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# AERODYNAMIC DRAG ON SPIKED BLUNT BODIES IN LOW-DENSITY HYPERSONIC FLOW

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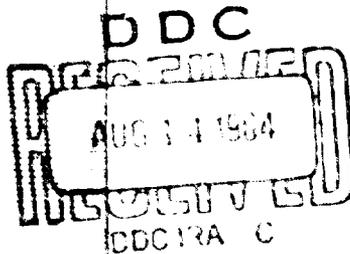
By

William H. Sims and Jerry S. Hahn  
von Kármán Gas Dynamics Facility  
ARO, Inc.

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**ARNOLD ENGINEERING DEVELOPMENT CENTER  
AIR FORCE SYSTEMS COMMAND  
UNITED STATES AIR FORCE**

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AERODYNAMIC DRAG ON SPIKED BLUNT  
BODIES IN LOW-DENSITY HYPERSONIC  
FLOW

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ARO, Inc.

a subsidiary of Sverdrup and Parcel, Inc.

August 1964

ARO Project No. VL2407

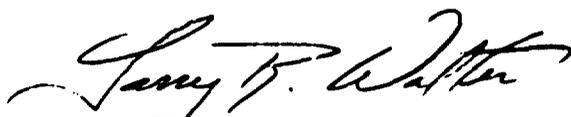
## ABSTRACT

Aerodynamic drag on spiked blunt bodies has been measured in hypersonic, low-density flow of nitrogen. Two models were tested: a spherically capped cone of 10-deg half-angle at  $0 \leq \alpha \leq 40$  deg, and a right circular cylinder at  $\alpha = 0$ . Reynolds numbers, based on total body lengths and free-stream conditions, varied from 200 to 1200. Mach number was constant at 10.1.

Results have been compared with modified Newtonian and free-molecule calculations. Effects of hypersonic rarefied flow are apparent, with drag coefficient increasing for large angles of attack for all spike lengths. A correlation procedure suggested in an earlier report for a large class of similar bodies at 0-deg angle of attack is shown to be effective in the case of spiked bodies too. It is apparent that the marked reduction of drag effected by use of spikes on blunt-nosed bodies at higher Reynolds numbers is greatly diminished when low Reynolds numbers exist. However, a moderate reduction is shown for small angles of attack at the Reynolds numbers of the present experiment.

## PUBLICATION REVIEW

This report has been reviewed and publication is approved.



Larry R. Walter  
1st Lt, USAF  
DCS/Research



Donald R. Eastman, Jr  
DCS/Research

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## NOMENCLATURE

$C_{\infty}$	Chapman-Rubesin Constant, $(\mu_w T_{\infty})/(\mu_{\infty} T_w)$
$C_D$	Drag coefficient, $D/(q_{\infty} S)$
$C_D^*$	Normalized drag coefficient, $(C_D - C_{D_i})/(C_{DFM} - C_{D_i})$
$C_{D_i}$	Inviscid-fluid drag coefficient
$D$	Aerodynamic drag force, or diameter
$L$	Model characteristic length; length measured along surface from forward stagnation point to base
$M$	Mach number
$\dot{m}$	Mass flow
$p$	Pressure
$Re_{\infty, D}$	Reynolds number based on body diameter and free-stream conditions
$Re_{\infty, L}$	Reynolds number based on length $L$ and free-stream conditions
$T$	Temperature
$U$	Velocity
$\bar{v}_{\infty}$	Viscous interaction drag parameter, $M_{\infty} \sqrt{C_{\infty}/Re_{\infty, L}}$
$x$	Axial coordinate relative to nozzle exit, zero at exit, positive downstream
$y$	Radial coordinate relative to nozzle centerline, zero on centerline, positive upward
$\alpha$	Angle of attack
$\gamma$	Ratio of specific heats
$\mu$	Viscosity
$\rho$	Density

### SUBSCRIPTS

- $o$  Isentropic stagnation conditions. When used in combination with a prime ( $p_o'$ ), conditions at the stagnation point on a body are referred to.
- FM Free-molecule condition

- i Inviscid value
- L Based on model characteristic length
- w Wall conditions
- ∞ Free-stream or test section conditions

## 1.0 INTRODUCTION

The aerodynamic characteristics of blunt bodies fitted with spikes or "windshields" have been studied extensively with the purpose of reducing the drag forces and heating rates on the bodies (Refs. 1-7). Although those studies have encompassed a wide range of Mach numbers, they have been restricted to the high Reynolds number range which does not indicate the viscous interaction effects which planetary entry vehicles encounter at very high altitudes.

For the speed regime of satellite vehicles entering the Earth's atmosphere, the necessity of minimizing convective heating led to blunt shapes for payload housing. However, as velocities increase to interplanetary speeds radiation heating assumes a more important role than does convective heating, reviving interest in the more slender configurations. When the roles of drag coefficient and heat-transfer coefficient are considered in minimizing the ratio of heat transfer to drag coefficients (Ref. 8), the desired body fineness ratio then is much smaller. Because earlier experiments have revealed the effect of low Reynolds numbers on the drag of a type of blunt body of interest for planetary probes and Earth satellites (Ref. 9), it was believed worthwhile to investigate the drag of the same shape after modification to what might be considered a low-drag, low-radiation-heating configuration by addition of a nose spike. While the effect of a spike is well known in general, it was doubted if the effect would be as favorable under simulated high-altitude conditions.

In order to extend available data into the rarefied flow regime, an investigation was conducted in the low-density, hypersonic tunnel (Gas Dynamic Wind Tunnel, Hypersonic (L)) of the von Kármán Gas Dynamics Facility (VKF), at the Arnold Engineering Development Center (AEDC), Air Force Systems Command (AFSC). This report contains results of this investigation concerning the aerodynamic drag at various angles of attack for a Mach number of 10.1 and Reynolds number, based on model wetted length, from 200 to 1200.

## 2.0 APPARATUS

### 2.1 WIND TUNNEL

Tunnel L is a continuous, arc-heated, ejector-pumped, low-density wind tunnel. The major components are (1) a d-c arc heater of the

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Manuscript received July 1964.

constricted-arc type with a 40-kv power supply, (2) a settling section of variable length but normally about 6 in. long, (3) a contoured aerodynamic nozzle with uniform test section fluid properties, (4) a test chamber of 48-in. diameter surrounding the test section and containing instrumentation and probe carrier, (5) an interchangeable diffuser, (6) a heat exchanger, (7) an air ejector of two stages, and (8) the VKF vacuum pumping system. All critical components of the tunnel are protected by back-side water cooling. The two-stage ejector system is driven by air instead of steam because of the ready availability of the former in the present case. The working gas in this case was nitrogen. A more detailed description of the tunnel is given in Ref. 10.

## 2.2 DRAG BALANCE

Although of small size, Tunnel L is suitable for aerodynamic-force tests if small models are used and a balance capable of measuring the extremely small aerodynamic loads is available. The one-component balance utilized throughout these tests is capable of good accuracy even when full-scale loads as low as 0.02 lb are of concern. Figure 1 shows the balance with a model in Tunnel L.

The balance has an internal parallelogram-type structure, with the deflection being proportional to the force applied along the axis of the sting. The deflection is sensed with a linear variable differential transformer with a 0.005-in. linear range. Approximately 0.003-in. deflection of the balance is equivalent to 0.3 lb.

Calibration of the balance\* was performed several times during the period of tunnel operation. Figure 2 shows typical calibrations, indicating the repeatability of the calibration constant. Aerodynamic drag loads were on the order of 0.01 lb during the test. The effect of normal-force interaction was studied by placing dummy loads on the balance sting greater than the expected normal-force loads during the test, and the interaction was found to be negligible. Because the balance only measures forces parallel to the sting, to measure drag at angles of attack, models must be constructed with appropriate provisions to achieve a range of angles of attack. In the present case, this was accomplished by fabricating separate models.

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\*This balance was developed by the Transducer Development Section, Instrumentation Branch, VKF, under the supervision of D. S. Bynum.

## 2.3 MODELS

The basic configuration of the models is a 10-deg semi-vertex blunted cone with a modified spherical nose segment and a right circular cylinder. The right circular cylinder was tested with its axis of symmetry parallel to the flow centerline. The models are shown in Figs. 3 and 4, with the basic dimensions indicated in Fig. 4. For purposes of data reduction, the characteristic length is defined as: (1) the length measured along the surface of the model from the stagnation point of the hemispherical nose to the rim of the flat base, plus the axial length of the spike, for the Mars entry body, and (2) the total axial length from the spike tip to the flat base for the right circular cylinder. After fabrication, the models were inspected with an optical comparator, and the angles of attack were measured as given in Fig. 4.

## 3.0 EXPERIMENTAL PROCEDURE

The test models were placed on the balance sting at a predetermined station in the test region of the nozzle. The models were first tested at a positive angle of attack, then rotated 180 deg and tested at a negative angle of attack. Run duration was limited to not more than approximately 20 sec to prevent excessive heating of the balance components and to retain the relatively cold-wall model conditions.

The right circular cylinder was tested only at 0-deg angle of attack.

Shown in Fig. 5 are impact-pressure profiles for the stations in the nozzle where the models were placed for testing. The nozzle used is a Mach 10, completely contoured, 0.1481-in. -diam-throat nozzle. The surveys show that the nozzle is completely free of axial gradients in the test section. Test conditions were  $p_o = 18$  psia,  $T_o = 5625^\circ R$ ,  $M_\infty = 10.1$ , and  $Re_\infty/in. = 388$ .

## 4.0 RESULTS AND DISCUSSION

The models were tested at both positive and negative angles of attack to check for flow angularity in the free-stream. Since no angularity was obviously present, all data have been plotted without distinction, except in the case of Fig. 6. During these runs the sting mount was found to be at a negative 2-to-3-deg angle of attack, thereby requiring the zero-shift found in Fig. 6.

The data have been reduced to coefficient form and are presented as functions of both  $L_{\text{spike}}/D_{\text{base}}$  and the viscous interaction parameter (cf. Ref. 11),

$$\bar{v}_w = M_\infty \sqrt{C_D \cdot \text{Re}_{\infty, L}}$$

where

$$C_D = (\mu_w T_\infty) / (\mu_\infty T_w)$$

and

$$\text{Re}_{\infty, L} = U_\infty \rho_\infty L / \mu_\infty$$

and  $L$  is the body length as defined in Fig. 4 and Section 2.3. The coefficient  $(C_D)^{1/2}$  was essentially constant ( $\approx 0.83$ ) for this investigation.

A comparison of all data at each angle of attack is shown in Fig. 6. Some data show variations of  $\pm 10$  percent, although in the majority of the cases the maximum scatter is on the order of  $\pm 5$  percent.

In order to retain the relatively cold-wall conditions desired, the models were allowed to remain in the flow on the average of only 10 to 20 sec. It has been shown (cf. Refs. 11 and 12) that the aerodynamic drag in low-density, hypersonic flow is a function of the wall-to-stagnation temperature ratio,  $T_w/T_0$ . The scatter indicated in Fig. 6 could be caused by slight variations in model wall temperature, although there is no systematic variation indicated by the data. The value of  $T_w/T_0$  was estimated for the present tests to be 0.2.

Figure 7 indicates that as  $\bar{v}_w \rightarrow 0$  the viscous effects are reduced, as found in earlier studies. Here it may be noted that the reduction in  $\bar{v}_w$  for the present tests was obtained by increasing the model characteristic length,  $L$ , whereas in Ref. 9 the variation was obtained by changing the flow conditions. The correlation of the spiked body data with the basic body of Ref. 9 is very good considering the differences in the forebodies.

As is noted in earlier studies, for bluff bodies such as the right circular cylinder, drag coefficients may be reduced by more than an order of magnitude (cf. Ref. 1) in high Reynolds number cases using the sharp spikes. However, as shown in Figs. 7 and 8, no such marked reduction occurs for the density altitude simulated here. Although a reduction of 27 percent in drag is realized, the length of spike required to accomplish this ( $5.0 D_{\text{base}}$ ) may be prohibitively long.

The variation of  $C_D$  with  $\bar{v}_w$  is shown in Fig. 9. Here a very revealing effect occurs which is undoubtedly due to the predominant viscous

effects on the spikes. Whereas in earlier studies reductions in  $C_D$  were realized even at large angles of attack when spikes were incorporated in the body, this is no longer true for the present tests: for increasing spike length and angle of attack above approximately 25 deg, the spike has the effect of increasing the drag.

The value of about 25 deg for maximum angle of attack at which a drag reduction may be expected for various spike lengths is clearly demonstrated in Fig. 10. Here it may be seen that the drag coefficient is essentially constant for a variable spike length at an approximate value of angle of attack of 24 deg.

Following the analysis of Ref. 9, Fig. 11 is prepared showing the correlation of the normalized parameter,  $C_D^*$ , with the viscous interaction parameter,  $\bar{v}_\infty$ . Included in Fig. 11, from Ref. 9, are data obtained at 0-deg angle of attack, which have been correlated with the present tests for varying spike lengths ( $0 \leq L_{\text{spike}}/D_{\text{base}} \leq 5$ ). The degree of correlation is indeed gratifying, showing the removal of forebody shape dependence. The effects were removed by normalizing the data using the parameter of Ref. 9,

$$C_D^* = (C_D - C_{D_i}) / (C_{D_{FM}} - C_{D_i})$$

When  $C_D^*$  is plotted as a function of the viscous interaction drag parameter,  $\bar{v}_\infty$ , for sufficiently rarefied flow,  $C_D^*$  will approach 1.0, and for nearly inviscid flow,  $C_D^*$  will approach 0.0.

The correlation of the spiked body drag with that of Ref. 9 is seen to be much better in Fig. 11 as compared to that given in Fig. 7. The values of  $C_{D_i}$  used in Fig. 11 were obtained from Ref. 14.

Data corresponding to minimum and maximum values of  $\bar{v}_\infty$  for the range of angle of attack from 0 to 40 deg have been plotted in Fig. 12, which compares the data to both modified Newtonian theory and the theory for free-molecule flow (Ref. 13). Simulation well into the transition regime between continuum, inviscid-fluid flow, and free-molecule flow was achieved. It was assumed that the incident molecules were at  $T_\infty$ , the reflected molecules at  $T_w$ , and the wall temperature was constant over the model.

## 5.0 CONCLUDING REMARKS

Aerodynamic drag has been determined for a short 10-deg blunted cone and a right circular cylinder with spikes as forebodies in a flow

regime in which viscous interaction effects are significant. Comparison of the data to inviscid, modified Newtonian, and free-molecule theory indicates that the drag coefficient was affected significantly by viscous-fluid effects.

Reductions in drag coefficient for small angles of attack and  $0 \leq L_{\text{spike}}/D_{\text{base}} \leq$  were realized, although, contrary to high Reynolds number cases, increase in drag were obtained for the large angles of attack ( $\geq 25$  deg) with spike length increasing. Approximately 25-percent reductions in  $C_D$  were obtained at 0-deg angle of attack. However, this magnitude of reduction in drag is far less than has been found to occur at high Reynolds numbers.

Correlation of the data for spiked and unspiked bodies by using the parameter  $C_D^*$  (suggested by J. L. Potter for use in Ref. 9) indicates that the model shape dependence of  $C_D$  was largely removed. This suggests a method for estimating approximate drag coefficients of a wide variety of similar shapes by obtaining inviscid and free-molecular drag coefficients and referring to the correlation curve presented herein.

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Fig. 1 Balance and Model Mounted in Tunnel L

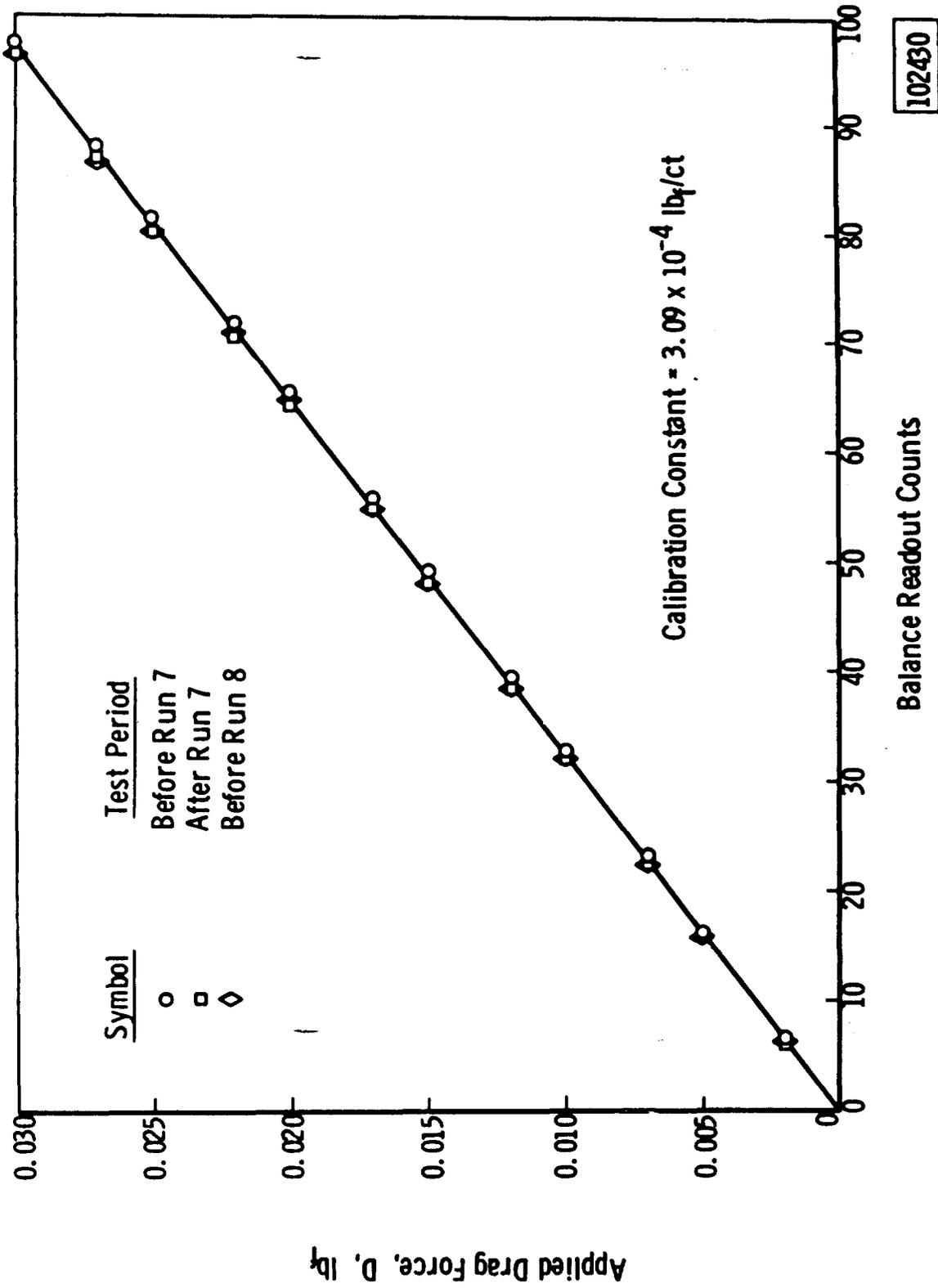
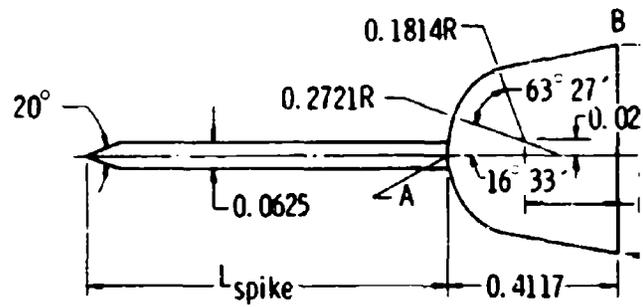


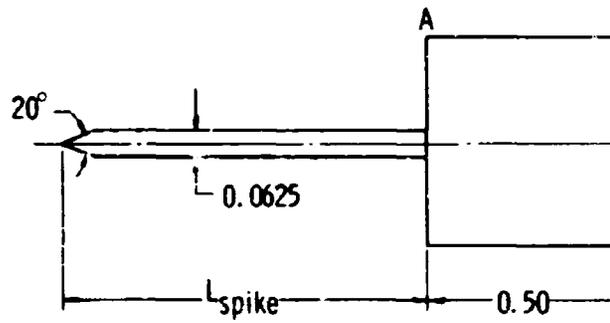
Fig. 2 Typical Balance Calibration



Fig. 3 Photograph of Models



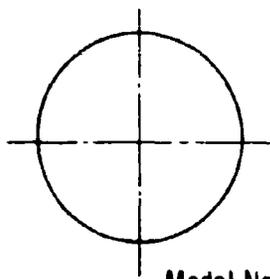
All Dimensions in Inches



12

Fig. 4

00  
266  
∠  
10°



Model No.

Angle of Attack

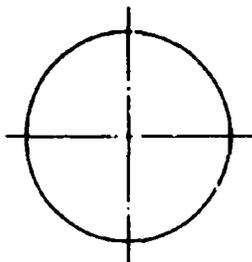
Mars Probe

$L = 0.542 + L_{spike}^*$

- 1
- 2
- 3
- 4
- 5

- 0
- 10°
- 20°
- 31° 26'
- 40°

0.50



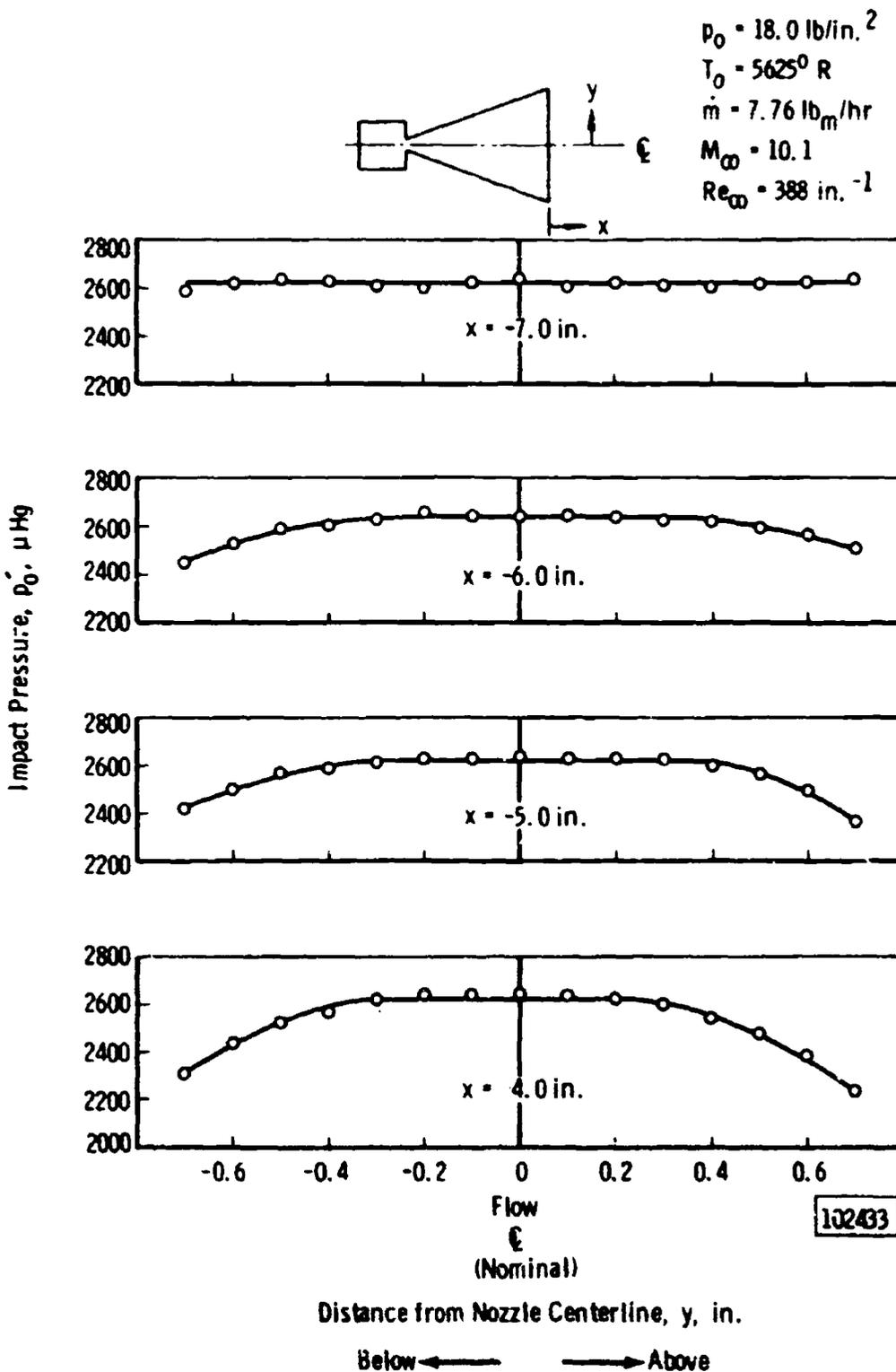
Right Circular Cylinder

$\alpha = 0^\circ, L = 0.50 + L_{spike}^*$

\*The length L is defined as the distance AB in the sketch plus  $L_{spike}$ .

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Model Dimensions



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Fig. 5 Radial Impact Pressure Surveys of Nozzle

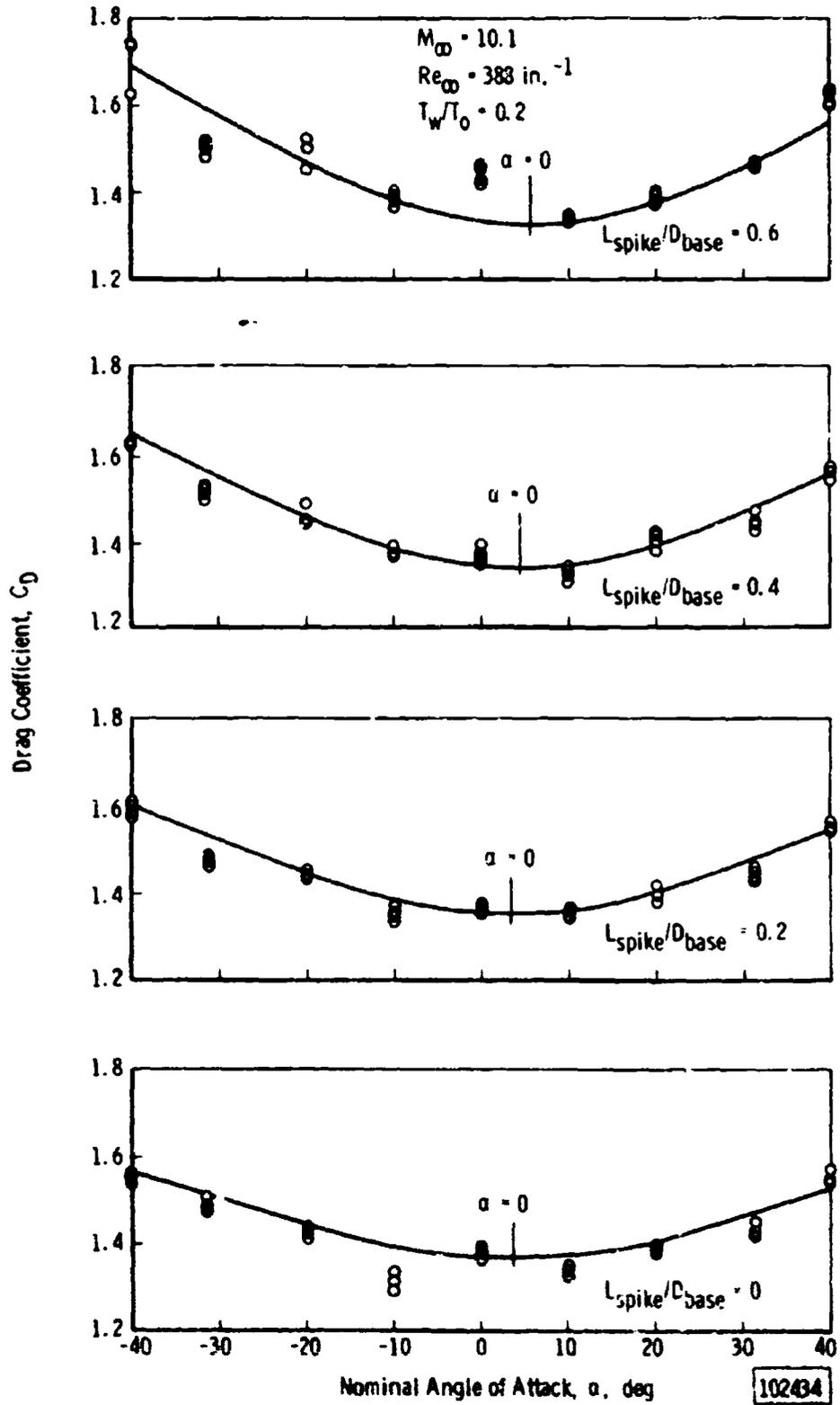


Fig. 6 Drag Coefficient as a Function of Angle of Attack

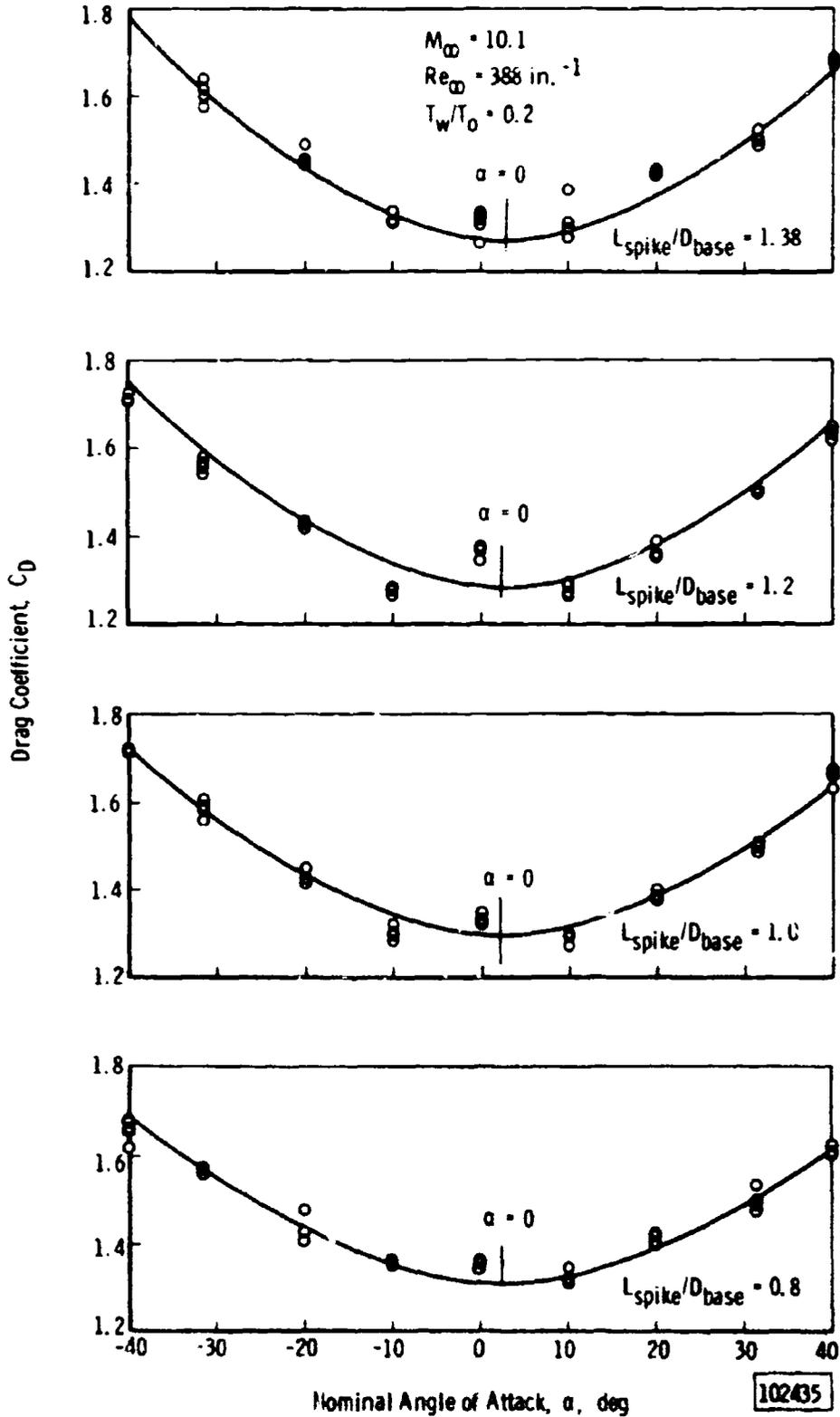


Fig. 6 Concluded

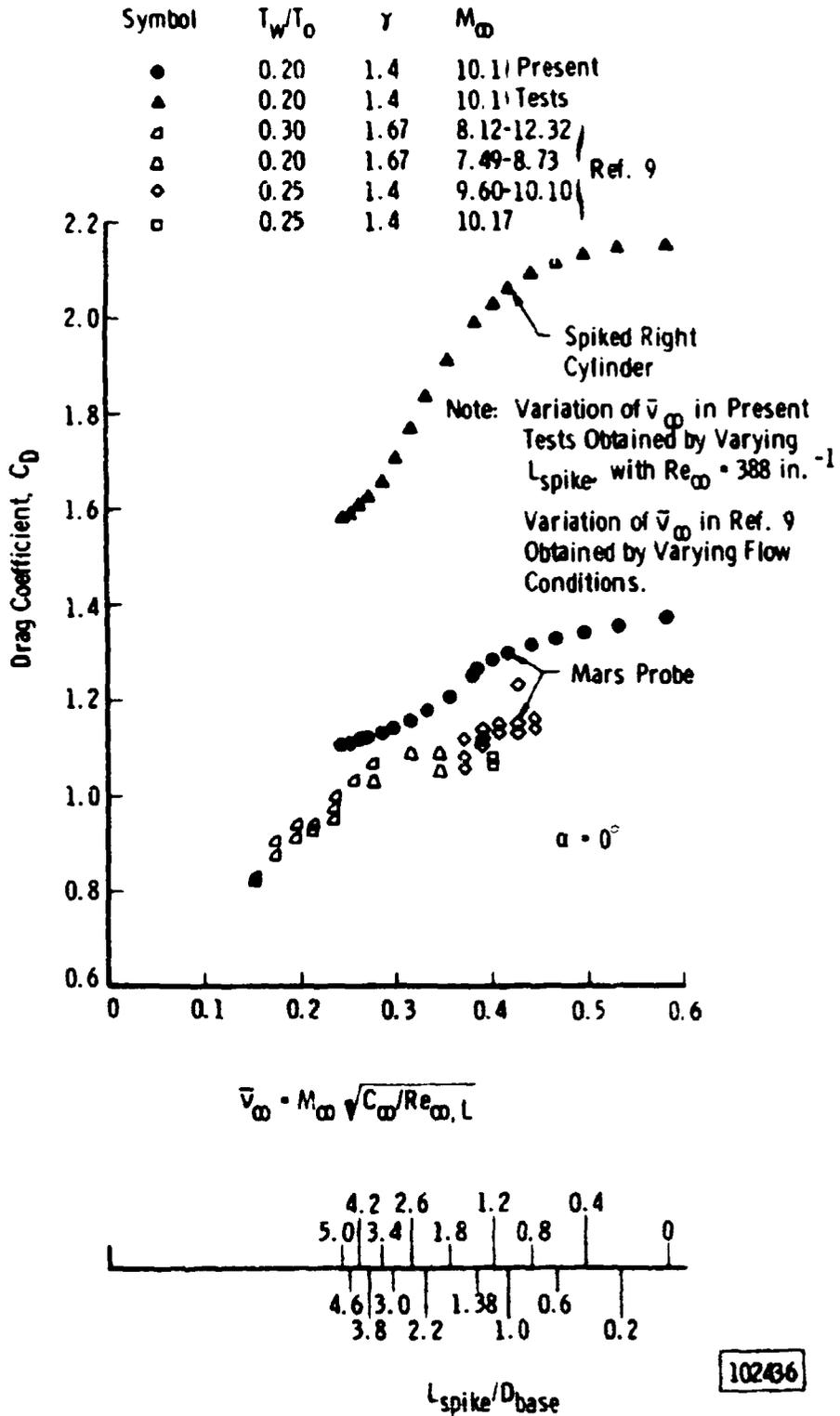


Fig. 7 Drag Coefficient as a Function of  $\bar{v}_\infty$  ( $\alpha = 0$  deg)

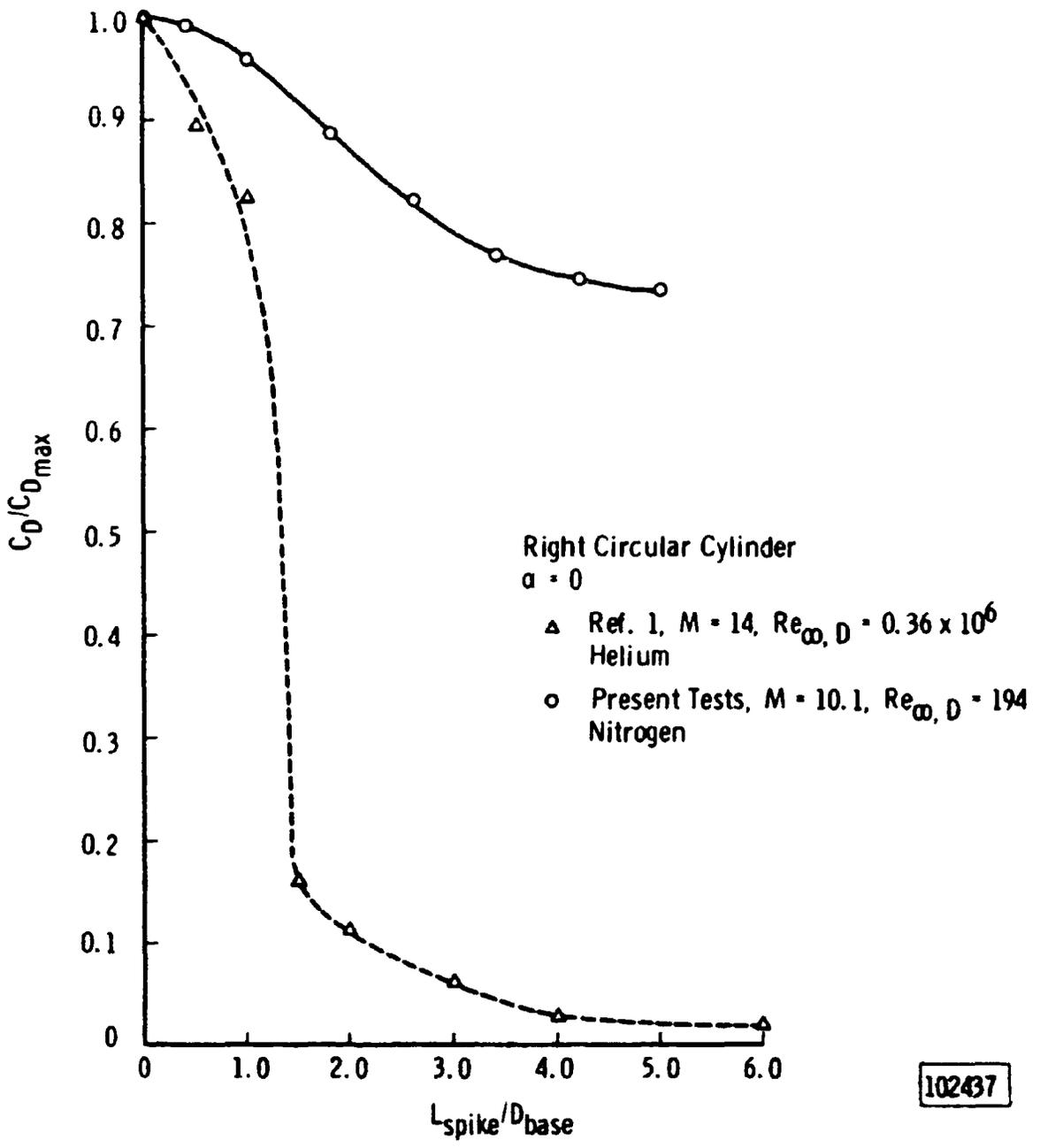


Fig. 8 Drag Coefficient Ratio,  $C_D/C_{D_{max}}$ , as a Function of Spike Length for the Right Cylinder

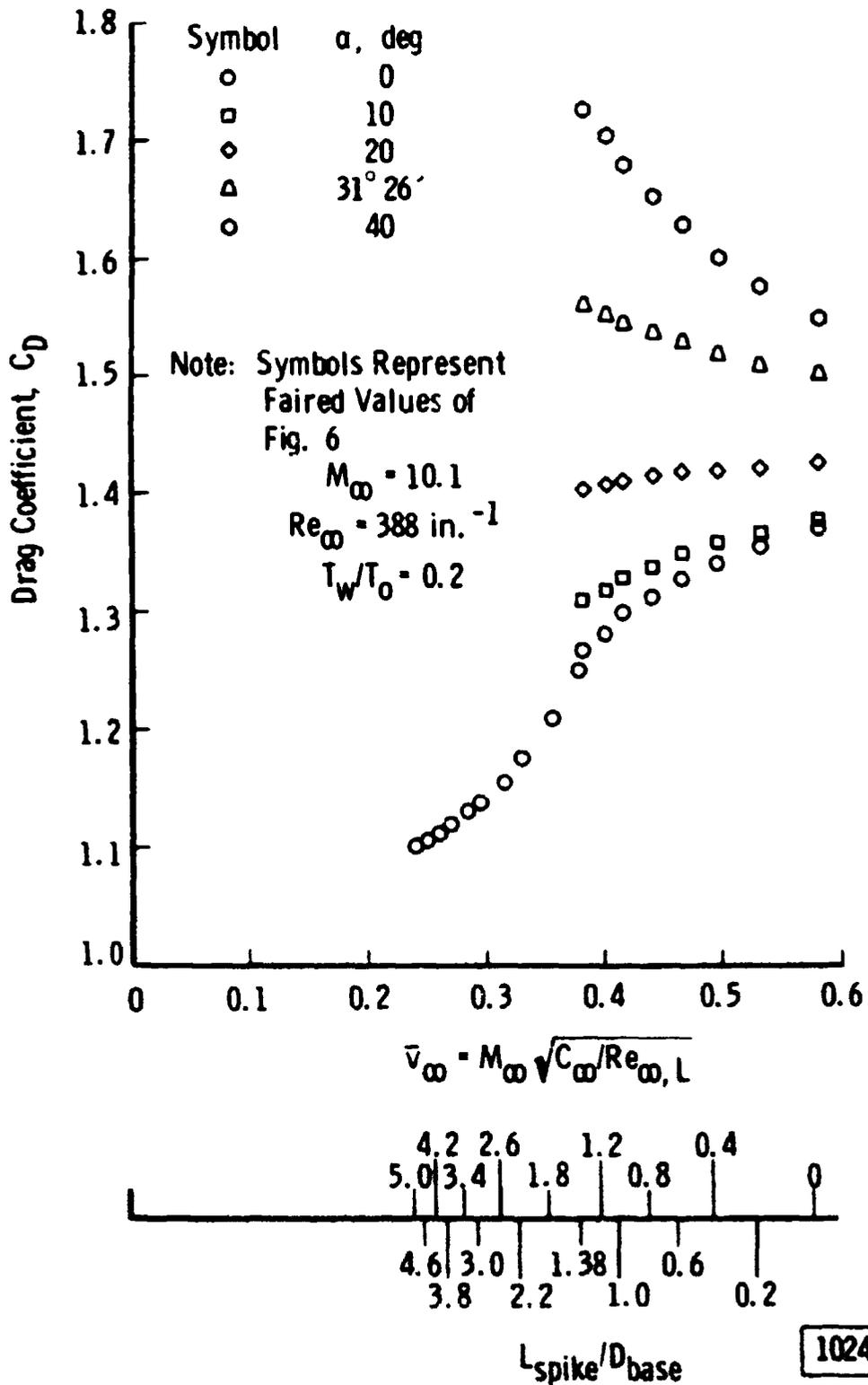


Fig. 9 Drag Coefficient of Mars Probe as a Function of  $\bar{v}_\infty$  for Varying Angle of Attack

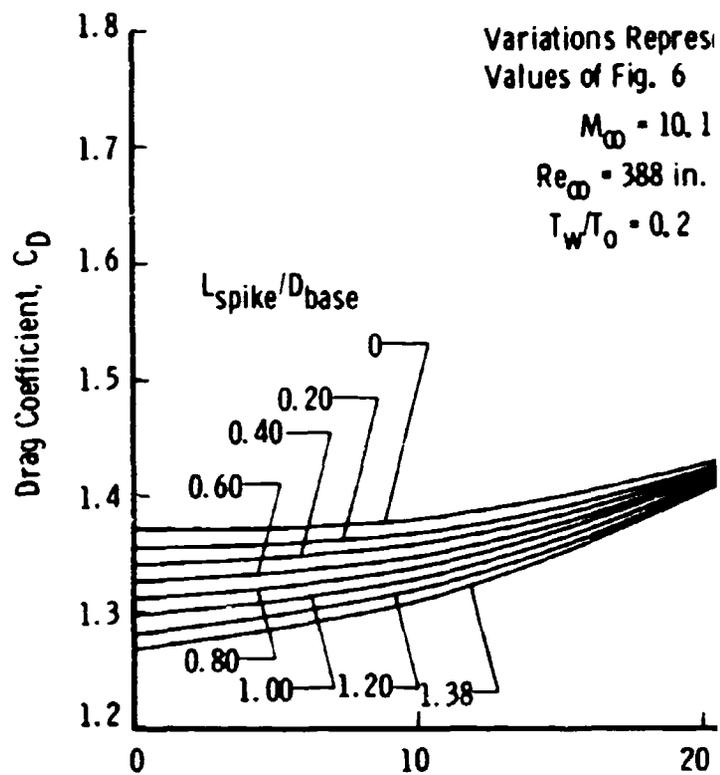
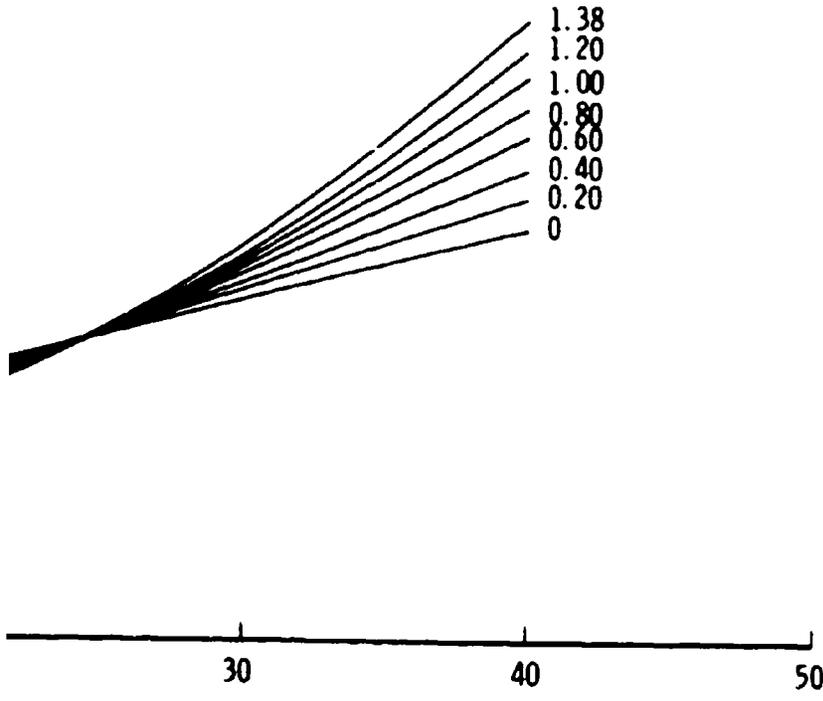


Fig. 10 Drag Coefficient of the Mars Probe

Faired

$L_{spike}/D_{base}$

- 1.38
- 1.20
- 1.00
- 0.80
- 0.60
- 0.40
- 0.20
- 0



Angle of Attack,  $\alpha$ , deg

102439

Function of Angle of Attack for Varying  $L_{spike}/D_{base}$

AEDC-TDR-64-160

Symbol	$M_\infty$	$\alpha$ , deg	Model	$T_w/T_0$	$\gamma$	Tests
○	10.1	0	Mars	0.20	1.4	Present
▲	7.49-12.32	0	Mars	0.20-0.30	1.4 & 1.67	Ref. 9

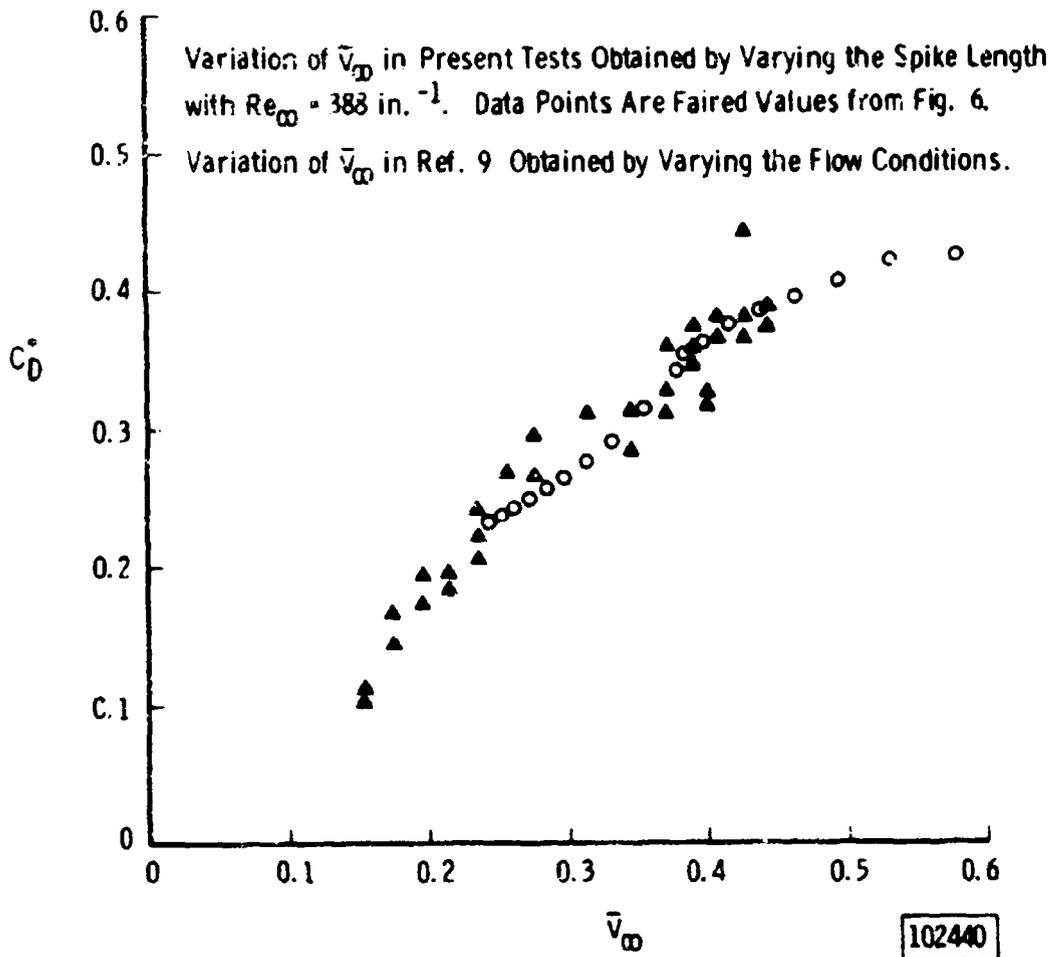


Fig. 11 Normalized Drag Coefficient,  $C_D^*$ , as a Function of  $\bar{V}_\infty$  for the Mars Probe

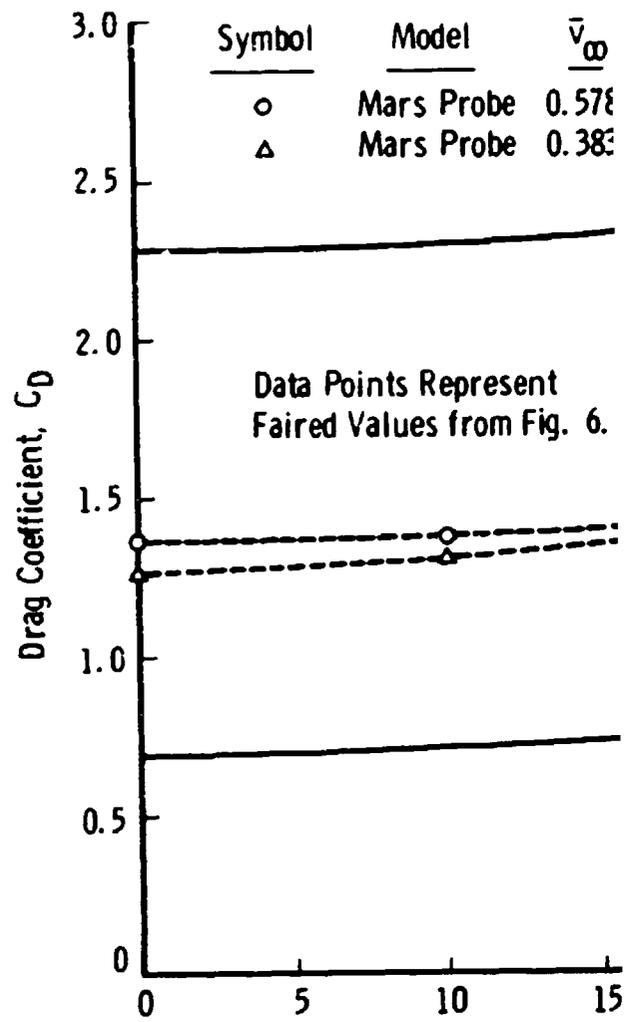
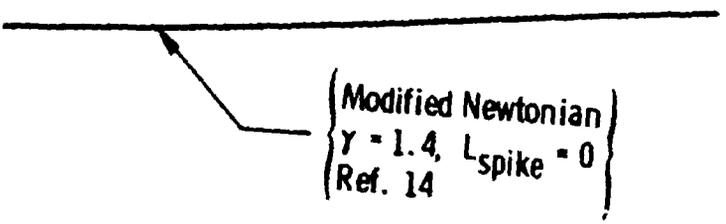
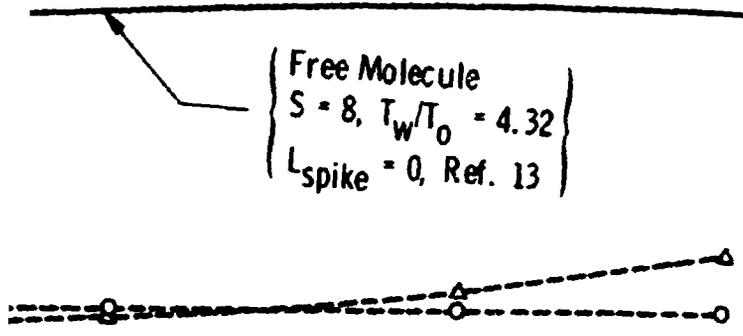


Fig. 12 Drag Coefficient as a Funct

$L_{spike}/D_{base}$	$M_{\infty}$	$Re_{\infty}$
0	10.1	388 in. <sup>-1</sup>
1.38	10.1	388 in. <sup>-1</sup>



20 25 30 35 40  
 Angle of Attack,  $\alpha$ , deg

102441

Angle of Attack at Constant Values of  $\bar{v}_{\infty}$

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