table>
Figure 10. Heat flux, in \( \frac{\text{GJ}}{\text{s m}^2} \), as a function of position in the arc:
- —, calculation in Sec. IVC; xxx, calculation in Sec. IVE.
crease in the mass of the arc. Primarily the acceleration is determined by the more massive projectile, however, and the arc mass has only a minimal effect. The length of the arc has decreased by approximately a factor of two as might be expected intuitively. With the decrease in \( \ell_a \), \( E_0 \) and consequently \( V_0 \) rise by about a factor of two resulting from the increase in resistance of the arc. Likewise, the current density \( J \) in the arc, though not shown in the table, is everywhere higher by about a factor of two, owing to the decreased area of the arc.

It is noteworthy that, within the interior of the arc, the remaining position-dependent variables considered previously (\( B, P, T, \rho, n_e, x_1, \) and \( x_2 \)) depend only very weakly on \( m_a \) when plotted as a function of the dimensionless distance \( \xi \). In fact, when \( m_a \) was changed from 0.1 g to 0.05 g we observed changes of, at most, a few percent across the interior of the arc, though more significant changes did occur very near the boundaries. Except for the temperature, this result is perhaps not too surprising. It does appear, however, that the higher rate of energy dissipation in the smaller arc would surely result in a higher temperature. The reason for the unexpected result is that, even though the Joule heating is indeed greater in the smaller arc, so are the temperature gradients across the arc. Therefore, although energy is dissipated at a higher rate, it is also radiated away more easily. For the one-dimensional model under study here, the two effects almost exactly compensate each other so the arc seeks nearly the same steady-state temperature in the two cases. This, incidentally, will probably not be the case in a two- or three-dimensional model and one expects the temperature to rise with decreasing \( m_a \) (or \( \ell_a \)).

The manner in which the parameters discussed above vary with \( \ell_a \) can be seen approximately from the special-case solution in Sec. IVA. Thus, one sees from Eqs. (4.2) and (4.3) that \( B \) and \( P \) do not vary with \( m_a \) as a function of \( \xi \). From Eq. (4.14), on the other hand, \( \ell_a \) varies directly with \( m_a \) (or \( p_\ell \)) in this limiting case and, therefore, as \( m_a \) decreases by a factor of two, so does \( \ell_a \). In accordance with Eq. (4.1), then, \( J \) should vary inversely with \( m_a \) as should \( E_0 \) and \( V_0 \). \( T \), on the other hand, is nearly independent of \( \ell_a \) or \( m_a \) within the interior of the arc [Eq. (4.10)] but some variation can be expected very close to the boundaries [Eqs. (4.11) and (4.12)]. Finally, since \( \rho, x_1, \) and \( x_2 \) depend only on \( P \) and \( T \), one expects them also to vary significantly with \( m_a \) and only very near the boundaries.

Of course, the variations predicted by the limiting-case solution are only approximate in view of the assumptions made in obtaining that
solution. It is interesting, nevertheless, that the approximate scaling laws predicted from results in Sec. IVA appear to hold very nearly even for solutions to the more general equations.

E. Application to the Proposed Westinghouse Experiment and Scaling Factors.

We have also undertaken calculating the properties of the arc in a gun of the size proposed for the Westinghouse experiment. In particular, the input data for that calculation are shown in Table V. The rail gap, rail height, and projectile mass were chosen to be values appropriate for the proposed experiment; the value of the pulsed current \( i \) was chosen so as to provide an acceleration sufficient to reach a velocity of 3 km/s in a distance of 4m; and the arc mass was selected, mostly by trial and error, to give an arc length of the order of 10 cm.

<p>| TABLE V. Input Data for Large Gun. These data were used in the numerical solution of the governing equations in Sec. IIID; they correspond roughly to a gun comparable in size to that proposed in the Westinghouse experiment |
| --- | --- | --- |</p>
<table>
<thead>
<tr>
<th>Quantity</th>
<th>Description</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>( w )</td>
<td>Rail separation</td>
<td>( 5 \times 10^{-2} ) m</td>
</tr>
<tr>
<td>( h )</td>
<td>Rail height</td>
<td>( 5 \times 10^{-2} ) m</td>
</tr>
<tr>
<td>( m_p )</td>
<td>Projectile mass</td>
<td>0.3 kg</td>
</tr>
<tr>
<td>( i )</td>
<td>Pulsed current</td>
<td>( 7.35 \times 10^5 ) A</td>
</tr>
<tr>
<td>( j )</td>
<td>Current per unit height on rails</td>
<td>( 1.47 \times 10^7 ) A/m</td>
</tr>
<tr>
<td>( m_a )</td>
<td>Arc mass</td>
<td>( 8 \times 10^{-4} ) kg</td>
</tr>
<tr>
<td>( \rho_a )</td>
<td>[See Eq. (3.29)]</td>
<td>0.32 kg/m²</td>
</tr>
<tr>
<td>( \rho_p )</td>
<td>[See Eq. (3.29)]</td>
<td>120 kg/m²</td>
</tr>
</tbody>
</table>

General results of the numerical calculation are shown in Table VI and, as can be seen, quantities are of the same order of magnitude as obtained in the RM calculation. The largest difference in the two sets of data occurs for the potential across the rails which is larger than that for the RM experiment (with \( m_a = 0.1g \)) by nearly a factor of five. The higher value in the present case results from the higher current and higher arc resistance in the larger gun.
Table VI. Results of Numerical Solution for Large Gun. Input data used in the calculation are given in Table V.

<table>
<thead>
<tr>
<th>Quantity</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$a$</td>
<td>$1.13 \times 10^6$ m/s$^2$</td>
</tr>
<tr>
<td>$\lambda_a$</td>
<td>7.82 cm</td>
</tr>
<tr>
<td>$E_0$</td>
<td>$4.14 \times 10^3$ volts/m</td>
</tr>
<tr>
<td>$&lt; T &gt;$</td>
<td>$4.68 \times 10^4$ $^\circ$K</td>
</tr>
<tr>
<td>$&lt; Z &gt;$</td>
<td>1.89</td>
</tr>
<tr>
<td>$V_o$</td>
<td>207 volts</td>
</tr>
<tr>
<td>$&lt; n_e &gt;$</td>
<td>$7.11 \times 10^{25}$ m$^{-3}$</td>
</tr>
</tbody>
</table>

Graphs of position-dependent quantities are denoted for this calculation by the curves drawn with x's in Figures 3-10. The general discussion of the curves for the RM experiment applies here as well, and no further discussion will be given.

It is of interest to ask whether we can determine some approximate scaling laws from the analytic solution in Sec. IVA and, if so, to what extent these laws predict the results obtained for the larger gun. Fairly simple scaling laws can be derived from the analytic solution provided we make three additional assumptions: First, we assume that the degree of ionization does not appreciably change from one experiment to the other as can be seen to be the case for the RM and Westinghouse experiments. Second, we neglect the variation of the logarithmic term in Eq. (4.15), i.e., assume $\sigma \approx T^{3/2}$. Finally, we note that, for constant ionization, $\lambda$ in Eq. (4.17) varies approximately as $T^{7/2}/\rho^2$. If we make use of these assumptions, some simple algebra yields the scaling laws shown in Table VII. The pertinent equations for deriving the appropriate scaling factor are indicated in the right-most column of the table. To use the table, the value of a particular quantity in the RM experiment (column 1) is multiplied by the ratio of scaling factors for the large gun and RM gun. The numerical value of this ratio for the two experiments is shown in column 3. The result is then the predicted value of the quantity for the larger gun.
Table VII. Approximate Scaling Factors. Scaling factors were derived from the limiting-case analytic solution in Sec. IVA.

<table>
<thead>
<tr>
<th>Quantity</th>
<th>Scaling Factor</th>
<th>Value</th>
<th>Equations</th>
</tr>
</thead>
<tbody>
<tr>
<td>$l_a$</td>
<td>$\rho_{l_a}/j^{16/11}$</td>
<td>0.92</td>
<td>3.66, 4.3, 4.10, 4.14, 4.15</td>
</tr>
<tr>
<td>$\alpha$</td>
<td>$j^2/(\rho_{l_a} + \rho_{l_p})$</td>
<td>0.076</td>
<td>3.64</td>
</tr>
<tr>
<td>$v_o$</td>
<td>$j^{18/11}w/\rho_{l_a}$</td>
<td>4.08</td>
<td>3.62, 3.66, 4.3, 4.10, 4.14, 4.15, 4.20</td>
</tr>
<tr>
<td>$E_o$</td>
<td>$j^{18/11}/\rho_{l_a}$</td>
<td>1.03</td>
<td>3.62, 3.66, 4.3, 4.10, 4.14, 4.15</td>
</tr>
<tr>
<td>$B$</td>
<td>$j$</td>
<td>0.77</td>
<td>4.2</td>
</tr>
<tr>
<td>$P$</td>
<td>$j^2$</td>
<td>0.59</td>
<td>4.3</td>
</tr>
<tr>
<td>$J$</td>
<td>$j^{27/11}/\rho_{l_a}$</td>
<td>0.84</td>
<td>3.66, 4.1, 4.3, 4.10, 4.14, 4.15</td>
</tr>
<tr>
<td>$T$</td>
<td>$j^{6/11}$</td>
<td>0.87</td>
<td>3.66, 4.3, 4.10, 4.15</td>
</tr>
<tr>
<td>$p$</td>
<td>$j^{16/11}$</td>
<td>0.68</td>
<td>3.66, 4.3, 4.10, 4.15</td>
</tr>
<tr>
<td>$n_e$</td>
<td>$j^{16/11}$</td>
<td>0.68</td>
<td>3.66, 3.70, 4.3, 4.10, 4.15</td>
</tr>
<tr>
<td>$q$</td>
<td>$j^{29/11}/\rho_{l_a}$</td>
<td>0.80</td>
<td>3.66, 4.3, 4.8, 4.10, 4.14, 4.15</td>
</tr>
</tbody>
</table>
Values obtained in this manner for the parameters in Table VI were:
\[ a = 1.13 \times 10^6 \text{ m/s}^2, \quad \ell_a = 8.46 \text{ cm}, \quad E_0 = 3.83 \times 10^3 \text{ volts/m}, \quad <T> = 4.88 \times 10^4 \text{ °K}, \quad V_0 = 192 \text{ volts}, \quad \text{and } <n_e> = 6.70 \times 10^{25} \text{ m}^{-3}. \]
As can be seen, values of the parameters obtained from the scaling laws agree with the actual theoretical values in Table VI to within, at worst, about 15%. We have also investigated the validity of the scaling laws in predicting the values of position-dependent quantities and, again, found reasonable agreement. Typical of the results is that shown in Figure 11. The curve denoted by the x's is the theoretical value of the arc temperature for the larger gun plotted as a function of \( \xi \) (see Figure 5); the curve denoted by the O's is the same function but obtained from the scaling laws. The latter curve was deduced by multiplying the temperature at every point \( \xi \) in the RM experiment by the appropriate scaling factor, namely, 0.87. As can be seen the results agree everywhere to within less than 10%.

It appears, therefore, that no major difficulties should be encountered if it should be desirable to employ an arc in the proposed Westinghouse experiment. All properties of the arc are expected to be the same order of magnitude as for the RM experiment. Furthermore, approximate values of the pertinent parameters can be obtained from the scaling factors in Table VII.

V. DISCUSSION

In this final section, we will discuss the calculation briefly, particularly the major assumptions, indicate the limitations of the model, and suggest what future calculations might be desirable. To summarize, we have proposed a model for determining the steady acceleration of the arc and projectile in the arc-driven electric gun and for describing the fluid-mechanical properties of the arc. A set of twelve coupled equations has been derived which, when solved, yields these properties. The theory has been applied to the RM experiment as well as to the experiment proposed by Westinghouse. It has been demonstrated that use of an arc in the larger gun should pose no major obstacles.

As pointed out in Sec. I, some earlier analysis of arc dynamics in the RM experiment has been carried out by McNab. He assumed that one-third of the measured muzzle voltage ( \( \cong 53 \text{ volts} \) ) occurred across the plasma and used this experimental value to calculate the temperature of the arc. The spatial variation of all flow parameters was neglected and the gas was assumed to be, at most, singly ionized. In addition, the experimental value of the acceleration was used in the calculation and the arc length was assumed to be 10 cm. Values obtained for the pressure, temperature, electron density, and arc mass were: \( P = 110 \text{ MPa}, \)
Figure 11. Comparison of numerical results of temperature profile with results obtained from scaling laws: xxx, numerical results from calculation in Sec. IVE; OOO, results obtained from scaling laws in Table VII.
The rationale for assuming that only one-third of the potential difference between the rails occurs across the arc is, as McNab pointed out, that some contact potential surely exists at the rail-arc interface. This contact potential has not been included in the present calculation primarily because it is not clear experimentally how significant a potential drop actually exists. Admittedly, however, the contact potential is probably not negligible and some further investigation is appropriate. Presumably, the effect could be included in the model with little additional difficulty.

The major assumption that has been employed in the present calculations is that the entire acceleration process can be approximated by conditions appropriate to the steady state. This approximation should be reasonable provided the time required for a steady state to be established is small compared to the total time of acceleration. Obviously, the validity of the approximation cannot be rigorously ascertained without, in fact, solving the time-dependent problem. Nevertheless, several necessary conditions might be mentioned.

First, it is clear that for the steady-state approximation to be valid, the current, which initially flows on the surface of the arc, must diffuse through it in a time small compared to the total acceleration time. Alternatively, the skin depth, \(\delta\), of the plasma must be large compared with its length. The skin depth of the plasma at time \(t\) can be estimated from the expression\(^2\)

\[
\delta = \left( \frac{\pi t}{\mu \sigma} \right)^{1/2} = \left( \frac{\pi t \alpha V_0}{\mu j w} \right)^{1/2},
\]

where \(\sigma_0\) here denotes the mean conductivity of the arc. The second equality in Eq. (5.1) follows from Eqs. (3.15) and (4.20) with \(J\) approximated by \(j/\ell_a\). For an acceleration time appropriate to the RM experiment, namely, 1.6 ms and assuming \(V_0 = 47\) volts, the theoretical value, we find, \(\delta \approx 30\) cm. Clearly, \(\delta\) is considerably larger than the arc length of 9.2 cm. That the skin depth here is larger than those generally associated with solid conductors results from the lower conductivity in the gaseous state.

A second condition which must be satisfied in order to justify the steady-state approximation is that the time required for the plasma to reach its steady-state internal energy must be small compared to the total acceleration time. The internal energy of the plasma at any time can be determined from the relation

\[ E_{\text{int}} = E_T + E_i + E_e \]  

(5.2)

where \( E_T \), \( E_i \), and \( E_e \) denote the thermal, ionization, and electronic energies, respectively, whereas the energy which has been dissipated in the arc at time \( t \) is given by

\[ E_D = h_w \int_0^t J^2 \sigma \, d\xi = h_w \int_0^t E_0 \, d\xi. \]  

(5.3)

Assuming that the gas is completely doubly ionized, a simple estimate reveals that for the RM experiment, \( E_{\text{int}} \approx 6 \text{ kJ} \). If we neglect losses in energy due to radiation during the time for which the plasma is being heated, the time required for the plasma to reach its steady internal energy can be found by substituting \( E_{\text{int}} \) on the left-hand side of Eq. (5.3) and solving for \( t \). We find \( t \approx 0.4 \text{ ms} \), a value somewhat smaller than the total acceleration time of 1.6 ms. The assumption that radiation losses are negligible during the time of heating is probably reasonable, since the radiation flux varies as \( T^4 \). It is of interest to note, incidentally, that the total energy dissipated in the arc during the acceleration time of 1.6 ms is about 20 kJ. This energy is considerably less than the kinetic energy of the arc and projectile which is, using the theoretical value of the acceleration, about 870 kJ. In the model, the remaining energy supplied by the source is stored in the magnetic field, and it can be shown that this energy is identical to the kinetic energy of the arc and projectile.

Finally, a less stringent condition which must be satisfied in order to justify the steady-state approximation is that the time of acceleration must be large compared to the time necessary for a sound wave to traverse the arc. If this condition is not met, it is clear that the flow variables cannot become equilibrated during the time of acceleration, and that they will be time dependent in a frame accelerating with the arc. One can estimate, however, that the sound speed in the plasma is of the order of a few kilometers per second. Thus, the time necessary for a disturbance to traverse an arc 10 cm long is probably somewhat less than \( 10^{-4} \text{ s} \). Again, this is substantially less than the acceleration time of 1.6 ms.

The above considerations do not prove the validity of the steady assumption and further investigation is desirable. In principle, a time-dependent theoretical treatment, accounting for the the initial
compression and expansion of the arc and the diffusion of current within it, should be possible. Such a calculation, however, would be immensely more difficult than that undertaken here and would necessitate additional experimental data and assumptions. It would be necessary to know, for instance, the conditions of the arc prior to the time the acceleration begins and this information is not currently available. Probably so detailed a calculation is not justified considering our current state of experimental knowledge. In future experiments it would be desirable if investigators could measure the temperature of the arc by, for example, spectroscopic means. The adequacy of various theoretical treatments could then be ascertained and more sophisticated calculations undertaken.

Some of the remaining assumptions made in the model calculation merit some brief discussion. First, we found that over most of the arc essentially all of the ions were doubly ionized. The high degree of ionization suggests that some triple ionization is probably also present, and triple ionization is not accounted for. As has been pointed out, however, in a two- or three-dimensional model, one expects lower temperatures and, in that case, higher ionization is probably negligible. Account could be taken, of course, of triple ionization by including an additional equation in the hierarchy represented by Eqs. (3.53). The spectrum of trebly ionized copper has been reported in the literature, and so the calculation should be quite straightforward. In practice, however, the algebra becomes extremely tedious and is probably not justified in view of the rather limited improvements anticipated in the results.

The relative importance of ordinary heat conduction, neglected in the calculation, and radiation can be estimated by comparing the coefficient of thermal conductivity to the coefficient of radiation heat conduction. The latter coefficient is defined in Eq. (3.38), viz.,

\[
\kappa_R = \frac{16\alpha_s \lambda T^3}{3},
\]

whereas the thermal-conductivity coefficient can at least be approximated by the expression appropriate for a Lorentz gas. One has

\[
\kappa_c = \frac{1.96 \times 10^{-9} T^{5/2}}{Z} \left[ \log \left( \frac{1.23 \times 10^7 T^{3/2}}{Z\sqrt{n_e}} \right) \right]^{-1}
\]

and the ratio of the two values is

\[ \frac{\kappa_R}{\kappa_c} = 1.5 \times 10^2 \lambda Z T^{1/2} \log \left( \frac{1.23 \times 10^7 T^{3/2}}{Z \sqrt{n_e}} \right). \]  

(5.6)

Radiation mean free paths, \( \lambda \), in the calculation were found to be typically of the order of \( 10^{-4} \) m, and, assuming as approximate mean values, \( Z = 2, T = 5.6 \times 10^4 \) deg, \( n_e = 10^{26} \) m\(^{-3} \), we find \( \kappa_R/\kappa_c \approx 15 \). Thus, radiation is substantially more important than heat conduction for the case under study here. The small value of \( \lambda \) quoted above, incidentally, serves also to justify representing the radiation flux by Eq. (3.38). As pointed out in Sec. IIIB, the validity of that assumption depends on the condition \( \lambda \ll \ell_a \).

It was also suggested in Sec. IIIB that the condition \( \lambda \ll \ell_a \) should imply that the properties of the arc are nearly independent of the temperature at the projectile surface. This assertion was used to justify employing the boundary condition in Eq. (3.39) to determine the surface temperature. To check the validity of the assertion, we have performed the calculation holding the projectile surface at some different temperature and observed little change in the results. In fact, although we lowered the temperature at the surface by more than an order of magnitude from the value predicted in the original calculation, we observed negligible change in \( T \) within the interior of the arc. There was a substantial difference in the temperature within a mean free path or so of the boundary for the two calculations, but this difference is of little practical importance.

One of the least satisfactory aspects of the present calculation is the reliance on Eqs. (4.15) and (4.17) for the conductivity and mean free path for the arc. As pointed out, the derivation of Eq. (4.17) is based on the hydrogenic approximation and the resulting expression is probably accurate to within no better than an order of magnitude. Furthermore, the theory used to develop Eq. (4.15) is known to break down for high electron densities and low temperatures. For the cases under study here, we are probably very near, if not beyond, the limit of validity of the theory. Experiments, however, have suggested that Eq. (4.15) may be more generally applicable than would be expected on purely theoretical grounds. At any rate, future attempts to determine more accurate expressions for these quantities, or to establish more firmly the validity of existing ones, would be desirable.

It may be mentioned, incidentally, that a modification to Eq. (4.15) has been derived for the case in which conduction takes place normal to a strong magnetic field. The revised expression accounts for the tendency of the electrons to spiral in such a field, reducing the conductivity. Since the fields under consideration here are quite large, it might appear that the modified conductivity would be appropriate. It must be remembered, however, that the density is also quite large over most of the arc and, thus, the mean free path is small. Therefore, the spiralling effect is substantially reduced. Quantitatively, the condition which must be satisfied in order to use the high-field conductivity is that the electron gyration radius be small compared to its mean free path. Our estimates indicate, however, that the ratio of these two parameters is 10 or greater except very near the trailing edge of the arc. Therefore, the use of Eq. (4.15), without the high-field approximation, is justified. This point has been discussed further by McNab.

The foregoing discussion makes clear the need for some specific future studies. First, it would be worthwhile to extend the calculations to two or three dimensions. As pointed out previously, the one-dimensional model probably overestimates the temperature of the arc, and does not account for any spatial variation of the flow parameters in directions normal to the acceleration direction. In addition, use of infinitely high rails overestimates the inductance per unit length of the rails and is responsible, in part, for the relatively high theoretical value for the acceleration obtained in Sec. IV.C. Second, some consideration of time-dependent effects would be worthwhile, if only to better justify the steady-state assumption. Third, it would be of interest to carry out the calculations for arcs other than the copper-vapor arc studied here. From such investigations we could determine how the properties of the arc material affect the overall arc dynamics and which arcs produce the most desirable effects. Finally, some effort should be expended to determine the amount of heat transferred to the rails. When compared to the results for more conventional guns, the analysis should provide a preliminary step in the study of gun-tube erosion for the rail gun.

ACKNOWLEDGMENT

We thank D. Eccleshall and A. Gauss for useful discussions.

REFERENCES


8. Authors' unpublished calculations.


10. Authors' unpublished calculations.


14. See Ref. 13, Chap. 3.


APPENDIX

The purpose of this appendix is to prove the statement made in Sec. III that the acceleration of the arc and projectile is independent of how the current is distributed in the arc and is given by

\[
a = \frac{\mu j^2}{2\left(\rho_a + \rho_p \frac{k}{a}\right)}.
\]

(A.1)

From Eqs. (3.5) and (3.29) we have

\[
a = \frac{\mu k}{\rho_a + \rho_p \frac{k}{a}} \int_0^1 J(\xi) \left[ \int_0^1 J(\xi') d\xi' \right] d\xi.
\]

(A.2)

Now define the function

\[
u(\xi) = \int_\xi^1 J(\xi)d\xi
\]

and differentiate to produce

\[
\frac{du}{d\xi} = - J(\xi).
\]

(A.3)

(A.4)

Substituting Eqs. (A.3) and (A.4) into Eq. (A.2), we find

\[
a = \frac{-\mu k^2}{\rho_a + \rho_p \frac{k}{a}} \int_0^1 u \frac{du}{d\xi} d\xi,
\]

(A.5)

whence

\[
a = \frac{-\mu k^2}{2\left(\rho_a + \rho_p \frac{k}{a}\right)} \left[u^2(1) - u^2(0)\right].
\]

(A.6)

However, according to Eq. (3.16), u(0) = \frac{j}{k a}, whereas u(1) = 0, so

\[
a = \frac{\mu j^2}{2\left(\rho_a + \rho_p \frac{k}{a}\right)}.
\]

(A.7)
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