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August 1970  
Report 1341-26F

APPLICATIONS OF CUMULATIVE DAMAGE IN THE PREPARATION  
OF PARAMETRIC GRAIN DESIGN CURVES AND THE  
PREDICTION OF GRAIN FAILURES ON PRESSURIZATION

FINAL REPORT

1 April 1969 through 28 February 1970

VOLUME II - APPENDICES A THROUGH M

By

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J. D. McConnell

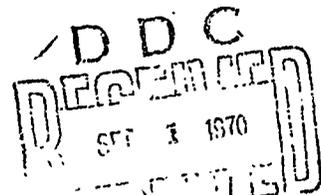
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Sacramento, California

and

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Prepared For

Department of the Navy  
Naval Ordnance Systems Command (ORD-0331)  
Contract No. N00017-69-C-4423



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APPLICATIONS OF CUMULATIVE DAMAGE IN THE PREPARATION  
OF PARAMETRIC DESIGN CURVES AND THE PREDICTION OF  
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VOLUME II - APPENDICES A THRU M

PREPARED FOR

DEPARTMENT OF THE NAVY  
NAVAL ORDNANCE SYSTEMS COMMAND (ORD-0331)  
CONTRACT NO. N00017-69-C-4423

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Aerojet Solid Propulsion Company

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VOLUME II

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## APPENDICES

APPENDIX A

MODULUS DATA INPUT FOR THE COMPUTER

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Appendix A

MODULUS DATA INPUT FOR THE COMPUTER

The relaxation modulus was represented by a sixteen-term Prony series. This relation for the tensile modulus,  $E(t)$ , is

$$E(t) = A_0 + \sum_{i=1}^m A_i e^{-\beta_i t} \quad (A-1)$$

where  $A_0$ ,  $A_i$ , and  $\beta_i$  are constants.

For an incompressible material the relaxation modulus in shear,  $\mu(t)$ , is given by

$$\mu(t) = \frac{E(t)}{3} = \frac{A_c}{3} + \sum_{i=1}^m \frac{A_i}{3} e^{-\beta_i t} \quad (A-2)$$

The viscoelastic stress analyses requires the shear modulus representation.

The Prony series constants employed in the present parameter study are given in Table A-1, for the CTPB propellant, and in Table A-2, for the HTPB propellant.

To complete the viscoelastic description the time-temperature shift function,  $a_T$ , is required. Hence, also listed in Tables A-1 and A-2 are the logarithms of  $a_T$  at 12 different temperatures from  $-100^\circ$  to  $+200^\circ\text{F}$ , for the two referenced propellants.

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TABLE A-2

## MODULUS INPUT FOR THE HTPB PROPELLANT

Prony Series Parameters					
<u>Log (t/a<sub>T</sub>)</u> <u>(min)</u>	<u>E</u> <u>psi</u>	<u>β<sub>i</sub></u> <u>(hr<sup>-1</sup>)</u>	<u>A<sub>i</sub></u>	<u>A<sub>i</sub>/3</u>	<u>i</u>
			80	26.67	0
-8	10000	3 x 10 <sup>9</sup>	4376.65	1458.9	1
-7	7000	3 x 10 <sup>8</sup>	3697.78	1232.6	2
-6	4000	3 x 10 <sup>7</sup>	2056.49	685.50	3
-5	2400	3 x 10 <sup>6</sup>	896.865	298.96	4
-4	1600	3 x 10 <sup>5</sup>	665.701	221.90	5
-3	1050	3 x 10 <sup>4</sup>	384.337	128.11	6
-2	720	3 x 10 <sup>3</sup>	250.028	83.343	7
-1	500	3 x 10 <sup>2</sup>	180.589	60.196	8
0	350	3 x 10 <sup>1</sup>	106.550	35.517	9
1	260	3 x 10 <sup>0</sup>	67.0877	22.363	10
2	205	3 x 10 <sup>-1</sup>	35.8845	11.962	11
3	170	3 x 10 <sup>-2</sup>	39.3243	11.441	12
4	140	3 x 10 <sup>-3</sup>	24.4644	8.155	13
5	120	3 x 10 <sup>-4</sup>	15.1300	5.043	14
6	110	3 x 10 <sup>-5</sup>	-2.4636	-0.8212	15
7	100	3 x 10 <sup>-6</sup>	33.0018	11.001	16

## Time-Temperature Shift Function

<u>Temp., °F</u>	<u>Log<sub>10</sub> a<sub>T</sub></u>
-75	6.90
-50	4.93
-25	3.41
0	2.35
25	1.48
50	0.72
77	0
100	-0.46
125	-0.90
150	-1.24
170	-1.47

APPENDIX B  
PARAMETER STUDY FOR HISTORY 1

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APPENDIX B

PARAMETER STUDY FOR HISTORY 1

The results of a series of one-dimensional, thermoviscoelastic analyses are presented graphically in this appendix. All of the analyses were based upon the environmental temperature history described in the text and shown separately in each figure. The data for the CTPB propellant are presented in Figures B-1 to B-6, while those for the HTPB propellant are given in Figures B-7 to B-12.

No analyses of the results are made here.

A. CTPB PROPELLANT

The following graphs give the thermoviscoelastic solutions for these grain designs.

PARAMETER STUDY OF INNER-BORE HOOP STRAINS  
(CTPB PROPELLANT - HISTORY 1  
(B = 4 in.)

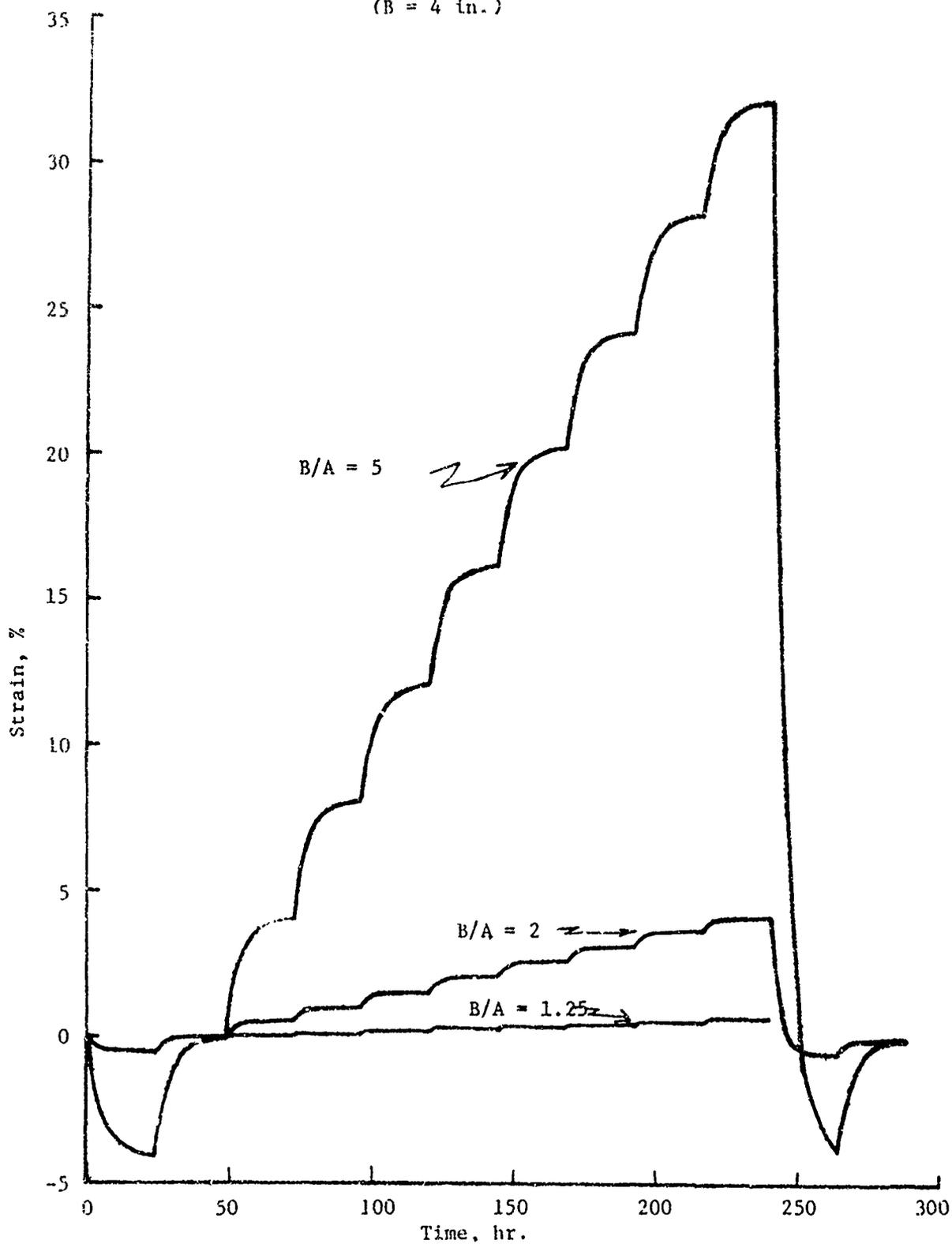


Figure B-1

PARAMETER STUDY OF INNER-BORE HOOP STRAINS  
CTPB PROPELLANT - HISTORY 1  
(B = 8 in.)

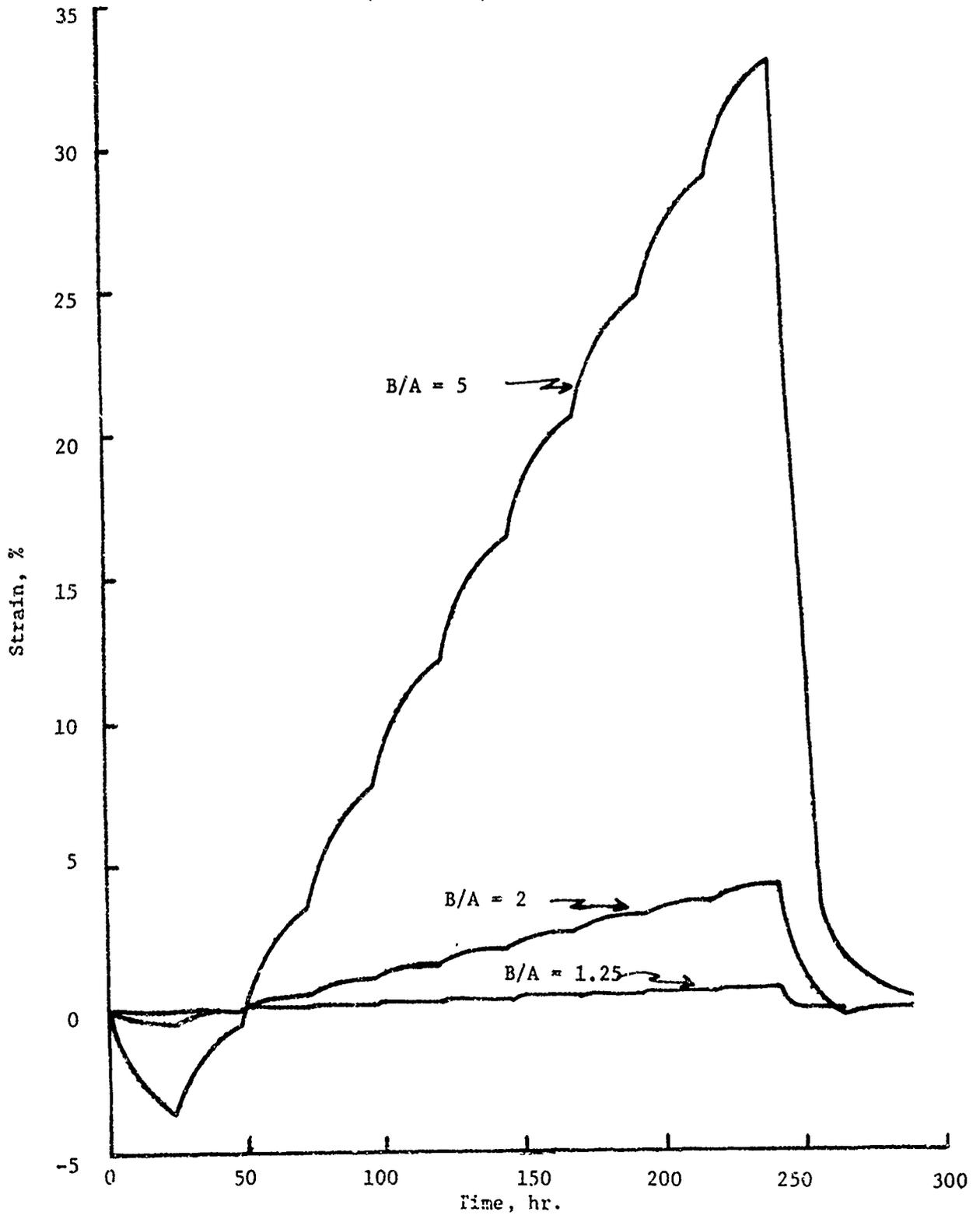
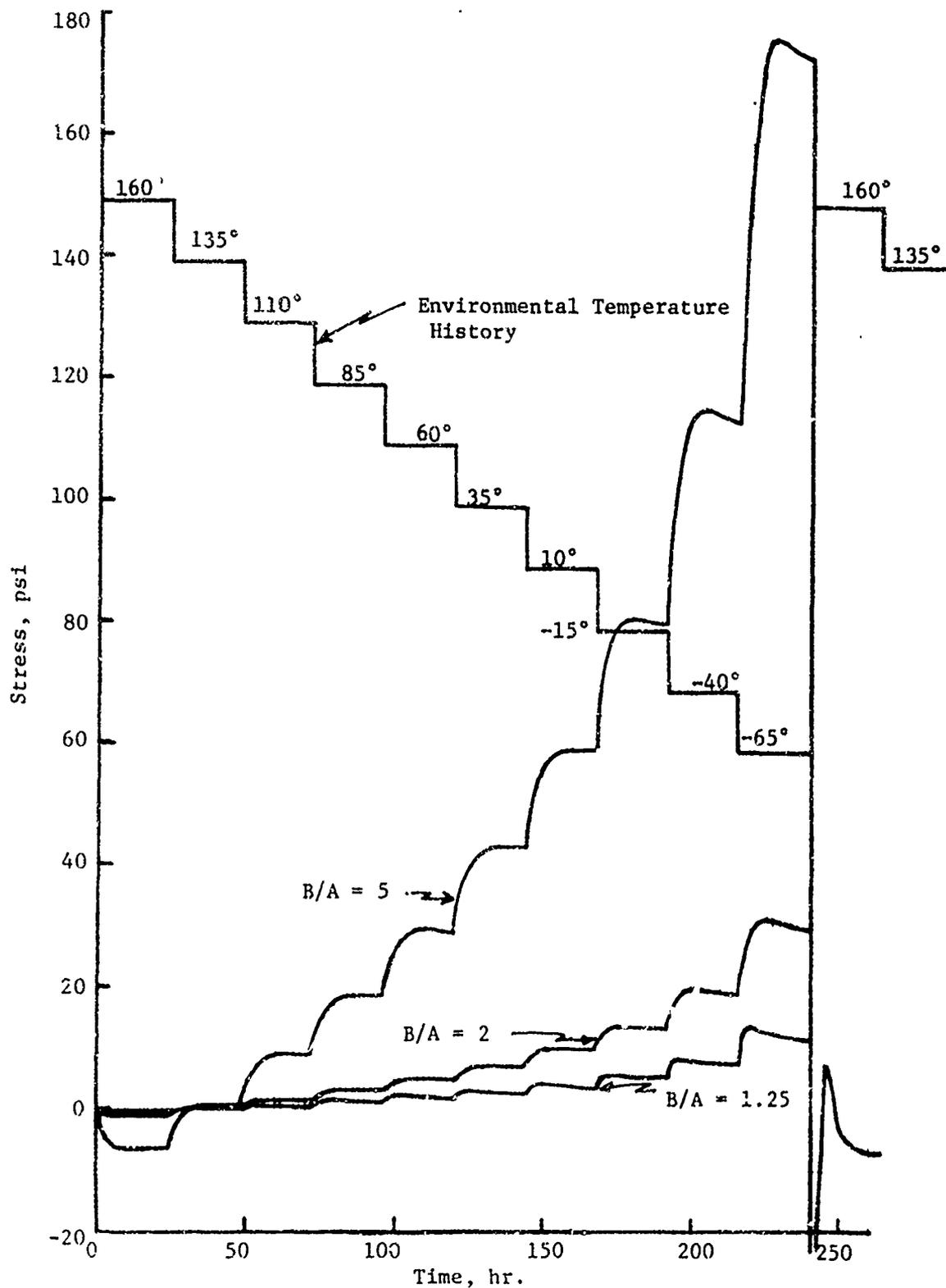


Figure B-2

PARAMETER STUDY OF INNER-BORE HOOP STRESS SOLUTIONS  
CTPB PROPELLANT - HISTORY 1  
(B = 4 in.)



PARAMETER STUDY OF INNER-BORE HOOP STRESS SOLUTIONS  
CTPB PROPELLANT - HISTORY 1  
(B = 8 in.)

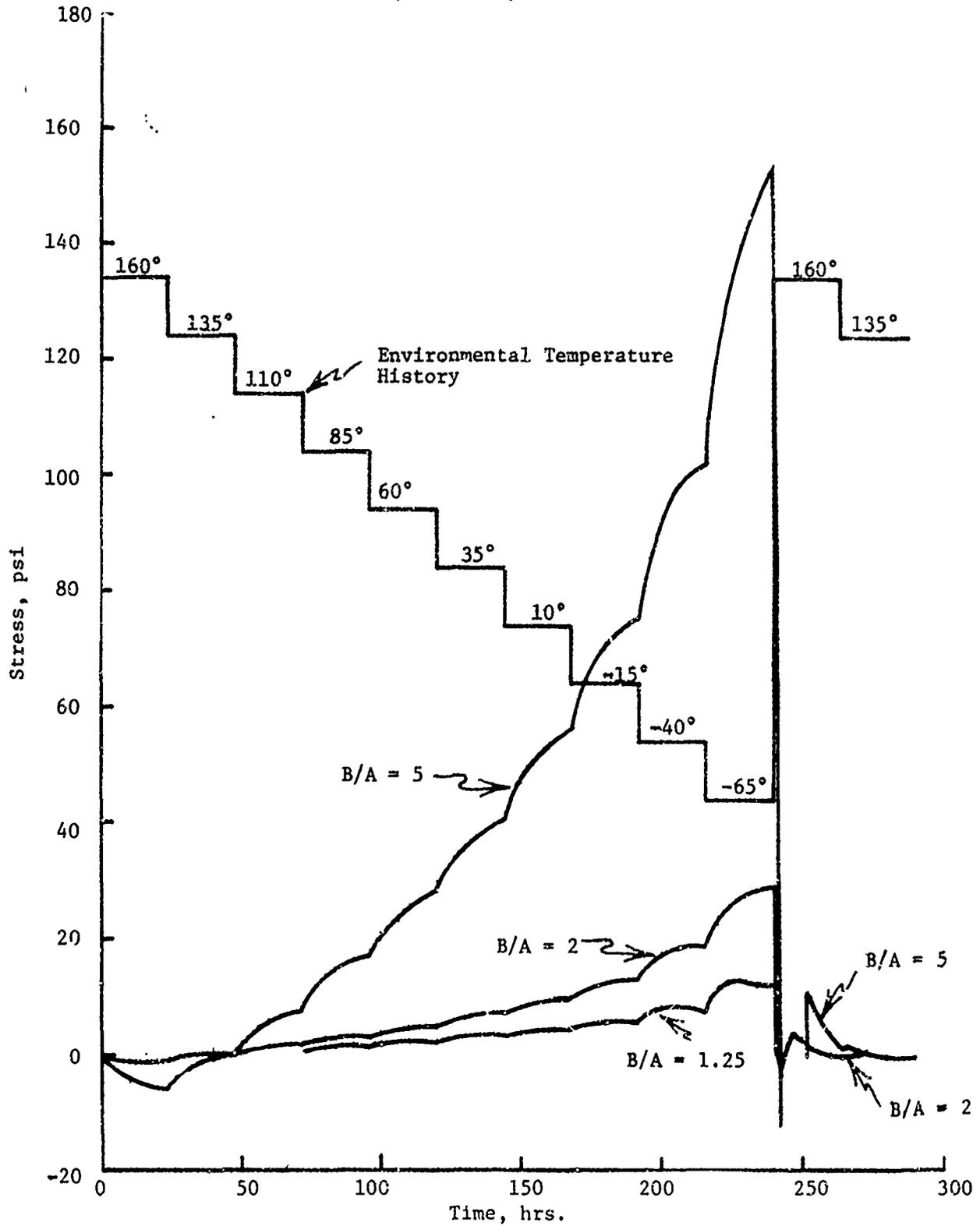


Figure B-4

PARAMETER STUDY OF RADIAL BOND STRESS SOLUTIONS  
CTPB PROPELLANT - HISTORY 1

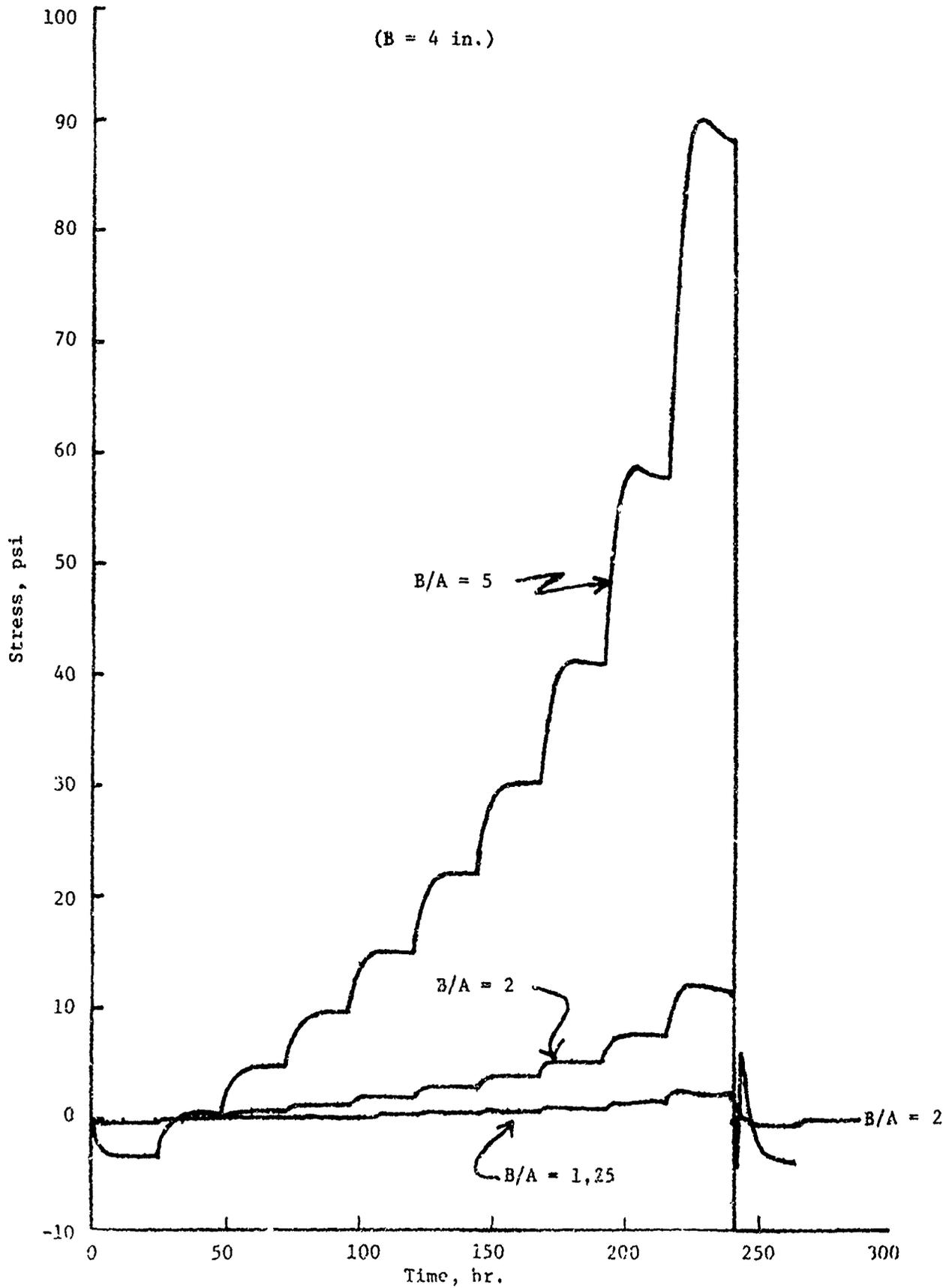


Figure B-5

PARAMETER STUDY OF RADIAL BOND STRESS SOLUTIONS  
CTPB PROPELLANT - HISTORY 1

(B = 8 in.)

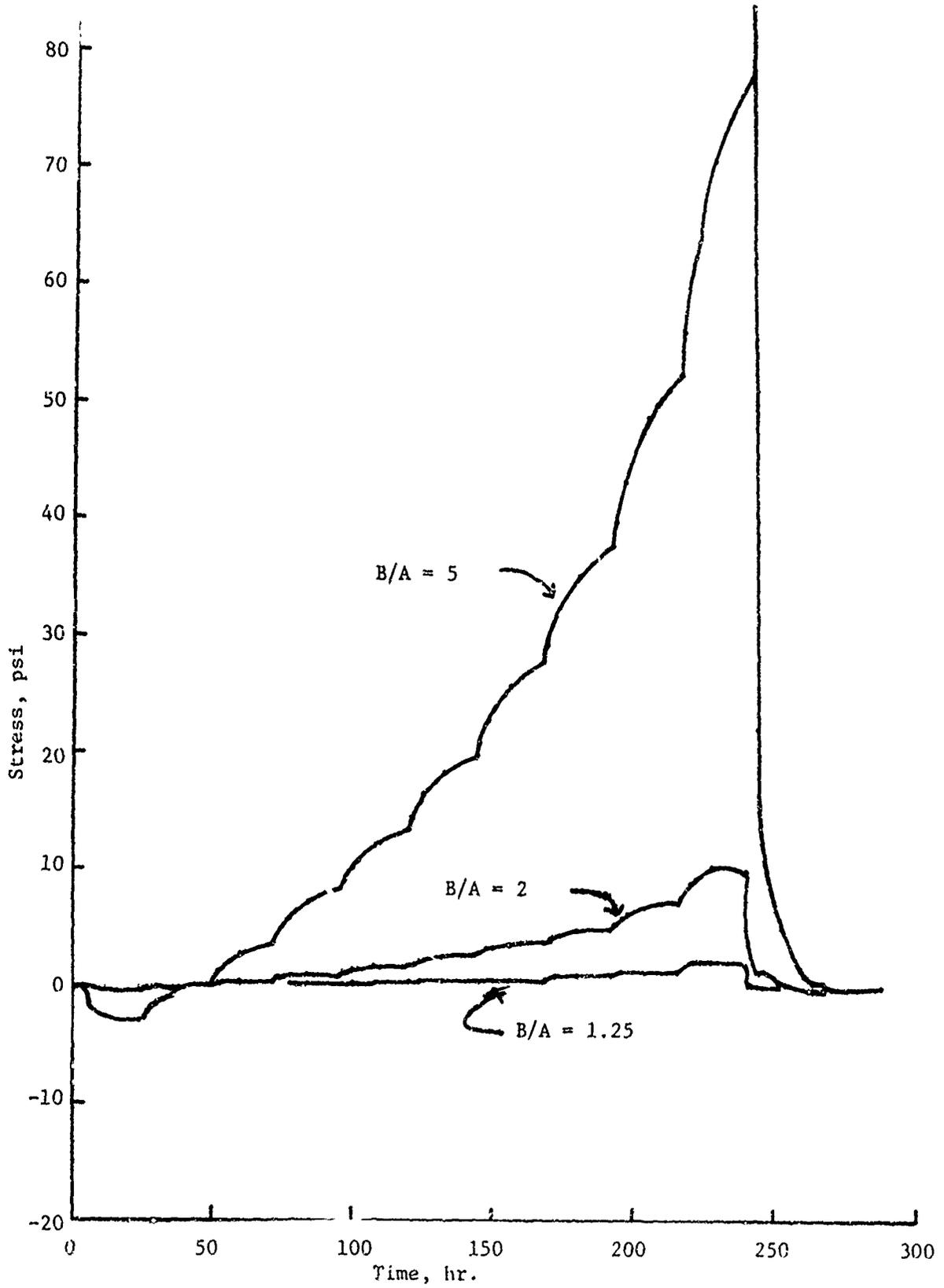


Figure B-6

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Appendix B

B. HTPB PROPELLANT

The following graphs give the thermoviscoelastic solutions for these grain designs.

PARAMETER STUDY OF INNER-BORE HOOP STRAINS  
HTPB PROPELLANT - HISTORY 1

(B = 4 in.)

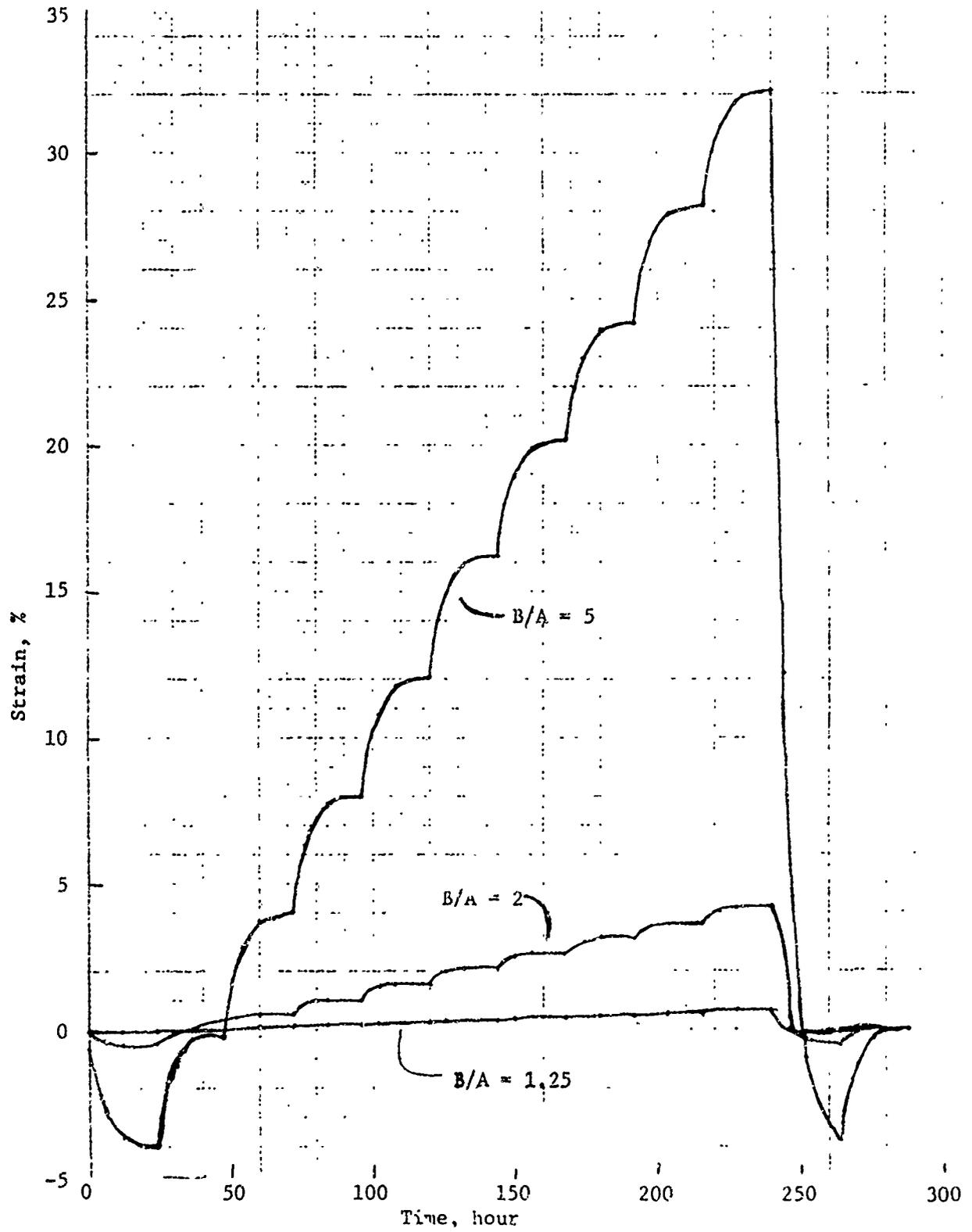


Figure B-7

PARAMETER STUDY OF INNER-BORE HOOP STRAINS  
HTPB PROPELLANT - HISTORY 1

Appendix B

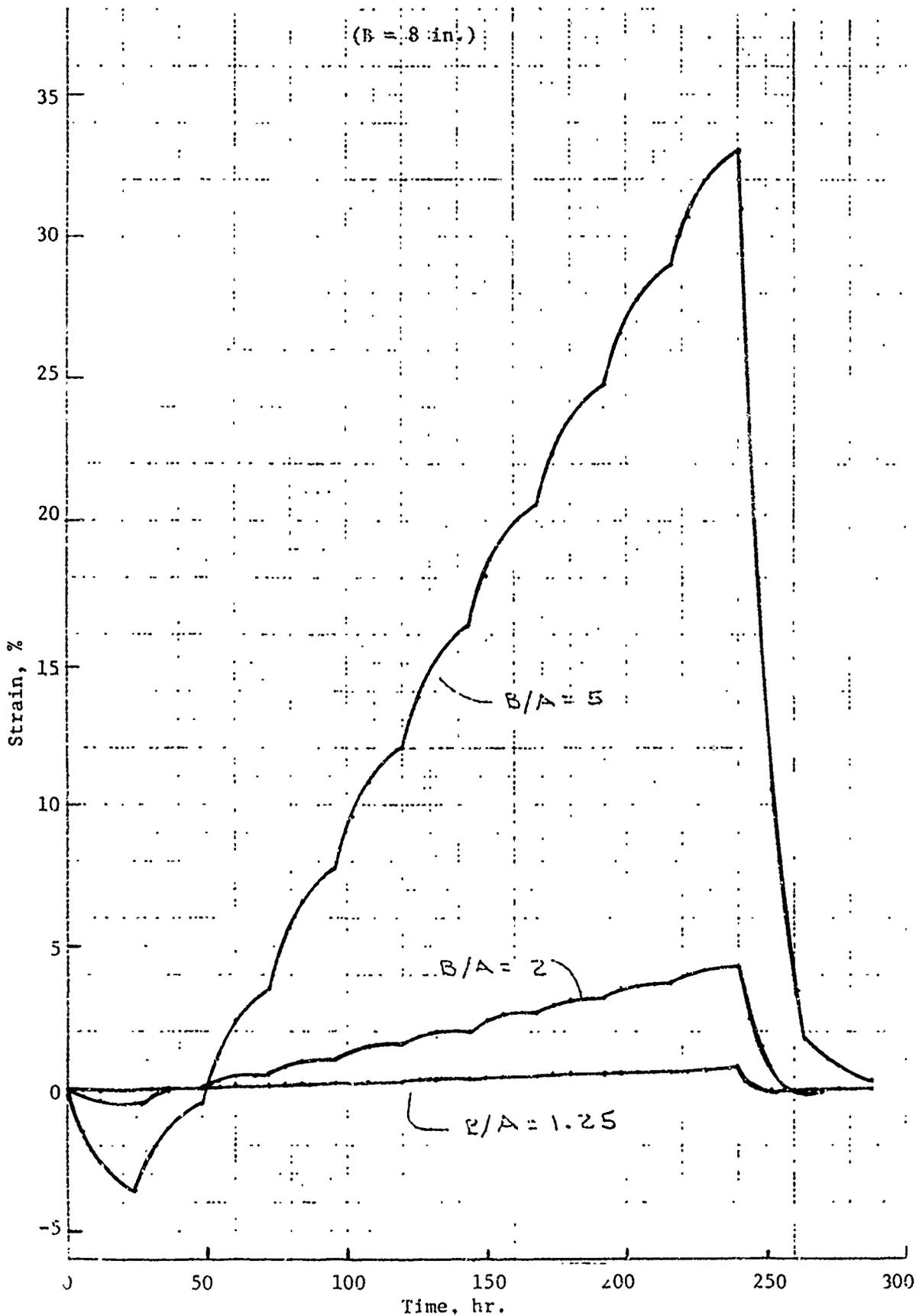


Figure B-8

PARAMETER STUDY OF INNER-BORE HOOP STRESS SOLUTIONS  
HTPB PROPELLANT - HISTORY 1

(B = 4 in.)

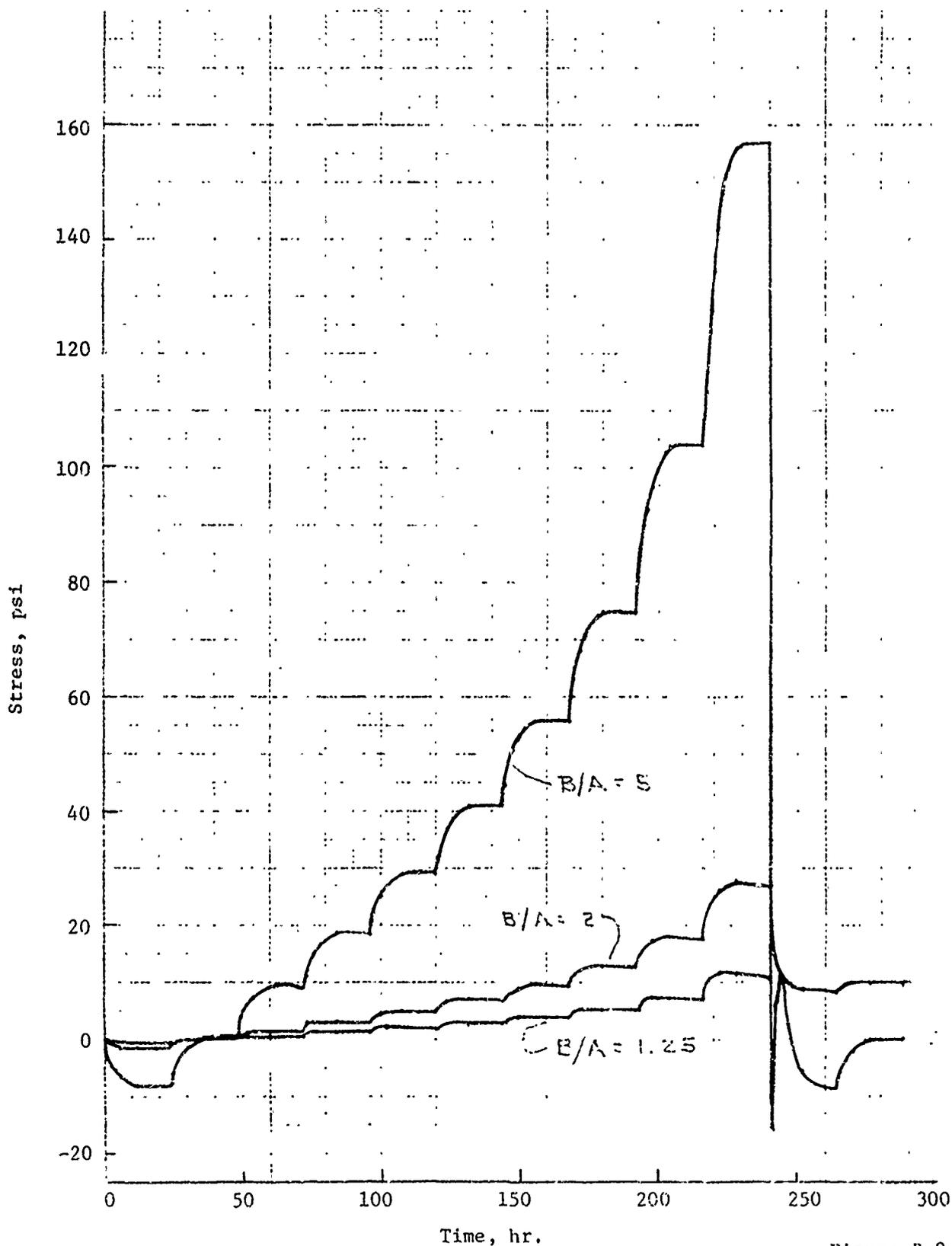


Figure B-9

PARAMETER STUDY OF INNER-BORE HOOP STRESS SOLUTIONS  
HTPB PROPELLANT - HISTORY 1  
(B = 8 in.)

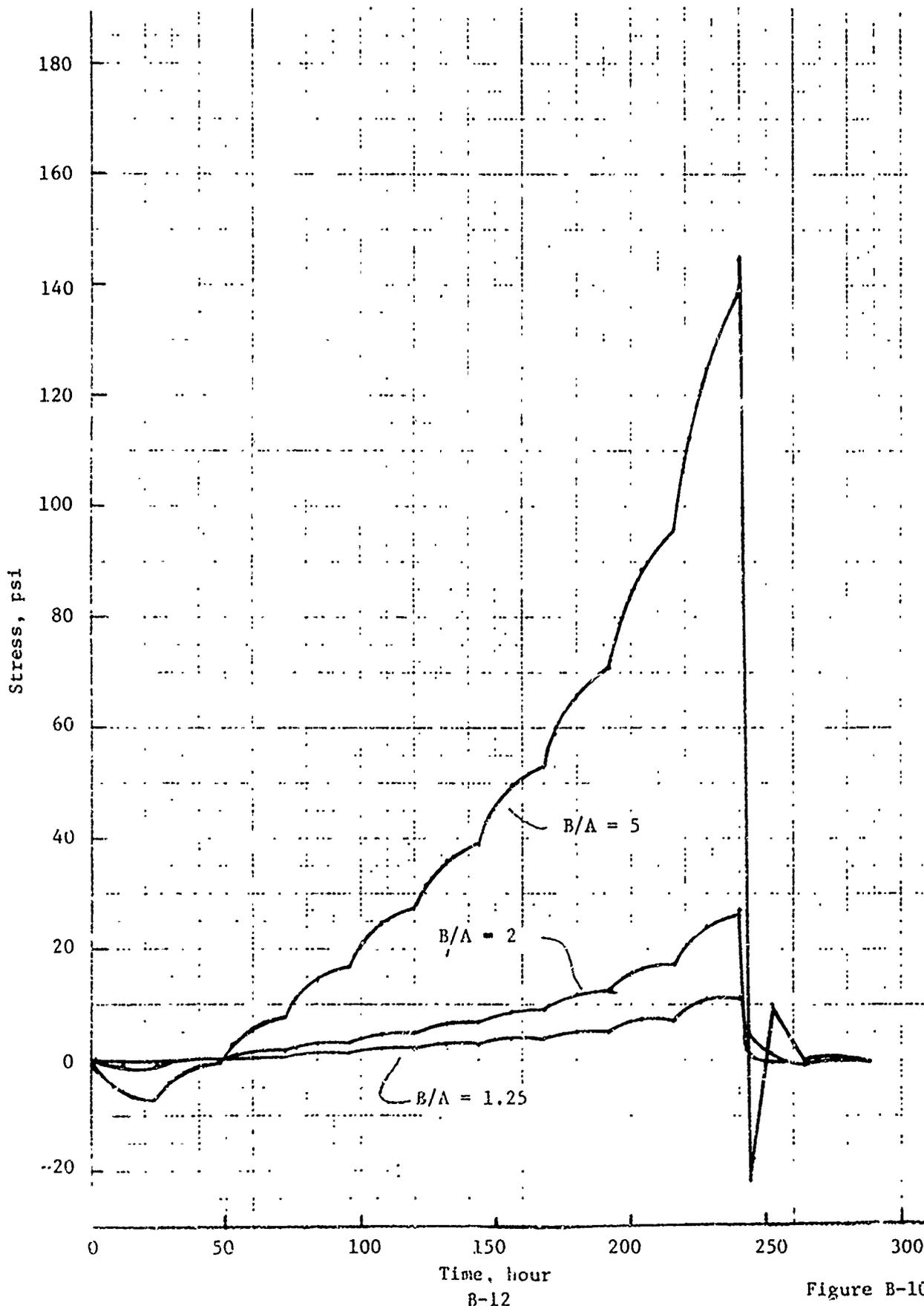
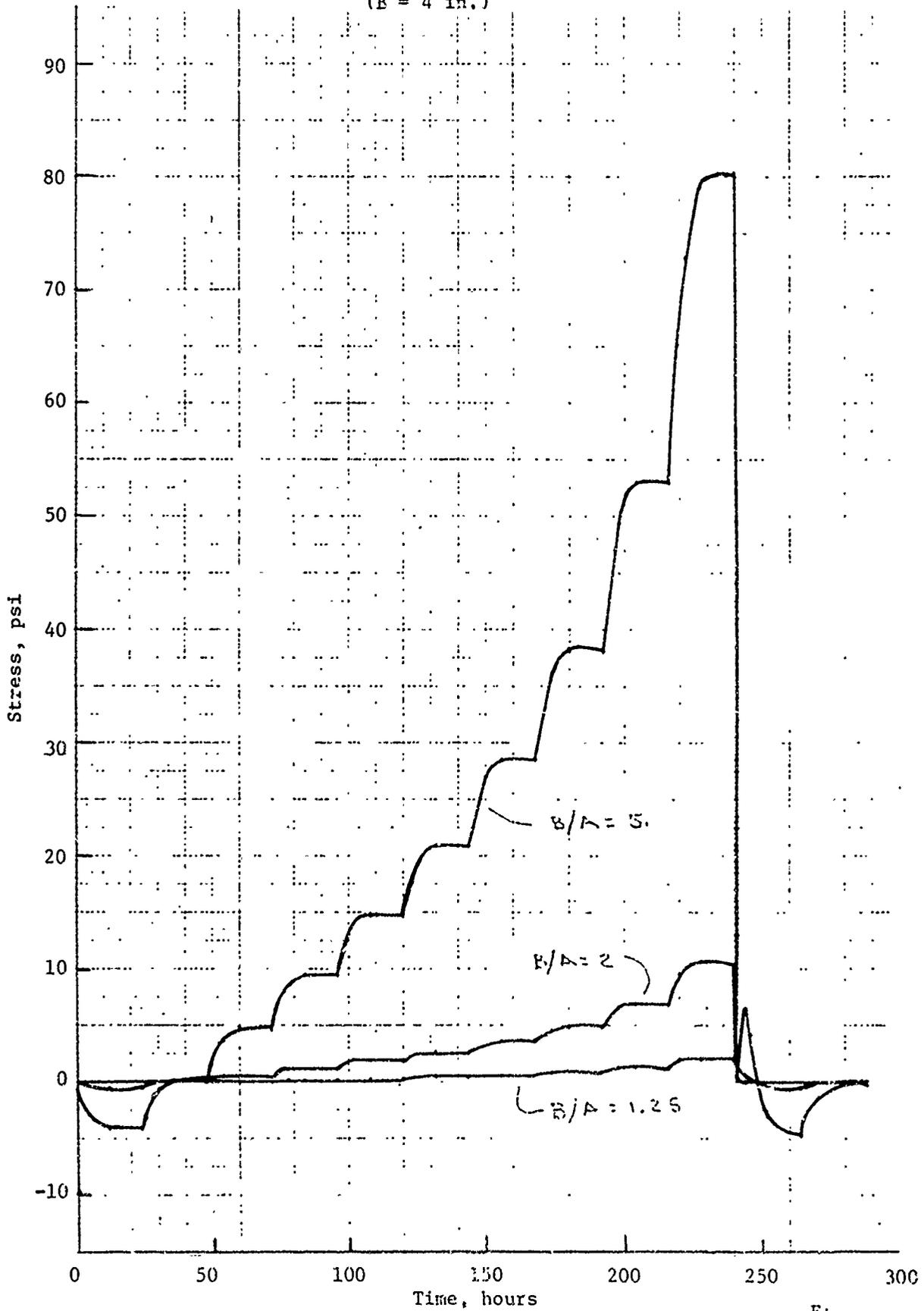
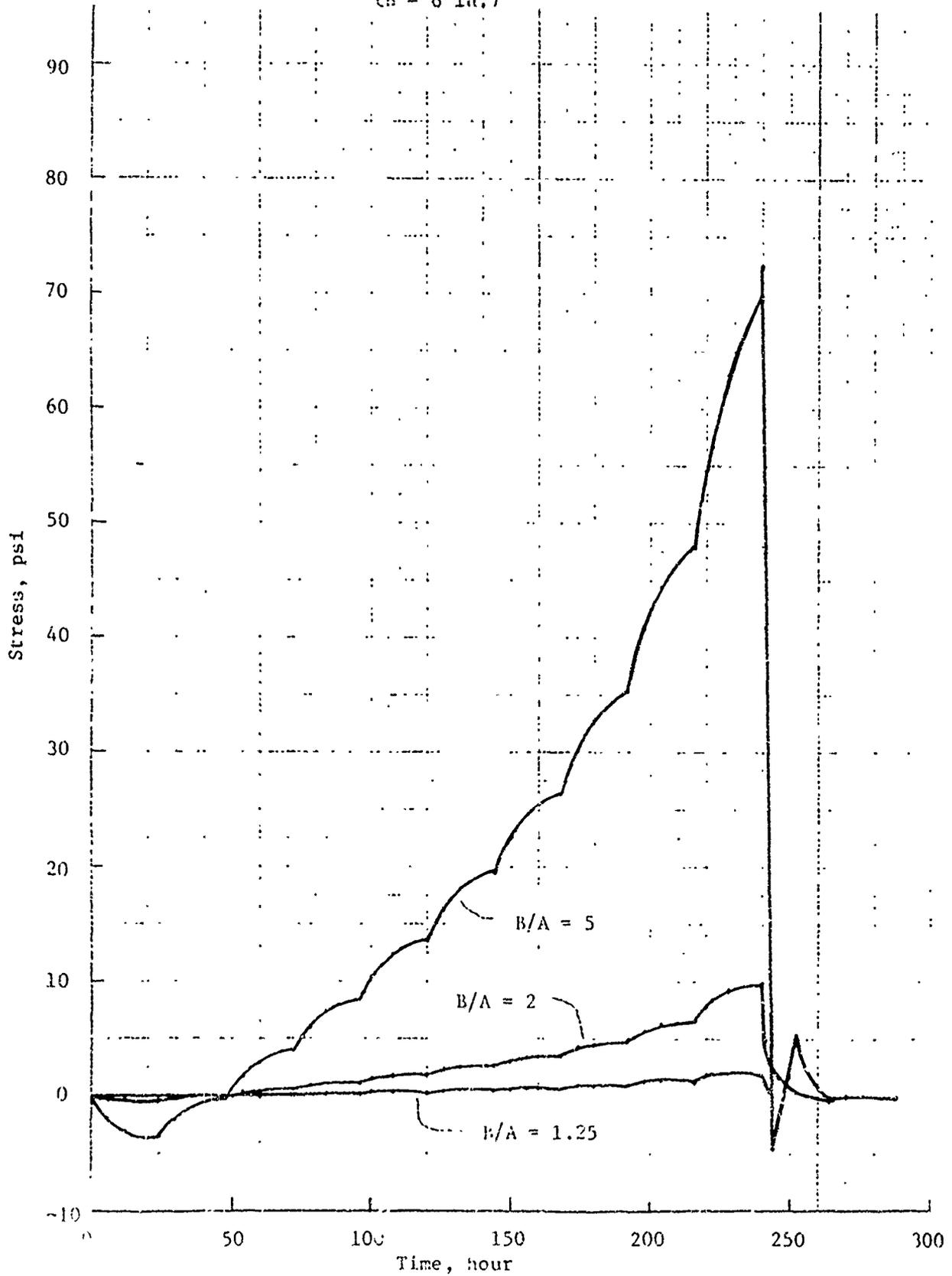


Figure B-10

PARAMETER STUDY OF RADIAL BOND STRESS SOLUTIONS  
HTPB PROPELLANT - HISTORY 1  
(B = 4 in.)



PARAMETER STUDY OF RADIAL BOND STRESS SOLUTIONS  
HTPB PROPELLANT - .. STORY 1  
(R = 8 in.)



APPENDIX C

PARAMETER STUDY FOR HISTORY 2

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APPENDIX C

PARAMETER STUDY FOR HISTORY 2

The results of a series of one-dimensional, thermoviscoelastic analyses are presented graphically in this appendix. All of the results were based upon the environmental temperature history described in the e text and shown separately in each figure. The data for the CTPB and HTPB propellants are presented separately.

No analyses of the results are made here.

A. CTPB PROPELLANT

The following graphs give the thermoviscoelastic solutions for these grain designs.

PARAMETER STUDY OF INNER-BORE HOOP STRAINS  
CTPB PROPELLANT - HISTORY 2

(B = 4 in.)

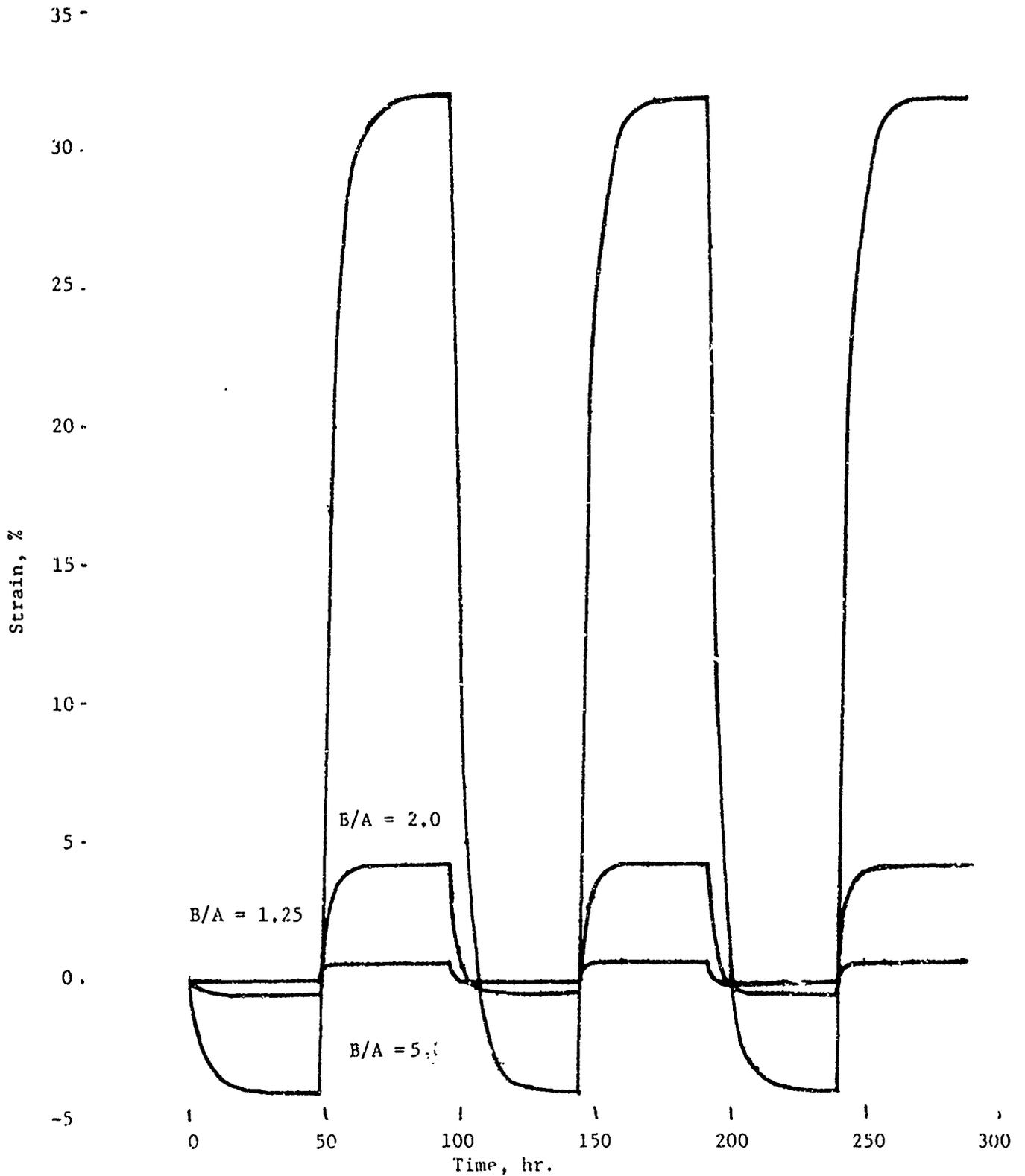


Figure C-1

PARAMETER STUDY OF INNER-BORE HOOP STRAINS  
CTPB PROPELLANT - HISTORY 2  
(B = 8 in.)

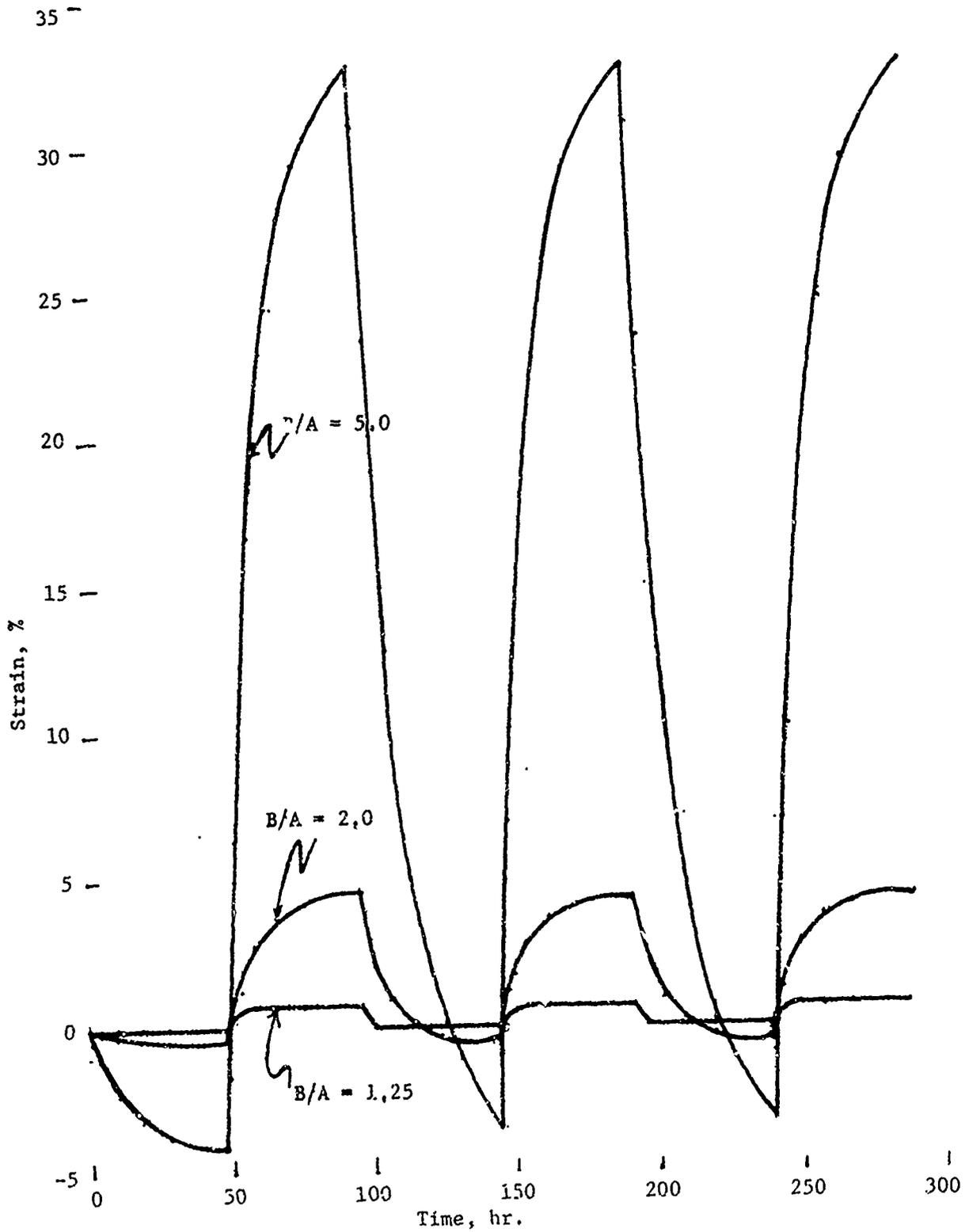


Figure C-2

PARAMETER STUDY OF INNER-BORE HOOP STRESS  
CTPB PROPELLANT - HISTORY 2

(B = 4 in.)

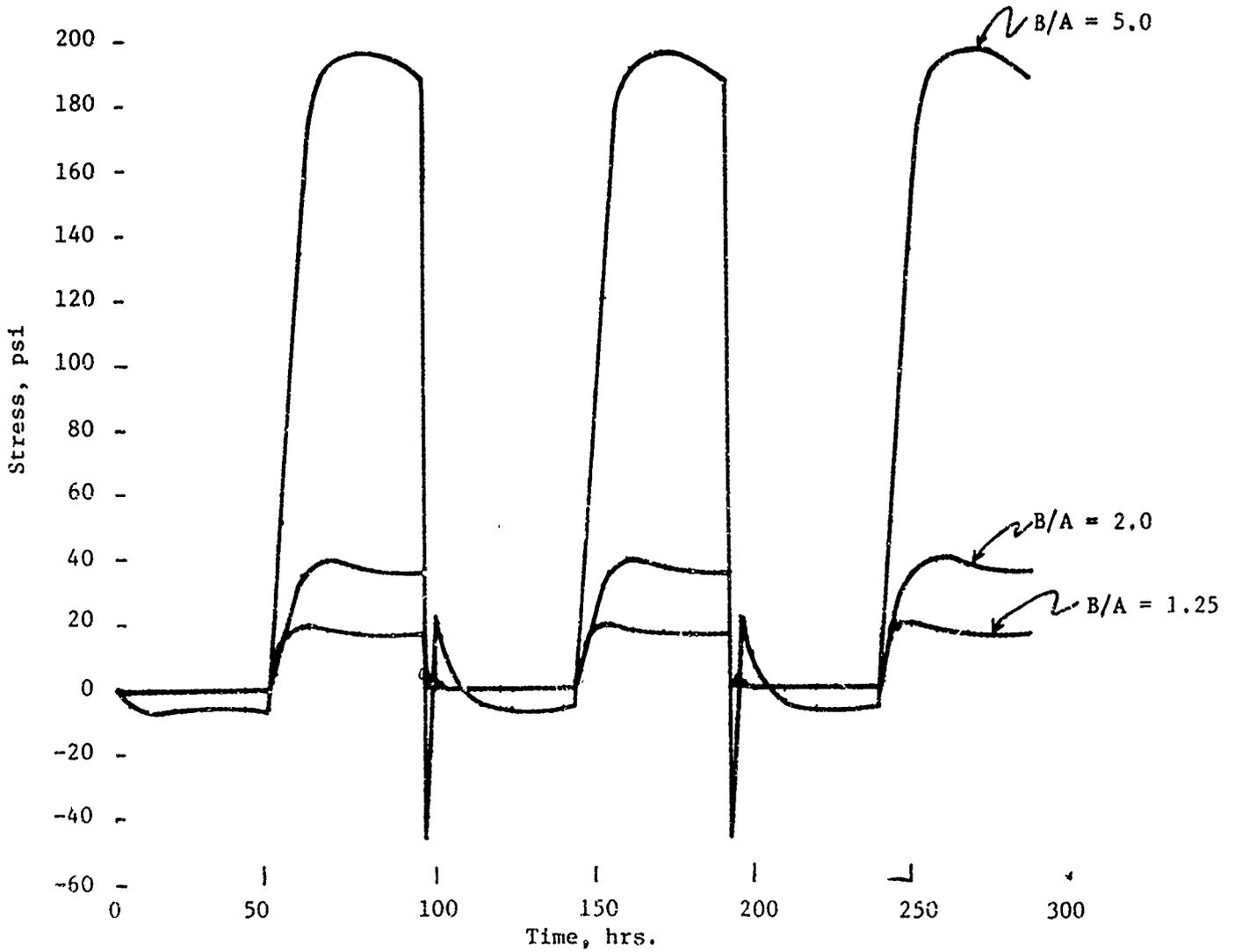


Figure C-3

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Appendix C

PARAMETER STUDY OF INNER-BORE HOOP STRESS  
CTPB PROPELLANT - HISTORY 2

(B = 8 in.)

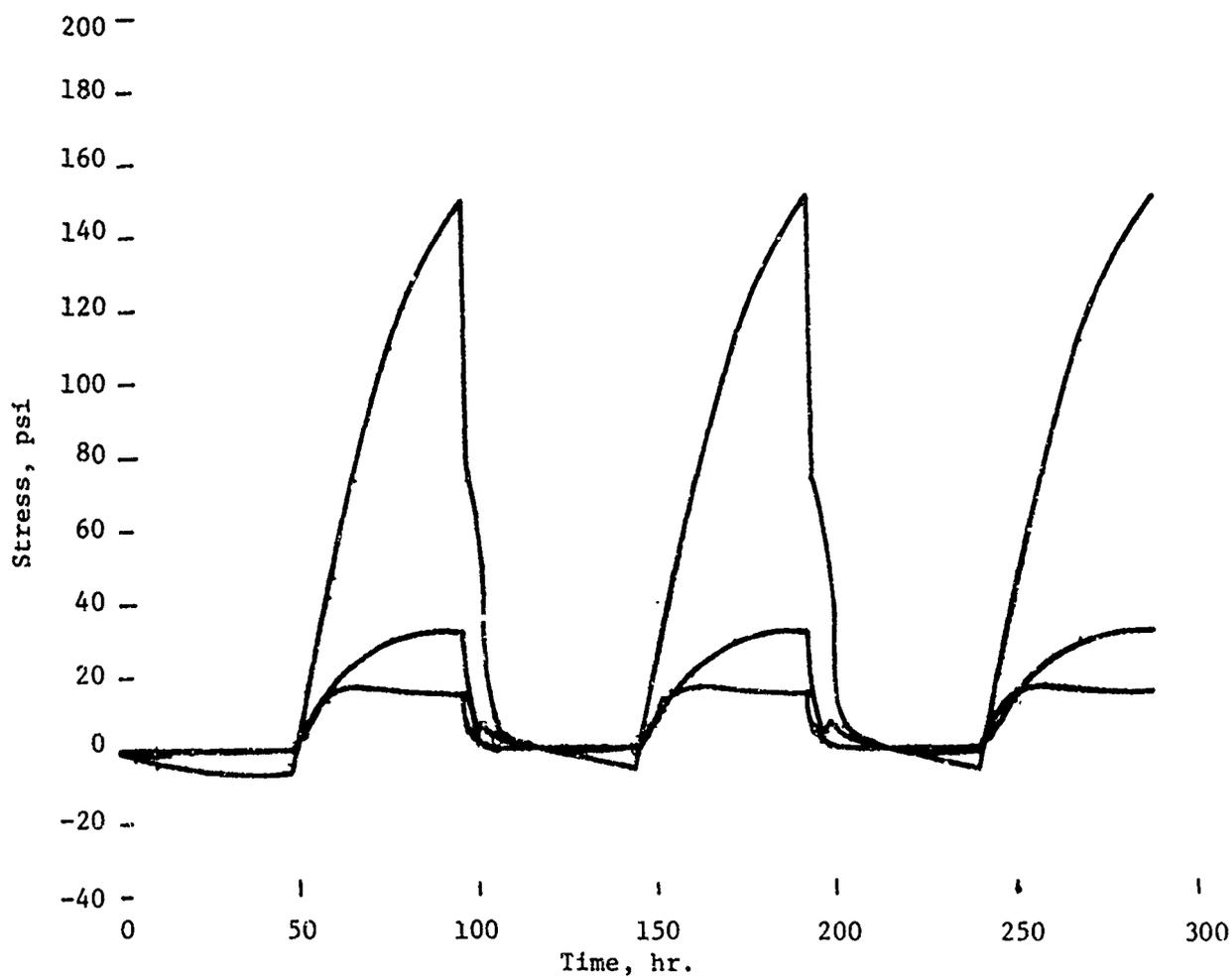


Figure C-4

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Appendix C

PARAMETER STUDY OF RADIAL BOND STRESS SOLUTIONS  
CTPB PROPELLANT - HISTORY 2

(B = 4 in.)

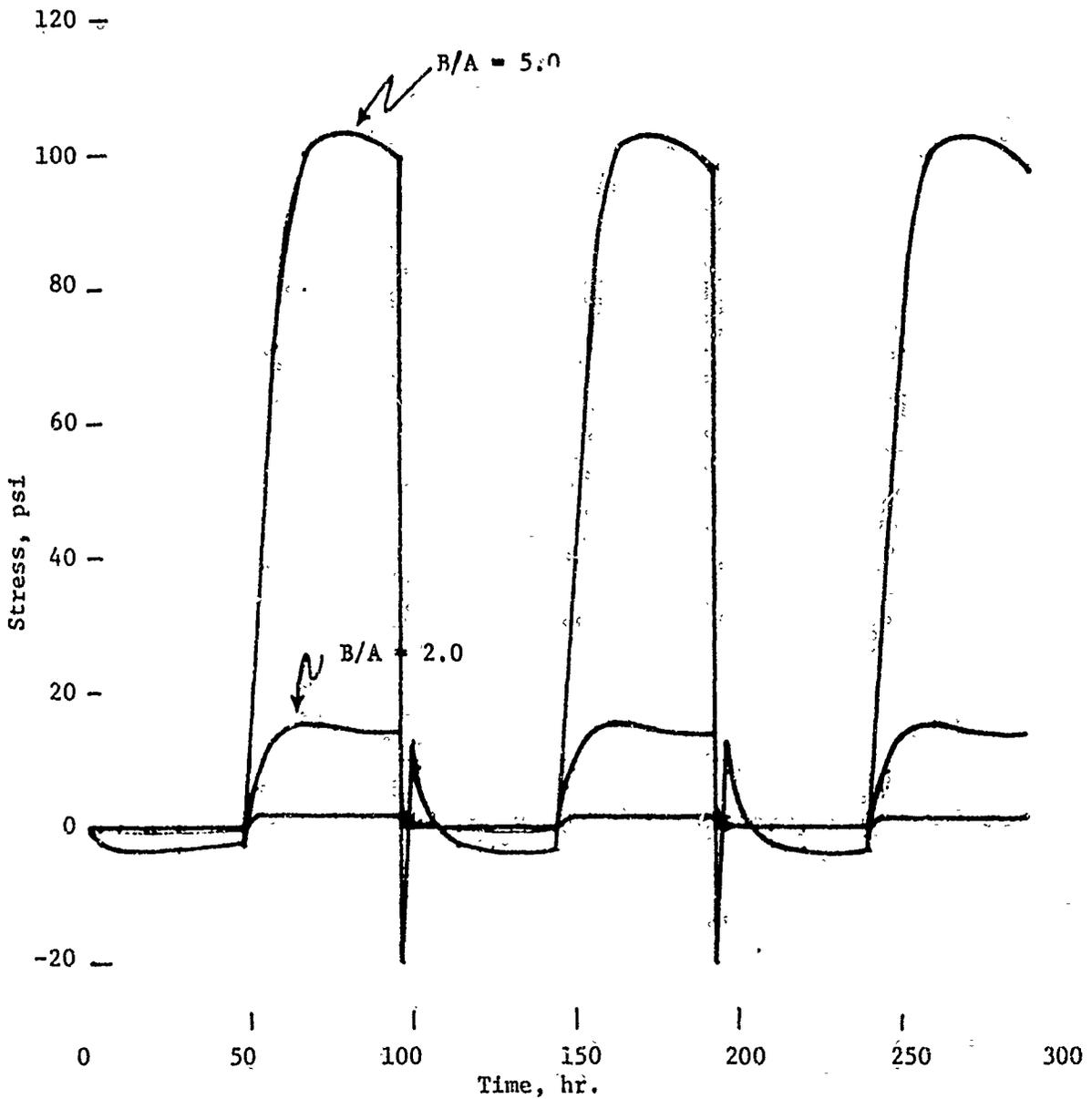


Figure C-5

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Appendix C

PARAMETER STUDY OF RADIAL BOND STRESS SOLUTIONS  
CTPB PROPELLANT - HISTORY 2

(B = 8 in.)

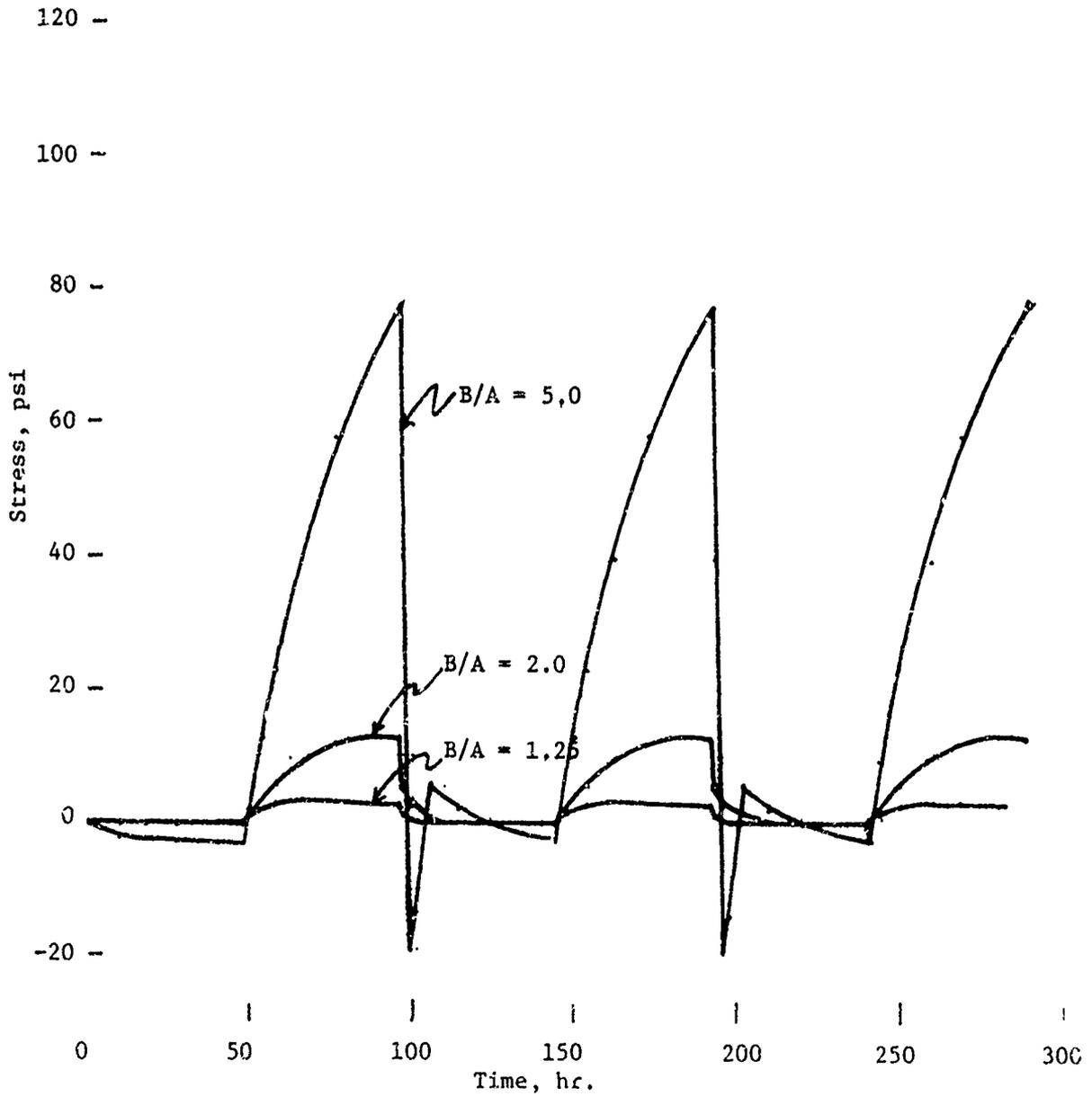


Figure C-6

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Appendix C

B. HTPB PROPELLANT

The following graphs give the thermoviscoelastic solutions for these grain designs.

PARAMETER STUDY OF INNER-BORE HOOP STRAINS  
HTPB PROPELLANT - HISTORY 2

(B = 4 in.)

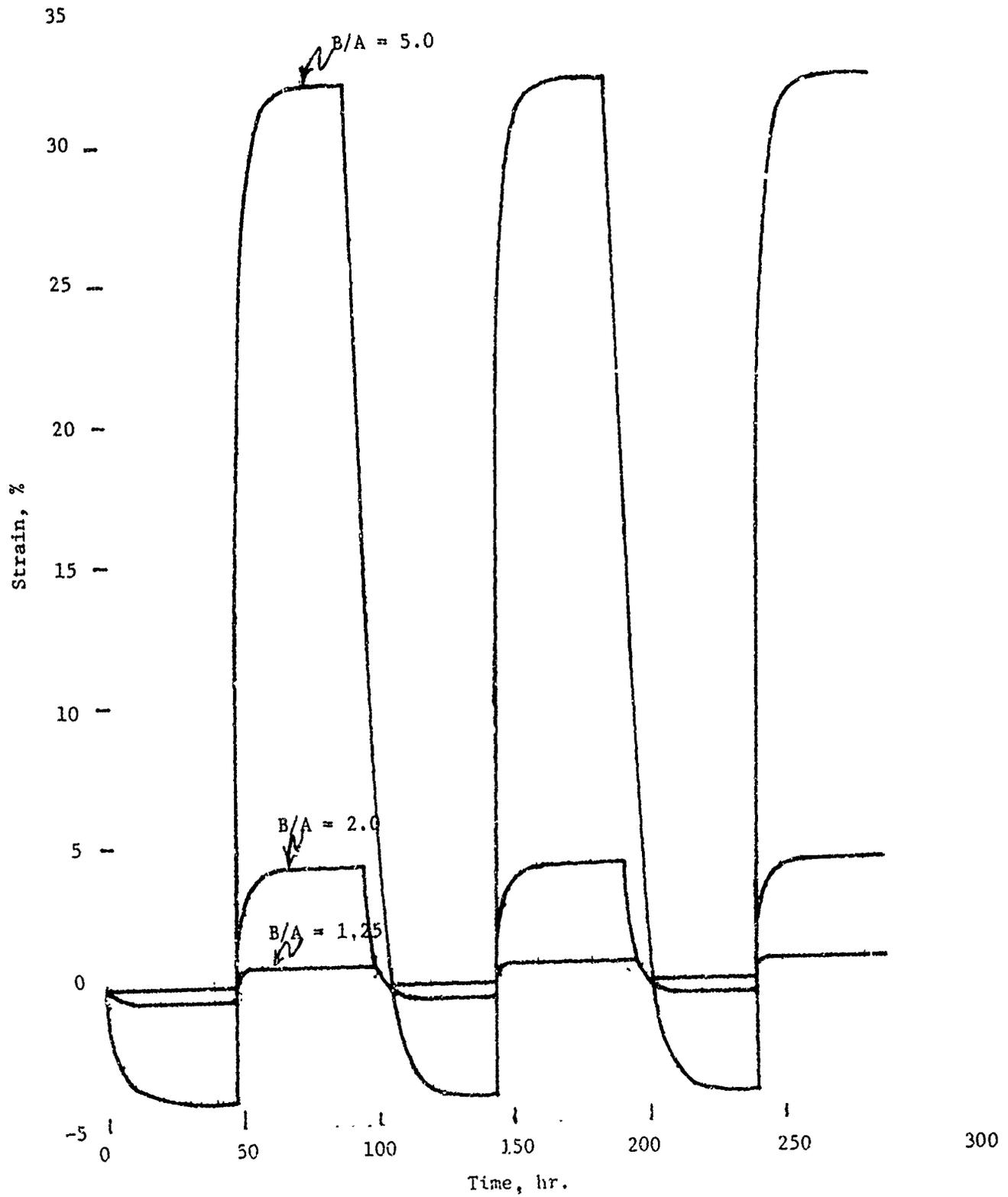


Figure C-7

PARAMETER STUDY OF INNER-BORE HOOP STRAINS  
HTPB PROPELLANT - HISTORY 2

(B = 8 in.)

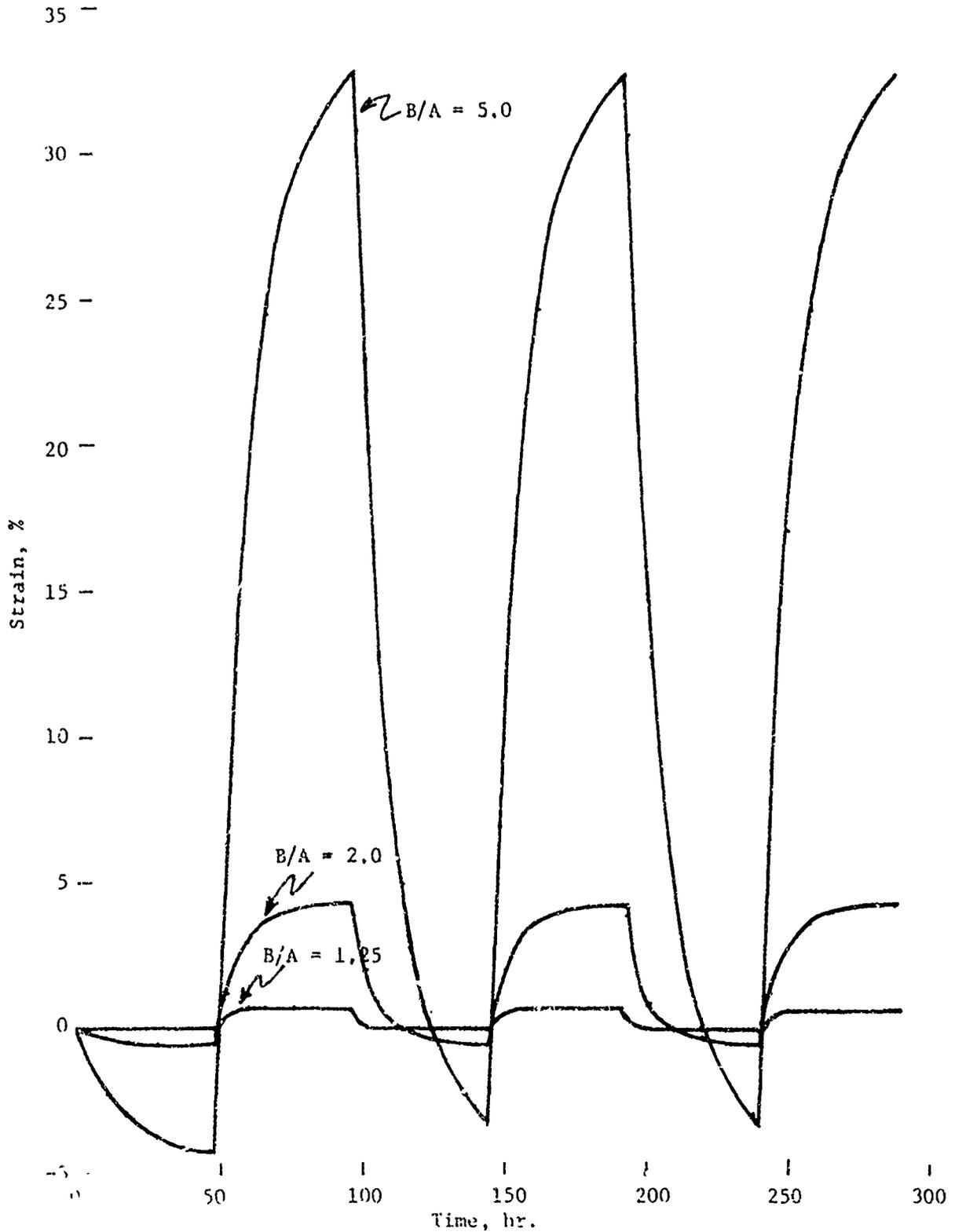


Figure C-8

PARAMETER STUDY OF INNER-BORE HOOP STRESS SOLUTIONS  
HTPB PROPELLANT - HISTORY 2

(B = 4 in.)

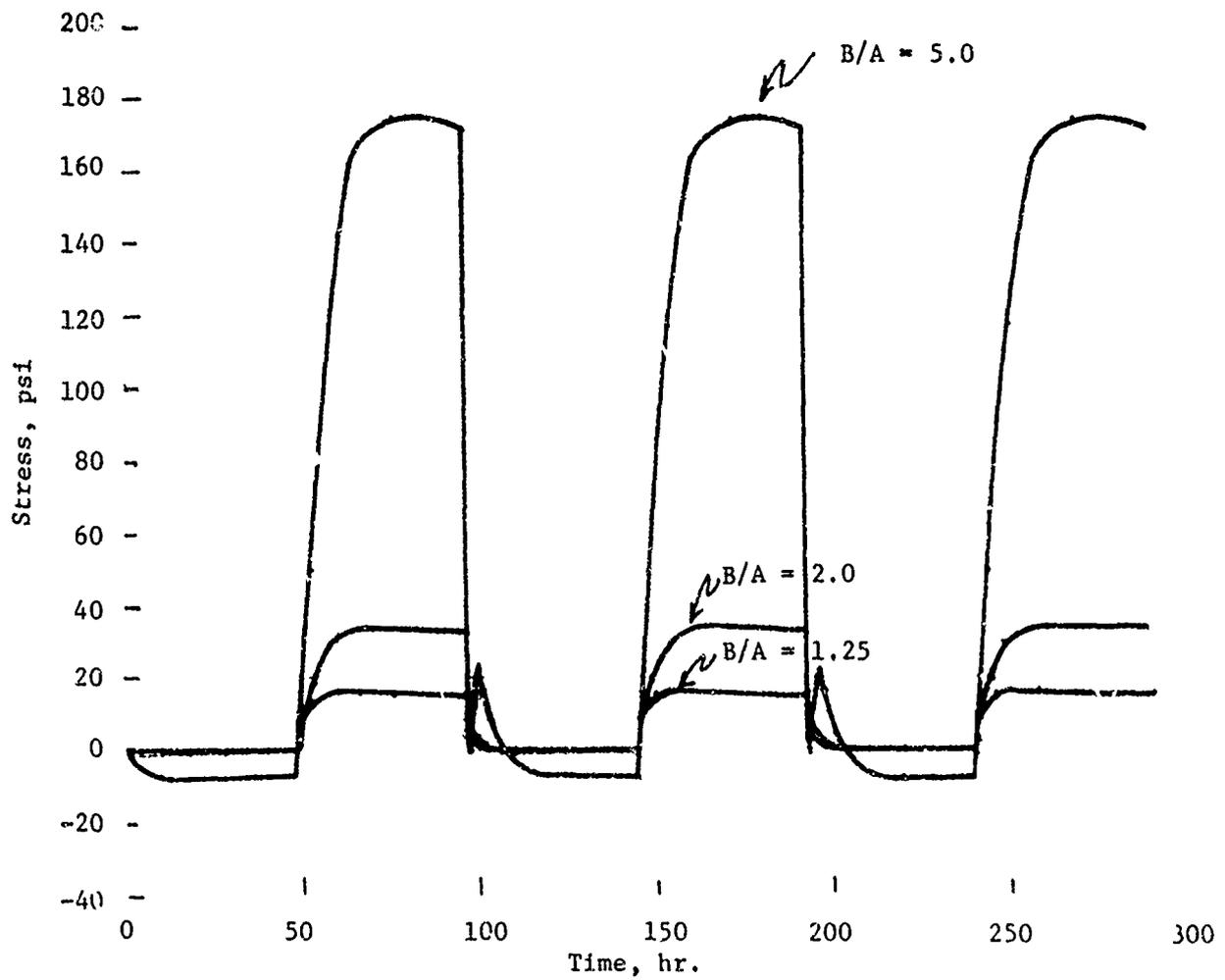
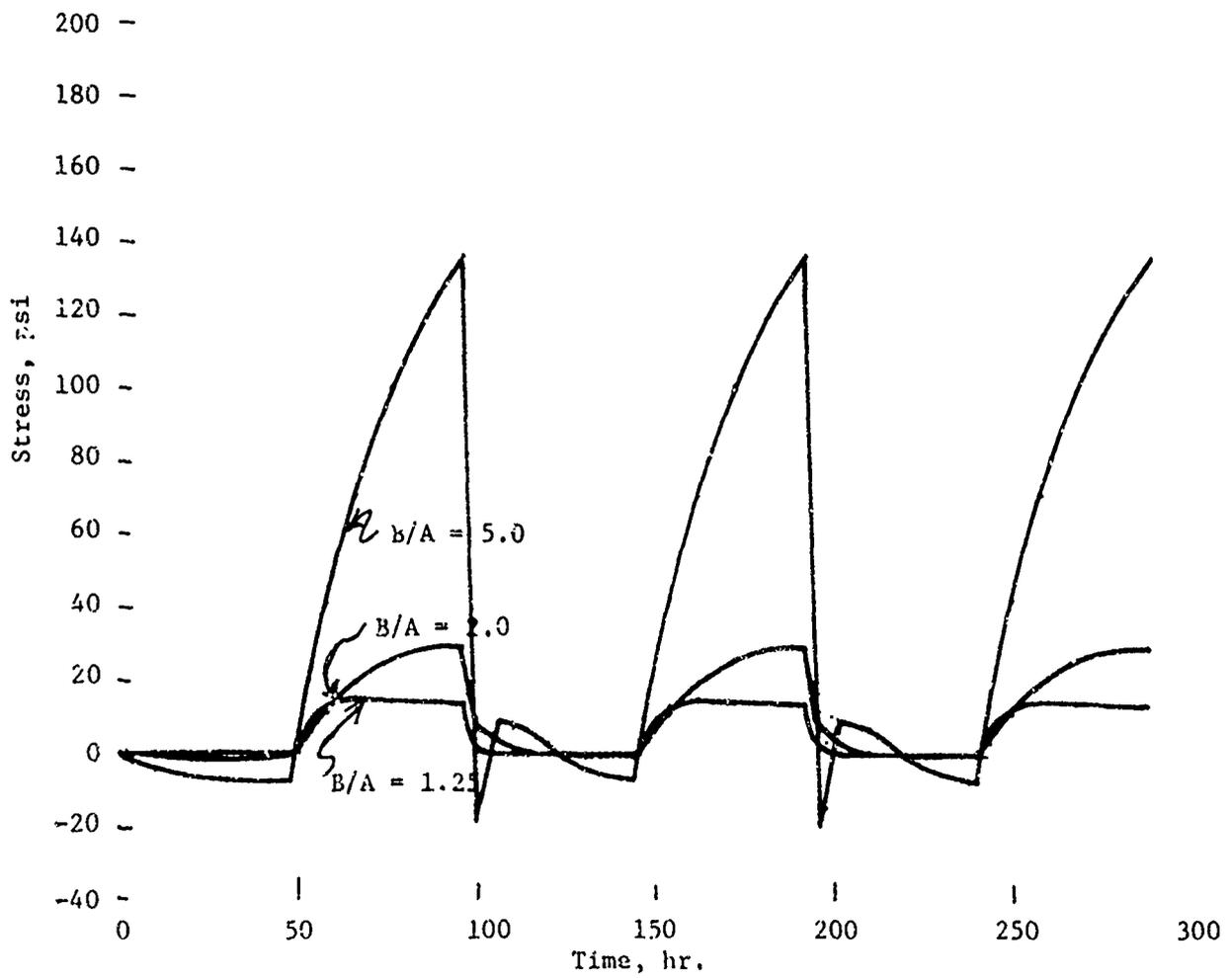


Figure C-9

PARAMETER STUDY OF INNER-BORE HOOP STRESS SOLUTIONS  
HTPB PROPELLANT - HISTORY 2

(B = 8 in.)



PARAMETER STUDY OF RADIAL BOND STRESS SOLUTIONS  
HTPB PROPELLANT - HISTORY 2

(B = 4 in.)

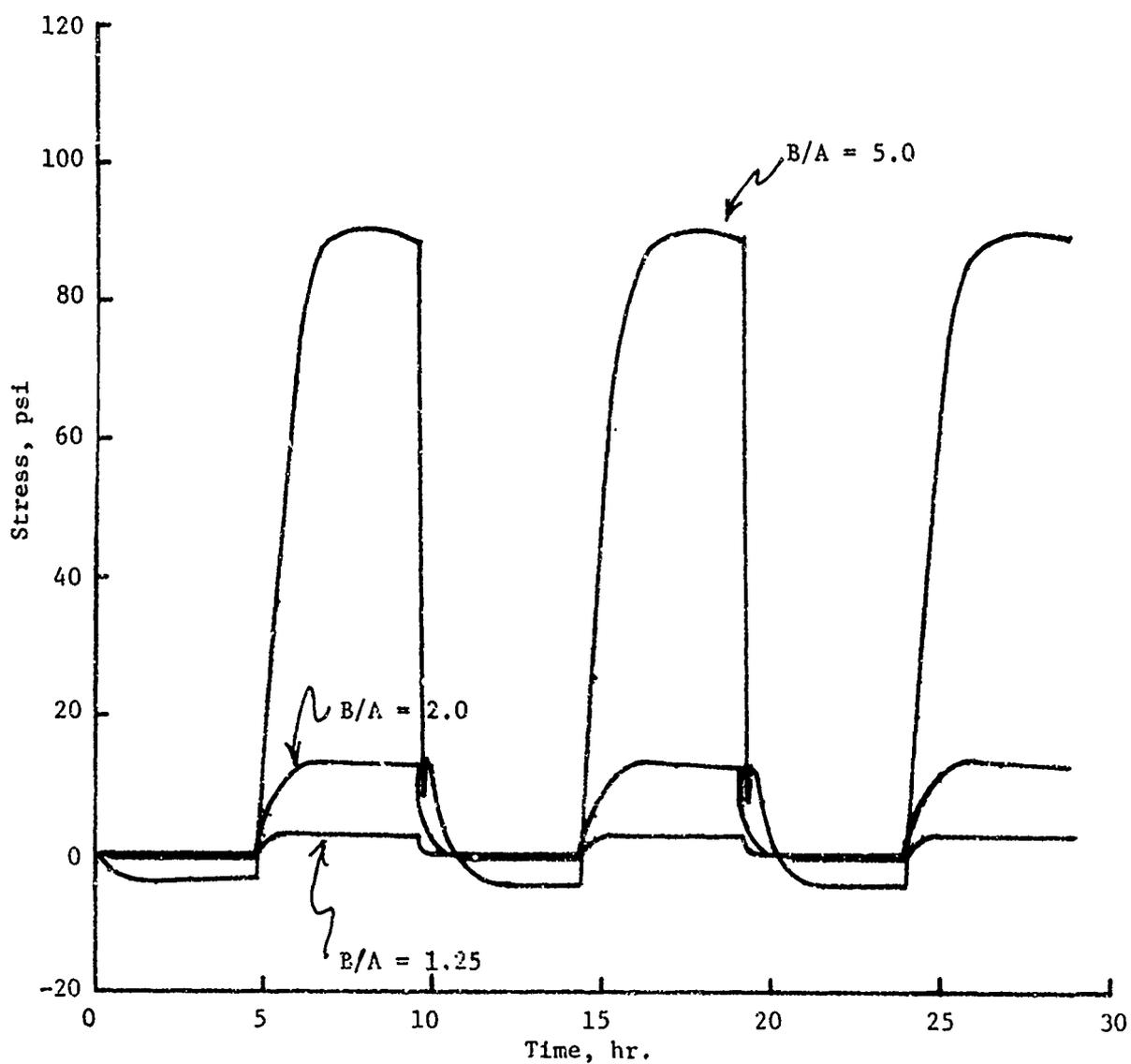


Figure C-11

PARAMETER STUDY OF RADIAL BOND STRESS SOLUTIONS  
HTPB PROPELLANT - HISTORY 2  
(B = 8 in.)

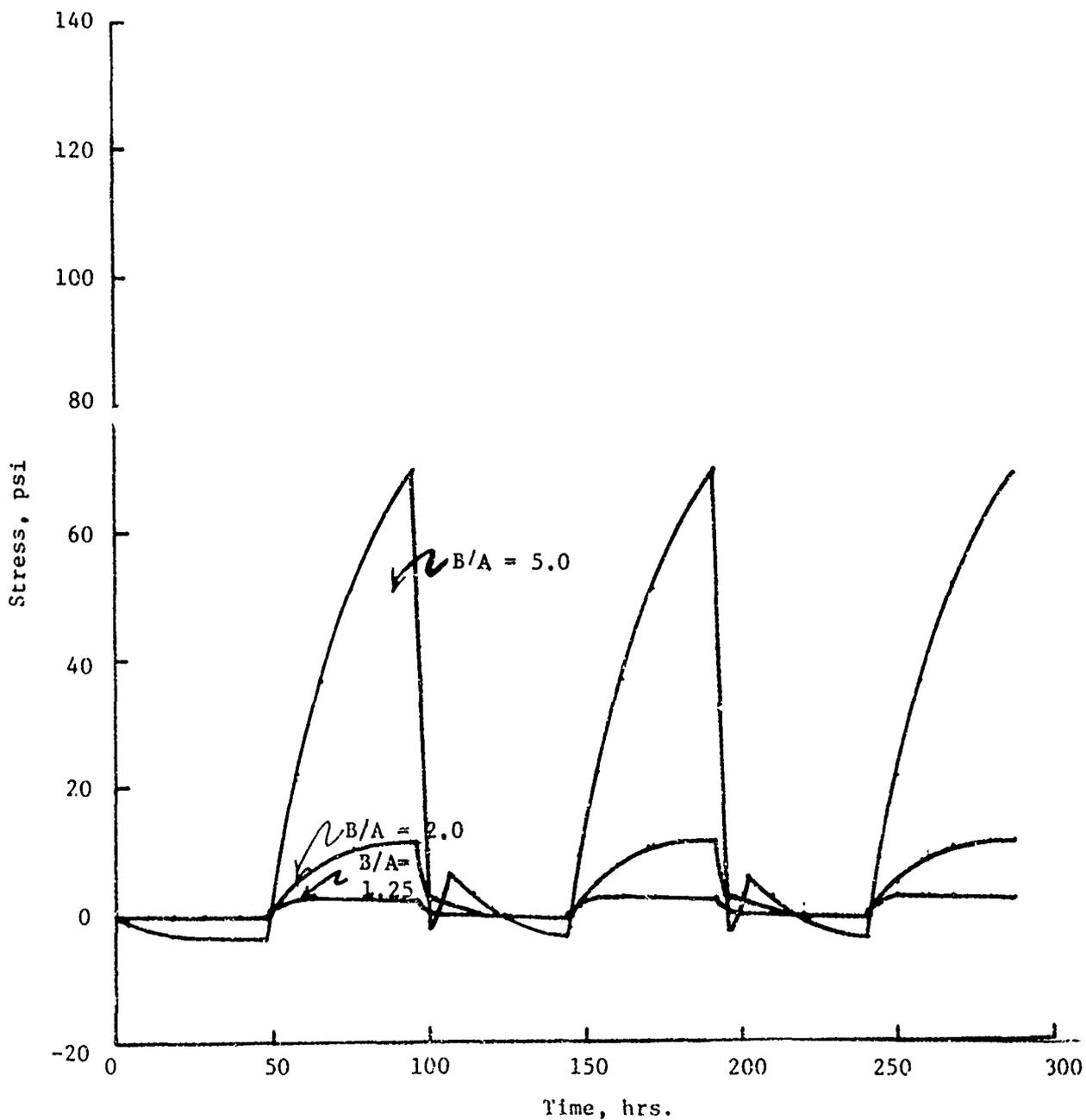


Figure C-12

APPENDIX D

A NEW NORMALIZED RELATION FOR THE RELAXATION MODULUS

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APPENDIX D

A NEW NORMALIZED RELATION FOR THE RELAXATION MODULUS

A. NORMALIZATION OF THE SHEAR MODULUS

Conventional viscoelastic stress analyses involve the relaxation modulus in shear,  $\mu(t)$ . The basic relations for this modulus require difficult to perform experiments, the results of which are not always satisfactory. It was desirable, therefore, to devise a simpler to use expression for this modulus. This was done starting with the relation now used,

$$\mu(t) = \mu_e + (\mu_g - \mu_e) \int_{-\infty}^{\infty} h e^{-t/\tau} d\ln\tau \quad (D-1)$$

where  $\mu_g$  is the glassy shear modulus

$\mu_e$  is the equilibrium shear modulus

$h$  represents a continuous distribution of relaxation times (normalized)

$t$  is the time of the test

$\tau$  is a relaxation time

Since  $\mu_g$  is difficult to evaluate experimentally an attractive substitute was sought and found.

We solved for  $\mu(t)$  at some specific time, like one minute, to obtain  $\mu(1)$ .

$$\mu(1) = \mu_e + (\mu_g - \mu_e) \int_{-\infty}^{\infty} h e^{-1/\tau} d\ln\tau \quad (D-2)$$

Letting

$$C = \int_{-\infty}^{\infty} h e^{-1/\tau} d\ln\tau \quad (D-3)$$

where  $C$  is a constant, we solve for  $\mu_g - \mu_e$  in Equation (D-2) using Equation (D-3) and inserting the result into Equation (D-1) gives

$$\mu(t) = \mu_e + (\mu(1) - \mu_e) \int_{-\infty}^{\infty} \frac{h e^{-1/\tau}}{C} d\ln\tau \quad (D-4)$$

For practical experimental purposes the constant C can be combined with h to give h', a quantity which is experimentally identified in the same manner as h.

Thus, the new relation becomes

$$\mu(t) = \mu_e + (\mu(1) - \mu_e) \int_{-\infty}^{\infty} h'e^{-t/\tau} d\ln\tau \quad (D-5)$$

In engineering practice it is unnecessary to evaluate h'. Instead, a graphical plot of  $\mu(t)$  versus time is usually sufficient. When normalized results are required a plot of  $\frac{\mu(t) - \mu_e}{\mu(1) - \mu_e}$  versus the time is equivalent

to a plot of  $\int_{-\infty}^{\infty} h'e^{-t/\tau} d\ln\tau$  versus the time.

Obviously, a broad range of relaxation curves can be obtained for a given distribution of relaxation times, h'.

#### B. NORMALIZATION OF THE PRONY SERIES

The new relation permits a normalization of the Prony Series as well. This relation in its usual form is given as

$$\mu(t) = \alpha_0 + \sum_{m=1}^m \alpha_m e^{-\beta_m t} \quad (D-6)$$

where the  $\alpha_m$  and  $\beta_m$  are constants

$\alpha_0$  is the equilibrium relaxation modulus

We can normalize Equation (D-6) to give a form similar to that of Equation (D-5). First we replace  $\alpha_0$  by the equivalent term  $\mu_e$  then normalize the constants  $\alpha_m$ , as shown below, to give

$$\mu(t) = \mu_e + (\mu(1) - \mu_e) \sum_{m=1}^m \alpha'_m e^{-\beta_m t} \quad (D-7)$$

where

$$\alpha'_m = \alpha_m / (\mu(1) - \mu_e) \quad (D-8)$$

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Equation (D-7) forms the engineering basis of our normalization procedures. This normalization method defines the modulus in terms of two easily determined parameters,  $\mu_e$  and  $\mu(1) - \mu_e$ . These same parameters can be used to normalize the stress and strain data from our engineering analyses.

APPENDIX E  
INCREMENTAL ANALYSIS PROCEDURE

## APPENDIX E

## INCREMENTAL ANALYSIS PROCEDURE

In an attempt to minimize accumulated numerical errors in our linear viscoelastic analyses, Dr. Herrmann developed this new approach. The "total stress analysis" was replaced by an "incremental analysis procedure"; i.e., instead of solving for the total stress and strain in the propellant for a given point in time, one could solve instead for the incremental changes in stress and strain. The incremental equations are very similar to those previously reported for the "total analysis" with the following exceptions (the equations referred to by number are reported in Reference (E-1).

Consider first, Equation (13),

$$S_{ijN} = 2\mu_N e_{ijN} + L_{ijN} \quad (13)$$

The quantities  $S_{ijN}$  and  $e_{ijN}$  in Equation (13) need to be interpreted as the incremental changes in stress and strain during time step N (i.e.,

$$S_{ijN} = 2\mu_N \Delta e_{ijN} + L_{ijN} \quad \text{where } S_{ijN} = S_{ijN-1} + \Delta S_{ijN}, \text{ etc.}). \quad \text{Equation (18)}$$

$$L_{ijN} = 2 [\chi_{ijN} - (\mu_N - \alpha_0) e_{ijN-1}] \quad (18)$$

is replaced by

$$L_{ijN} = 2 \sum_{m=1}^M \gamma_m [e^{-\beta_m \tau_N} - 1] C_{ijNm}$$

Equation (19)

$$X_{ijN} = \sum_{m=1}^M \alpha_m C_{ijNm} \quad (19)$$

is eliminated and Equation (24)

$$C_{ijNm} = e^{-\beta_m \Delta \xi_N} [C_{ijN-1,m} + (e_{ijN-1} - e_{ijN-2}) J_{N-1,m}] \quad (24)$$

becomes

$$C_{ijNm} = e^{-\beta_m \Delta \xi_{N-1}} C_{ijN-1,m} + \Delta e_{ijN-1} J_{N-1,m} \quad (24)$$

Finally, Equations (1), (2) and (3)

$$\tau_{ij} = S_{ij} + \delta_{ij} \sigma, \quad \sigma = \frac{1}{33} \tau_{ii} \quad (1)$$

$$\epsilon_{ij} = e_{ij} + \delta_{ij} \frac{\theta}{3}, \quad \theta = \epsilon_{ii} \quad (2)$$

$$\sigma = K (9 - 3\alpha\Delta T) \quad (3)$$

where

- K = Bulk modulus
- $\alpha$  = Coefficient of linear thermal expansion
- $\Delta T = T(x, t) - T_0$
- $T_0$  = Initial stress free reference temperature

are replaced by their corresponding incremental forms (Note:  $\Delta T_N = T_N - T_{N-1}$ ).

REFERENCES

- E-1 Herrmann, L. R., and Peterson, F. E., "A Numerical Procedure for Viscoelastic Stress Analysis", Bulletin of the 7th Meeting of the ICRPG Mechanical Behavior Working Group, CPIA Publication No. 177, p. 155 (October 1968).

APPENDIX F

PRONY SERIES CURVE FIT ANALYSIS

APPENDIX F

PRONY SERIES CURVE FIT ANALYSIS

The shear relaxation modulus for most solid propellants has been found to fit the following series function with relatively few terms:

$$\phi(t) = A_0 + \sum_{i=1}^n A_i e^{-\beta_i t} \quad (F-1)$$

Equation (F-1) is a "Prony" series with two unknown coefficients  $A_i$  and  $\beta_i$ . The method of collocation is used to find these coefficients:

$$\text{Let } \beta_i = \frac{1}{2t_i} \quad (F-2)$$

Substitution of Equation (F-2) into Equation (F-1) gives

$$\phi = A_0 + \sum_{i=1}^n A_i e^{-\frac{t}{2t_i}} \quad (F-3)$$

Now, choose  $n$  points for the evaluation of  $\phi$

$$\phi_j = A_0 + \sum_{i=1}^n A_i e^{-\frac{t_j}{2t_i}} \quad (J = 1, n) \quad (F-4)$$

Equations (F-4) are sufficient to solve for the  $A_i$ . In matrix notation;

$$[\bar{E}] \{A_i\} = \{\phi_j - A_0\} \quad (F-5)$$

where,

$$E_{ji} = e^{-\frac{t_j}{2t_i}}$$

Equation (F-5) is readily solved for  $A_i$ ;

$$\{A_i\} = [E]^{-1} \{\phi_j - A_0\} \quad (F-6)$$

Equation (F-6) has been programmed for computer solution from a times burning terminal in the BASIC language. A listing of the program is given on Page F-3. The order of data input is given below:

1.  $n$
2.  $A_0$
3.  $t_j$  ( $j = 1, n$ )
4.  $\theta_j$  ( $j = 1, n$ )

Data statements 600 to 9000 may be used for data. Sample data statements are shown below:

600 Data 7,100

610 Data 1E-4, 1E-3, 1E-2, 1E-1, 1, 10, 100

620 Data 3000, 1800, 1000, 620, 410, 320, 280

A sample run with this data is shown on Page F-4.

PROGRAM LISTING

```

100 REM "PERRY SERIES CURVE FIT"
110 DIM T(20,1),F(20,1),A(20,20),C(20,20)
120 DIM F(1,20),C(1,20)
130 REAL N,E1
140 MAT REAL I(N,1)
150 MAT F = ZER(N,N)
160 MAT C = ZER(N,N)
170 MAT F = TRN(T)
180 PRINT "INPUT TIMES AND MODULI"
190 MAT PRINT F;
200 MAT A = ZER(N,N)
210 FOR J=2 TO N
220 LET E = -T(J,1)/T(1,1)
230 LET A(J,J) = 0.60653
240 IF E < -20.0 THEN 280
250 LET A(1,J) = EXP(0.5/E)
260 LET A(J,1) = EXP(0.5*E)
270 (9 TO 300
280 LET A(1,J) = 1.0
290 LET A(J,1) = 0.0
300 NEXT J
310 LET A(1,1) = 0.60653
320 LET K1 = N - 1
330 FOR I=2 TO K1
340 LET L = I
350 LET K2 = K1 - I + 2
360 FOR J=2 TO K2
370 LET L = L + 1
380 LET A(J,L) = A(1,1)
390 LET A(L,J) = A(1,1)
400 NEXT J
410 NEXT I
420 MAT C = ZER(N,N)
430 MAT C = INV(A)
440 MAT READ E(N,1)
450 MAT C = TRN(E)
460 MAT PRINT C;
470 FOR J=1 TO N
480 LET E(J,1) = F(J,1) - F1
490 NEXT J
500 MAT T = C*F
510 PRINT "SOLUTION"
520 MAT F = TRN(T)
530 MAT PRINT F;
540 (1 TO 20)
550 END

```

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Appendix F

SAMPLE RUN

PRON 9:57 SF FRI 02/13/70

INPUT TIMES AND MODULI

.0001 .001 .01 .1 1 10 100

3000 1800 1000 620 410 320 230

SOLUTION

1370.27 1031.23 464.66 247.646 184.314 -106.615 297.955

OUT OF DATA IN 440

APPENDIX G

INCLUSION OF NON-ZERO THICKNESS STRESSES IN  
PLANE STRESS ANALYSES

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APPENDIX G

INCLUSION OF NON-ZERO THICKNESS STRESSES  
IN PLANE STRESS ANALYSES

The generalized plane stress option was modified so that the stress throughout the thickness of the body, may be specified as a constant rather than zero. The values of the thickness stress constitutes one of the input parameters. The inclusion of a non-zero thickness stress required the modification of the governing variational equation.

It was determined that the appropriate form of the variational function, for a nearly incompressible material <sup>(G-1)</sup> is (for  $T = T_N$ ):

$$\begin{aligned}
 F_N = \iint \{ & \frac{2\mu_N}{3} [(\Delta\epsilon_{x_N})^2 + (\Delta\epsilon_{y_N})^2 - (\Delta\epsilon_{x_N})(\Delta\epsilon_{y_N})] + \frac{1}{2} \mu_N (\Delta\gamma_{x_4_N})^2 \\
 & + (\mu_N \Delta\bar{H}_N - \Delta\beta_N/3)(\Delta\epsilon_{x_N} + \Delta\epsilon_{y_N}) + L_{xx_N} \Delta\epsilon_{x_N} + L_{yy_N} \Delta\epsilon_{y_N} \\
 & + L_{xy_N} \Delta\gamma_{xy_N} - \frac{(\mu_N)^2}{2\bar{K}_N} (\Delta\bar{H}_N)^2 + \Delta\bar{H}_N \left( \frac{\Delta\beta_N}{2} - 3\mu_N \alpha \Delta T_N \right) \\
 & \left. - \Delta F_{x_N} \Delta u_{x_N} - \Delta F_{y_N} \Delta u_{y_N} \right\} dx dy - \int \Delta u_N \cdot \Delta(\text{applied boundary load}) ds
 \end{aligned}$$

where

$$\Delta \epsilon_{xx_N} = \frac{2\mu_N}{3} (2\Delta \epsilon_{x_N} - \Delta \epsilon_{y_N}) + \mu_N \Delta \bar{H}_N + L_{xx_N} - \frac{\Delta \beta_N}{3}$$

$$\Delta \epsilon_{zz_N} = \frac{1}{3} (\Delta \epsilon_{x_N} + \Delta \epsilon_{y_N}) - \frac{\Delta \bar{H}_N}{2} + \frac{2}{3\mu_N} (\Delta \sigma_N - L_{zz_N}) + \frac{1}{3} \alpha \Delta T_N$$

$$\Delta \beta_N = 2\mu_N \alpha \Delta T_N + (\Delta \sigma_N - L_{zz_N})$$

$$\bar{K}_N = \frac{8\mu_N (1 - \frac{\mu_N}{6K})}{3(1 + \frac{4\mu_N}{3K})}$$

The symbol  $\Delta \sigma_N$  denotes the incremental change in the specified thickness stress,  $L_{zz_N}$  denotes the history term associated with  $\epsilon_z$ , the other symbols have their usual meanings.

#### REFERENCES

- G-1 Herrmann, L. R., "Elasticity Equations for Incompressible and Nearly Incompressible Materials by a Variational Theorem", AIAA J., Vol. 3, No. 10, pp. 1896-1901, October 1965.

APPENDIX H

A COMPUTER PROGRAM FOR VISCOELASTIC SOLIDS  
OF REVOLUTION SUBJECTED TO TIME - VARYING THERMAL  
AND MECHANICAL LOAD ENVIRONMENTS

VERSION 2.1

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Appendix H

A COMPUTER PROGRAM FOR VISCOELASTIC SOLIDS OF REVOLUTION  
SUBJECTED TO TIME-VARYING THERMAL AND MECHANICAL LOAD ENVIRONMENTS

- VERSION 2.1 -

I. INTRODUCTION

The purpose of the computer code described in this section is to perform viscoelastic stress analyses. The analyses is applicable to arbitrary revolved solids and plane structures subjected to loads of mechanical or thermal origin. The program is segmented into two (2) phases: (1) Transient Heat Transfer Analysis; and (2) Viscoelastic Stress Analysis. The purpose of the heat transfer phase is to generate temperature distributions in the body as a function of time which are used subsequently in performing the stress analysis. The two phases of the program can be used in sequence within a given job or each phase can be used separately.

The method of solution employs the finite element procedure for solving the spatial problems (heat conduction and stress analysis) and time marching techniques to evaluate temperatures/stresses at successive points in time. The transient heat transfer problem is solved using the procedure developed by Wilson and Nickell\*. Knowing thermal and mechanical loads as a function of time and having available the viscoelastic properties of the material(s), a set of equivalent elastic parameters is defined for a particular point in time; the equivalent elastic problem is posed using the procedure given by Herrmann and Peterson\*\*. An elastic stress analysis must be performed at each point in time for which the viscoelastic response of the body is required. The stress analysis problem is solved using a finite element method given by Herrmann.\*\*\*

II. APPLICATIONS

The principal application of the program is to stress analysis of solid propellant grains maintained in time varying temperature environments. A typical application might be the grain stress analysis of a motor system subjected to thermal cycling. Mechanical loads may also be applied to the body either isothermally or with simultaneous time varying temperature changes. The kinds of mechanical loading considered in the analysis include surface pressures, body forces (spin and/or axial accelerations), concentrated nodal forces, and specified nodal displacements; all mechanical loads can vary with time in accordance with user-supplied table.

\* Wilson, E. L., and Nickell, R. E., "Application of the Finite Element Method to Heat Conduction Analysis", Nuclear Engineering and Design 4 (1966), p. 276-286. North Holland Publishing Company, Amsterdam.

\*\* Herrmann, L. R., and Peterson, F. E., "A Numerical Procedure for Viscoelastic Stress Analysis", CPIA - 7th Meeting, Working Group on Mechanical Behavior (ICRPG), November 1968.

\*\*\* Herrmann, L. R., "Elasticity Equations for Incompressible Materials by A Variational Theorem", Journal of the AIAA, p. 1896-1900, October 1965.

A. PHYSICAL PROPERTIES

The program can be used to perform simple elastic solutions, time-dependent elastic or thermoelastic analyses, or thermoviscoelastic analyses. A viscoelastic analysis requires a complete material property characterization including the master relaxation curve and shift function for each time dependent material, bulk modulus, expansion coefficient, density, etc. Table H-1 illustrates the thermal and mechanical properties data required to perform the thermoviscoelastic stress analysis of a bipropellant grain with a separate viscoelastic liner and an elastic case.

Shift function data is accepted by the program in the form of a table of  $\log a_T$  versus  $T$ , ( $^{\circ}F$ ); shift factors at temperatures other than those supplied in the input table are determined using linear interpolation between given points.

Relaxation data must be input as the coefficients  $(A_i, \beta_i)$  in a Prony Series fit to the experimental data. The relaxation behavior in shear must be expressed as an exponential series.

$$\phi(t) = A_0 + \sum_{i=1}^n A_i e^{-\beta_i t} \quad (H-1)$$

where  $A_0$  is the shear equilibrium modulus and  $(A_i, \beta_i)$  are found from curve fitting\* calculations based on experimental data. Each viscoelastic material must have its relaxation behavior expressed in a separate series expansion. Elastic materials have no terms in the series other than  $A_0$ . If there are no terms in the series expansion ( $M = 0$ ) the program will not read a shift function table.

The special problem of bulk rapid pressurization of a propellant grain where a pressure shift function  $a$  is required is handled in a different manner. This type of problem<sup>P</sup> can only be run isothermally with no superimposed thermal loads. In this case the shift function input values are interpreted as the product  $a a_T$  as a function pressure where  $a_T$  is a constant for the temperature under consideration.

\* One recommended curve fitting procedure is a "collocation method" originated by Schapery and summarized in the ICRPG Solid Propellant Mechanical Behavior Manual starting at Section 2.2-4 (June 1963). The method involves assuming values for the constants  $\beta_i$  and solving a set of linear simultaneous equations for the constants  $A_i$ . A time-share routine called "PRONY" has been programmed to perform the calculations at Aerojet.

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PHYSICAL PROPERTY INFORMATION REQUIRED  
FOR A THERMOVISCOELASTIC STRESS ANALYSIS

PROBLEM IDENTIFICATION:

Propellant No. 1 -  
Propellant No. 2 -  
Liner -  
Case -

Physical Property	Propellant No. 1	Propellant No. 2	Liner	Case
Coefficient of Linear Thermal Expansion ( $^{\circ}\text{F}^{-1}$ )				
Density ( $\text{lb-in.}^{-3}$ )				
Specific Heat Capacity ( $\text{btu-lb}^{-1} \text{ } ^{\circ}\text{F}^{-1}$ )				
Thermal Conductivity, ( $\text{Btu-in.}^{-1} \text{ hr}^{-1} \text{ } ^{\circ}\text{F}^{-1}$ )				
Bulk Modulus ( $\text{lb-in.}^{-2}$ )				
Shear Relaxation Modulus ( $\text{lb.-in.}^{-2} \text{ vs. hr}$ )	(Table or curve as a function of time)			
Shift Factor ( $a_T \text{ vs. } ^{\circ}\text{F}$ )	(Table or curve as a function of temperature)			
Elastic Shear Modulus ( $\text{lb-in.}^{-2}$ )				

Table H-1

### III. DATA INPUT DESCRIPTION

This section supplies information necessary for the preparation of data input cards. The input sequence is separated into four major groups:

1. Grid Definition
2. Solution Time and Temperature Information
3. Transient Heat Transfer Solution Data
4. Stress Analysis Information

#### A. NOMENCLATURE

The abbreviation "cc" used below stands for "card columns". The variable names assigned to the various parameters used by the program are given below in upper case letters; for example, "NIP" stands for the total number of nodes in the finite element mesh. All variables starting with any of the letters I, J, K, L, M, N are to be input to the program as integers (i.e., without a decimal point). All integers are to be packed to the right of the field specified by the "cc" numbers. Any variable whose first letter is not an I, J, ..., N is a real number requiring a decimal; "R(N)", for example, is the radius of the 'N-th' nodal point (entered in cc 6-15). If  $R(N) = 13.45$ , then the number "13.45" can be placed anywhere in the field: cc 6-15. Real numbers can also be input in "E" format; 13.45 could be entered as 1.345E1, .1345E2, 1345.E-2, etc., providing the set of characters is packed to the right of the cc field.

Whenever applicable, units of the variables are stated in symbolic notations. The symbols used below are defined as follows:

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(F)	=	Force units
(L)	=	Length units
(T)	=	Time units
(°F)	=	Temperature units
(R)	=	Radian
(Btu)	=	Thermal Heat Flow Units

Thus, the quantity (F) (L)<sup>-2</sup> written after the shear modulus means "psi" if pounds and inches are the units chosen by the user. There are no units, conversion factors, etc., built into the program; thus, once a set of units is chosen it must be used consistently throughout the analysis.

B. SEQUENCE OF OPERATIONS

The flow of program execution is controlled by three (3) user-supplied variables:

IPF	=	Plot Control Flag
NTEM	=	Temperature Information Flag
JOB	=	Job Control Flag

Table H-2 contains values which can be assigned to these variables showing what operation results from a particular specification. Certain combinations are not possible. For example, if IPF < 0, the program reads mesh data, prepares a plot and returns control to that portion of the program which looks for the next job; thus, the variables "NTEM" and "JOB" cannot be specified. "JOB" has no meaning unless IPF ≥ 0 and NTEM = 0.

The option NTEM = 1 is impractical for real problems because of the amount of card data involved; this option is useful when solving "check cases" with temperature distributions generated from an analytical expression or formula. The NTEM = 2 option saves re-running the temperature problem if only the mechanical properties or mechanical loads change. NTEM = 3 is used for the isothermal problem in which the loading is mechanical in origin. Viscoelastic materials exhibit temperature dependence, so material temperatures must be defined even though there are no driving thermal strains in the body to be analyzed.

The variable "JOB" (which is only defined if NTEM = 0) controls what the program does with the results of the heat transfer solution and where the program goes after the heat transfer calculations. If JOB = 0, element temperatures are saved temporarily for use in the stress analysis to follow. JOB = 1 results in the same operation as JOB = 0, but in addition the element temperatures are saved for use in a later analysis (or series of analyses). If JOB = 2, the temperatures are saved (and printed at user specified time intervals) on a tape for use at some other time; at this point the program is through with this job and looks for another. JOB = 3 allows the user to run the program solely as a heat transfer analysis.

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EXECUTION CONTROL VARIABLES

FLAG	VALUE	OPERATION PERFORMED
IRF	< 0 = 0 > 0	Read grid data only, plot grid and <u>stop</u> . Read all data, <u>execute</u> the job <u>without</u> a plot. Read all data, <u>execute</u> the job <u>with</u> a plot.
NTEM	= 0 = 1 = 2 = 3	Calculate the element temperatures using the heat transfer analysis. Read the element temperatures from card input. Read the element temperatures from a tape created during a previous run. Read the element temperatures from card input and use the same distribution for all solution time points (isothermal response).
JOB	= 0 = 1 = 2 = 3	Run the heat transfer problem and use the results to perform the stress analysis. Run the heat transfer problem, save the element temperatures on a permanent file (which can be used as input to subsequent jobs) and use the results to perform the stress analysis. Run the heat transfer problem, save the element temperatures on a permanent file, and <u>stop</u> . Run the heat transfer problem and <u>stop</u> .

C. DATA CARD INPUT

1. Grid Definition

a. Start Cards

(1) First Card (A3)

cc

1-3 Enter the characters "TVA"

(2) Title Card (12A6)

cc

1-72 HED Title information for job and plot (center about cc 36  
for plot)

b. Control Card (One card, 3I5)

cc

1-5 NNP Number of nodal points  $\leq$  273

6-10 NEL Number of quadrilateral elements  $\leq$  240

11-15 IPF Plot flag < 0, plot only  
= 0, run only  
> 0, plot and run

c. Node Coordinate Cards (I5, 2F10.3, I5, 2F10.3, I5)

cc

1-5 N Node Number

6-15 R(N) Radial Coordinate (L)

16-25 Z(N) Axial Coordinate (L)

26-30 NE Ending Node Point Number

31-40 R(NE) Radial Coordinate (L)

41-50 Z(NE) Axial Coordinate (L)

51-55 NI Node Number Increment

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If the ending node number NE is not zero (or blank), then nodes will be generated in equal distance increments along a line between node N and node NE. The first generated node is assigned the number  $N + NI$ ; the second generated node number is  $N + 2NI$ , etc. Note that the node number difference  $(NE - N)$  must be positive and divisible by NI.

If NI is omitted it will be assigned a value of "1" automatically.

d. Element Numbering Cards (815)

cc

1-5	N	Element Number
6-10	IX (N, 1)	Node numbers describing the corner points of the quadrilateral
11-15	IX (N, 2)	
16-20	IX (N, 3)	
21-25	IX (N, 4)	
26-30	MN(N)	Material Number
31-35	NIG	Number of elements to be generated
36-40	NNI	Node Number Increment

If the number of elements to be generated (NIG) is not zero, then NIG elements will be generated. The first generated element is assigned the number  $N + 1$ ; the second generated element is numbered  $N + 2$ , etc. The node numbers of the second generated element are found by adding NNI to the node numbers of the first generated element, etc. If NNI is omitted it will be assigned a value of "1".

The material number assigned to generated elements is the same as that for element N. Material numbers are not necessary if the program is to plot the grid only (IPF < 0).

If IPF < 0; data input ends here.

2. Solution Time and Temperature Information

a. Control Card (One card 2I5, F10.0, 2I5, F10.0).

cc

- 1-5 NDT Total number of time increments to be used in the solution for element temperatures and/or stresses.
- 6-10 NTR Number of regions on the time axis having the same value of time increment ratio.  $\leq 50$
- 11-20 TMF Value of time at the end of the NDT<sup>th</sup> increment. (T)
- 21-25 NBCF Number of functions describing time dependent boundary conditions.  $\leq 10$
- 26-30 NTEM Temperature information flag:
- = 0 Element temperatures are to be calculated using the heat transfer analysis.
  - = 1 Element temperatures are to be read from cards.
  - = 2 Element temperatures are to be read from a tape created on a previous run.
  - = 3 Element temperatures are to be read from cards, and this distribution is to be used for all solution time points.
- 31-40 TZ Temperature of every element at time zero (°F) (stress free temperature).

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b. Solution Time Points

At least one card in this section

(1) First Card (3 (15,2FLO.0))

cc

1-5 NTI(1) Number of increments for which the time increment ratio C(1) remains constant in region 1.

6-15 DT (1) Value of time after NTI(1) time increments in region 1.

16-25 C (1) Time increment ratio in region 1.

26-30 NTI (2) Same as cc 1-5 for region 2.

31-40 DT (2) Value of time after NTI (1) HNTI (2) time increments (T)

41-50 C (2) Same as cc 16-25 for region 2

51-55 NTI (3)

56-65 DT (3) Region 3

66-75 C (3)

(2) Second Card (3 (15, 2 F10.0)) (If required)

cc

1-5 NTI (4)

6-15 DT (4) Region 4

16-25 C (4)

... Etc.

Use as many cards in this section as are required to enter NTR groups of (NTI (I), DT (I), C (I)). Note that

NTR  
 $\sum_{i=1}^{\text{NTR}} \text{NTI}_i = \text{NDT}$ , otherwise an error message will be issued by the program.

The solution time points in region r are found using:

$$t_{i+1} = t_i + C_r * (t_i - t_{i-1})$$

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This method of solution time point input has the effect of automatically producing small time steps at the beginning of the region while continuously widening the time steps toward the end of the region. As an example, if 50 solution time points are specified over a 24 hour period with  $C = 1.1$  the first solution time point will occur at .0206 hrs (1.24 minutes) and the last solution step ( $t_{50} - t_0$ ) will be 2.19 hours (132 minutes).

It is important to choose  $C$  such that the smallest time step will not be so small as to produce a reduced time falling off the mechanical properties table or the final time step too large. The following equations may be used to find these values:

$$\frac{\Delta T_i}{T_f} = \frac{C-1}{C^N-1} \quad \frac{\Delta T_N}{T_i} = \frac{C^{N-1}(C-1)}{C^N-1} \quad (H-2)$$

where

- $C$  = time increment ratio
- $\Delta T_i$  = Initial solution time step
- $\Delta N$  = total number of solution time points
- $\Delta T_N$  = final time step
- $T_f$  = final value of time ( $T_0 = 0$ )

These two equations are plotted for various values of  $C$  in Figures H-1 and H-2 respectively.

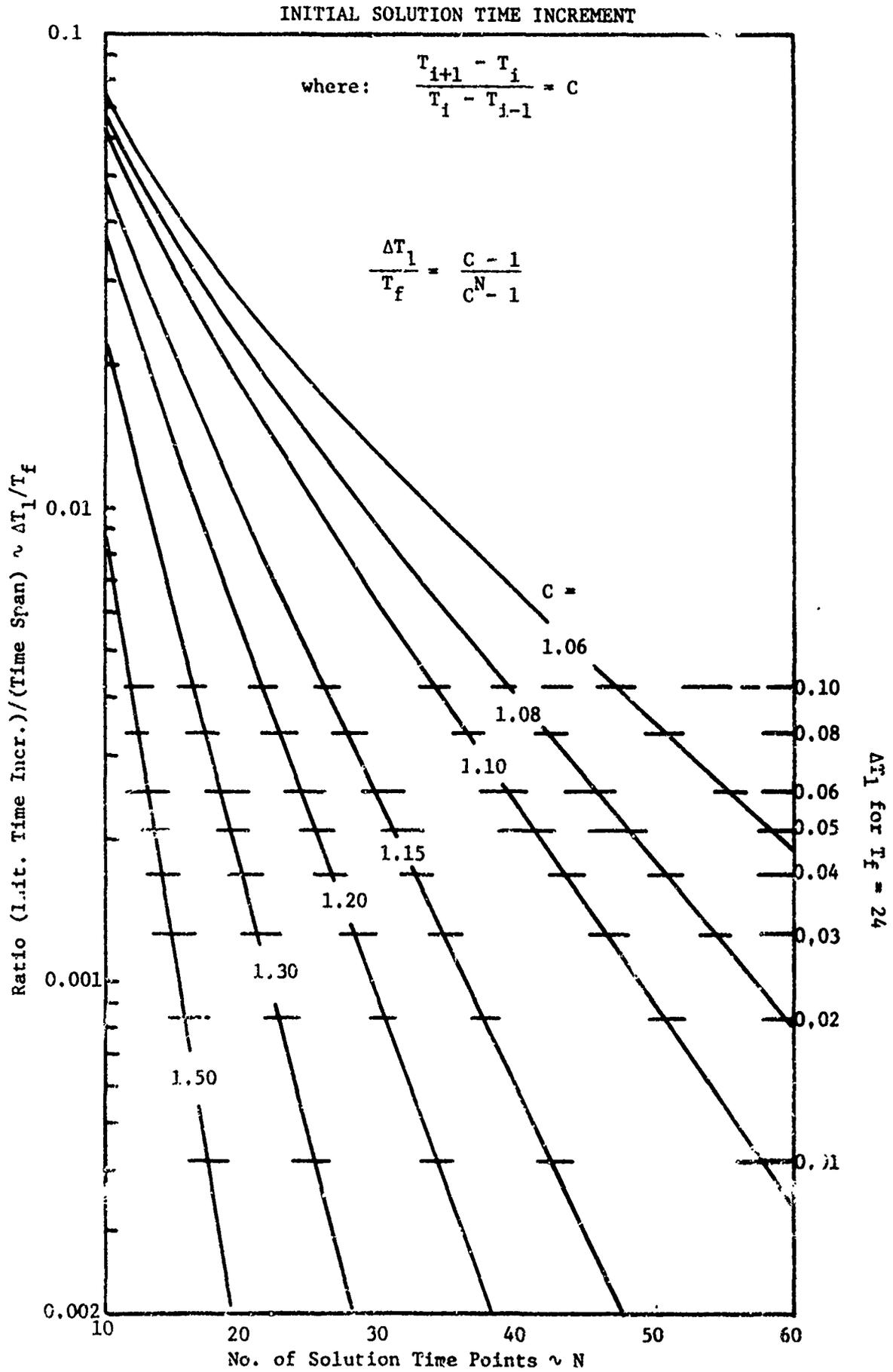


Figure H-1

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FINAL SOLUTION TIME INCREMENT

where:  $\frac{T_{i+1} - T_i}{T_i - T_{i-1}} = C$

$$\frac{\Delta T_N}{T_f} = \frac{C^{N-1} (C - 1)}{C^N - 1}$$

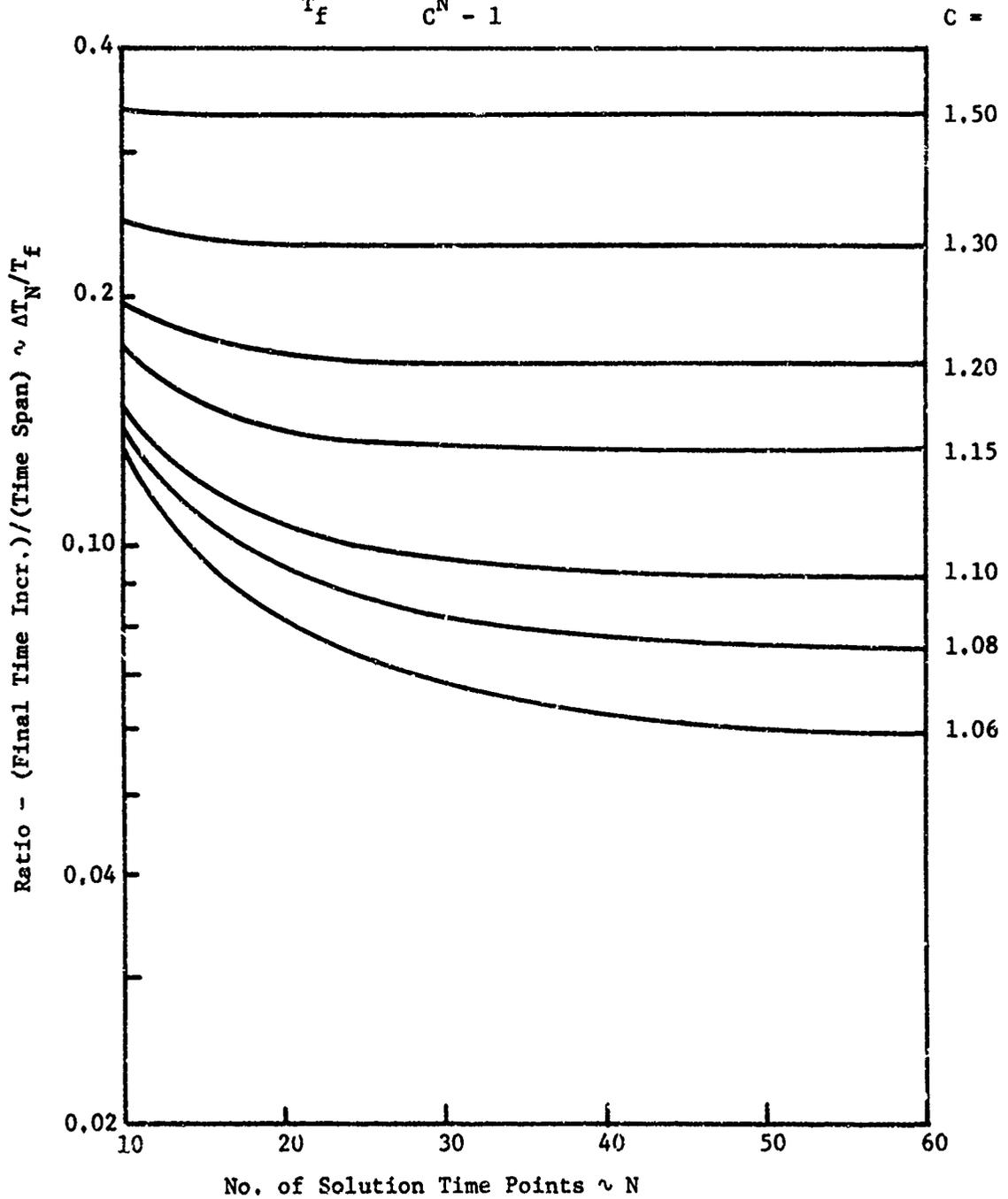


Figure H-2

c. Boundary Condition Function Cards

Skip this section if NBCF = 0

(1) Card One (2I5)

cc

1-5 N Number assigned to this function

6-10 NPTS(N) Number of points in the table describing  
this function.  $\leq 30$

(2) Card Two (8F10.0)

cc

1-10 TFN (N, 1) Time at point 1,  $t_1$  (T)

11-20 FN (N, 1) Value of the function at time  $t_1$ ,  $f_1$

21-30 TFN(N, 2) Time at point 2,  $t_2$  (T)

31-40 FN (N, 2) Value of the function at time  $t_2$ ,  $f_2$

41-50 TFN (N, 3) }  
51-60 FN (N, 3) } Point 3

61-70 TFN(N, 4) }  
71-80 FN (N, 4) } Point 4

(3) Card Three (8F10.0) (If required)

cc

1-10 TFN (N, 5) }  
11-20 FN (N, 5) } Point 5

... etc.

Use as many cards 2, 3, etc., in this section as are required to enter NPTS(N) pairs of (TFN(N, I), FN(N, I)) which define this function (Number N). There are NBCF sets of cards 1, 2, 3, etc. in this section. Data for a new function begins on a new card 1.

Figure H-3 represents a function which might be used to describe the pressure transient in a motor. The last point in the table must have a value of time which is greater than or equal to the length of solution period (TMF); for this case  $16.0 > 14.0 = \text{TMF}$  (Figure 3.1).

EXAMPLE BOUNDARY CONDITION FUNCTION

I	TFN (3, I)	FN (3, I)
1	0.0	0.0
2	2.0	0.8
3	4.0	1.0
4	5.0	0.7
5	16.0	0.7

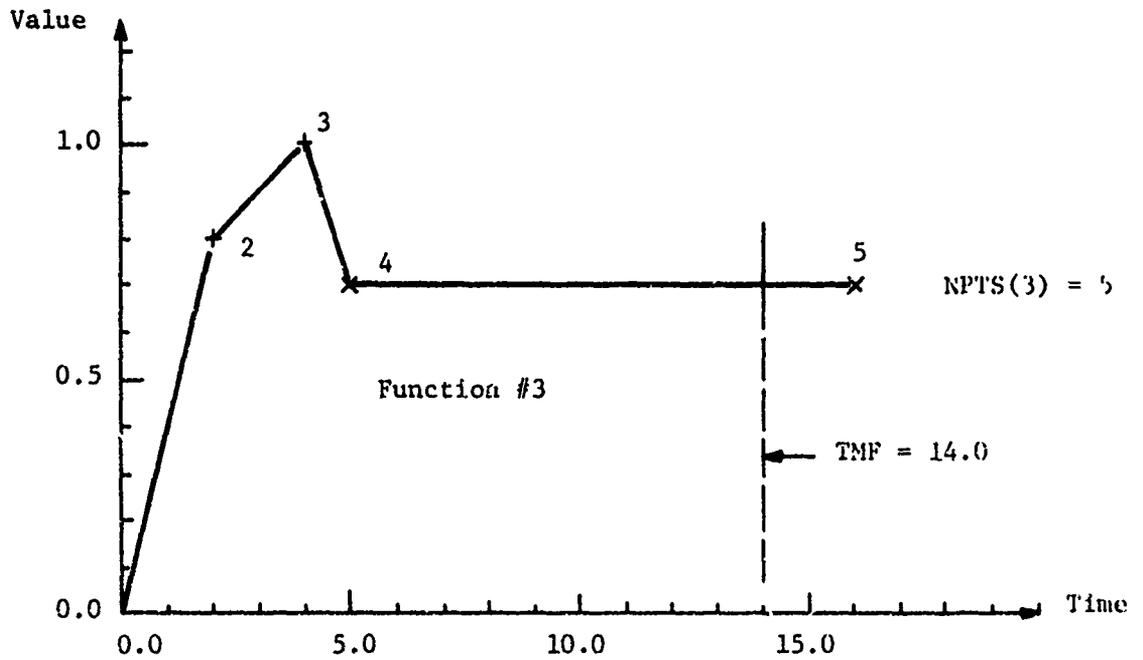


Figure H-3



Suppose that temperature output is required at time points 2, 4, 7 and 8 of Figure 2.1, then one card would be input in this section:

Card 1: 2,2,3,1,1,1 ; [2 (2) + 3 (1) + 1 (1) = 8].

If temperatures at all 8 points is requested, then

Card 1: 1, 8 ; [1 (8) = 8].

e. Average Element Temperature Cards (3I5, F10.0)

(Card 2-a is the reference for values of NDT, NTEM and TZ).

Skip this section if NTEM = 0, or NTEM = 2

cc

1-5	NELS	Starting element number for this group.
6-10	NELG	Number of elements with the same average temperature as element number NELS.
11-15	NELI	Element number increment.
16-25	TAVG	Average element temperature for this group of elements. (°F)

If NTEM = 1, there are NDT sets of element temperatures that must be defined in this section (one set for each of the NDT time points contained in the solution period). All element temperatures must be prescribed at a given time point before proceeding to the next point. If every element has a different temperature, then NEL cards (with cc 6-15 blank) must be prepared for that time point. It is possible to generate element temperatures at a time point if several elements are at the same temperature. NELG elements are assigned average temperatures TAVG. The number assigned to the first generated element is NELS + NELI; the second is NELS + 2 (NELI), etc.

Suppose that a body described using 50 elements (NEL = 50) is at a uniform 77°F, when  $t \leq 0$  (TZ = 77.0), and at the end of the first time increment elements 1-25 drop to 60°F while elements 26-50 reach 45°F. Two cards are required to define the element temperature distribution at the end of time increment one ( $t = t_1$ ):

Card 1: 1, 24, 1, 60.0

Card 2: 26, 24, 1, 45.0

If NTEM = 3, then there is only one set of element temperatures which must be input in this section. This temperature distribution applied to all solution time points; the body starts at  $t = 0^-$  at a uniform temperature TZ (at which the body is assumed to be "stress free"), and at  $t = 0^+$  the element temperatures assume the values prescribed in this section of the data input and remain constant for all time,  $t > 0$ .

3. Transient Heat Transfer Solution Data

Skip this section if NTEM = 1, 2, or 3

a. Control Card (One card; 4I5)

cc

1-5 NMAT Number of materials with different thermal properties.  $\leq 10$

6-10 NNBC Number of nodal point boundary conditions (temperatures or heat fluxes)

11-15 NCBC Number of convection boundary conditions  $\leq 65$

16-20 JOB Job Control Flag

= 0 : run heat transfer and use the results to perform the stress analysis.

= 1 : run heat transfer, save element temperatures on a permanent file, and use the results to perform the stress analysis.

= 2 : run heat transfer, save the results on a permanent file, and stop.

= 3 : run heat transfer and stop.

21-25 KAT KAT = 0 Axisymmetric Analysis  
KAT  $\neq$  0 Planar Analysis

b. Material Cards (1I0, 6F10.0)

cc

1-10 N Material number

11-20 XCOND(N) Conductivity:  $K_{rr}$ ,  $(\text{Btu})(T)^{-1} (L)^{-2} (^\circ\text{F}/L)$

21-30 YCOND(N) Conductivity:  $K_{zz}$

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31-40	XYCOND(N)	Conductivity: $K_{rz}$
41-50	SPHT (N)	Specific Heat, $(\text{Btu})(\text{F})^{-1}(\text{°F})^{-1}$
51-60	DENS(N)	Weight density, $(\text{F})(\text{L})^{-3}$
61-70	QX(N)	Heat generated per unit volume, $(\text{Btu})(\text{T})^{-1}(\text{L})$

Use one card for each different material number assigned in the element array (cards 1-d); NMAT cards must be prepared in this section - order is unimportant.

If the thermal conductivity of a material is independent of direction, then

$$K_{rr} = K_{zz} = k$$

$$k_{rz} = 0$$

The heat generated per unit volume is assumed to be constant with time.

c. Nodal Point Boundary Conditions (215, F10.0, I5)

Skip this section if NNBC = 0

cc

1-5	N	Node Number
6-10	KODE(N)	Boundary condition type { = 0, externally supplied heat flux = 1, prescribed node temperature
11-20	T(N)	Boundary value amplitude { = Heat flux (KODE(N) = 0), $(\text{Btu})(\text{T})^{-1}(\text{R})$ = Temperature (KODE(N) = 1), $(\text{°F})$
21-25	NFN(N)	Function number

All nodal points not specified in this section are assumed to have externally supplied heat flux of zero for all values of time.

A function number equal to zero (or blank) means that the prescribed boundary condition is applied at time zero and remains constant for all time,  $t > 0$ .

The functions assigned in this section must have been defined previously in Section 2-c. For time varying boundary conditions, the magnitude of the boundary value at some time  $t$  is found by selecting the value of the function at  $t$  and then multiplying this value times the boundary value amplitude (cc 11-20). A given function can be used to describe any number of boundary conditions.

d. Convection Boundary Conditions

Skip this section if NCBC = 0

(NCBC Cards, 2I5, 2F10.0, I5)

cc

1-5	I(N)	Node number $i$
6-10	J(N)	Node number $j$
11-20	H(N)	Heat transfer coefficient, $h$ : $(\text{BTU})(\text{T})^{-1}(\text{L})^{-2}(\text{°F})^{-1}$ $q = h(T - T_0)$
21-30	TE(N)	Environmental temperature amplitude, $\bar{T}_0$
31-35	NFCV(N)	Function number

If the environmental temperature  $T$  is time dependent, then a non-zero function number must be specified in cc 31-35.  $\bar{T}_0$  will be multiplied by the appropriate value of the function of time  $t$  in order to establish the value of environmental temperature,  $T_0$ .

If the environment does not change temperature with time, then  $\text{NFCV}(N) = 0$  and  $T_0 = \bar{T}_0$ , constant for  $t > 0$ .

If JOB = 2 or 3 (Card 3-a), then data ends here

4. Stress Analysis Information

The program will not read data in this section if  
NTEM = 0 (card 2a) and JOB = 2 or 3 (card 3a)

a. Title card (20A4)

cc

1-8 HED Any alpha numeric information (printed with  
the solution)

b. Control Card (5I5, 2(F10.0, I5), 3I5, F10.0)

cc

1-5 NMAT Number of materials  $\leq 4$

6-10 NCMN Number of elements with material identification  
numbers which are to be redefined.

11-15 NBCN Number of node points for which boundary  
cards are used  $\leq 60$

16-20 NPC Number of pressure cards  $\leq 55$

21-25 NDMG Number of elements for damage evaluation  $\leq 20$

26-35 ANGV Angular velocity amplitude, (R) (T)<sup>-1</sup>

36-40 NFAV Function number for ANGV

41-50 AZZ Axial acceleration amplitude, (L) (T)<sup>-2</sup>

51-55 NFAZ Function number for AZZ

56-60 IDSF Pressure boundary condition function no.  
for use of pressurization shift function data

61-65 IPSC Geometry type flag

IPSC = 0 Axisymmetric analysis  
= 1 Plane strain analysis  
= 2 Generalized plane strain analysis  
= 3 Generalized plane stress analysis

66-70 NSM Material No. (if IPSC = 2) of case material

71-80 SZV Value of normal stress (if IPSC = 3)  
(F) (L)<sup>-2</sup>

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NMAT is the total number of materials (viscoelastic and elastic).

If the material I.D. numbers assigned to the elements in Section 1-d are appropriate for both the heat transfer and stress analyses, then NCMN is set to zero (or blank). NBCN is a count of nodes at which force and/or displacement boundary values are specified. NPC is the total number of element sides subjected to pressure loads.

IDSP is the boundary condition function number which describes the bulk pressure as a function of time when an isothermal pressurization case is being run. For a thermal analysis leave this field blank. This function will be used to find the pressurization shift function values in the properties determination and also will be used in the damage calculations. When IPSC - 2 a special generalized plane strain analysis will be run. The normal strain will be set equal to the average thermal strain ( $\alpha_c \Delta T_c$ ) in the case which is found by the material number NSM specified in cc 66-70.

c. Material Properties

(1) Control Card (3I5, 4F10.0)

cc

1-5 K Material number

6-10 NON(K) Number of terms in the Prony series representation of the shear relaxation function.  $\leq 16$

11-15 NSFP(K) Number of points in the shift function table.  $\leq 16$

16-25 APO(K) Equilibrium shear modulus, (F) (L)<sup>-2</sup>

26-35 XK(K) Bulk modulus, (F)(L)<sup>-2</sup>

36-45 AIP(K) Linear coefficient of thermal expansion, (L)(L)<sup>-1</sup>(°F)<sup>-1</sup>

46-55 DENS(K) Mass density, (F)(L)<sup>-4</sup>(T)<sup>2</sup>

The shear relaxation function is written in the form:

$$\phi(t) = A_0 + \sum_{i=1}^M A_i e^{-\beta_i t}$$

where

NON(K) = M for the K<sup>th</sup> material  
APO(K) = A<sub>0</sub> for the K<sup>th</sup> material

An elastic material is input by leaving cc 6-15 blank and entering the shear and bulk moduli in cc 16-25 and cc 26-35, respectively. A non-zero value of density is required for the calculation of body forces arising from specified values of spin velocity and/or axial acceleration.

(2) Prony Series Coefficients Card(s) (8F10.0)

Skip this section if NON(K) = 0

cc

1-10	AP(K, 1)	A <sub>1</sub> for material K	(F)(L) <sup>-2</sup>
11-20	BP(K, 1)	$\beta_1$	(T) <sup>-1</sup>
21-30	AP(K, 2)	A <sub>2</sub>	(F)(L) <sup>-2</sup>
31-40	BP(K, 2)	$\beta_2$	(T) <sup>-1</sup>
41-50	AP(K, 3)	A <sub>3</sub>	(F)(L) <sup>-2</sup>

etc.

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Use as many cards in this section as are required to specify  
NOM(K) pairs of  $(A_1, \beta_1)$ ; four pairs per card.

(3) Shift Function Table (3F10.0)

Skip this section if NSFP(K) = 0

cc

1-10	FST(K,1)	Temperature at 1st point, $T_1$ ( $^{\circ}$ F)
11-20	FS(K,1)	$\text{Log}_{10} a_{T_1}$
21-30	FST(K,2)	Temperature at 2nd point, $T_2$ ( $^{\circ}$ F)
31-40	FS(K,2)	$\text{Log}_{10} a_{T_2}$
41-50	FST(K,3)	etc.

Use as many cards in this section as are required to specify  
NSFP(K) pairs of  $(T_1, \text{Log}_{10} a_T)$ ; four pairs per card. If IDSP > 0 (card

4b) FST (K, 1) will be interpreted as pressures and FS (K, 1) are  $\text{Log}_{10} a_p$ .

d. Element Material Numbers

Skip this section if NCMN = 0

cc

1-5	N1 (1)	Element number
6-10	N2 (1)	Material number assigned to element N1 (1)
11-15	N3 (1)	Number of elements with the same material number as element N1 (1)
16-20	N4 (1)	Element number increment
21-25	N1 (2)	Element number
26-30	N2 (3)	Material number assigned to element N1 (2)
31-35	N3 (2)	Number of elements with the same material number as element N1 (2)

etc.

Use as many cards in this section as are required to re-define the material numbers of NCMN elements; 16 entries per card are possible.

Suppose that a 50 element problem is to have all its material numbers changed (NCMN = 50), and all even numbered elements are material 1 while all odd elements are material 2; one card describing these changes would read:

[1, 2, 24, 2, 2, 1, 24, 2]

e. Node Point Boundary Specification(s)

At least one card in this section

(I5, 2(I5, F10.0, I5))

cc

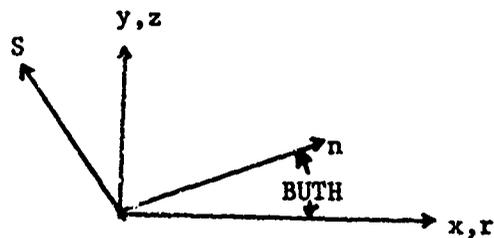
1-5	K	Node point number (NB(N) = K)	
6-10	NFLR(N)	Radial boundary condition type	
		$\left\{ \begin{array}{l} = 0; \text{externally applied } \underline{\text{force}} \\ = 1; \text{specified } \underline{\text{displacement}} \end{array} \right.$	$\begin{array}{l} (F) (R)^{-1} \\ (L) \end{array}$
11-20	BVR(N)	Radial boundary value amplitude	
21-25	NFNR(N)	Function Number	
26-30	NFLZ(N)	Axial boundary condition type	
		$\left\{ \begin{array}{l} = 0; \text{externally applied } \underline{\text{force}} \\ = 1; \text{specified } \underline{\text{displacement}} \end{array} \right.$	$\begin{array}{l} (F) (R)^{-1} \\ (L) \end{array}$
31-40	BVZ(N)	Axial boundary value amplitude	
41-45	NFNZ(N)	Function number	
46-55	BUTH(N)	Skew boundary angle (degrees)	

A total of NBCN cards must be prepared in this section. The axial displacement at one node must be specified as a minimum requirement.

Positive boundary values are in the direction of the positive coordinate axes.

Zero (or blank) function numbers assigned to boundary value components implies time independence (constant for  $t > 0$ ). The variation of a boundary value with time is determined by multiplying amplitude times the appropriate value of the corresponding function. All nodes not specified in this section are assumed to have no externally applied loads and are free to displace as the solution dictates.

The shew boundary is shown in the figure below. If  $BUTH(N) \neq 0$  the boundary conditions are expressed in the n-s system.



f. Pressure Loads

Skip this section if NPC = 0

cc

1-5	IPC(N)	Node number i
6-10	JPC(N)	Node number j
11-20	PR(N)	Pressure amplitude (F) (L) <sup>-2</sup>
21-25	NFNP(N)	Function

There are NPC cards in this section.  $NFNP(N) = 0$  means that pressure is applied as a step function at  $t = 0^+$ .

Positive pressure acts in the direction shown in Figure 4.1.

g. Damage Parameters

Skip this section if NDMG = 0

cc

1-5	LDMG(N)	Element no. whose damage is to be evaluated
6-15	STZR(N)	$\sigma_{to}$
16-25	TZR(N)	$t_o$ See below
26-35	SCR(N)	$\sigma_{cr}$

There are NDMG cards in this section. LDMG(N) may be positive or negative. If positive, the hoop stress will be used in damage calculations; if negative the maximum principal r-z stress will be used. The damage is evaluated using

$$PED_t = \frac{1}{a_T} \int_0^t \frac{(\sigma(t') - \sigma_{cr} + P(t'))^B}{(\sigma_{to} - \sigma_{cr})^B a_p (P(t'))} dt$$

If IDSP = 0 (card 4b) then  $P(t') = 0$  for all times. If IDSP > 0 the  $P(t')$  will be found from the boundary condition function indicated by IDSP.

Data input ends at this point

IV. PROGRAM OUTPUT DESCRIPTION

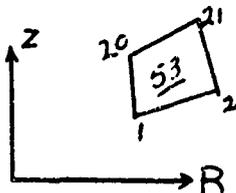
Output from the program includes:

1. Input geometry, material properties and solution time information in a self-explanatory format.
2. Nodal point temperatures at the specified time-point interval.
3. The radial, tangential, axial and shear stresses and strains and the average element temperature at the specified time-print interval.
4. The damage rate and accumulated damage for specific elements at each time-print interval.

The printed program output consists of (1) "echo" reproduction of the data input cards identified in self-explanatory format, and (2) results of the analysis which might include nodal point temperatures, element stresses/strains, node displacements, etc.

A. ELEMENT NODE NUMBERING

It should be noted that element node number data may not be listed in the same order as these data appear on the input card. The program logic permutes the order of the element node numbers so that the largest node number is always last (4th) in the printed list for each element. For example, if element number 53 (shown below)



is input as (1, 2, 21, 20), the program will print the data as (20, 1, 2, 21) so that "21" is last while the original counter clockwise order is preserved. Efficiency is gained if the user specifies the 4th node as the largest for every element.

The reason for having the largest node as last one in the sequence for a given element is that three (3) equations are assigned to this node as opposed to only two (2) equations per node for the others. A node number that is not the largest one in any element has the R and Z displacement components as its unknowns (2 total). All other nodes have R, Z displacement components plus the "mean pressure variable"  $H$  as unknowns at that point (3 total). Thus, node "21" of element "53" above has assigned to it  $U_{R21}$ ,  $U_{Z21}$ , and  $H_{53}$  as unknowns.



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$$PED_t = \frac{1}{a_t} \int_0^t \frac{(\sigma(t') - \sigma_{cr} + P(t'))^B}{(\sigma_{to} - \sigma_{cr})^B a_p (P(t'))} dt'$$

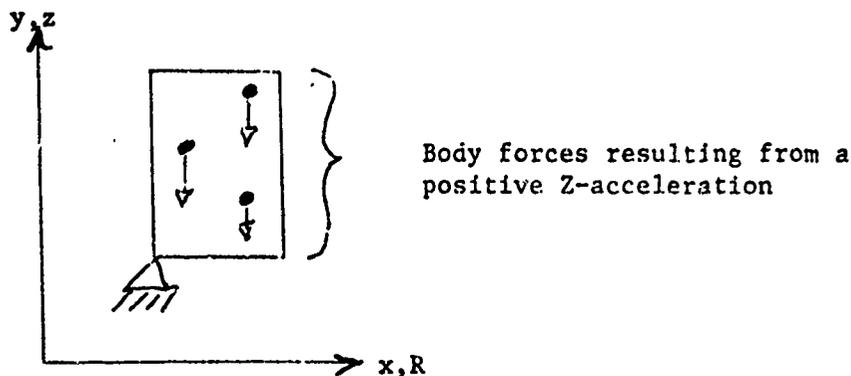
If IDSP = 0 (Card 4b) then  $P(t') = 0$  for all times. If IDSP > 0 the  $P(t')$  will be found from the boundary condition function indicated by IDSP.

The value of  $P(t')$  is that portion of the inner-bore firing pressure,  $P_i(t)$ , which is transmitted to the point in the grain where the principal stress,  $\sigma(t')$ , is evaluated. The relation of  $P(t')$  to  $P_i(t')$  in infinite-length cylinders is well known ( ) (See Section IV of this report). For finite length cylinders the ratio of  $P(t')$  to  $P_i(t)$  must be obtained from the stress analysis.

For metal cases  $P(t')$  seldom differs from  $P_i(t')$  by more than 5%. For most firing problems this difference is not significant and  $P(t')$  can be approximated by  $P_i(t')$ .

Data input ends at this point

A positive spin velocity produces hoop tension, and positive axial acceleration causes body forces to be applied on the body acting in the (-Z) direction:



## V. EXAMPLE PROBLEMS

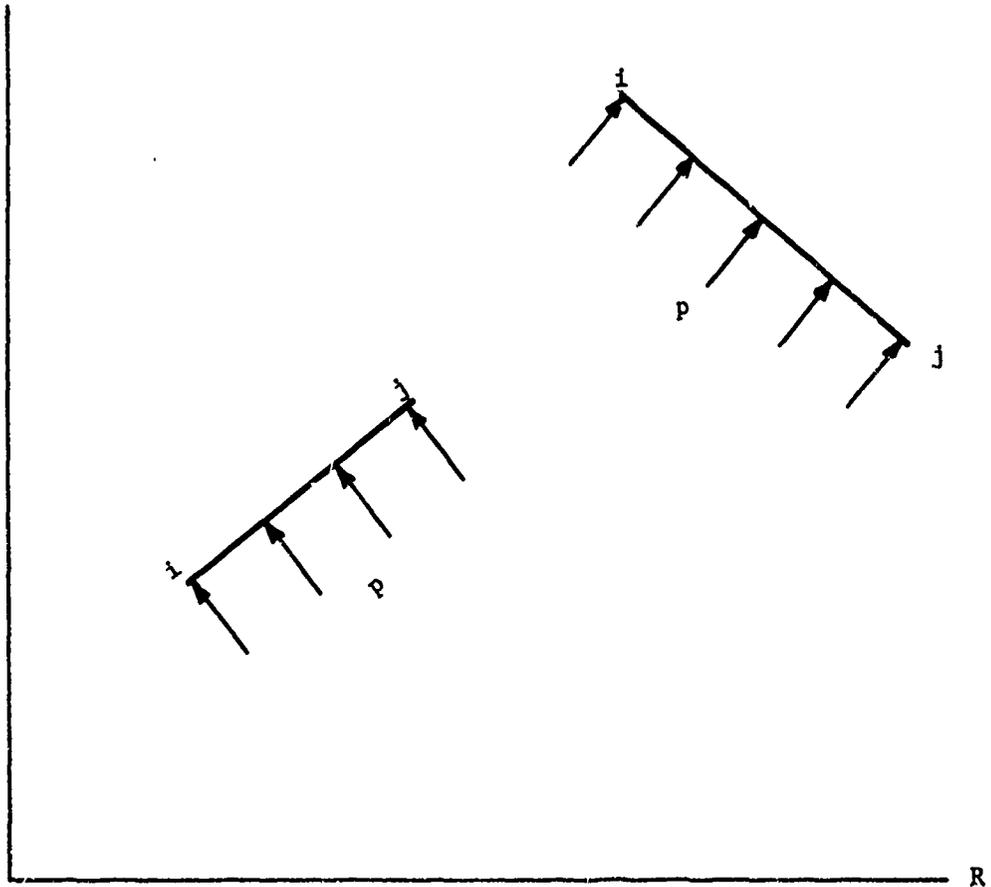
### A. TRANSIENT HEAT CONDUCTION IN A LONG CYLINDER

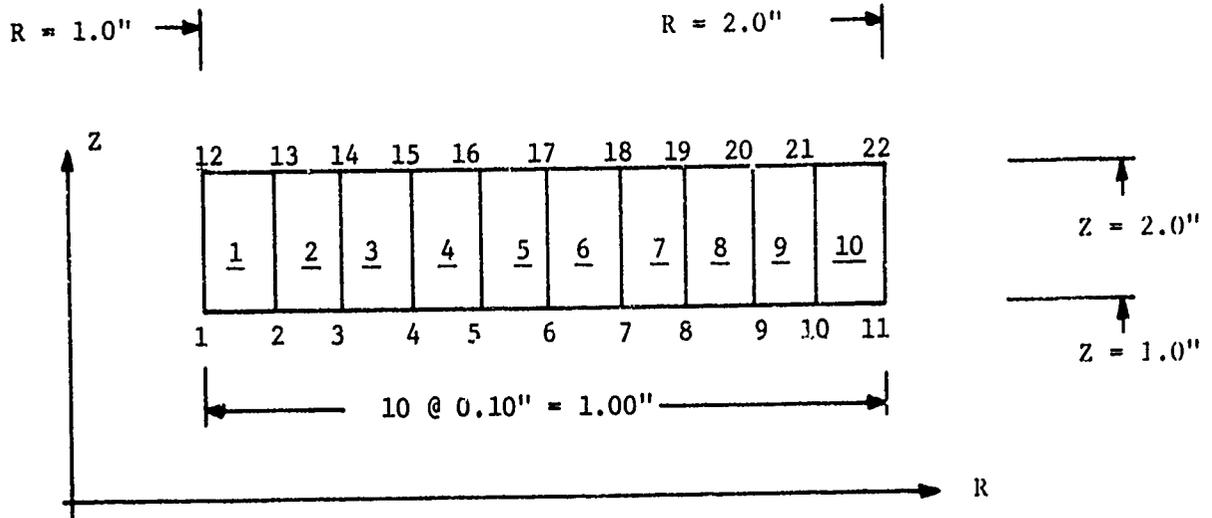
The purpose of this example is to illustrate the use of the program in solving heat conduction problems. A long, hollow cylinder constructed from a single material is initially at a uniform temperature of  $0^{\circ}\text{F}$ ; then, at  $t = 0$  the outer surface of the cylinder is instantaneously heated to  $1^{\circ}\text{F}$  along its entire length. The ends of the cylinder are insulated against axial heat flow so that at any axial station the heat flow is purely radial.

Figure H-4 shows a one (1) inch slice of the cylinder whose inner and outer radii are 1.00" and 2.00", respectively. The slice has been modeled with a mesh composed of ten (10) equal sized elements; the "Z" axis is the center-line of the cylinder. At time zero the temperature of nodes 11 and 22 is changed from  $0^{\circ}\text{F}$  ( $TZ = 0.0$ ) to  $1^{\circ}\text{F}$ , and as time proceeds the interior of the cylinder begins to warm up; thermal equilibrium is reached when the entire cylinder is at a uniform  $1^{\circ}\text{F}$ . Nodes 1-10 and 12-21 are insulated in the sense that no externally supplied heat enters the body at these points. The program assumes that all nodes not specifically included as boundary condition nodes are insulated against externally supplied heat flow; i.e., for all non-boundary nodes, the amount of heat entering a node must balance the amount of heat leaving that node in a unit of time.

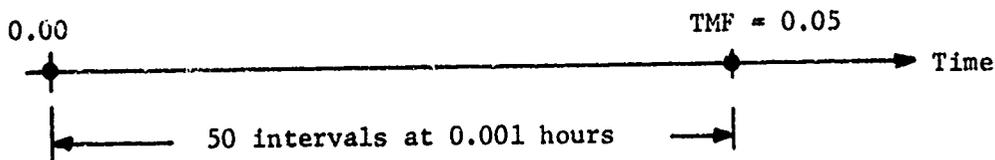
The solution span is sub-divided into fifty (50) equal time increments of 0.01 hours each so that the time at the end of solution is 0.050 hours ( $TMF = 0.05$ ), Figure H-5.

SIGN CONVENTION FOR PRESSURE LOADS

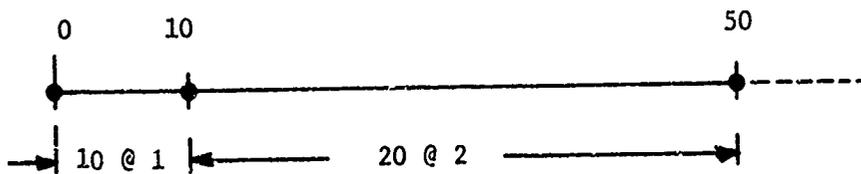




a. Mesh For Example Problem A



a. Solution Time Point Array



b. Solution Output Intervals

Figure H-5: Solution Time Point and Output Schedules

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The output printing schedule is set up so that results are printed at every solution time point for the first ten (10) increments and then at every other solution for the remaining forty (40) increments, Figure H-5.

10 print operations at an interval of 1 = 10  
20 print operations at an interval of 2 = 40  
50 increments

The thermal properties of the material are summarized as follows:

$$K_{rr} = 0.20 \text{ (Btu)(hr.)}^{-1} \text{ (in.)}^{-2} \text{ (}^{\circ}\text{F/in.)}^{-1}$$

$$K_{zz} = 0.20$$

$$K_{rz} = 0.$$

$$\text{Specific Heat} = 0.20 \text{ (Btu) (lb.)}^{-1} \text{ (}^{\circ}\text{F)}^{-1}$$

$$\text{Weight Density} = 0.20 \text{ (lb.) (in.)}^{-3}$$

$$\text{Heat generated per unit volume per unit time} = 0.*$$

The data cards for this job are shown in Table H-3.

Figure H-6 is a plot of temperature versus time for three (3) points in the cylinder: (1) outer surface (nodes 11 or 22); (2) mid-radius (nodes 6 or 17); and, (3) inner-radius (nodes 1 or 12). For long times, all nodes approach 1°F in the limit.

A value of 3 was assigned to the control variable "JOB" causing a termination of execution after the heat transfer solution. If the results were to be saved\*\*, then the node temperatures would be averaged for each element before saving the results.

#### B. ELASTIC RING SUBJECTED TO AXIAL TENSION

The purpose of this example is to illustrate the use of the program in solving elastic problems. A hollow, short cylinder is subjected to an axial tension of 6000 psi on one surface and restrained (without radial shear) against axial displacement on the opposite end (Figure H-7). The problem has been modeled with four (4) quadrilateral elements as shown in Figure H-8. The applied stress has been converted to equivalent concentrated loads of 4000, 12000, and 8000 lbs./radian applied at nodes 7, 8 and 9, respectively.

Output from the computer program is shown in Figure H-9 a, b and c.

For purposes of data preparation, unit heat generation is treated as a physical property which can vary from material to material.

\*\*JOB = 1 or 2



TRANSIENT TEMPERATURES IN THE CYLINDER OF EXAMPLE A

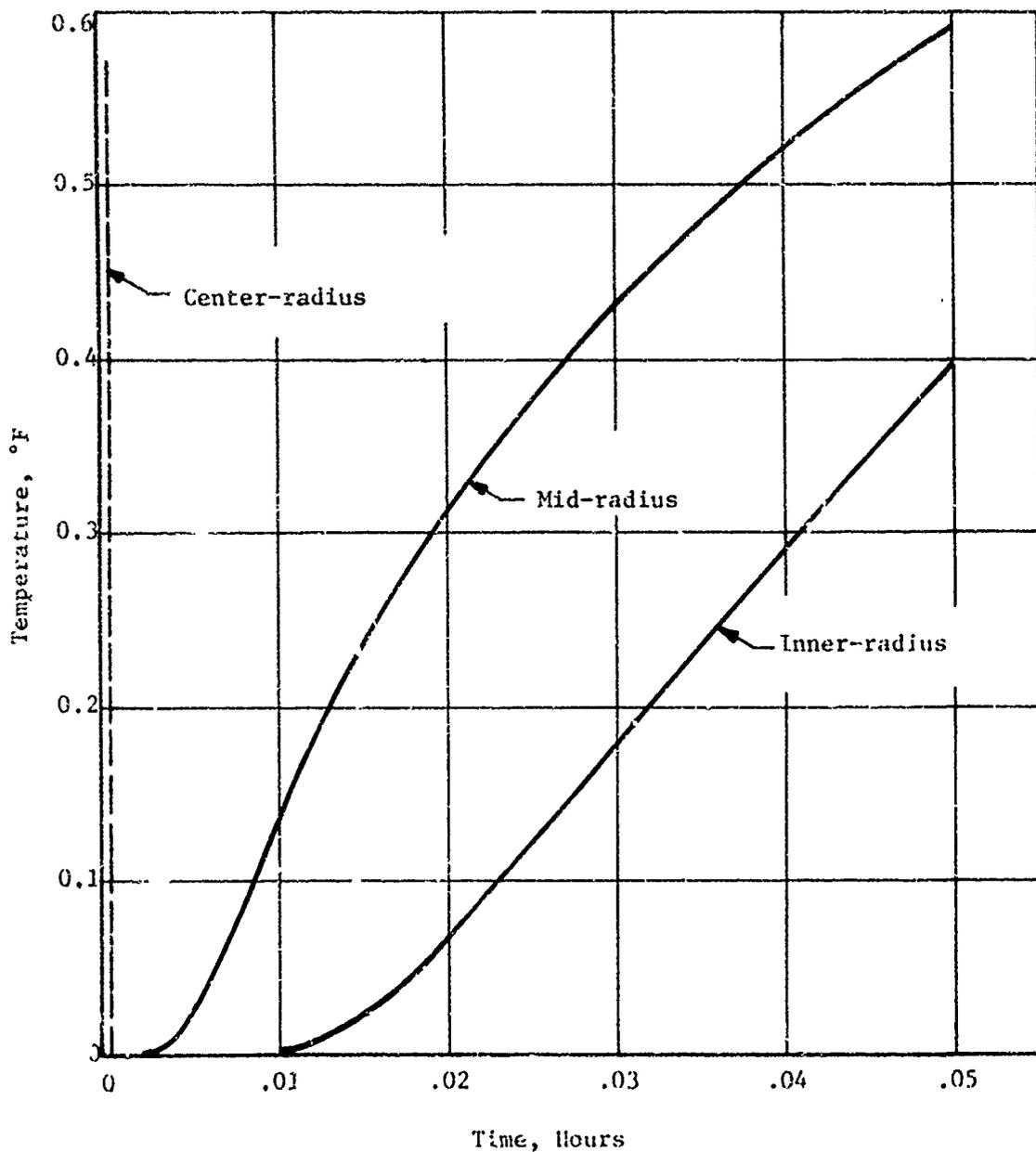
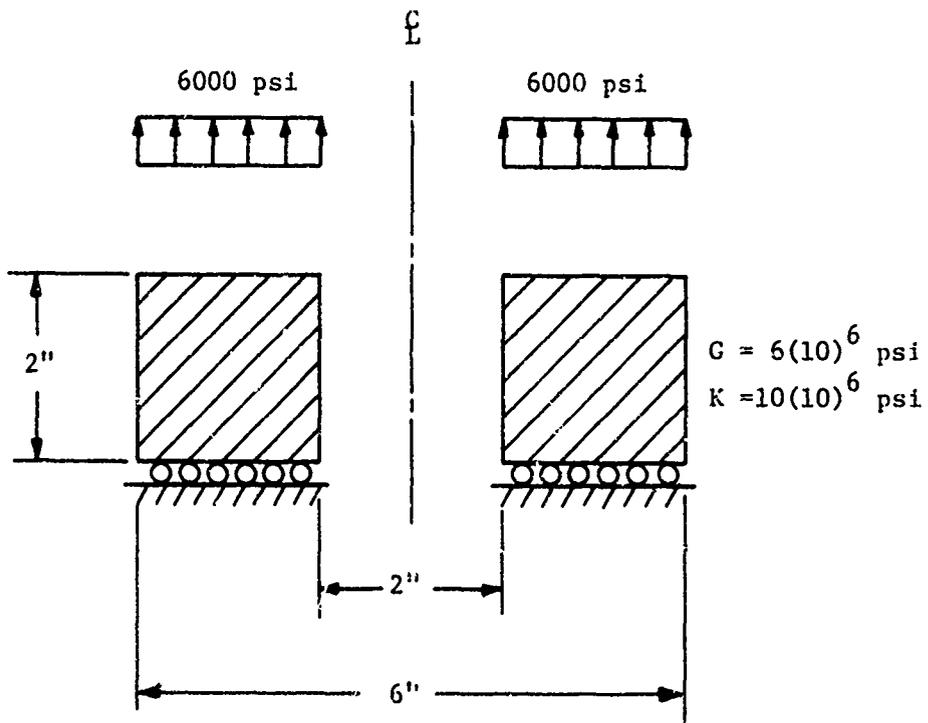


Figure H-6

EXAMPLE B: AXIAL LOADING OF AN ELASTIC CYLINDER



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GRID FOR EXAMPLE B

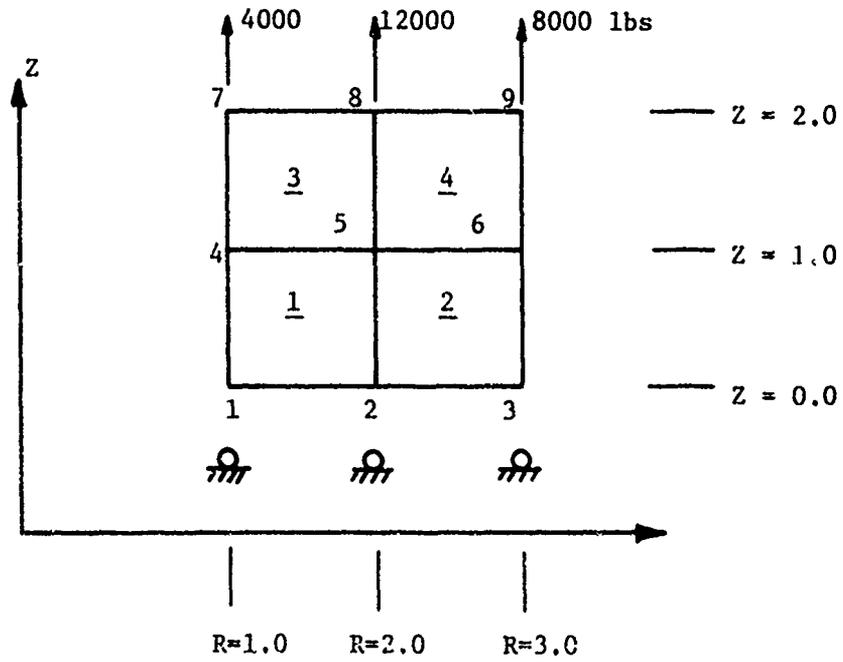


Figure H-8



APPENDIX H

MECHANICAL PROPERTIES INFORMATION

P/A = 6000.0 PSI, AXIAL

```

NUMBER OF MATERIALS..... 1
NUMBER OF ELEMENTS WITH REDEFINED MATERIALS..... 0
NUMBER OF NODES WITH SPECIFIED BOUNDARY VALUES..... 8
NUMBER OF PRESSURE CARDS..... 0
ANGULAR VELOCITY AMPLITUDE..... 0.0
ANGULAR VELOCITY FUNCTION..... 0
AXIAL ACCELERATION AMPLITUDE..... 0.0
AXIAL ACCELERATION FUNCTION..... 0
OUTPUT INTERVAL FLAG..... 0
DISPLACEMENT PRINT CONTROL FLAG..... 0
    
```

MATERIALS DATA

MATERIAL NUMBER	TERMS IN PRONY SERIES	POINTS IN SHIFT FUNCTION	EQUILIBRIUM MODULUS	BULK MODULUS	EXPANSION COEFFICIENT
1	0	0	6000000.000	10000000.000	0.0

SERIES REPRESENTATION OF THE SHEAR RELAXATION FUNCTIONS

MATERIAL NUMBER	TERM IN THE SERIES	COEFFICIENT ALPHA(I)	EXPONENT BETA(I)
1	ELASTIC MATERIAL (NO SERIES EXPANSION)		

TABULATION OF TIME-TEMPERATURE SHIFT FUNCTIONS

MATERIAL NUMBER	POINT NUMBER	TEMPERATURE T(I)	SHIFT FACTOR LOG-10 A(T(I))
1	TEMPERATURE INDEPENDENT MATERIAL		

NOT REPRODUCIBLE

NODAL POINT BOUNDARY CONDITIONS

NODE NUMBER	TYPE CODE	P A D I A L BOUNDARY VALUE	FUNCTION NUMBER	TYPE CODE	A X I A L BOUNDARY VALUE	FUNCTION NUMBER
1	0	C.C	0	1	0.0	0
2	0	C.C	0	1	0.0	0
3	0	C.C	0	1	0.0	0
4	0	C.C	0	0	0.0	0
5	0	C.C	0	0	0.0	0
7	0	C.C	0	0	0.0	0
8	0	C.C	0	0	0.400000E 04	0
9	0	C.C	0	0	0.120000E 05	0
0	0	C.C	0	0	0.900000E 04	0

NODE	DISPLACEMENT	TIME =
1	-1.00000E-04	6.00000E 01
2	-2.00000E-04	
3	-3.00001E-04	
4	-1.00001E-04	
5	-2.00001E-04	
6	-3.00002E-04	
7	-1.00003E-04	
8	-2.00003E-04	
9	-3.00003E-04	

Figure H-9b

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	SIGY	SIGX	SIGZ	SICRZ
1	-1.22070E-03	-7.41250E-03	6.00000E 03	-4.14729E-03
2	-4.39453E-03	1.22070E-03	6.00002E 03	-2.48838E-03
3	-9.76562E-03	-2.73437E-02	6.00001E 03	-4.36557E-05
4	-4.15039E-03	-9.76562E-03	6.00001E 03	-3.97267E-03

	EPR	FPTF	FPZ	EPRZ	TEM
	-9.39799E-05	-1.00000E-04	4.00000E-04	-6.91216E-10	0.0
	-1.00001E-04	-1.00000E-04	4.00002E-04	-4.14730E-10	0.0
	-9.99799E-05	-1.00001E-04	4.00002E-04	-7.27596E-12	0.0
	-1.00000E-04	-1.00001E-04	4.00001E-04	-6.62112E-10	0.0

Figure H-9c

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Appendix II

The solution time span which has no meaning when constant loads are applied to elastic media consists of one (1) time increment arbitrarily selected as being 60 seconds long; one print operation is performed at the end of the first (and only) time increment. The average temperature of all elements is read in as 0°F. The pertinent mechanical properties are the shear ( $G = 6(10)^6$  psi) and bulk ( $K = 10(10)^6$  psi) moduli of the material. There were eight (8) of the nine (9) nodes designated as boundary nodes; nodes 4 and 6 are unloaded and unrestrained and do not have to appear in the statement of boundary conditions. Nodes 4 and 6 were inadvertently retained from a previous data deck.

The results consist of R and Z displacements of each node, average element stresses and strains and the average element temperatures all quoted at  $t_1 = 60$  seconds. The applied axial stress is recovered exactly as 6000 psi (SIGZ) constant in each element.

C. PLANE-STRAIN VISCOELASTIC CYLINDER, EXAMPLE PROBLEM

The problem is a long cylindrical bore propellant grain (1.50 I.D., 8.0 O.D.) in a .060 steel case. The element geometry is shown in Figure H-10. The propellant relaxation and shift function curves are shown in Figures H-11 and H-12. Sixteen decade reduced time points were used to perform a prony series curve fit to the relaxation function and the coefficients are shown in Table H-4.

The motor, initially stress free at 135°F, was subjected to the thermal environment, through a heat transfer coefficient at the case, shown in Figure H-13. All nodes in the system were fixed in the axial direction to simulate a plane strain condition and the linear cumulative damage was calculated for two elements in the system, one at bore and one next to the case - grain bond.

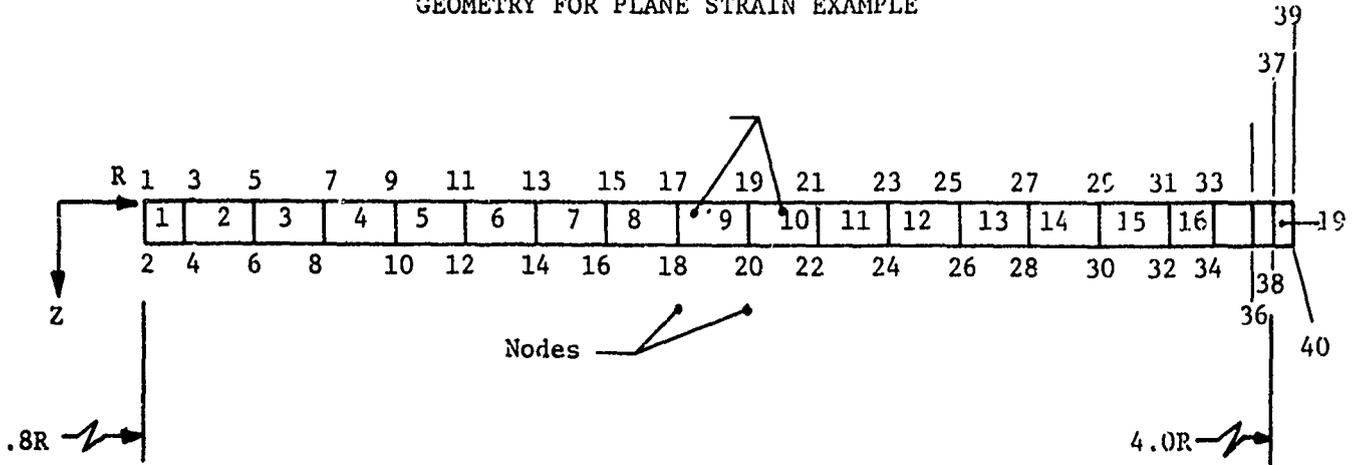
A listing of the data input cards required to describe this problem is shown in Table H-5. Line 2 is the title; line 3 is the control card; lines 4-9 describe the node point coordinates; lines 10, 11 establish the element I.D.; line 12 is the solution time point and reference temperature control and lines 13-29 describe the solution time points. Lines 31-36 describe the free stream temperature function. Line 37 describes the output print interval. Lines 39 and 40 are the thermal properties for the grain and case. Line 41 describes the convection boundary condition. Line 42 is the stress analysis title card and 43 is the stress control card. Lines 45-48 are the relaxation series coefficients. Lines 49-51 are the shift function points. Line 52 describes the case properties. Lines 53-92 are the displacement boundary conditions. The last two lines give the damage parameters.

Selected portions of the output from this analysis are shown in Table H-6.

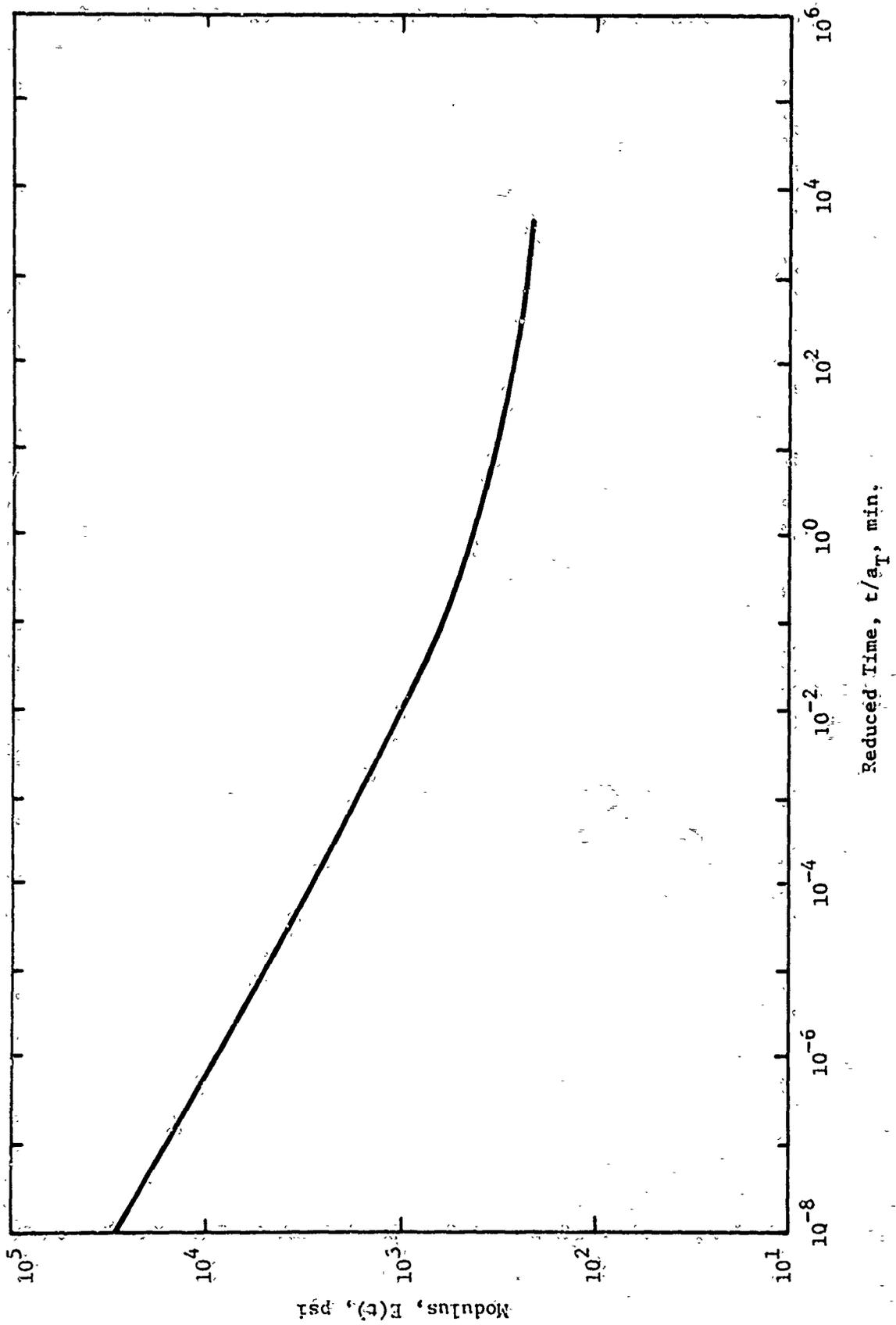
Aerojet Solid Propulsion Company  
Report 1341-26F

Appendix II

GEOMETRY FOR PLANE STRAIN EXAMPLE



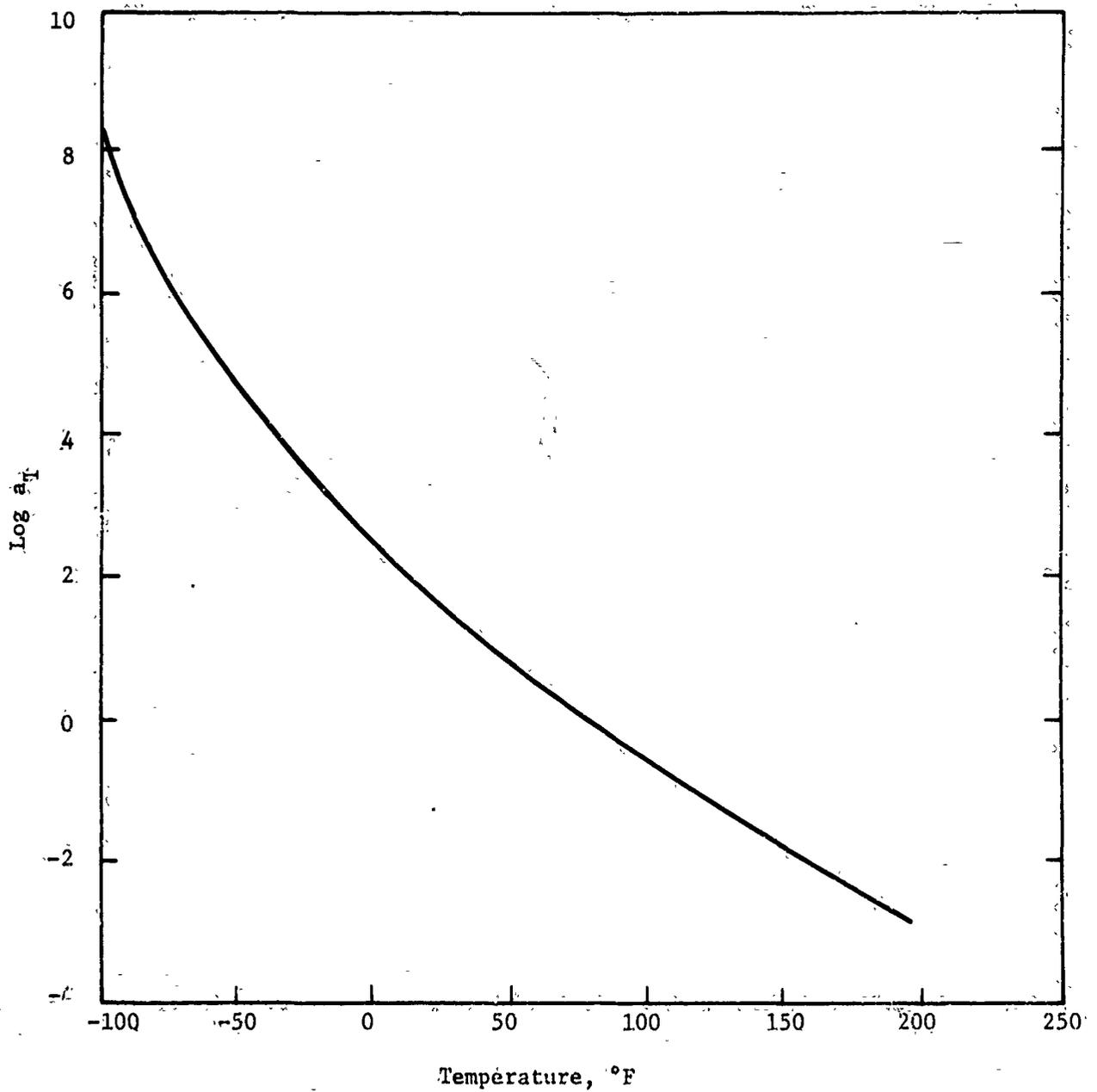
RELAXATION MODULUS OF A CTPB PROPELLANT



Aerojet Solid Propulsion Company  
Report 1341-26F

Appendix H

TIME TEMPERATURE SHIFT FACTORS FOR A CTPB PROPELLANT



Aerojet Solid Propulsion Company  
Report 1341-26F

Appendix H

Propellant Relaxation Function

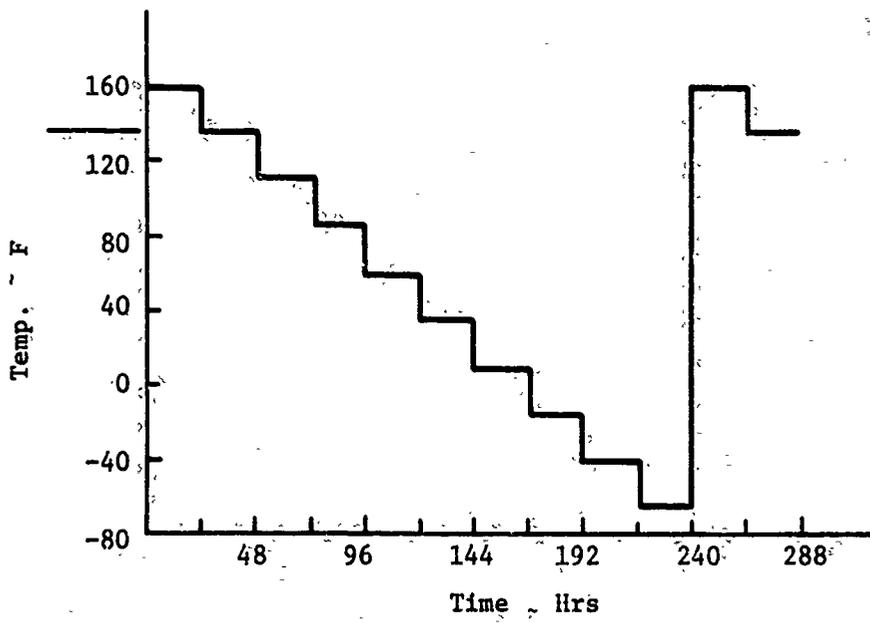
$\log(t/a_T)$ (min)	$E_r$ (psi)	$B_i$ (hr <sup>-1</sup> )	$A_i$	$A_i/3$	$i$
			100	33.333	0
-9	44000	$3 \times 10^{10}$	25836	8612	1
-8	29000	$3 \times 10^9$	12087	4029	2
-7	14000	$3 \times 10^8$	6919.2	2306.4	3
-6	8300	$3 \times 10^7$	3915.5	1305.2	4
-5	5000	$3 \times 10^6$	2435.2	811.40	5
-4	3000	$3 \times 10^5$	1341.9	447.3	6
-3	1800	$3 \times 10^4$	1033.9	344.63	7
-2	1000	$3 \times 10^3$	457.98	152.66	8
-1	620	$3 \times 10^2$	265.80	88.60	9
0	410	$3 \times 10^1$	137.74	45.91	10
1	320	$3 \times 10^0$	.16481	.0546	11
2	280	$3 \times 10^{-1}$	113.47	37.82	12
3	210	$3 \times 10^{-2}$	-2.9029	-.9676	13
4	190	$3 \times 10^{-3}$	60.2506	20.0835	14
5	150	$3 \times 10^{-4}$	4.26975	1.42325	15
6	130	$3 \times 10^{-5}$	49.4143	1.64714	16

$$E_r = A_0 + \sum_{i=1}^{16} A_i e^{-B_i t}$$

Aerojet Solid Propulsion Company  
Report 1341-26F

Appendix H

FREE-STREAM TEMPERATURE  
( $H = .0125 \text{ BTU/HR/IN.}^2/\text{F}$ )



H-47

Figure H-13

APPENDIX H

Data Input for Example Problem 3

VISCOELASTIC PARAMETER STUDY #A=5.00 B=0 EQUIVALENT PLANE STRAIN		VISCOELASTIC PARAMETER STUDY #A=5.00 B=0 EQUIVALENT PLANE STRAIN	
40	10	0.01	0.01
39	10	0.01	0.01
38	10	0.01	0.01
37	10	0.01	0.01
36	10	0.01	0.01
35	10	0.01	0.01
34	10	0.01	0.01
33	10	0.01	0.01
32	10	0.01	0.01
31	10	0.01	0.01
30	10	0.01	0.01
29	10	0.01	0.01
28	10	0.01	0.01
27	10	0.01	0.01
26	10	0.01	0.01
25	10	0.01	0.01
24	10	0.01	0.01
23	10	0.01	0.01
22	10	0.01	0.01
21	10	0.01	0.01
20	10	0.01	0.01
19	10	0.01	0.01
18	10	0.01	0.01
17	10	0.01	0.01
16	10	0.01	0.01
15	10	0.01	0.01
14	10	0.01	0.01
13	10	0.01	0.01
12	10	0.01	0.01
11	10	0.01	0.01
10	10	0.01	0.01
9	10	0.01	0.01
8	10	0.01	0.01
7	10	0.01	0.01
6	10	0.01	0.01
5	10	0.01	0.01
4	10	0.01	0.01
3	10	0.01	0.01
2	10	0.01	0.01
1	10	0.01	0.01
0	10	0.01	0.01

Table H-6

APPENDIX H

Table H-6  
Computer Output for Example Problem C

TWO-DIMENSIONAL TIME/INVISCIDELASTIC ANALYSIS  
VISCOELASTIC PARAMETER STUDY B/A=9.00 B=4 EQUIVALENT PLANE STRAIN MIP=1

CONTROL PARAMETERS  
NUMBER OF NODES ..... 40  
NUMBER OF ELEMENTS .... 19

NODE COORDINATE DATA

NODE	R-COORDINATE	Z-COORDINATE
1	0.00000	0.00000
2	0.50000	0.10000
3	0.90000	0.00000
4	0.50000	0.10000
5	1.10714	0.00000
6	1.10714	0.10000
7	1.31428	0.00000
8	1.31428	0.10000
9	1.52143	0.00000
10	1.52143	0.10000
11	1.72857	0.00000
12	1.72857	0.10000
13	1.93571	0.00000
14	1.93571	0.10000
15	2.14285	0.00000
16	2.14285	0.10000
17	2.35000	0.00000
18	2.35000	0.10000
19	2.55714	0.00000
20	2.55714	0.10000
21	2.76428	0.00000
22	2.76428	0.10000
23	2.97142	0.00000
24	2.97142	0.10000
25	3.17857	0.00000
26	3.17857	0.10000
27	3.38570	0.00000
28	3.38570	0.10000
29	3.59284	0.00000
30	3.59284	0.10000
31	3.80000	0.00000
32	3.80000	0.10000
33	4.00000	0.00000
34	4.00000	0.10000
35	4.20000	0.00000
36	4.20000	0.10000
37	4.40000	0.00000
38	4.40000	0.10000
39	4.60000	0.00000
40	4.60000	0.10000

Table 5-6 (cont.)

ELEMENT DATA	ELEMENT	NODE 1	NODE 2	NODE 3	NODE 4	MATERIAL
	1	2	1	3	4	1
	2	3	2	4	1	1
	3	4	3	1	2	1
	4	1	4	2	3	1
	5	2	1	3	4	1
	6	3	2	4	1	1
	7	4	3	1	2	1
	8	1	4	2	3	1
	9	2	1	3	4	1
	10	3	2	4	1	1
	11	4	3	1	2	1
	12	1	4	2	3	1
	13	2	1	3	4	1
	14	3	2	4	1	1
	15	4	3	1	2	1
	16	1	4	2	3	1
	17	2	1	3	4	1
	18	3	2	4	1	1
	19	4	3	1	2	1
	20	1	4	2	3	1
	21	2	1	3	4	1
	22	3	2	4	1	1
	23	4	3	1	2	1
	24	1	4	2	3	1
	25	2	1	3	4	1
	26	3	2	4	1	1
	27	4	3	1	2	1
	28	1	4	2	3	1
	29	2	1	3	4	1
	30	3	2	4	1	1
	31	4	3	1	2	1
	32	1	4	2	3	1
	33	2	1	3	4	1
	34	3	2	4	1	1
	35	4	3	1	2	1
	36	1	4	2	3	1
	37	2	1	3	4	1
	38	3	2	4	1	1
	39	4	3	1	2	1
	40	1	4	2	3	1

TIME - TEMPERATURE CONTROL INFORMATION

TOTAL NUMBER OF TIME INCREMENTS..... 336  
 NUMBER OF REGIONS WITH EQUAL TIME INCREMENTS..... 34  
 TIME AT END OF LAST TIME INCREMENT..... 298.000  
 NUMBER OF TIME DEPENDENT BOUNDARY CONDITION FUNCTIONS..... 1  
 ELEMENT TEMPERATURE FLAG..... 0  
 STRESS-FREE TEMPERATURE..... 135.000

APPENDIX H

Table S.4. (cont.)

SOLUTION TIME POINTS	REGION	NUMBER OF INCREMENTS	INCREMENT VALUE
1		1	0.0250
2		2	0.0550
3		3	0.1700
4		4	0.4500
5		5	0.8000
6		6	1.5000
7		7	3.0000
8		8	0.0250
9		9	0.0550
10		10	0.1700
11		11	0.4500
12		12	0.8000
13		13	1.5000
14		14	3.0000
15		15	0.0250
16		16	0.0550
17		17	0.1700
18		18	0.4500
19		19	0.8000
20		20	1.5000
21		21	3.0000
22		22	0.0250
23		23	0.0550
24		24	0.1700
25		25	0.4500
26		26	0.8000
27		27	1.5000
28		28	3.0000
29		29	0.0250
30		30	0.0550
31		31	0.1700
32		32	0.4500
33		33	0.8000
34		34	1.5000
35		35	3.0000
36		36	0.0250
37		37	0.0550
38		38	0.1700
39		39	0.4500
40		40	0.8000
41		41	1.5000
42		42	3.0000
43		43	0.0250
44		44	0.0550
45		45	0.1700
46		46	0.4500
47		47	0.8000
48		48	1.5000
49		49	3.0000
50		50	0.0250
51		51	0.0550
52		52	0.1700
53		53	0.4500
54		54	0.8000
55		55	1.5000
56		56	3.0000
57		57	0.0250
58		58	0.0550
59		59	0.1700
60		60	0.4500
61		61	0.8000
62		62	1.5000
63		63	3.0000
64		64	0.0250
65		65	0.0550
66		66	0.1700
67		67	0.4500
68		68	0.8000
69		69	1.5000
70		70	3.0000
71		71	0.0250
72		72	0.0550
73		73	0.1700
74		74	0.4500
75		75	0.8000
76		76	1.5000
77		77	3.0000
78		78	0.0250
79		79	0.0550
80		80	0.1700
81		81	0.4500
82		82	0.8000
83		83	1.5000
84		84	3.0000
85		85	0.0250
86		86	0.0550
87		87	0.1700
88		88	0.4500
89		89	0.8000
90		90	1.5000
91		91	3.0000
92		92	0.0250
93		93	0.0550
94		94	0.1700
95		95	0.4500
96		96	0.8000
97		97	1.5000
98		98	3.0000
99		99	0.0250
100		100	0.0550
101		101	0.1700
102		102	0.4500
103		103	0.8000
104		104	1.5000
105		105	3.0000
106		106	0.0250
107		107	0.0550
108		108	0.1700
109		109	0.4500
110		110	0.8000
111		111	1.5000
112		112	3.0000
113		113	0.0250
114		114	0.0550
115		115	0.1700
116		116	0.4500
117		117	0.8000
118		118	1.5000
119		119	3.0000
120		120	0.0250
121		121	0.0550
122		122	0.1700
123		123	0.4500
124		124	0.8000
125		125	1.5000
126		126	3.0000
127		127	0.0250
128		128	0.0550
129		129	0.1700
130		130	0.4500
131		131	0.8000
132		132	1.5000
133		133	3.0000
134		134	0.0250
135		135	0.0550
136		136	0.1700
137		137	0.4500
138		138	0.8000
139		139	1.5000
140		140	3.0000
141		141	0.0250
142		142	0.0550
143		143	0.1700
144		144	0.4500
145		145	0.8000
146		146	1.5000
147		147	3.0000
148		148	0.0250
149		149	0.0550
150		150	0.1700
151		151	0.4500
152		152	0.8000
153		153	1.5000
154		154	3.0000
155		155	0.0250
156		156	0.0550
157		157	0.1700
158		158	0.4500
159		159	0.8000
160		160	1.5000
161		161	3.0000
162		162	0.0250
163		163	0.0550
164		164	0.1700
165		165	0.4500
166		166	0.8000
167		167	1.5000
168		168	3.0000
169		169	0.0250
170		170	0.0550
171		171	0.1700
172		172	0.4500
173		173	0.8000
174		174	1.5000
175		175	3.0000
176		176	0.0250
177		177	0.0550
178		178	0.1700
179		179	0.4500
180		180	0.8000
181		181	1.5000
182		182	3.0000
183		183	0.0250
184		184	0.0550
185		185	0.1700
186		186	0.4500
187		187	0.8000
188		188	1.5000
189		189	3.0000
190		190	0.0250
191		191	0.0550
192		192	0.1700
193		193	0.4500
194		194	0.8000
195		195	1.5000
196		196	3.0000
197		197	0.0250
198		198	0.0550
199		199	0.1700
200		200	0.4500
201		201	0.8000
202		202	1.5000
203		203	3.0000
204		204	0.0250
205		205	0.0550
206		206	0.1700
207		207	0.4500
208		208	0.8000
209		209	1.5000
210		210	3.0000
211		211	0.0250
212		212	0.0550
213		213	0.1700
214		214	0.4500
215		215	0.8000
216		216	1.5000
217		217	3.0000
218		218	0.0250
219		219	0.0550
220		220	0.1700
221		221	0.4500
222		222	0.8000
223		223	1.5000
224		224	3.0000
225		225	0.0250
226		226	0.0550
227		227	0.1700
228		228	0.4500
229		229	0.8000
230		230	1.5000
231		231	3.0000
232		232	0.0250
233		233	0.0550
234		234	0.1700
235		235	0.4500
236		236	0.8000
237		237	1.5000
238		238	3.0000
239		239	0.0250
240		240	0.0550
241		241	0.1700
242		242	0.4500
243		243	0.8000
244		244	1.5000
245		245	3.0000
246		246	0.0250
247		247	0.0550
248		248	0.1700
249		249	0.4500
250		250	0.8000
251		251	1.5000
252		252	3.0000
253		253	0.0250
254		254	0.0550
255		255	0.1700
256		256	0.4500
257		257	0.8000
258		258	1.5000
259		259	3.0000
260		260	0.0250
261		261	0.0550
262		262	0.1700
263		263	0.4500
264		264	0.8000
265		265	1.5000
266		266	3.0000
267		267	0.0250
268		268	0.0550
269		269	0.1700
270		270	0.4500
271		271	0.8000
272		272	1.5000
273		273	3.0000
274		274	0.0250
275		275	0.0550
276		276	0.1700
277		277	0.4500
278		278	0.8000
279		279	1.5000
280		280	3.0000
281		281	0.0250
282		282	0.0550
283		283	0.1700
284		284	0.4500
285		285	0.8000
286		286	1.5000
287		287	3.0000
288		288	0.0250
289		289	0.0550
290		290	0.1700
291		291	0.4500
292		292	0.8000
293		293	1.5000
294		294	3.0000
295		295	0.0250
296		296	0.0550
297		297	0.1700
298		298	0.4500
299		299	0.8000
300		300	1.5000
301		301	3.0000
302		302	0.0250
303		303	0.0550
304		304	0.1700
305		305	0.4500
306		306	0.8000
307		307	1.5000
308		308	3.0000
309		309	0.0250
310		310	0.0550
311		311	0.1700
312		312	0.4500
313		313	0.8000
314		314	1.5000
315		315	3.0000
316		316	0.0250
317		317	0.0550
318		318	0.1700
319		319	0.4500
320		320	0.8000
321		321	1.5000
322		322	3.0000
323		323	0.0250
324		324	0.0550
325		325	0.1700
326		326	0.4500
327		327	0.8000
328		328	1.5000
329		329	3.0000
330		330	0.0250
331		331	0.0550
332		332	0.1700
333		333	0.4500
334		334	0.8000
335		335	1.5000
336		336	3.0000
337		337	0.0250
338		338	0.0550
339		339	0.1700
340		340	0.4500
341		341	0.8000
342		342	1.5000
343		343	3.0000
344		344	0.0250
345		345	0.0550
3			



APPENDIX H.

Table H-4 (cont.)

MECHANICAL PROPERTIES INFORMATION  
VISCOELASTIC PARAMETER STUDY 8/4/53.00 8% EQUIVALENT PLANE STRAIN

NUMBER OF MATERIALS WITH DESIGNED MATERIALS..... 2  
 NUMBER OF ELEMENTS WITH SPECIFIED BOUNDARY VALUES..... 40  
 NUMBER OF PRESSURE CARDS..... 0  
 NUMBER OF ELEMENTS FOR DAMAGE EVALUATION..... 2  
 ANGULAR VELOCITY AMPLITUDE..... 0.0  
 AXIAL ACCELERATION AMPLITUDE..... 0.0  
 AXIAL ACCELERATION FUNCTION..... 0  
 DISPLACEMENT PRINT CONTROL FLAG..... 0

MATERIALS DATA

MATERIAL NUMBER	PRONY SERIES	TERMS IN SHIFT FUNCTION	POINTS IN EQUILIBRIUM MODULUS	BULK MODULUS	EXPANSION COEFFICIENT	HEIGHT DENSITY
1	16	12	33,300	500000.000	0.56700E-04	0.0
2	10	6	11500000.000	25000000.000	0.59000E-03	0.0

SERIES REPRESENTATION OF THE SHEAR RELAXATION FUNCTIONS

MATERIAL NUMBER	TERM IN THE SERIES	COEFFICIENT ALPHA(I)	EXPONENT BETA(I)
1	1	0.80120E 04	0.30000E 11
1	2	0.40290E 04	0.30000E 10
1	3	0.23064E 04	0.30000E 09
1	4	0.13052E 04	0.30000E 08
1	5	0.81140E 03	0.30000E 07
1	6	0.44730E 03	0.30000E 05
1	7	0.34663E 03	0.30000E 05
1	8	0.15200E 03	0.30000E 04
1	9	0.88000E 02	0.30000E 03
1	10	0.45910E 02	0.30000E 02
1	11	0.54600E 01	0.30000E 01
1	12	0.37820E 02	0.30000E 00
1	13	0.96760E 00	0.30000E 01
1	14	0.20083E 02	0.30000E 02
1	15	0.1432E 01	0.30000E 03
1	16	0.16671E 01	0.30000E 06

2 ELASTIC MATERIAL (NO SERIES EXPANSION)

TEMPERATURE INDEPENDENT MATERIAL

MATERIAL NUMBER	POINT NUMBER	TEMPERATURE T(I)	SHIFT FACTOR LOG-10 A(T(I))
1	1	-100.000	6.2800
1	2	-75.000	6.0000
1	3	-50.000	4.6000
1	4	-25.000	3.5400
1	5	0.0	2.5200
1	6	25.000	1.6000
1	7	50.000	0.8000
1	8	77.000	0.0
1	9	100.000	-0.5600
1	10	125.000	-1.2200
1	11	150.000	-1.8200
1	12	200.000	-2.9400

Table H-6 Cont'd

APPENDIX H

Table H-6 (cont.)

NODAL POINT BOUNDARY CONDITIONS		1 A O I A L		A X I A L	
NODE NUMBER	TYPE CODE	BOUNDARY VALUE	FUNCTION NUMBER	BOUNDARY VALUE	FUNCTION NUMBER
1	0	0.00	0	0.00	0
2	0	0.00	0	0.00	0
3	0	0.00	0	0.00	0
4	0	0.00	0	0.00	0
5	0	0.00	0	0.00	0
6	0	0.00	0	0.00	0
7	0	0.00	0	0.00	0
8	0	0.00	0	0.00	0
9	0	0.00	0	0.00	0
10	0	0.00	0	0.00	0
11	0	0.00	0	0.00	0
12	0	0.00	0	0.00	0
13	0	0.00	0	0.00	0
14	0	0.00	0	0.00	0
15	0	0.00	0	0.00	0
16	0	0.00	0	0.00	0
17	0	0.00	0	0.00	0
18	0	0.00	0	0.00	0
19	0	0.00	0	0.00	0
20	0	0.00	0	0.00	0
21	0	0.00	0	0.00	0
22	0	0.00	0	0.00	0
23	0	0.00	0	0.00	0
24	0	0.00	0	0.00	0
25	0	0.00	0	0.00	0
26	0	0.00	0	0.00	0
27	0	0.00	0	0.00	0
28	0	0.00	0	0.00	0
29	0	0.00	0	0.00	0
30	0	0.00	0	0.00	0
31	0	0.00	0	0.00	0
32	0	0.00	0	0.00	0
33	0	0.00	0	0.00	0
34	0	0.00	0	0.00	0
35	0	0.00	0	0.00	0
36	0	0.00	0	0.00	0
37	0	0.00	0	0.00	0
38	0	0.00	0	0.00	0
39	0	0.00	0	0.00	0
40	0	0.00	0	0.00	0

DAMAGE PARAMETERS ... MSG: EL. NO. = DAMAGE BASED ON MAX. PRINC. M-L STRESS  
 PDS: EL. NO. = DAMAGE BASED ON HOOP STRESS  
 ELEMENT SIGMA(T-ZERO) T-ZERO SIGMA(CHIT-1)  
 -10 1.00-00 0.02 0.0 0.43  
 1.00-00 0.02 0.0 0.43

Table H-6 Cont'd

APPENDIX H

Table 5.4 (cont.)

TIME = 1.000000000-01

SIGX	SIGY	SIGZ	SIGZ	SIGZ	EPZ	EPZ	EPZ	EPZ	EPZ	TEM
1	8.00E-03	1.38E-01	7.20E-02	-2.16E-03	3.63E-04	3.63E-04	0.0	0.0	0.0	1.35E-02
2	2.00E-02	1.18E-01	9.90E-02	-5.02E-03	1.62E-04	1.62E-04	0.0	0.0	0.0	1.35E-02
3	4.00E-02	9.90E-02	7.20E-02	-3.63E-03	7.20E-05	7.20E-05	0.0	0.0	0.0	1.35E-02
4	6.00E-02	7.20E-02	4.95E-02	-2.16E-03	3.63E-05	3.63E-05	0.0	0.0	0.0	1.35E-02
5	8.00E-02	4.95E-02	2.70E-02	-1.35E-03	1.81E-05	1.81E-05	0.0	0.0	0.0	1.35E-02
6	1.00E-01	2.70E-02	1.35E-02	-6.75E-04	9.05E-06	9.05E-06	0.0	0.0	0.0	1.35E-02
7	1.20E-01	1.35E-02	6.75E-03	-3.38E-04	4.52E-06	4.52E-06	0.0	0.0	0.0	1.35E-02
8	1.40E-01	6.75E-03	3.38E-03	-1.69E-04	2.26E-06	2.26E-06	0.0	0.0	0.0	1.35E-02
9	1.60E-01	3.38E-03	1.69E-03	-8.45E-05	1.13E-06	1.13E-06	0.0	0.0	0.0	1.35E-02
10	1.80E-01	1.69E-03	8.45E-04	-4.22E-05	5.65E-07	5.65E-07	0.0	0.0	0.0	1.35E-02
11	2.00E-01	8.45E-04	4.22E-04	-2.11E-05	2.82E-07	2.82E-07	0.0	0.0	0.0	1.35E-02
12	2.20E-01	4.22E-04	2.11E-04	-1.05E-05	1.41E-07	1.41E-07	0.0	0.0	0.0	1.35E-02
13	2.40E-01	2.11E-04	1.05E-04	-5.25E-06	7.05E-08	7.05E-08	0.0	0.0	0.0	1.35E-02
14	2.60E-01	1.05E-04	5.25E-05	-2.62E-06	3.52E-08	3.52E-08	0.0	0.0	0.0	1.35E-02
15	2.80E-01	5.25E-05	2.62E-05	-1.31E-06	1.76E-08	1.76E-08	0.0	0.0	0.0	1.35E-02
16	3.00E-01	2.62E-05	1.31E-05	-6.55E-07	8.78E-09	8.78E-09	0.0	0.0	0.0	1.35E-02
17	3.20E-01	1.31E-05	6.55E-06	-3.27E-07	4.39E-09	4.39E-09	0.0	0.0	0.0	1.35E-02
18	3.40E-01	6.55E-06	3.27E-06	-1.64E-07	2.19E-09	2.19E-09	0.0	0.0	0.0	1.35E-02
19	3.55E-01	3.27E-06	1.64E-06	-8.20E-08	1.09E-09	1.09E-09	0.0	0.0	0.0	1.35E-02

TIME = 3.200000000-01

SIGX	SIGY	SIGZ	SIGZ	SIGZ	EPZ	EPZ	EPZ	EPZ	EPZ	TEM
1	3.75E-02	6.30E-01	3.34E-01	-7.25E-07	2.10E-03	2.10E-03	0.0	0.0	0.0	1.35E-02
2	1.20E-01	4.95E-01	2.47E-01	-3.38E-07	1.54E-03	1.54E-03	0.0	0.0	0.0	1.35E-02
3	2.20E-01	3.63E-01	1.81E-01	-1.69E-07	1.13E-03	1.13E-03	0.0	0.0	0.0	1.35E-02
4	3.20E-01	2.70E-01	1.35E-01	-1.05E-07	8.45E-04	8.45E-04	0.0	0.0	0.0	1.35E-02
5	4.20E-01	1.81E-01	9.05E-02	-6.75E-08	6.30E-04	6.30E-04	0.0	0.0	0.0	1.35E-02
6	5.20E-01	1.35E-01	6.75E-02	-4.22E-08	4.72E-04	4.72E-04	0.0	0.0	0.0	1.35E-02
7	6.20E-01	9.05E-02	4.95E-02	-2.82E-08	3.52E-04	3.52E-04	0.0	0.0	0.0	1.35E-02
8	7.20E-01	6.75E-02	3.63E-02	-1.76E-08	2.62E-04	2.62E-04	0.0	0.0	0.0	1.35E-02
9	8.20E-01	4.95E-02	2.70E-02	-1.13E-08	1.99E-04	1.99E-04	0.0	0.0	0.0	1.35E-02
10	9.20E-01	3.63E-02	1.81E-02	-7.25E-09	1.49E-04	1.49E-04	0.0	0.0	0.0	1.35E-02
11	1.00E-01	2.70E-02	1.35E-02	-4.72E-09	1.13E-04	1.13E-04	0.0	0.0	0.0	1.35E-02
12	1.10E-01	1.81E-02	9.05E-03	-3.11E-09	8.45E-05	8.45E-05	0.0	0.0	0.0	1.35E-02
13	1.20E-01	1.35E-02	6.75E-03	-2.07E-09	6.30E-05	6.30E-05	0.0	0.0	0.0	1.35E-02
14	1.30E-01	9.05E-03	4.95E-03	-1.35E-09	4.72E-05	4.72E-05	0.0	0.0	0.0	1.35E-02
15	1.40E-01	6.75E-03	3.63E-03	-9.05E-10	3.52E-05	3.52E-05	0.0	0.0	0.0	1.35E-02
16	1.50E-01	4.95E-03	2.70E-03	-6.30E-10	2.62E-05	2.62E-05	0.0	0.0	0.0	1.35E-02
17	1.60E-01	3.63E-03	1.81E-03	-4.22E-10	1.99E-05	1.99E-05	0.0	0.0	0.0	1.35E-02
18	1.70E-01	2.70E-03	1.35E-03	-2.82E-10	1.49E-05	1.49E-05	0.0	0.0	0.0	1.35E-02
19	1.80E-01	1.81E-03	9.05E-04	-1.76E-10	1.13E-05	1.13E-05	0.0	0.0	0.0	1.35E-02

TIME = 1.000000000 00

SIGX	SIGY	SIGZ	SIGZ	SIGZ	EPZ	EPZ	EPZ	EPZ	EPZ	TEM
1	1.11E-01	1.86E-00	9.97E-01	-1.21E-06	7.43E-03	7.43E-03	0.0	0.0	0.0	1.35E-02
2	2.22E-01	1.41E-00	7.43E-01	-4.22E-06	5.42E-03	5.42E-03	0.0	0.0	0.0	1.35E-02
3	3.33E-01	1.05E-00	5.42E-01	-2.82E-06	3.91E-03	3.91E-03	0.0	0.0	0.0	1.35E-02
4	4.44E-01	7.43E-01	3.91E-01	-1.69E-06	2.70E-03	2.70E-03	0.0	0.0	0.0	1.35E-02
5	5.55E-01	5.42E-01	2.70E-01	-1.05E-06	1.81E-03	1.81E-03	0.0	0.0	0.0	1.35E-02
6	6.66E-01	3.91E-01	1.81E-01	-6.75E-07	1.35E-03	1.35E-03	0.0	0.0	0.0	1.35E-02
7	7.77E-01	2.70E-01	1.35E-01	-4.22E-07	9.97E-04	9.97E-04	0.0	0.0	0.0	1.35E-02
8	8.88E-01	1.81E-01	9.97E-02	-2.82E-07	7.43E-04	7.43E-04	0.0	0.0	0.0	1.35E-02
9	9.99E-01	1.35E-01	7.43E-02	-1.69E-07	5.42E-04	5.42E-04	0.0	0.0	0.0	1.35E-02
10	1.10E-01	9.97E-02	5.42E-02	-1.05E-07	3.91E-04	3.91E-04	0.0	0.0	0.0	1.35E-02
11	1.20E-01	7.43E-02	3.91E-02	-6.75E-08	2.70E-04	2.70E-04	0.0	0.0	0.0	1.35E-02
12	1.30E-01	5.42E-02	2.70E-02	-4.22E-08	1.81E-04	1.81E-04	0.0	0.0	0.0	1.35E-02
13	1.40E-01	3.91E-02	1.81E-02	-2.82E-08	1.35E-04	1.35E-04	0.0	0.0	0.0	1.35E-02
14	1.50E-01	2.70E-02	1.35E-02	-1.69E-08	9.97E-05	9.97E-05	0.0	0.0	0.0	1.35E-02
15	1.60E-01	1.81E-02	9.97E-03	-1.05E-08	7.43E-05	7.43E-05	0.0	0.0	0.0	1.35E-02
16	1.70E-01	1.35E-02	7.43E-03	-6.75E-09	5.42E-05	5.42E-05	0.0	0.0	0.0	1.35E-02
17	1.80E-01	9.97E-03	5.42E-03	-4.22E-09	3.91E-05	3.91E-05	0.0	0.0	0.0	1.35E-02
18	1.90E-01	7.43E-03	3.91E-03	-2.82E-09	2.70E-05	2.70E-05	0.0	0.0	0.0	1.35E-02
19	2.00E-01	5.42E-03	2.70E-03	-1.69E-09	1.81E-05	1.81E-05	0.0	0.0	0.0	1.35E-02

Table H-6 Cont'd



APPENDIX H

NOT REPRODUCIBLE

Table 5.4 (cont.)

TIME = 7.200000000000 01

SLIP	SLIPM	SLIPZ	SLIPZ	EPZ	EPZ	EPZ	TEM
1	5000	01	0017	00	00	00	1.10E 02
2	1.75E	00	0042	00	00	00	1.10E 02
3	2.75E	00	0070	00	00	00	1.10E 02
4	3.75E	00	0098	00	00	00	1.10E 02
5	4.75E	00	0126	00	00	00	1.10E 02
6	5.75E	00	0154	00	00	00	1.10E 02
7	6.75E	00	0182	00	00	00	1.10E 02
8	7.75E	00	0210	00	00	00	1.10E 02
9	8.75E	00	0238	00	00	00	1.10E 02
10	9.75E	00	0266	00	00	00	1.10E 02
11	1.07E	00	0294	00	00	00	1.10E 02
12	1.17E	00	0322	00	00	00	1.10E 02
13	1.27E	00	0350	00	00	00	1.10E 02
14	1.37E	00	0378	00	00	00	1.10E 02
15	1.47E	00	0406	00	00	00	1.10E 02
16	1.57E	00	0434	00	00	00	1.10E 02
17	1.67E	00	0462	00	00	00	1.10E 02
18	1.77E	00	0490	00	00	00	1.10E 02
19	2.00E	00	0518	00	00	00	1.10E 02

TIME = 9.600000000000 01

SLIP	SLIPM	SLIPZ	SLIPZ	EPZ	EPZ	EPZ	TEM
1	1.11E	00	0042	00	00	00	6.45E 01
2	1.21E	00	0070	00	00	00	6.45E 01
3	1.31E	00	0098	00	00	00	6.45E 01
4	1.41E	00	0126	00	00	00	6.45E 01
5	1.51E	00	0154	00	00	00	6.45E 01
6	1.61E	00	0182	00	00	00	6.45E 01
7	1.71E	00	0210	00	00	00	6.45E 01
8	1.81E	00	0238	00	00	00	6.45E 01
9	1.91E	00	0266	00	00	00	6.45E 01
10	2.01E	00	0294	00	00	00	6.45E 01
11	2.11E	00	0322	00	00	00	6.45E 01
12	2.21E	00	0350	00	00	00	6.45E 01
13	2.31E	00	0378	00	00	00	6.45E 01
14	2.41E	00	0406	00	00	00	6.45E 01
15	2.51E	00	0434	00	00	00	6.45E 01
16	2.61E	00	0462	00	00	00	6.45E 01
17	2.71E	00	0490	00	00	00	6.45E 01
18	2.81E	00	0518	00	00	00	6.45E 01
19	3.00E	00	0546	00	00	00	6.45E 01

TIME = 1.200000000000 02

SLIP	SLIPM	SLIPZ	SLIPZ	EPZ	EPZ	EPZ	TEM
1	1.75E	00	0042	00	00	00	6.45E 01
2	1.85E	00	0070	00	00	00	6.45E 01
3	1.95E	00	0098	00	00	00	6.45E 01
4	2.05E	00	0126	00	00	00	6.45E 01
5	2.15E	00	0154	00	00	00	6.45E 01
6	2.25E	00	0182	00	00	00	6.45E 01
7	2.35E	00	0210	00	00	00	6.45E 01
8	2.45E	00	0238	00	00	00	6.45E 01
9	2.55E	00	0266	00	00	00	6.45E 01
10	2.65E	00	0294	00	00	00	6.45E 01
11	2.75E	00	0322	00	00	00	6.45E 01
12	2.85E	00	0350	00	00	00	6.45E 01
13	2.95E	00	0378	00	00	00	6.45E 01
14	3.05E	00	0406	00	00	00	6.45E 01
15	3.15E	00	0434	00	00	00	6.45E 01
16	3.25E	00	0462	00	00	00	6.45E 01
17	3.35E	00	0490	00	00	00	6.45E 01
18	3.45E	00	0518	00	00	00	6.45E 01
19	3.50E	00	0546	00	00	00	6.45E 01

Table H-6 Cont'd



APPENDIX H

NOT REPRODUCIBLE

Table 3.4 (cont.)

TIME = 2.150000000 02

SIGR	SIGZ	SIGY	SIGX	SIGZ	SIGY	SIGX	SIGZ	SIGY	SIGX	EPZ	EPY	EPX	TEM
1	0.99E 00	1.15E 02	0.34E 01	0.15E 00	-3.12E 01	2.63E 01	0.00	0.00	0.00	1.56E 00	-4.65E 01	TEM	
2	2.42E 01	1.04E 01	1.23E 03	DAMAGE	0.50E 02	0.00	0.00	0.00	0.00	1.77E 00	0.00	0.00	0.00
3	4.41E 01	0.73E 01	0.23E 01	0.51E 00	0.23E 01	2.01E 01	0.00	0.00	0.00	1.59E 00	0.00	0.00	0.00
4	4.91E 01	0.04E 01	0.11E 01	0.79E 00	-1.22E 01	1.22E 01	0.00	0.00	0.00	1.60E 00	0.00	0.00	0.00
5	4.91E 01	7.52E 01	0.00E 01	0.79E 00	-1.22E 01	1.22E 01	0.00	0.00	0.00	1.79E 00	0.00	0.00	0.00
6	5.34E 01	0.00E 01	0.39E 01	0.77E 00	-0.67E 02	2.75E 02	0.00	0.00	0.00	1.49E 00	0.00	0.00	0.00
7	5.44E 01	0.77E 01	0.49E 01	4.12E 00	0.50E 02	2.08E 02	0.00	0.00	0.00	1.11E 00	0.00	0.00	0.00
8	5.55E 01	0.59E 01	0.39E 01	3.42E 00	0.50E 02	1.12E 01	0.00	0.00	0.00	0.51E 00	0.00	0.00	0.00
9	5.57E 01	0.59E 01	0.39E 01	3.42E 00	0.50E 02	1.12E 01	0.00	0.00	0.00	0.51E 00	0.00	0.00	0.00
10	5.70E 01	0.44E 01	0.39E 01	1.18E 00	0.76E 02	7.65E 02	0.00	0.00	0.00	7.00E 00	0.00	0.00	0.00
11	5.79E 01	0.44E 01	0.39E 01	1.18E 00	0.76E 02	7.65E 02	0.00	0.00	0.00	6.56E 00	0.00	0.00	0.00
12	5.83E 01	0.44E 01	0.39E 01	1.18E 00	0.76E 02	7.65E 02	0.00	0.00	0.00	6.56E 00	0.00	0.00	0.00
13	5.83E 01	0.44E 01	0.39E 01	1.18E 00	0.76E 02	7.65E 02	0.00	0.00	0.00	6.56E 00	0.00	0.00	0.00
14	5.83E 01	0.44E 01	0.39E 01	1.18E 00	0.76E 02	7.65E 02	0.00	0.00	0.00	6.56E 00	0.00	0.00	0.00
15	5.83E 01	0.44E 01	0.39E 01	1.18E 00	0.76E 02	7.65E 02	0.00	0.00	0.00	6.56E 00	0.00	0.00	0.00
16	5.83E 01	0.44E 01	0.39E 01	1.18E 00	0.76E 02	7.65E 02	0.00	0.00	0.00	6.56E 00	0.00	0.00	0.00
17	5.83E 01	0.44E 01	0.39E 01	1.18E 00	0.76E 02	7.65E 02	0.00	0.00	0.00	6.56E 00	0.00	0.00	0.00
18	5.83E 01	0.44E 01	0.39E 01	1.18E 00	0.76E 02	7.65E 02	0.00	0.00	0.00	6.56E 00	0.00	0.00	0.00
19	2.99E 01	4.07E 03	2.58E 00	DAMAGE	-5.63E 01	1.97E 03	0.00	0.00	0.00	-2.47E 00	-4.05E 01	TEM	

TIME = 2.400000000 02

SIGR	SIGZ	SIGY	SIGX	SIGZ	SIGY	SIGX	SIGZ	SIGY	SIGX	EPZ	EPY	EPX	TEM
1	1.06E 01	1.77E 02	0.80E 01	1.32E 00	-1.50E 01	3.42E 01	0.00	0.00	0.00	2.67E 00	-6.61E 01	TEM	
2	3.42E 01	1.50E 02	2.51E 01	DAMAGE	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
3	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
4	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
5	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
6	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
7	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
8	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
9	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
10	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
11	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
12	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
13	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
14	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
15	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
16	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
17	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
18	7.79E 01	1.50E 02	0.80E 01	1.32E 00	0.91E 01	2.42E 01	0.00	0.00	0.00	2.95E 00	0.00	0.00	0.00
19	4.58E 01	0.21E 03	3.30E 00	DAMAGE	-1.55E 01	1.71E 03	0.00	0.00	0.00	-2.64E 00	-6.60E 01	TEM	

TIME = 2.640000000 02

SIGR	SIGZ	SIGY	SIGX	SIGZ	SIGY	SIGX	SIGZ	SIGY	SIGX	EPZ	EPY	EPX	TEM
1	7.84E 01	7.18E 00	0.14E 00	7.78E 00	-2.4E 02	3.65E 02	0.00	0.00	0.00	2.17E 00	1.56E 02	TEM	
2	2.21E 00	0.82E 00	0.00E 00	DAMAGE	1.91E 01	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
3	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
4	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
5	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
6	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
7	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
8	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
9	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
10	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
11	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
12	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
13	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
14	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
15	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
16	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
17	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
18	3.04E 00	5.91E 00	0.40E 00	1.22E 00	2.20E 02	2.73E 02	0.00	0.00	0.00	1.9E 00	0.00	0.00	0.00
19	2.18E 00	0.50E 00	0.00E 00	DAMAGE	1.91E 01	1.54E 00	0.00	0.00	0.00	4.02E 00	1.56E 02	TEM	

Table H-6 Cont'd



APPENDIX I

NON-LINEAR ANALYSIS BASED ON PROPELLANT DILATATION

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Appendix I

NON-LINEAR ANALYSIS BASED ON PROPELLANT DILATATION

In general, the response of grains to various loading conditions is mainly determined by the dilatational behavior of the propellant, hence, it would appear that accounting for the non-linear dilatational response of propellant is of primary importance.

Although insufficient experimental data is available to permit a comprehensive characterization of the non-linear dilatational effects, it was felt that an evaluation could be obtained by utilizing a description which qualitatively accounts for the behavior reported for a limited class of stress states in References I-1 and I-2, and which predicts reasonable results for other stress states. Because of the tentative nature of the characterization, it was deemed desirable to approximate the non-linear behavior by an equation which could be incorporated into the existing analysis with a minimum amount of effort.

With the above objectives in mind the following approximations were made: (1) The thermo-rheologically simple linear viscoelastic distortional stress-strain law and the temperature induced volume change relationships would remain unchanged; (2) the stress induced dilatational response would be approximated as elastic. It was felt that the viscoelastic dilatation (compare Figures 11 and 12 of Reference I-2), is of secondary importance as compared to the basic non-linear effects. Additionally, the lack of experimental evidence concerning dilatation during unloading precludes its consideration at this time. (3) The stress-dilatation relationship would be considered to be temperature independent (it was felt that the actual temperature dependence was of secondary importance). (4) The characterization would be limited to relatively small strains. (5) The elastic relationship between the dilatation and the stress state could be expressed as:

$$(\theta - 3\alpha\Delta T) \approx f(g(\theta_1)) = f(\tau_{ij}) \quad (I-1)$$

where "f" is a non-linear algebraic function of the quantity "g",  $g(\theta_1)$  is in turn a non-linear function of the stress invariants. The stress invariants are defined by the equations

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$$\theta = \tau_{11} + \tau_{22} + \tau_{33} \quad (I-2)$$

$$\theta_2 = \begin{vmatrix} \tau_{22} & \tau_{23} \\ \tau_{32} & \tau_{33} \end{vmatrix} + \begin{vmatrix} \tau_{11} & \tau_{31} \\ \tau_{31} & \tau_{33} \end{vmatrix} + \begin{vmatrix} \tau_{11} & \tau_{12} \\ \tau_{12} & \tau_{22} \end{vmatrix}$$

$$\theta_3 = \begin{vmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{12} & \tau_{22} & \tau_{23} \\ \tau_{13} & \tau_{23} & \tau_{33} \end{vmatrix}$$

For linear theory we have  $g = \theta$  and  $f = \frac{K}{3}g$  i.e.

$$(\theta - 3\alpha\Delta T) = K \frac{\theta}{3} \quad (I-3)$$

Appropriate forms of the functions "f" and "g" were determined in the following manner. For a uniaxial state of stress (i.e.,  $\tau_{ij} = 0$  except  $\tau_{11} \neq 0$ ) noting that  $\theta_2 = \theta_3 = 0$ , it was assumed that

$$g(\theta_1) \sim \theta = \tau_{11}, \text{ i.e.,}$$

$$(\theta - 3\alpha\Delta T) \sim f(\tau_{11}) \quad (I-4)$$

Inspecting results from uniaxial tests (and uniaxial tests with small superimposed hydrostatic pressures) the form of the function "f" was determined. The form of the function "g" was determined by inspecting the results of uniaxial tests with various levels of superimposed hydrostatic pressures. Lastly, the forms of the functions "f" and "g" were appropriately modified so that the predictions for other stress states would intuitively agree with the physical explanation given in Reference (I-2) for the non-linear dilatation phenomenon.

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The experimental results presented in Figures 8, 9, 10, 12 and 14 of Reference (I-2) were plotted in the form  $\theta \sim \tau_{11}$  in Figure I-1. Although these data certainly demonstrate a dependence upon temperature and strain rate (and of course a dependence upon "volume of loading"), insufficient data were available to permit a description of this dependence, hence, it was neglected. No data was available for compressive stress states, however, it was anticipated that for negative stresses the relationship would be relatively linear. The data presented in Figure I-1 (i.e., the function "f") was approximated by a hyperbola, i.e., the relationship between  $\theta$  and the function "g" was written as:

$$\theta = \frac{P_2 + P}{2} + \frac{\beta_2 - \beta}{2} + B \quad (I-5)$$

where

$$\beta_1 = \theta_0 + \frac{1}{K_T} (g_1 - g_0)$$

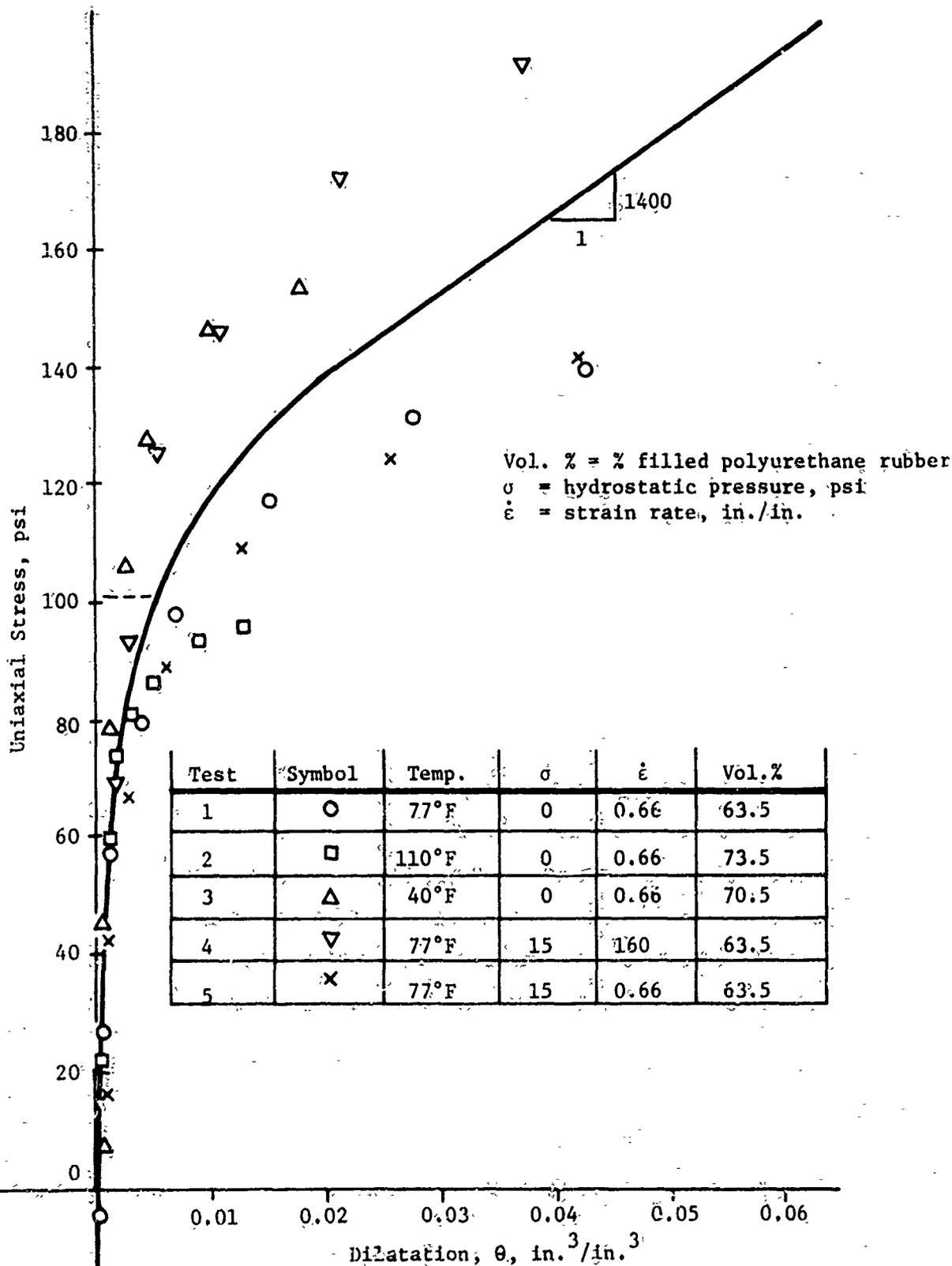
$$B = \frac{\beta_1 (\theta_0 - g_0/K_c)}{1 - \frac{\beta_1 K_c g}{g_1}}$$

$$\beta_2 = \frac{BK_T}{g_1} - \frac{g}{K_c}$$

$$\beta = \frac{1}{K_T} (g_1 - g)$$

The meaning of the parameters  $K_T$ ,  $K_c$ ,  $g_1$ ,  $g_0$  and  $\theta_0$  is illustrated in

VOLUME CHANGE  
(Data taken from Reference (7))



1,500,000

1

Figure I-1

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Figure I-2. The form of the function  $g(\theta_1)$  was determined by considering the data presented in Figure 1 of Reference (I-2). A number of different functional forms were investigated from among which the following form was selected.

$$g(\theta_1) = \theta_1 - K_1 \theta_1^2 + K_2 \theta_1^3 + K_3 \theta_1^3 \quad (I-6)$$

The values of  $K_1$ ,  $K_2$ , and  $K_3$  were selected by noting that Equation (I-1) states that for a given amount of dilatation the value of "g" should be a constant. Thus for the different stress states (corresponding to different values of hydrostatic pressure) given in Figure 1 of Reference (I-2) an attempt was made to select the function "g" so that for a given value of  $\theta$  all states would yield a common value of "g". The following values were found for the parameters

$$K_1 = 4.9 \times 10^{-3}$$

$$K_2 = 2.3 \times 10^{-5}$$

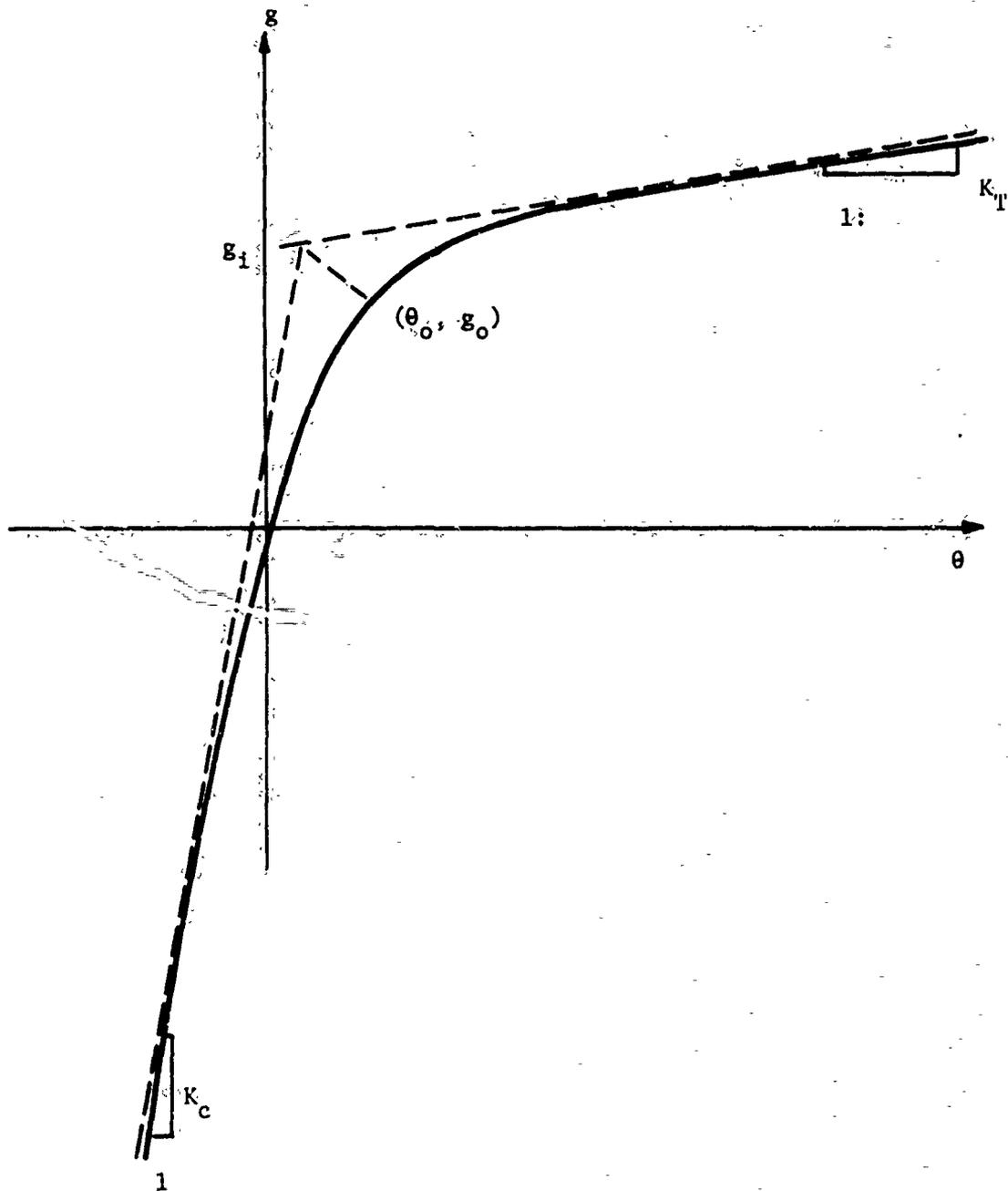
$$K_3 = 5.7 \times 10^{-6}$$

Using these parameters the following table was constructed

Hydrostatic Pressure, psi	$\theta = .005$		$\theta = .01$	
	$\theta/3$		$\theta/3$	
	g		g	
15	.66	54	84	68
65	.66	-5	99	14
165	101	-150	125	-115

If the dilatational response could be described by a linear elastic law all the entries in Column 3 (and in Column 5) would need to be approximately equal, the extreme grossness of this approximation is evident. If the non-linear function "g" is to represent the experimental data all the entries in Column 2 (and in Column 4) would need to be

PARAMETERS DEFINING HYPERBOLIC  
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approximately equal, while this is not true, the very substantial improvement of the non-linear representation as compared to the linear representation is evident.

While no experimental information was available for stress states other than the uniaxial test with superimposed hydrostatic pressure, it is extremely important that the proposed model predicts reasonable results for other stress states as these stress states may occur in a given grain problem. Utilizing the proposed non-linear model dilatation was predicted for the following stress states:

- (a) Uniaxial stress with superimposed hydrostatic pressure (Figure I-3)
- (b) Hydrostatic pressure (Figure I-4)
- (c) Biaxial stress with superimposed hydrostatic pressure (Figure I-5)
- (d) Simple shear with superimposed hydrostatic pressure (Figure I-6)

The straight lines in Figure I-3 indicate the predictions of the linear model, the curved lines the predictions of the non-linear model. The predictions of the non-linear model qualitatively appear to be reasonable.

The incorporation of the non-linear dilatational relationship (Equation (I-1)) into the existing thermoviscoelastic analyses presented some difficulties. The existing thermoviscoelastic analysis employs the following incremental relationship for dilatation (for time increment  $N$ ):

$$(\Delta\theta_N - 3\alpha\Delta T_N) = K_N \frac{\Delta\theta_N}{3} + \chi_N (t_{N-1} \leq t \leq t_N) \quad (I-7)$$

In the previous linear analysis  $K_N$  was considered to be a constant (the elastic bulk modulus) and  $\chi_N = 0$ . The utilization of Equation (I-7) as an approximation to Equation (I-1) was accomplished as follows:

Having obtained the solution for time  $t_{N-1}$  consider the utilization of Equation (I-7) for  $t_{N-1} \leq t \leq t_N$ . Symbolically denoting the stress state at time  $t_{N-1}$  as  $\tau_{ij,N-1}$  and the incremental change in stress state for

$t_{N-2} \leq t_{N-1}$  as  $\Delta\tau_{ij,N-1}$ . The following two associated stress states are defined:

DILATATIONAL PREDICTIONS FOR UNIAXIAL STRESS WITH SUPERIMPOSED HYDROSTATIC PRESSURE

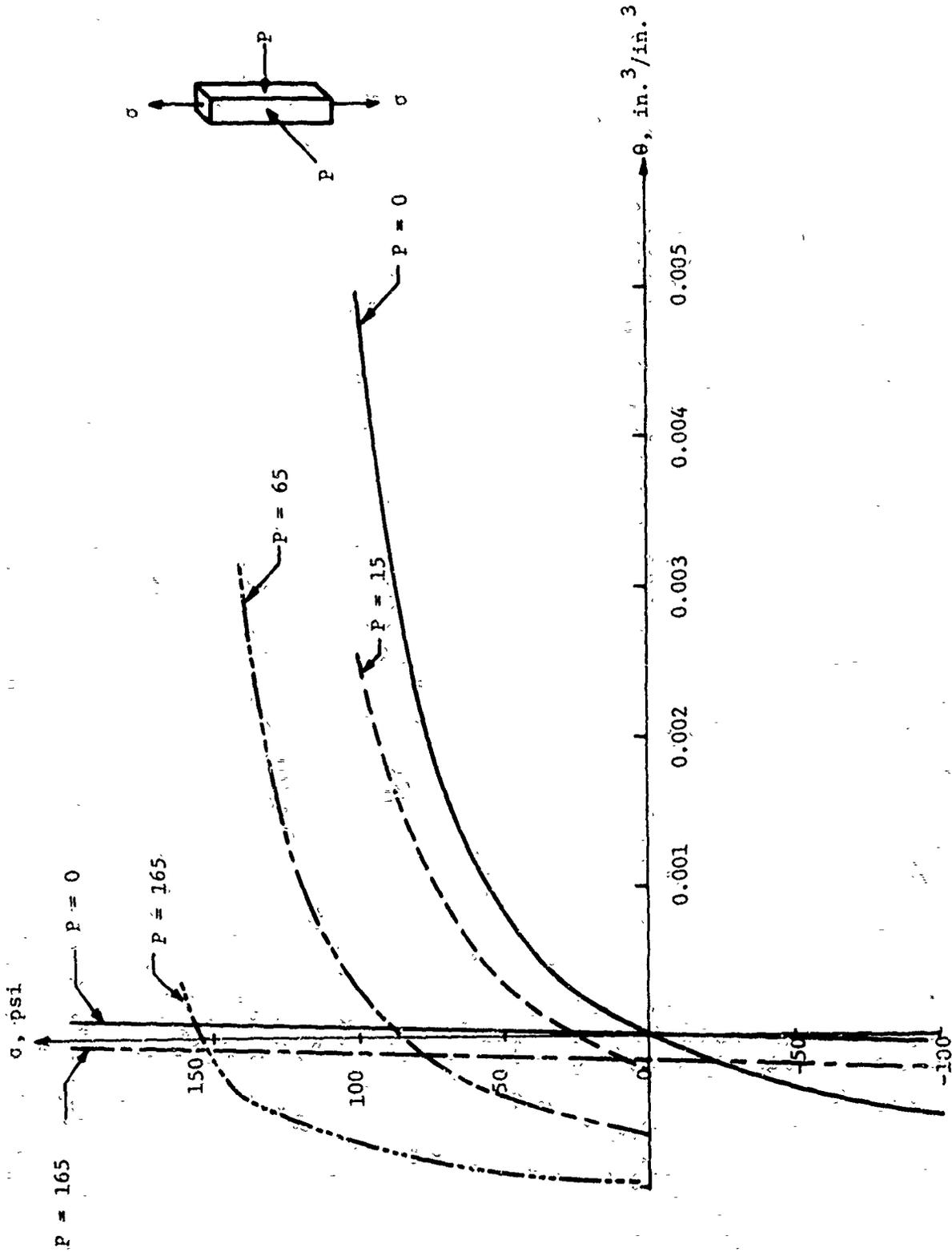
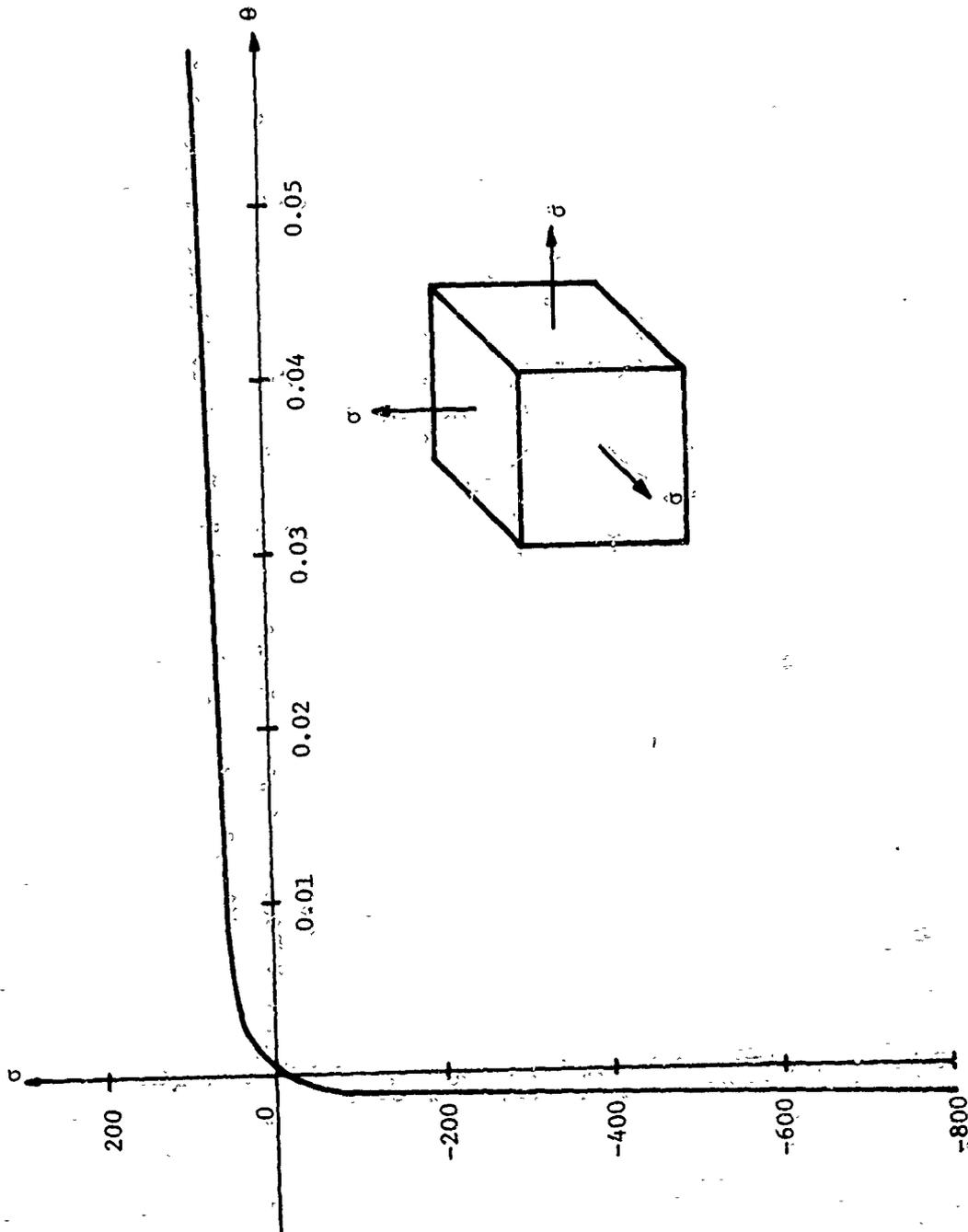
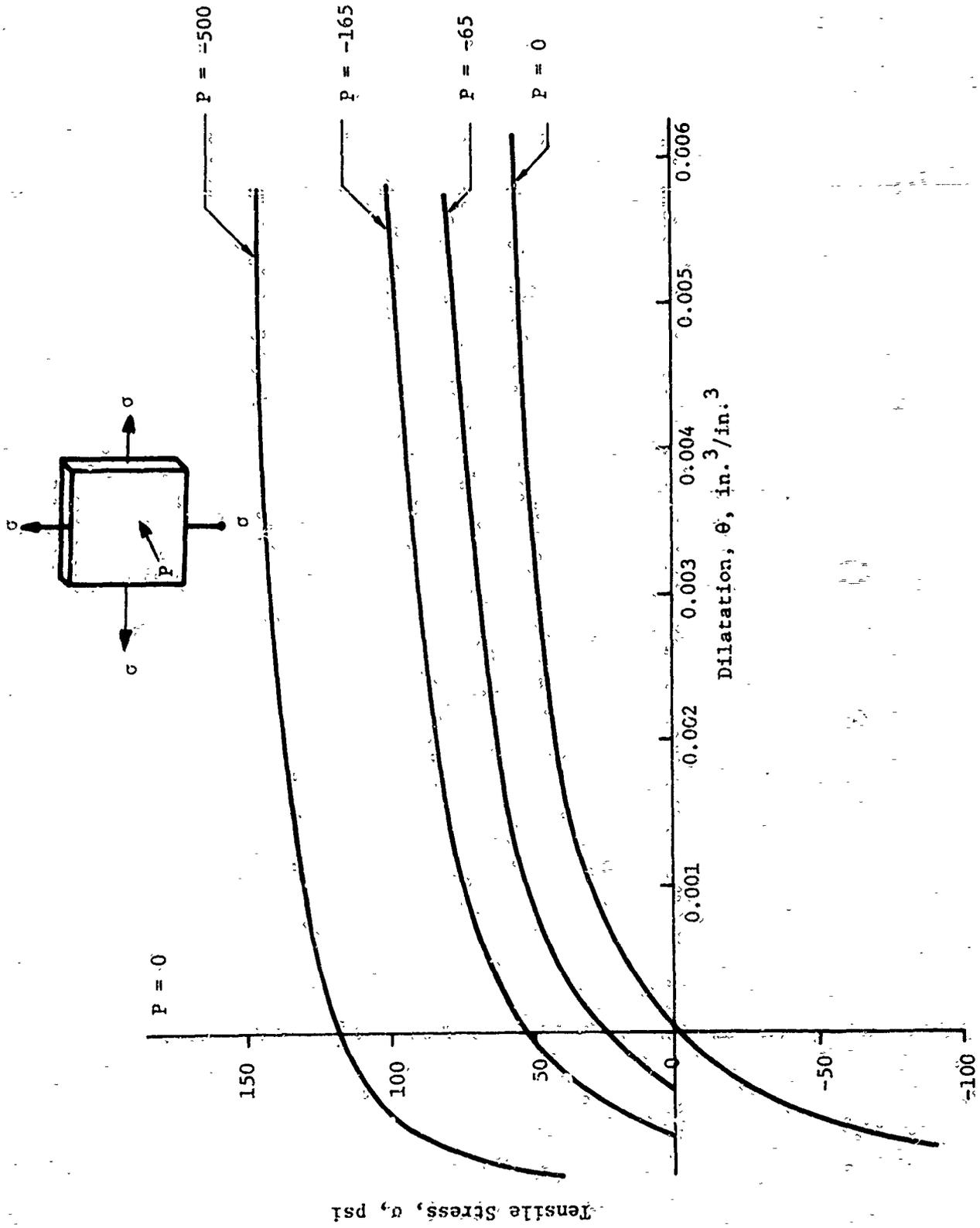


Figure I-3

DILATATION PREDICTIONS FOR HYDROSTATIC PRESSURE





DILATATIONAL PREDICTIONS FOR BIAXIAL STRESS WITH SUPERIMPOSED HYDROSTATIC PRESSURE

Figure I-5

DILATATIONAL PREDICTIONS FOR SHEAR WITH SUPERIMPOSED HYDROSTATIC PRESSURE

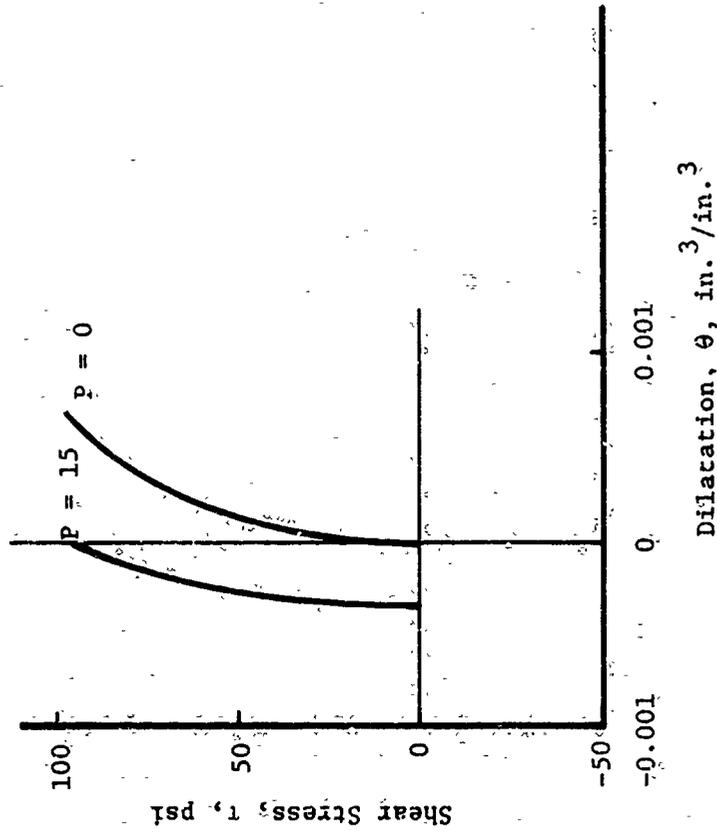
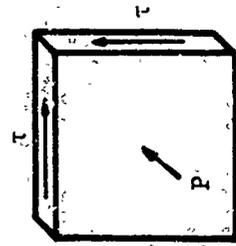


Figure I-6

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$$\tau_{ija} \equiv \tau_{ij_{N-1}} - \Delta\tau_{ij_{N-1}} \quad (I-8)$$

$$\tau_{ijb} \equiv \tau_{ij_{N-1}} + \Delta\tau_{ij_{N-1}} \quad (I-9)$$

Utilizing Equations (I-1), (I-2), (I-8), and (I-9), the following quantities are calculated  $\theta_a$ ,  $\theta_b$ ,  $\theta_a$  and  $\theta_b$ . The following approximate relationship is written for values of  $\theta$  between  $\theta_a$  and  $\theta_b$

$$\theta = \frac{\theta_a \theta_b - \theta_b \theta_a}{\theta_a - \theta_b} + \frac{\theta_a - \theta_b}{\theta_a - \theta_b} \theta \quad (I-10)$$

Assuming that the absolute value of the change in stress during the increment  $\Delta\tau_N$  will be of the same order of magnitude as  $|\Delta\tau_{ij_{N-1}}|$

(i.e., using Equation (I-10) and writing  $\theta_N = \theta_{N-1} + \Delta\theta_N$  and  $\theta_N = \theta_{N-1} + \Delta\theta_N$  yields

$$\theta_{N-1} + \Delta\theta_N = \frac{\theta_a \theta_b - \theta_b \theta_a}{\theta_a - \theta_b} + \frac{\theta_a - \theta_b}{\theta_a - \theta_b} (\theta_{N-1} + \Delta\theta_N) \quad (I-11)$$

Comparing the above expression to Equation (I-7) yields

$$K_N = \frac{\theta_a - \theta_b}{\theta_a - \theta_b}$$

$$X_N = \frac{\theta_a \theta_b - \theta_b \theta_a}{\theta_a - \theta_b} + \frac{\theta_a - \theta_b}{\theta_a - \theta_b} \theta_{N-1} - \theta_{N-1}$$

Because of the secant approximation to the non-linear function, in general,  $X_N \neq 0$ .

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References.

- I-1 Farris, R. J., "The Character of the Stress-Strain Function for Highly Filled Elastomers", Trans. of the Soc. of Rheology 12:2, 303-314 (1968).
- I-2 Farris, R. J., "The Influence of Vacuole Formation on the Response and Failure of Filled Elastomers", Trans. of the Soc. of Rheology 12:2, 315-334 (1968).

APPENDIX J

BASIC CUMULATIVE DAMAGE EQUATIONS

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BASIC CUMULATIVE DAMAGE EQUATIONS

The LCD relation merely states the manner in which damage can be added. To apply the relation in a three-dimensional stress field requires a time-dependent, stress failure criterion. An empirical approach showed that the applicable relation is a time-dependent, maximum principal stress, failure criterion (MPS).

Combining the LCD and MPS criteria leads to integral relations which take full account of the past stress-time-temperature history at a point in the grain.

1. Linear Cumulative Damage Relations

The very simple relation, applicable to solid propellant failures, is defined in terms of tests made under a constantly imposed "true" stress,  $\sigma_t$ . For a number, N, of discrete stress levels the accumulated damage fraction,  $\Sigma D$ , is given by the following linear relation:

$$\Sigma D = \frac{1}{P(n)} \sum_{i=1}^N \frac{\Delta t_i}{t_{fi}} \quad (J-1)$$

where  $\Sigma D$  is the cumulative damage

$P(n)$  is a statistical distribution parameter and relates the  $n^{\text{th}}$  test specimen in the distribution to the mean of the population.

$\Delta t_i$  is the increment of time the specimen is exposed to the  $i^{\text{th}}$  "true" stress level

$t_{fi}$  is the mean time-to-failure for the population of specimens if the specimens saw only the  $i^{\text{th}}$  "true" stress level.

The accumulated damage,  $\Sigma D$ , thus gives the fraction of that damage required to fail the specimen. Thus, by definition  $\Sigma D = 1$  at failure.

The parameter,  $P(n)$ , is a highly useful term in that it provides the focal point for all the statistical studies pertinent to the cumulative damage relations. In its simplest form  $P(n)$  defines the position of the individual failure with respect to the mean of the distribution of these failures. This is seen on considering specimens held under a single stress, where  $P(n)$  equals the ratio of the time-to-failure,  $t_f(n)$ , for the  $n^{\text{th}}$  individual divided by the mean time-to-failure for the entire population,  $\bar{t}_f$ .

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Thus, we have

$$P(n) = t_f(n) / \bar{t}_f \quad (J-2)$$

The cumulative damage relation merely preserves this concept of  $P(n)$  for conditions of complicated loading histories.

In Reference J-1, it was shown that  $P(n)$  is independent of the stress level. This justifies placing the parameter outside the summation in Equation (J-1).

Statistical evaluations of  $P(n)$  obtained from solid propellant failure testing, show the parameter to follow approximately a log normal distribution.

2. Time-Dependent Maximum Principal Stress Failure Criterion

The most general form of the MPS failure criterion for solid propellants appears to be a modified power-law relation. However, a simple power-law approximation to this criterion covers all of the practical motor problems that we have met to date. This power-law relation has the following form:

$$\bar{t}_f = t_0 a_T \left( \frac{\sigma_t - \sigma_{cr}}{\sigma_{t_0} - \sigma_{cr}} \right)^{-B} \quad (J-3)$$

- where:
- $\sigma_t$  is the "true" stress applied to the specimen.
  - $\bar{t}_f$  is the mean time-to-failure of specimens held under the constant true stress,  $\sigma_t$ .
  - $t_0$  is the unit value of the time for whatever units are used in measuring  $t_f$ .
  - $\sigma_{t_0}$  is the true stress required to fail the specimen in the time  $t_0$ .
  - $\sigma_{cr}$  is the critical true stress below which no failures are observed.
  - $a_T$  is the time-temperature shift relation.

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It has been found to apply to solid propellant behavior with correlation coefficients usually exceeding 0.98.

The limiting stress,  $\sigma_{cr}$ , is difficult to evaluate because it is usually not large compared with the relatively large variability typical of solid propellants. It appears to be negligibly small (except for the effects of pressure) for all the propellants tested to date.

The cumulative damage relation is generalized as follows. First, Equation (J-3) is combined with Equation (J-1) to obtain the cumulative damage relation in terms of discrete stress levels, loading time intervals, and test temperatures.

$$\Sigma D = \frac{1}{P(n)} \Sigma \left[ \frac{\sigma_{ti} - \sigma_{cr}}{\sigma_{to} - \sigma_{cr}} \right]^B \frac{\Delta t_i}{t_o a_T} \quad (J-4)$$

where  $\sigma_{ti}$  is the  $i^{th}$  stress level.

For continuous changes in the stress and in the temperature, Equation (J-4) becomes:

$$\Sigma D = \frac{1}{P(n) (\sigma_{to} - \sigma_{cr})^B t_o} \int_0^t \frac{(\sigma_t - \sigma_{cr})^B}{a_T(t)} dt \quad (J-5)$$

where  $\sigma_t$ , the true stress, is now a function of time.

$a_T(t)$  is the time-temperature shift relation with the temperature expressed as a function of time.

Equation (J-5) represents a general form of the linear cumulative damage relation for solid propellants. This equation permits the summation of damage for any type of thermal or mechanical loading history, provided the stresses, times and temperatures are known. Also, Equation (J-5) can be applied without change to three dimensional stress problems.

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REFERENCES

- J-1 Bills, K. W., Jr., Peterson, F. E., Steele, R. D., and Sampson, R. C.,  
"Development of Criteria for Solid Propellant Screening and  
Preliminary Engineering Design", Aerojet Report 1159-81F  
(December 1968).

APPENDIX K

STUDY OF PROPELLANT FAILURE UNDER PRESSURE

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APPENDIX K

STUDY OF PROPELLANT FAILURE UNDER PRESSURE

A. FAILURE MECHANISMS

The basic mechanisms of propellant failure have been extensively studied under current and past research programs (K-1, K-2). Failure is considered to be a three step process beginning with vacuole formation. The vacuoles may initiate in the polymer or at the binder-filler interface. The associated volume change may be so negligible that the process is termed a "Mullin's Effect". The second step is the extension of the vacuoles until they overlap producing a thin membrane of polymer between them. The third and final step is the production of a critical, biaxial, stress field in one or more of the thin membranes. The resulting tears propagate very slowly relative to the speed of sound in the propellant. This failure mechanism is the basis of the considerations made later.

The maximum principal stress failure criterion, Equation (J-3), contains a simple stress difference term,  $\sigma_t - \sigma_{cr}$ . Some feel that this indicates a maximum shear stress criterion to be operative. In biaxial tension this is expressed by

$$\tau(\text{critical}) = (\sigma_1 - \sigma_2)/2 \quad (\text{K-1})$$

where  $\tau(\text{critical})$  is the maximum shear strength of the material  
 $\sigma_1$  and  $\sigma_2$  are principal stresses

Considering the stress difference terms only, for both failure criteria, leads to the tabulation in Table K-1. It is assumed that a maximum principal stress,  $\sigma$ , is imposed in tension. The remaining stresses are tabulated.

Table K-1 shows that the two criteria give identical results for simple uniaxial and strip-biaxial tensile data from which the MPS criterion was derived. However, the two criteria differ greatly when applied to the triaxial, tensile, stress field of the poker chip specimen. In this case, the stress difference for the maximum shear stress criterion is dependent upon  $1-k$ , which is very small, indicating that very large axial stresses,  $\sigma$ , would be required to fail the specimen. On the other hand, the MPS criterion gives a relatively large value for the stress difference term,  $\sigma_t - \sigma_{cr}$ . This difference, like those for the uniaxial and biaxial tensile data, equals the axial stress on the specimen. Tests on poker chip specimens showed the MPS criterion to hold, (K-2) while the maximum shear stress criterion is grossly in error.

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Appendix K

TABLE K-1

STRESS DIFFERENCES AT ATMOSPHERIC PRESSURE

Test Mode	MPS Criterion			Maximum Shear Stress Criterion		
	$\sigma_t$	$\sigma_{cr}$ *	$\sigma_t - \sigma_{cr}$	$\sigma_1$	$\sigma_2$	$\sigma_1 - \sigma_2$
Uniaxial Tensile Test	$\sigma$	0	$\sigma$	$\sigma$	0	$\sigma$
Strip-Biaxial Tensile Test	$\sigma$	0	$\sigma$	$\sigma$	0	$\sigma$
Poker Chip Tensile Test	$\sigma$	0	$\sigma$	$\sigma$	$k\sigma$	$(1-k)\sigma$

\*  $\sigma_{cr}$  is set equal to zero, which appears to be the case for many composite propellants.

\*\* The maximum tensile stress at the center of the specimen.

\*\*\* k is a proportionality factor which, in this case, is close to one.

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This result is not surprising in view of the failure mechanisms summarized above. Tensile failures in uniaxial, biaxial, and poker chip specimens follow the same mechanism. Once the vacuoles are produced all three test modes become equivalent, in that failure is produced by extension of a foam-like material until the biaxial stress in the membranes exceeds the critical value and tearing starts.

B. EVALUATING THE TIME-PRESSURE SHIFT FACTOR

The time-pressure shift factor for propellants is best understood on referring to the foam-like failure behavior mentioned above. Before the vacuoles are formed, or when they are still quite small,  $a_p$  equals one (up to about 1500 psi pressure). This was shown for tensile moduli by Wiegand, (K-3) Hazelton (K-4) and Lim and Tshoegel (K-5). At this point, the  $a_p$  values are those for the solid binder which requires large pressure changes to effect significant changes in  $a_p$ . (K-6 to 14). On the other hand, propellant failure data are sensitive to relatively small pressure changes. Dilatation constitutes the only physical difference in the propellant between the points where initial tensile moduli and failure data are obtained. At failure, this dilatation is extensive and can be partially suppressed by superimposed hydrostatic pressures. As shown by Farris (K-15) and Lim and Tshoegel (K-5), the dilatation at failure is positive, even at the higher pressure levels.

Taken together these observations indicate that  $a_p$  provides a measure of the suppression of vacuole formation. But,  $\sigma_{cr}$  is also a measure of the same effect. That is,  $\sigma_{cr}$  is the stress level at which dilatation is completely suppressed; or, conversely, the stress level where vacuoles are first formed. Also,  $\sigma_{cr}$  is pressure dependent, defining the point of vacuole formation over the pressure range. Thus,  $a_p$  must be a simple function of  $\sigma_{cr}$ . That is,

$$a_p = f(\sigma_{cr}) \quad (K-2)$$

Equation (K-2) tells us how to evaluate  $a_p$  deep in the grain. The critical stress acts in the same direction as the maximum principal stress,  $\sigma_t$ , and it includes that portion of the inner-bore pressure that is effective deep within the grain and which acts in the same direction as  $\sigma_t$ . The fraction,  $f$ , of the inner-bore pressure that acts within the grain can be obtained directly from existing stress analyses. Using this fraction the critical stress becomes, on using Equation (14) of the text,

$$\sigma_{cr} = (F/A)_{cr} = fP_i \quad (K-3)$$

where  $P_i$  is the inner-bore pressure

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The appropriate values of  $a_p$  for use in Equation (K-2) are obtained from empirically obtained curve of  $a_p$  versus pressure, the desired value of  $a_p$  read from the curve at a pressure numerically equal to  $\sigma_{cr}$ , the latter being obtained from Equation (K-3).

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Appendix K

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APPENDIX L  
EFFECTS OF PREVIOUS DAMAGE

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APPENDIX L

EFFECTS OF PREVIOUS DAMAGE

The cumulative damage relations can be used to evaluate the effects of previous damage upon propellant failure data. This may be done using the LCD analysis of a single test-to-failure curve which duplicates a given failure condition in the motor. When considering the inner-bore failure of a grain on motor pressurization we use a high rate, uniaxial tensile test performed under a superimposed hydrostatic pressure.

The cumulative damage relation appropriate to this analysis is derived here, starting with Equation (16) from the text. For this analysis, considerations are simplified by assuming the pressure and temperature to be held constant. Thus  $a_p$  and  $a_T$  become constants and may be taken outside the integral in Equation (16).

For the previously undamaged specimen the time-to-break,  $t_b$ , and the maximum true stress become normalizing parameters for the integral term, as originally shown in Reference (L-1). Thus, we let

$$A = \int_0^{t_b/t_b} \frac{(\sigma_t - \sigma_{cr})^B}{(\sigma_{tM} - \sigma_{cr})^B} d(t/t_b) \quad (L-1)$$

Equation (16) after normalization by substituting A, gives

$$\Sigma D = 1 = \frac{(\sigma_{tM} - \sigma_{cr})^B t_b A}{P(n) (\sigma_{to} - \sigma_{cr})^B t_o a_p a_T} \quad (L-2)$$

Prior to failure we can use the same normalization terms,  $t_b$  and  $(\sigma_{tM} - \sigma_{cr})^B$ , but take the quantity A prior to failure with the upper integration limit the time ( $t < t_b$ ) at which we wish to assess the damage. Thus,

$$A(t) = \int_0^{t/t_b} \frac{(\sigma_t - \sigma_{cr})^B}{(\sigma_{tM} - \sigma_{cr})^B} d(t/t_b) \quad (L-3)$$

and

$$\Sigma D(t) = \frac{(\sigma_{tM} - \sigma_{cr})^B t_b A(t)}{P(n) (\sigma_{to} - \sigma_{cr})^B t_o A_p} \quad (L-4)$$

This relation is greatly simplified on dividing Equation (L-4) by (L-2) to give

$$\Sigma D(t) = A(t)/A \quad (L-5)$$

Considering Equation (L-5), if the specimen which had been previously damaged fails at the time  $t$ , then the total damage on the specimen, by definition, must equal one. Since  $\Sigma D(t)$  is less than one, the difference must be accounted for by the previous damage,  $\Sigma D_p$ . Thus,  $\Sigma D(t)$  becomes

$$\Sigma D(t) = 1 - \Sigma D_p \quad (L-6)$$

The values of  $A$  and  $A(t)$  can be obtained by integration of the data from a single uniaxial test record, from which the ratio  $A(t)/A$  and hence  $\Sigma D_p$  can be plotted versus testing time. From the original test record we can make a plot of the stress versus time and the strain versus the time. Using these three plots then for failure at any given testing time,  $t$ , corresponding values for the stress, the strain and  $\Sigma D_p$  can be read off. Plotting the values of  $\sigma$  and  $\epsilon$  versus  $\Sigma D_p$  gives the desired failure curves and shows the reduction in the undamaged<sup>p</sup> values  $\epsilon_b$  and  $\sigma_b$  caused by the previous damage.

APPENDIX M  
INPUT DATA FOR PRESSURIZATION TESTS  
ON A PBAN PROPELLANT

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APPENDIX M

INPUT DATA FOR PRESSURIZATION TESTS ON A PBAN PROPELLANT

The data input procedures follow those shown in Appendix A. The Prony Series constants are tabulated in Table M-1. The time-temperature and the time-pressure shift factors are tabulated in Table M-2.

The cumulative damage parameters for this propellant are as follows:

$$B = 8.75$$

$$\sigma_{to} = 71 \text{ psi}$$

$$t_o = 1 \text{ min.}$$

For reference purposes we have provided a master relaxation curve, Figure M-1, and the curves for  $a_T$  and  $a_p$ , Figures M-2 and M-3, respectively.

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Appendix M

TABLE M-1

MODULUS INPUT FOR PBAN PROPELLANT

<u>log t/a<sub>T</sub>, min.</u>	<u>E(T) psi</u>	<u>B<sub>i</sub><sup>-1</sup> min.</u>	<u>A<sub>i</sub>/3</u>	<u>i</u>
			8	0
-11	11,000	5 x 10 <sup>10</sup>	3241.4	1
-10	6,600	5 x 10 <sup>8</sup>	1187.7	2
-9	3,700	5 x 10 <sup>6</sup>	287.07	3
-8	1,850	5 x 10 <sup>4</sup>	108.14	4
-7	1,200	5 x 10 <sup>2</sup>	45.09	5
-6	750	5 x 10 <sup>0</sup>	32.153	6
-5	550	5 x 10 <sup>-2</sup>	18.209	7
-4	398	5 x 10 <sup>-4</sup>	14.289	8

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Appendix M

TABLE M-2  
 SHIFT FACTORS FOR PBAN PROPELLANT

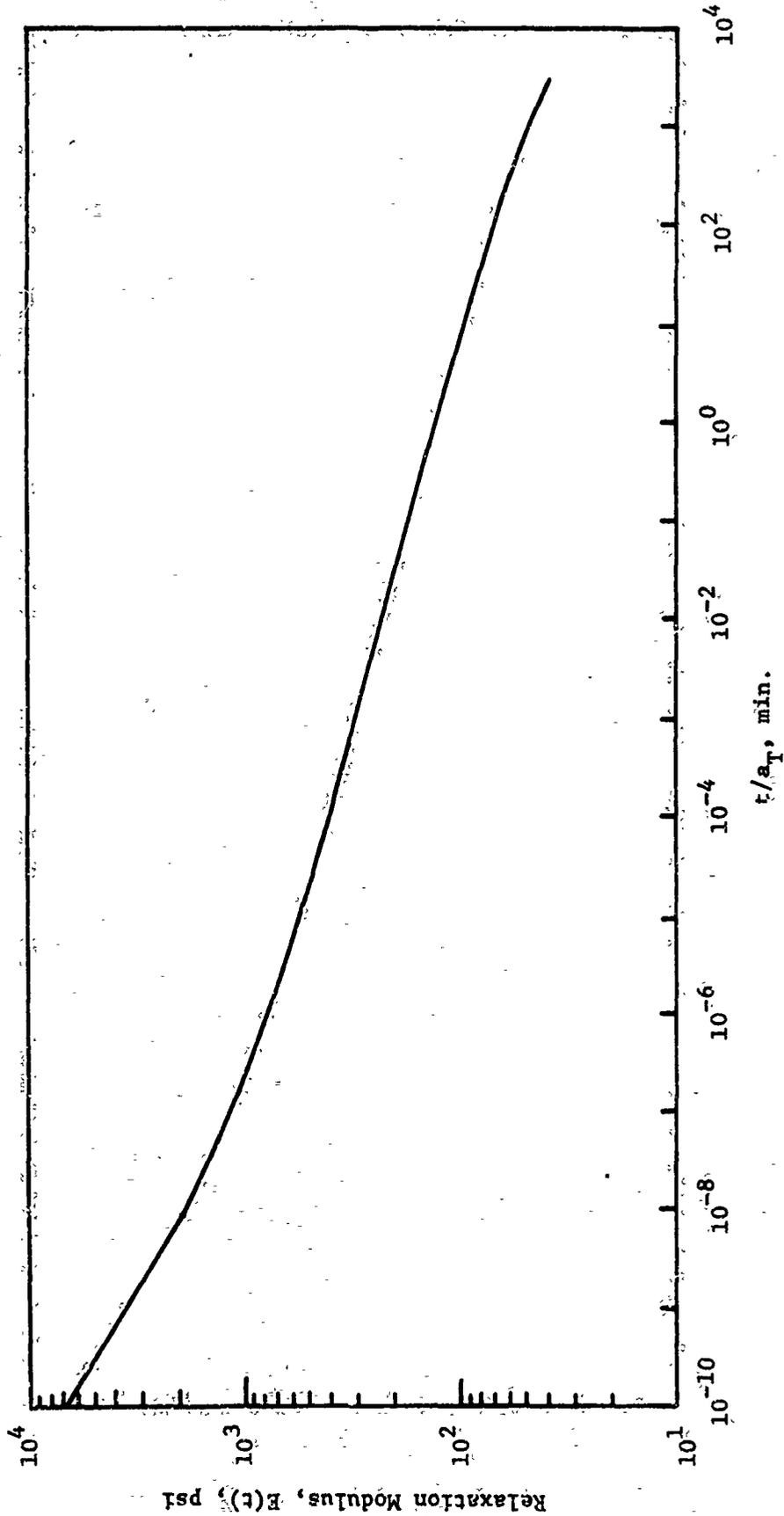
TIME-TEMPERATURE SHIFT FACTORS

<u>Temp., °F</u>	<u>log<sub>10</sub> a<sub>T</sub></u>
180	-2.508
150	-1.903
110	-0.876
77	0
40	2.097
0	4.057
-40	7.008
-75	10.528

TIME-PRESSURE SHIFT FACTOR

<u>Press., psig.</u>	<u>a<sub>p</sub></u>	<u>log<sub>10</sub> a<sub>p</sub></u>
0	1	0
200	51	1.71
600	150	2.176
1000	250	2.398

RELAXATION MODULUS FOR PBAN PROPELLANT



TIME-TEMPERATURE SHIFT FACTOR FOR PBAN PROPELLANT

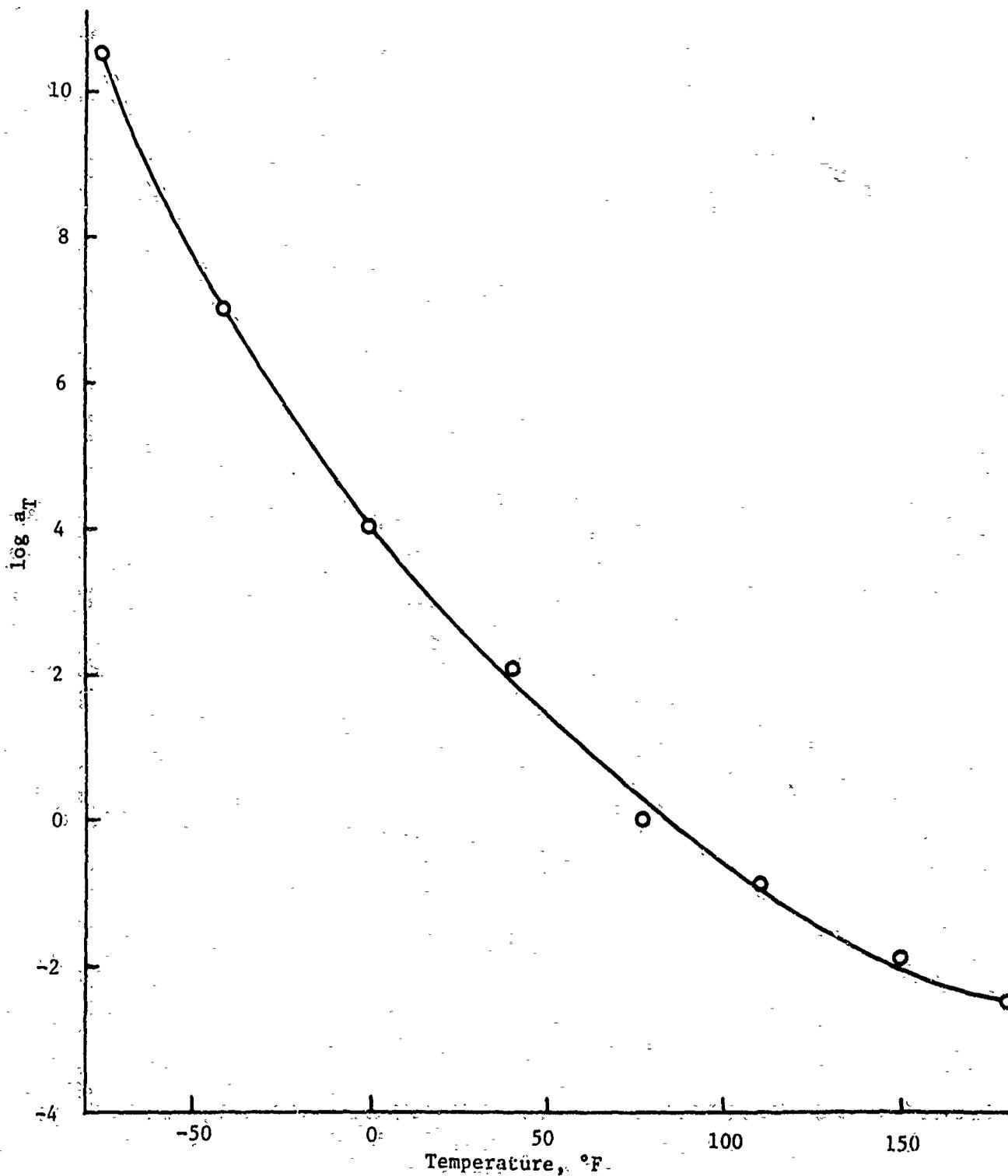


Figure M-2

TIME-PRESSURE SHIFT FACTOR FOR PBAN PROPELLANT

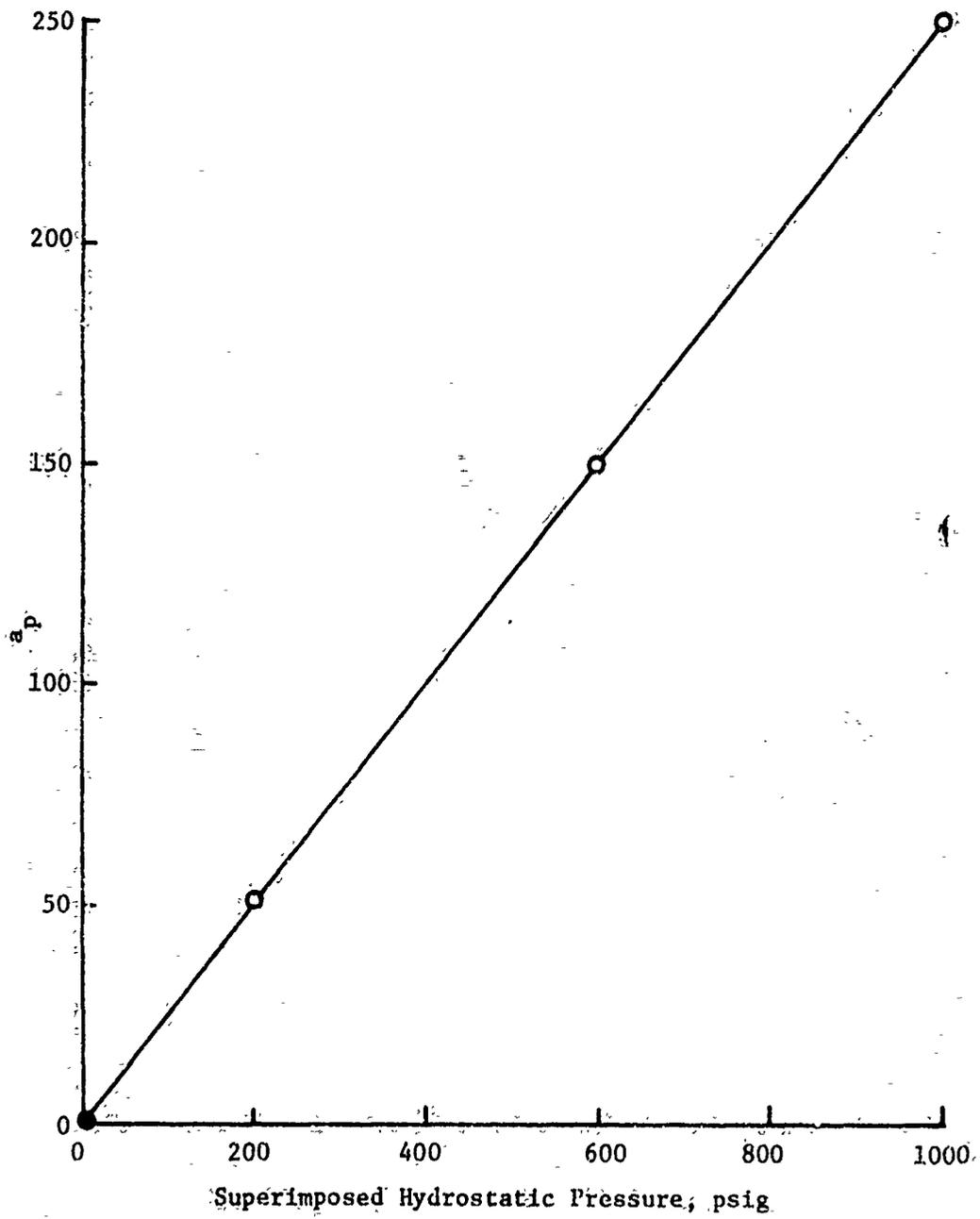


Figure M-3